



for a greener tomorrow



**MITSUBISHI  
ELECTRIC**

*Changes for the Better*

**FACTORY AUTOMATION**

# INVERTER FR-A800

Unparalleled Performance. Uncompromising Quality.



- Leading drive performance
- Security & safety
- Easy setup & easy to use

- Eco-friendly factories
- System support
- Environmental adaptability

# Unparalleled Performance. Uncom

*What is required of inverters in this constantly changing world?*

*At Mitsubishi, we have pursued the answer to this question through constant innovation and evolution.*

*Introducing our extensive range of high-value, next-generation inverters delivering outstanding drive performance in any environment, and a wealth of functionality covering startup to maintenance.*

*We utilized the traditional Mitsubishi philosophy to further perfect our inverters.*

**01**



## LEADING DRIVE PERFORMANCE

The enhanced Real sensorless vector control and vector control serve the needs of all machinery types.

**02**



## SECURITY & SAFETY

Rapid response is obtained when an unexpected trouble occurs.

**03**



## EASY SETUP & EASY TO USE

Fully equipped with a variety of simple functions and equipment to improve work efficiency.

**04**



## ECO-FRIENDLY FACTORIES

Save energy while increasing factory production.

**05**



## SYSTEM SUPPORT

Numerous functions and the extensive lineup of models are ready to support various systems.

**06**



## ENVIRONMENTAL ADAPTABILITY

The FR-A800 series complies with various standards and is usable in different scenes.

# A800



# promising Quality.



Features	P.1
Application Example PLC Function FR Configurator2	P.13
Connection Example	P.21
Standard Specifications	P.22
Outline Dimension Drawings	P.28
Terminal Connection Diagram Terminal Specification Explanation	P.39
Operation panel (FR-DU08(-01)) LCD operation panel (FR-LU08)	P.48
Parameter List	P.53
Explanations of Parameters	P.90
Protective Functions	P.144
Option and Peripheral Devices	P.147
Low-Voltage Switchgear/Cables	P.167
Precaution on Selection and Operation	P.173
Compatible Motors	P.179
Compatibility	P.200
Warranty Inquiry	P.204



# LEADING DRIVE PERFORMANCE

The new series is equipped with the new state-of-the-art high-speed processor developed by Mitsubishi. With better control performance and response level, safe and accurate operation is assured in a diverse range of applications.

## Swift, Smooth, yet Robust

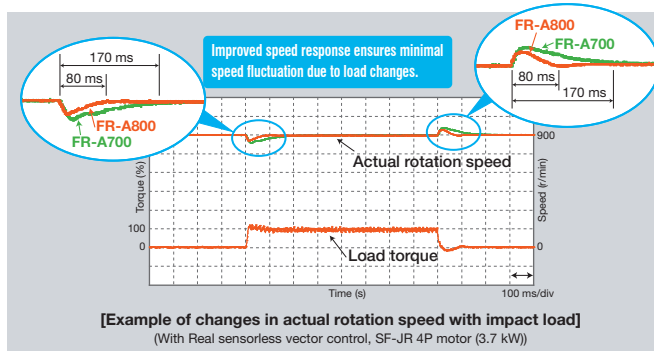
The enhanced Real sensorless vector control and vector control serve the needs of all machinery types.

The vector control is available when a vector control compatible option is installed.

### (1) For high-quality products

#### High response

**Response speed** Real sensorless vector control **50 Hz**\*1 [A700: 20 Hz]  
 Vector control **130 Hz**\*2 [A700: 50 Hz]



#### Faster response via terminals or communication

Process time for terminal and communication commands is minimized.

#### Terminal response, communication response

A700: 5 to 20 ms → A800: 2 to 3 ms\*3

#### Line control

Line control is necessary for the machining of elongated products such as paper, thread, wires, all kinds of sheet, and tape. This will respond rapidly to changes in line speed and suppress the occurrences of winding unevenness. This contributes to a steady supply of high-quality products.



\*1: At 3.7 kW with no load. Differs depending on the load conditions and motor capacity.

\*2: When the FR-A8AP or the FR-A8TP is installed.

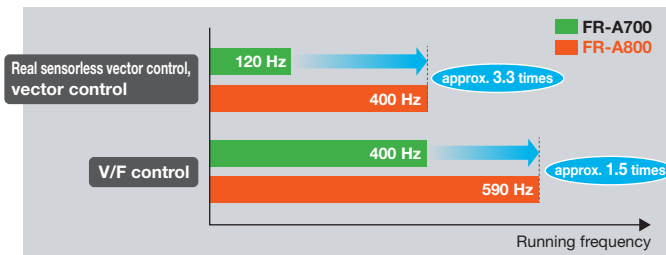
\*3: The communication response is 2 to 5 ms when communication options are used.

Speed response: The speed response indicates how fast the inverter follows the change in the speed command. (The larger value indicates the better speed trackability.)

### (2) Perform ultra-fine processing

#### High-speed rotation

**Operating frequency** Real sensorless vector control and vector control **400 Hz** [A700: 120 Hz]  
 V/F control **590 Hz**\*4 [A700: 400 Hz]



#### Machine tool

Cutting-edge machine tools are harder and thinner than ever before to be applicable to diverse new materials. High-speed rotation is required more than ever before in order to be applicable for fine and precise cutting on hard and difficult-to-grind materials.



\*4: According to the review result of the export control order about frequency changers, the upper limit of output frequency was determined to be 590 Hz for standard models.

### (3) Swiftly move heavy weights

#### High torque at low speed

##### Starting torque (When at 0.3 Hz)

Real sensorless vector control **200%** (ND rating)\*5,  
 Vector control **200%** (ND rating)\*5

(150% of initial setting for 5.5K and higher)

##### Zero-speed torque

Vector control **200%**. (Select HD rating.)\*5

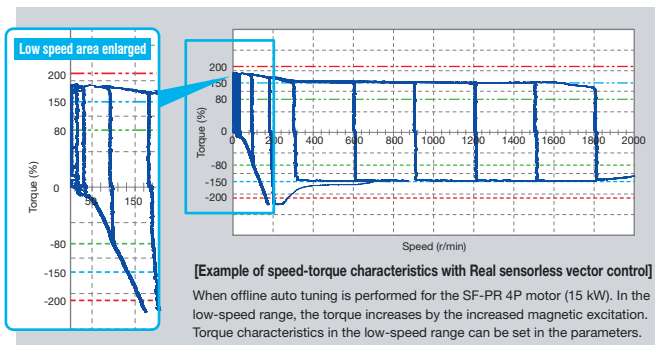
##### Speed control range

V/F control **1:10** (6 to 60 Hz: Driving)

Advanced magnetic flux vector control **1:120** (0.5 to 60 Hz: Driving)

Real sensorless vector control **1:200** (0.3 to 60 Hz: Driving)

Vector control **1:1500** (1 to 1500 r/min: Both driving/regeneration)



#### Cranes

Cranes are in operation daily at ports carrying fully-laden containers in response to strong demand from all over the world. Our new inverter realizes smooth cargo handling work at low speed and high torque for the slow and stable movements required for heavy objects.



\*5: Refer to page 9 for the multiple rating setting.

## (4) For accurate and stable transport between machines

### PM sensorless vector control

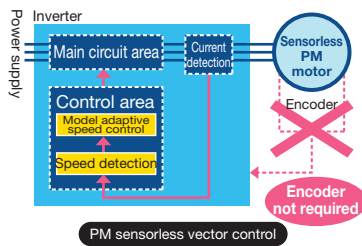
#### • What is a permanent magnet (PM) motor?

A PM motor is a synchronous motor with strong permanent magnets embedded in its rotor. The two major PM motor types are: the interior permanent magnet (IPM) motor with its magnets embedded inside the rotor, and the surface permanent magnet (SPM) motor with its permanent magnets attached on the rotor surface.

#### • What is PM sensorless vector control?

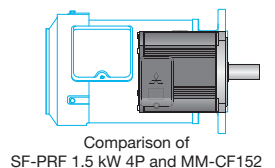
The speed and magnetic pole positions, the two essential bits of information to control a PM motor, are detected without a sensor (encoder). The speed detection internally-performed in an inverter enables highly accurate control of a PM motor, almost as accurate as an AC servo system, without the need of a sensor (encoder)\*6.

Combining with Mitsubishi MM-CF series IPM motors facilitates aspects of high-level control with no encoder such as "simple positioning"\*7 and "zero speed torque".



#### • Easy maintenance for sensor (encoder)-less motor

- No additional cables means less wiring space required.
- Improved reliability is obtained in unfavorable operating environments. (e.g. high vibration)
- PM motors are usually smaller and lighter than induction motors.



#### Transfer of circuit boards

The Simple positioning control delivers a precision workpiece, such as a printed substrate, to a precise position. Transfer of fragile glass substrates can be performed with a highly accurate driving system.



\*6: Speed fluctuation ratio: ±0.05% (digital input)

$$\text{Speed fluctuation ratio} = \frac{\text{Speed under no load} - \text{Speed under rated load}}{\text{Rated speed}} \times 100(\%)$$

\*7: Positional accuracy (with no load) of 1.5K and lower: ±1.8°, 2K and higher: ±3.6°

## (5) Taking motor performance to the max

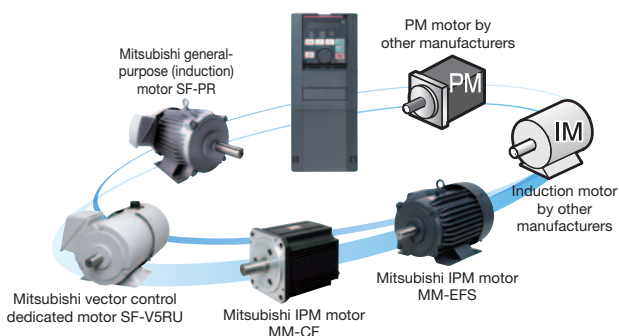
### Induction motors and magnet motors can be combined freely

#### • The cutting-edge auto tuning function

The PM motor auto tuning function, which has been newly developed, enables sensorless operation of other manufacturers' permanent magnet (PM) motors. Operation with all Mitsubishi induction motors and PM motors, in addition to induction motors and PM motors from other manufacturers\*8, is possible. That means you need less motors for spare and stocks.

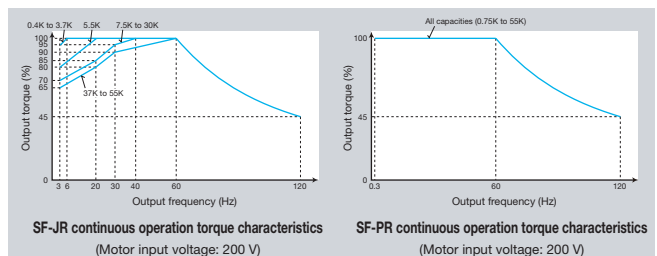
(With IPM motors other than MM-CF and PM motors manufactured by other companies, starting torque is limited to 50%, and simple positioning control and zero speed torque cannot be used even if tuned.)

\*8: Tuning may not be available depending on its motor characteristics.



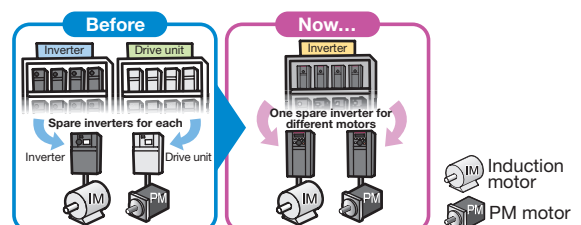
#### • Low speed, high torque realized with SF-PR motor

By combining with Mitsubishi's high-performance, energy-saving motor SF-PR, 100% continuous operation is possible from a low speed of 0.3 Hz for inverters of any capacity. (when using Real sensorless vector control)



#### • Sharing the spare inverter

One spare inverter is enough for the two types of motors (IM and PM).







# SECURITY & SAFETY

Swift recovery ensured by preventing trouble beforehand. The FR-A800 has been developed with reliability and safety foremost in mind.

## For Improved Equipment Reliability

Rapid response is obtained when an unexpected trouble occurs.

### (1) Improved system safety

#### Safety standards compliance **NEW**

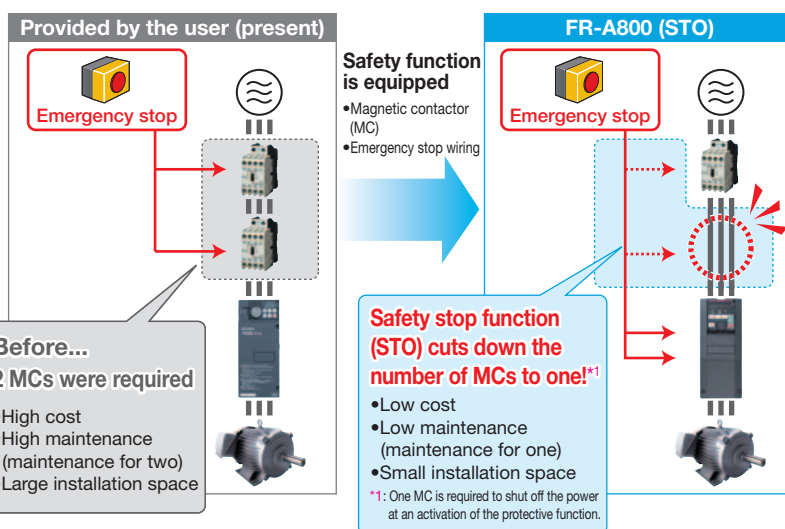
Controls with safety functions can be easily performed.

- PLd and SIL2 are supported as standard. (STO)
  - EN ISO 13849-1 PLd / Cat.3
  - EN 61508, EN 61800-5-2 SIL2
- Compatible with PLe and SIL3 using a built-in option (to be released soon).
  - EN ISO 13849-1 PLe / Cat.4
  - EN 61508, EN 61800-5-2 SIL3

In addition to STO, also compatible with SS1, SS2, SLS, and SOS by using an option (to be released soon).

Functions for IEC/EN 61800-5-2:2007
STO (Safe Torque Off)
SS1 (Safe Stop 1)
SS2 (Safe Stop 2)
SOS (Safe Operating Stop)
SLS (Safely-Limited Speed)

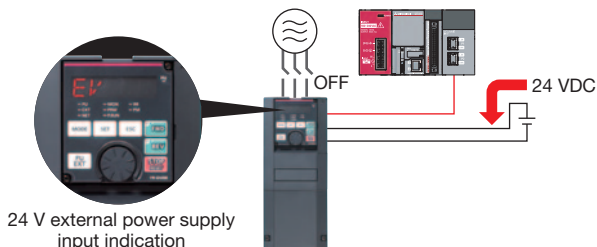
- Safety communication networks will be also supported by using an option (to be released soon).
  - CC-Link IE Safty communication function
  - PROFIsafe



### (2) Reliable and secure maintenance

#### Standard 24 VDC power supply for the control circuit **NEW**

In addition to the existing power supply input terminals (R1 and S1) of the control circuit, 24 VDC input is equipped as standard. The 24 VDC power supplied from outside can be fed to the control circuit locally, enabling the parameter settings, communication operation and safety maintenance without turning ON the main power.



#### Prevention of trouble with temperature monitoring **NEW**

The inverter is equipped with an internal temperature sensor, which outputs a signal when the ambient temperature is high. This facilitates the detection of rises in temperature inside the inverter following cooling fan malfunction, or rises in ambient temperature due to inverter operating conditions.

### (3) Quick reaction to troubles

#### Easy fault diagnosis **NEW**

- The operating status (output frequency, etc.) immediately before the protection function activates can be stored in the inverter built-in RAM with the trace function. Stored data (trace data) can be copied to a USB memory device, facilitating easy trouble analysis at a separate location by reading into the Inverter Setup Software (FR Configurator2).

Trace data stored in the built-in RAM is deleted when the power is turned OFF or the inverter is reset.



- Clock setting is now available in addition to the already-available cumulative energization time. The time and date at a protective function activation are easily identified. (The clock is reset at power-OFF.) The date and time are also saved with the trace data, making the fault analysis easier. By using the real-time clock function with the optional liquid crystal display (LCD) operation panel (FR-LU08) (when using battery), the time is not reset even when the power supply is turned OFF.

## (4) Long life components and life check function

### Long life components

- The service life of the cooling fans is now 10 years\*<sup>2</sup>. The service life can be further extended by ON/OFF control of the cooling fan.
- Capacitors with a design life of 10 years\*<sup>2\*3</sup> are adapted. With these capacitors, the service of the inverter is further extended.
- Life indication of life components

Components	Estimated lifespan of the FR-A800	Guideline of JEMA <sup>*4</sup>
Cooling fan	10 years* <sup>2</sup>	2 to 3 years
Main circuit smoothing capacitor	10 years* <sup>2*3</sup>	5 years
Printed board smoothing capacitor	10 years* <sup>2*3</sup>	5 years

\*<sup>2</sup>: Surrounding air temperature: Annual average of 40°C (free from corrosive gas, flammable gas, oil mist, dust and dirt).  
 The design life is a calculated value from the LD rating and is not a guaranteed product life.

\*<sup>3</sup>: Output current: 80% of the inverter LD rating

\*<sup>4</sup>: Excerpts from "Periodic check of the transistorized inverter" of JEMA (Japan Electrical Manufacturer's Association).

### Enhanced life diagnosis function

- An internal thermal sensor is equipped to all inverters as standard, which enables monitoring of the installation environment. Use this function as a guide for the life diagnosis. **NEW**
- Maintenance timers are available for up to three peripheral devices, such as motor and bearing.

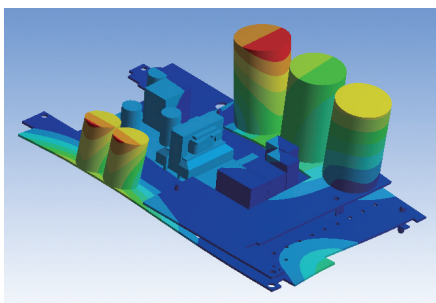


"Maintenance 1 output" warning

## (6) Reasons for high quality

### Design considering the hazardous environment

3D-vibration analysis is performed to confirm the vibration resistance. The analysis is also useful to find the best layout position and to further improve the product's rigidity. Assuming a hazardous service condition, the product reliability is thoroughly assessed in the design stage. Every effort is made to ensure the best quality of the Mitsubishi inverter.\*<sup>5</sup>



3D-vibration analysis

## (5) Renewal assurance

### Intercompatibility with existing models

- The inverter installation method is the same as that for the FR-A700 series, eliminating any concerns over replacement. Furthermore, FR-A700 series control circuit terminal blocks can be installed with the use of an option (FR-A8TAT).

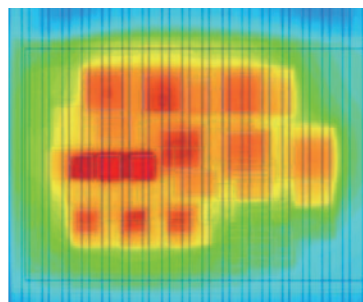


- The terminal response adjustment function allows a user to adjust the response speed in accordance with the existing facility. **NEW**
- The conversion function of Inverter Setup Software (FR Configurator2) enables parameter copy from an FR-A700 and even from an FR-A500 (to be supported soon).

☞ For the compatibilities and differences with the FR-A700 series, refer to page 200.

### Heat control for high quality

Resistance against heat is what makes an inverter reliable. A well-designed heat-resistant power module is essential in a reliable inverter. From the power module's design stage, its heat resistance is carefully considered.\*<sup>5</sup>



Hydraulic analysis and heat simulation

\*<sup>5</sup>: The usage beyond the product's specified service condition is not guaranteed.



# EASY SETUP & EASY TO USE

A range of equipment and functions are prepared allowing work to be performed anywhere to suit product life cycles.

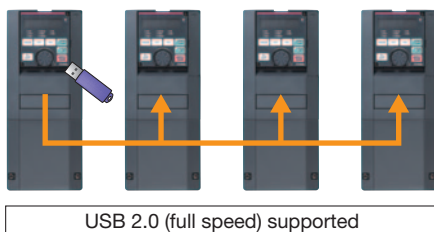
## From Startup to Maintenance

Fully equipped with a variety of simple functions and equipment to improve work efficiency.

### (1) Streamlining the startup process

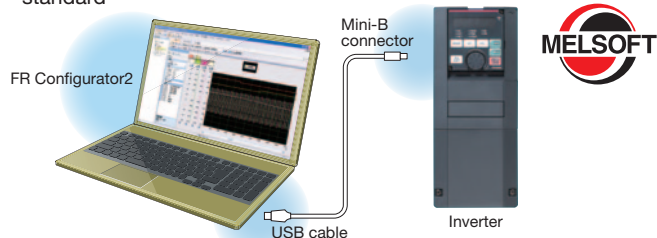
#### Parameter copying with USB memory **NEW**

- A USB host connector (A type), which allows external device connections, has been added. Parameters can be copied to commercial USB memory devices. (Refer to page 50)



#### Easy setup with the Inverter Setup Software (FR Configurator2)

- It is a software which is easy to use and has unity as Mitsubishi FA products with MELSOFT common design and good operability.
- Easy plug-and-play connection to USB terminal equipped as standard

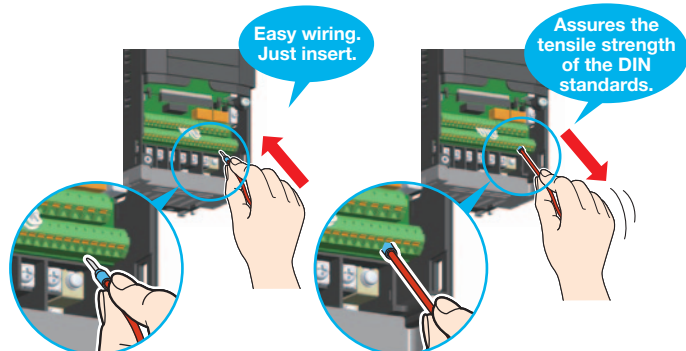


- Free trial version, which contains start-up functions, is available. It can be downloaded at Mitsubishi Electric FA Global Website.

For FR Configurator2, please refer to page 19.

#### Easy wiring to the control circuit **NEW**

Spring clamp terminals have been adopted for control circuit terminals. Wires can be protected against loosening under vibrations during transportation of the inverter. Ten additional terminals are used as compared to the FR-A700 series. Round crimping terminals can also be used by employing a control terminal option (FR-A8TR).



### (2) Easy-to-follow display improves the operability

#### Easy operation with GOT **NEW**

- Automatic communication is possible without specifying any parameter settings simply by connecting to the GOT2000 series.
- The PLC function device monitor can be displayed at the GOT2000 series. Batch control of multiple inverter device monitors is possible with a single GOT unit.
- The sample screen data for the A800 can be found in the screen design software of the GOT2000 series. The newest version of the screen design software can be downloaded from the Mitsubishi Electric FA Global Website.



#### Easy-to-follow parameter configuration **NEW**

One of the selectable mode by the operation panel is the Group parameter mode, which provides intuitive and simple parameter settings. (The conventional parameter setting mode is selected by default.)

Major division	Name
E	Environment
F	Acceleration/deceleration
D	Start and frequency commands
H	Protective function
M	Monitor
T	Multi function I/O terminal
C	Motor constant
A	Applications
B	Applications (position control)
N	Communication
G	Control

Conventional parameter (A700) Pr. 8 1 8

New parameter (A800) Pr. C + 1 + 1 2

Group number      Major division      Minor division      Parameter number

#### Easy-to-read operation panel **NEW**

A 5-digit, 12-seg display has been adopted for the operation panel (FR-DU08) for a more natural character display. Furthermore, an optional LCD operation panel (FR-LU08) adopting an LCD panel capable of displaying text and menus is also available.

FR-DU08 (12-segment type)

FR-LU08 (LCD type) (option)



### (3) To aid with maintenance

#### Reduced wiring check time

Split-type covers are adapted for all capacity models. Maintenance is now easy because all an operator has to do is to remove the cover for the target wiring area.



#### Maintenance and control of multiple inverters (Option) **NEW**

Serial number reading is possible using the optional LCD operation panel (FR-LU08) or the Inverter Setup Software (FR Configurator2). Administration of different inverters has become much more simple.





# ECO-FRIENDLY FACTORIES

The power consumption by motors is said to amount about the half of all power consumption made by the Japanese manufacturing industry. Factories can save more energy without dropping their production. Less energy and more production—the FR-A800 series will help you to get the both.

## The Next Step — Go Green

Save energy while increasing factory production.

### (1) Energy-saving function tailored to system, application

#### Variety of functions

- **Check the energy saving effect at a glance**

- You can check the energy saving effect on the energy saving monitor.
- The measured output power amount can be output in pulses.

- **Reduce power consumption during standby**

- Control circuits other than those for power-related parts can be operated with 24 VDC power supplied from an external power source. **NEW**
- Since the control circuit can use the external 24 VDC, other power control circuits can stay OFF while no driving is required, and that saves the standby energy.
- By turning the cooling fan ON/OFF based on the inverter status, wasteful power consumption during stoppages can be reduced.

- **Save energy with Optimum excitation control** **NEW**

The excitation current is constantly adjusted to drive the motor in the most efficient method which leads to energy saving. For example, with optimum excitation control with motor load torque of 10% when using the SF-JR, motor efficiency has increased by approximately 15% over the previous V/F control method.

- **Effective use of regenerative energy (option)**

Multiple inverters can be connected to the power regeneration common converter (FR-CV)/high power factor converter (FR-HC2) via a common PN bus.



Regenerative power is used at other inverters, and surplus energy is returned to the power supply, resulting in energy saving. The 315K or higher models are inverter-converter separated types, which are suitable for power regeneration. **NEW**

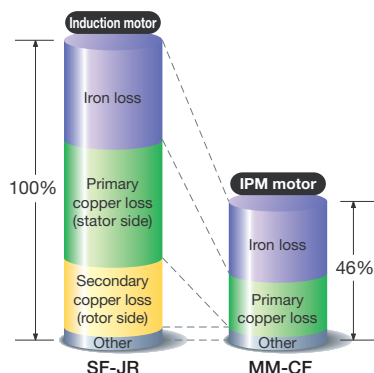
### (2) PM motor contributes to the energy saving in factories

#### PM motor

If the inverter is being used for an application requiring constant-torque, such as a conveyor, factory energy savings can be achieved by replacing your current induction motors with permanent magnet motors (PM motors). (Tuning is required for an IPM motor other than MM-CF, and for the PM motors of other manufacturers.)

- **Why is a PM motor so efficient?**

- The current does not flow to the rotor (secondary side), so there is no secondary copper loss.
- Magnetic flux is generated by permanent magnets, so less current is required to drive a motor.



#### Conveyor

A conveyor transports different goods and products according to its application. A PM motor can keep the carrying speed constant while saving energy.



- Features
- Application Example
- PLC Function
- FR Configurator2
- Connection
- Examples
- Standard
- Specs
- Outline
- Dimensions
- Terminal Connection
- Diagrams
- Terminal Specs
- Operation Panel
- Parameter List
- Explanations
- of Parameters
- Protective
- Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty
- Inquiry



# SYSTEM SUPPORT

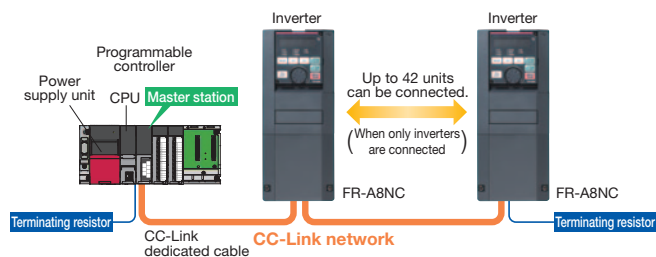
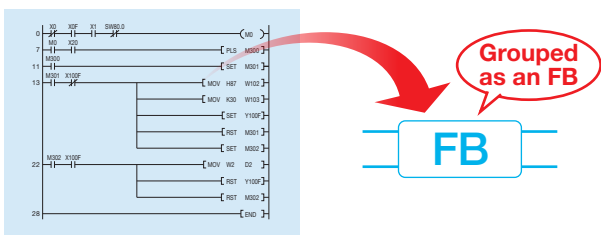
## High Equipment Functionality

Numerous functions and the extensive lineup of models are ready to support various systems.

### (1) Various network compatibility brings all the control in your hand

#### Compatibility to various open networks

- A controller can control and monitor an inverter via networks. RS-485 communication (Mitsubishi inverter protocol, MODBUS<sup>®</sup>RTU protocol), which is supported as standard, conveys data up to 115200 bps.
- A function block (FB) programming for CC-Link communication is available for the MELSEC-Q/L series. Inverter control sequence programs can be created easily. (An FB library (FB part library) can be downloaded from the Mitsubishi Electric FA Global Website.)
- Communication options are also available for the major network protocols such as CC-Link and SSCNET III/H (to be released soon) as well as DeviceNet<sup>™</sup>, PROFIBUS-DPV0, and LonWorks<sup>®</sup> (to be released soon). Other Ethernet networks are also supported.
- CC-Link IE Field    • FL-net remote I/O (to be released soon)

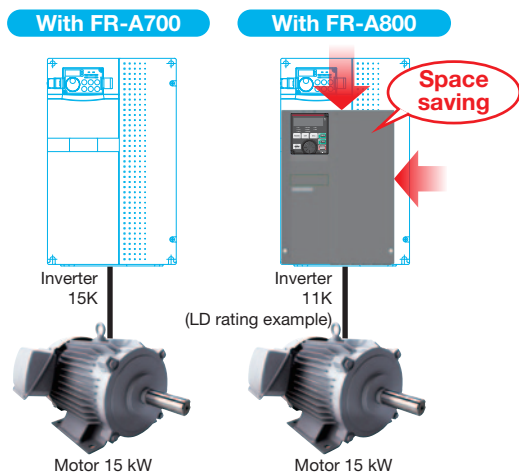


### (2) Selection of optimum capacity to suit the application

#### Multiple rating **NEW**

Rated current and four different overload capacity ratings (SLD rating (super light duty), LD rating (light duty), ND rating (normal duty), HD rating (heavy duty)) can be selected with parameters. The optimum inverter can be selected to suit the application, and by selecting an inverter with SLD or LD rating, equipment size can be reduced when compared with the FR-A700 series. The HD rating is best suited for applications requiring low speed and high torque.

If using an inverter with capacity of 75K or higher, or motor with capacity of 75 kW or higher, always select and install the inverter based on the capacity of the motor with DC reactor.



Rating	SLD	LD	ND	HD
	Super light duty	Light duty	Normal duty	Heavy duty
Application		Fan and Pump Shield Machines, Winding and Unwinding, Printing Machines	Cranes, Press	Conveyor
Pr.570 (E301) setting	0	1	2 (Initial value)	3
Overload current rating (inverse-time characteristics)	110% 60 s, 120% 3 s	120% 60 s, 150% 3 s	150% 60 s, 200% 3 s	200% 60 s, 250% 3 s
Surrounding air temperature	40°C	50°C	50°C	50°C

Refer to page 11 for the inverter rating selection.

### (3) Wire saving, space saving

#### Built-in brake transistor **NEW**

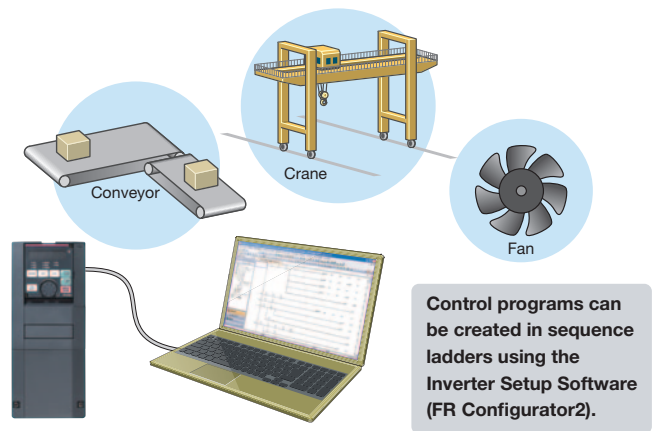
In addition to the 22K and lower, 400 V class 30 to 55K models have also been equipped with a built-in brake transistor. In an application where the motor is hardly decelerated, connecting a brake resistor can shorten the deceleration time; no brake unit or power regeneration converter is required. Wiring, space, and ultimately the cost will be all saved.

## (4) PLC control with an inverter

### Built-in PLC function in an inverter **NEW**

- Parameters and setting frequency can be changed at the program.
- Inverter control such as inverter operations triggered by input signals, signal output based on inverter operation status, and monitor output can be freely customized based on the machine specifications.
- All machines can be controlled by the inverter alone, and control can also be dispersed.
- Time-based operation is possible by using in combination with the real-time clock function (optional LCD operation panel (FR-LU08)).

Refer to page 17 for the details.



## (5) Direct installation by the machine

### IP55 compatible **NEW**

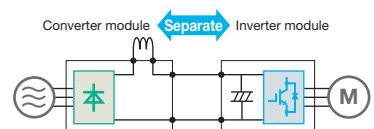
- Inverters can be installed nearby the machine, minimizing cable length between the inverter and motor.
- Support is available for use even in high-humidity or dusty environments, facilitating a more flexible choice of installation locations.
- By enclosing a DC reactor, it requires less wiring and less space.
- Compatible with cable glands to meet the IP55 specification at the wiring section.



## (6) Flexible configuration to meet the needs

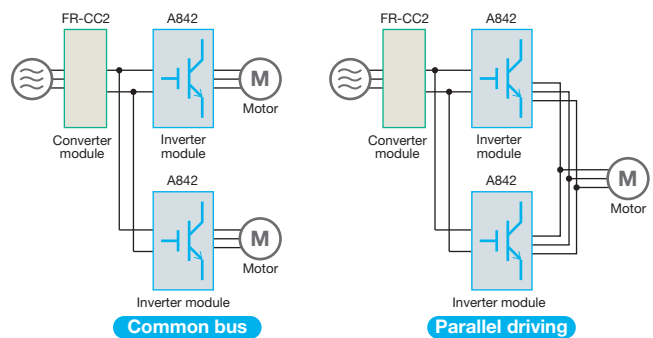
### Separate inverter and converter modules **NEW**

The inverter module and the converter module are physically separated for the 315K or higher capacity models.



Inverter module : FR-A842  
Converter module : FR-CC2

This facilitates flexible support for a variety of systems such as parallel drive and common bus line, allowing installation space to be minimized and costs reduced (to be supported soon).



Restrictions apply to parallel drive depending on the specifications. Please contact your sales representative beforehand.

## (7) Reduced tact time with functionality suited to the application

### Anti-sway control **NEW**

When an object is moved by a crane, swinging at the time of stopping is suppressed on the crane's transverse axis or traveling axis. This control cuts down the tact time and facilitates efficient operation.

### Increased magnetic excitation deceleration **NEW**

Deceleration time can be reduced without a brake resistor. Tact time can be eliminated at conveyor lines, etc.





# ENVIRONMENTAL ADAPTABILITY

## Installation Anywhere

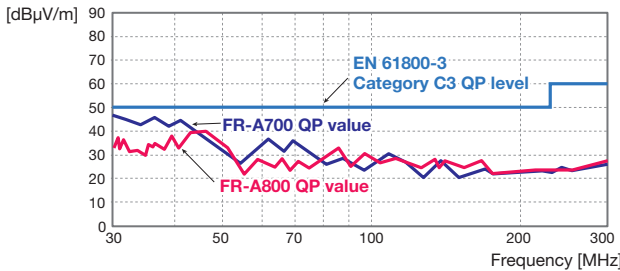
The FR-A800 series complies with various standards and is usable in different scenes.

### (1) Comprehensive noise countermeasures

#### Compliance with EU EMC Directive with inverter alone

Troublesome acquisition of standards is unnecessary.


- The FR-A800 series is equipped with an EMC filter as standard for compliance with EMC Directive with the inverter alone. (EN 61800-3 2nd Environment Category C3)
- The newly developed drive technology and the power supply technology minimize the EMI emitted from inverters.



	Capacitive filter (radio noise filter)	Input-side common mode choke (line noise filter)	DC reactor
55K or lower	Standard (built-in)	Standard (built-in)	Option (sold separately)
75K or higher	Standard (built-in)	Option (sold separately)	Option (sold separately)

### (2) Global compatibility

#### Compliance with a variety of standards

- Complies with UL, cUL, and EC Directives (CE marking), and the Radio Waves Act (South Korea) (KC marking). 
- Being RoHS compliant, the FR-A800 series inverters are friendly to people and to the environment.
- Class NK and CCS compliance allows use on ship equipment (to be supported soon).

### (3) Protected in hazardous environment

#### Circuit board coating

The inverters with PCB coating (IEC60721-3-3 3C2/3S2) and conductive plating are available for improved environmental resistance. (" -60" or "-06" is affixed to the end of the inverter model name.)

## Inverter by rating

### •200 V class

Inverter model FR-A820-□	SLD (Super light duty)		LD (Light duty)		ND (Normal duty initial value)		HD (Heavy duty)	
	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)
0.4K 00046	0.75	4.6	0.75	4.2	0.4	3	0.2	1.5
0.75K 00077	1.5	7.7	1.5	7	0.75	5	0.4	3
1.5K 00105	2.2	10.5	2.2	9.6	1.5	8	0.75	5
2.2K 00167	3.7	16.7	3.7	15.2	2.2	11	1.5	8
3.7K 00250	5.5	25	5.5	23	3.7	17.5	2.2	11
5.5K 00340	7.5	34	7.5	31	5.5	24	3.7	17.5
7.5K 00490	11	49	11	45	7.5	33	5.5	24
11K 00630	15	63	15	58	11	46	7.5	33
15K 00770	18.5	77	18.5	70.5	15	61	11	46
18.5K 00930	22	93	22	85	18.5	76	15	61
22K 01250	30	125	30	114	22	90	18.5	76
30K 01540	37	154	37	140	30	115	22	90
37K 01870	45	187	45	170	37	145	30	115
45K 02330	55	233	55	212	45	175	37	145
55K 03160	75	316	75	288	55	215	45	175
75K 03800	90/110	380	90	346	75	288	55	215
90K 04750	132	475	110	432	90	346	75	288

### •Overload current rating

SLD	110% 60 s, 120% 3 s (inverse-time characteristics) at surrounding air temperature 40°C
LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 50°C
ND	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 50°C
HD	200% 60 s, 250% 3 s (inverse-time characteristics) at surrounding air temperature 50°C

\*1: The applicable motor capacity is the maximum applicable capacity of a Mitsubishi 4-pole standard motor.

 For selection of the DC reactor and the converter unit, refer to page 179.

### •400 V class

Inverter model FR-A84□-□	SLD (Super light duty)		LD (Light duty)		ND (Normal duty initial value)		HD (Heavy duty)	
	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)	Motor capacity (kW) <sup>*)</sup>	Rated current (A)
0.4K 00023	0.75	2.3	0.75	2.1	0.4	1.5	0.2	0.8
0.75K 00038	1.5	3.8	1.5	3.5	0.75	2.5	0.4	1.5
1.5K 00052	2.2	5.2	2.2	4.8	1.5	4	0.75	2.5
2.2K 00083	3.7	8.3	3.7	7.6	2.2	6	1.5	4
3.7K 00126	5.5	12.6	5.5	11.5	3.7	9	2.2	6
5.5K 00170	7.5	17	7.5	16	5.5	12	3.7	9
7.5K 00250	11	25	11	23	7.5	17	5.5	12
11K 00310	15	31	15	29	11	23	7.5	17
15K 00380	18.5	38	18.5	35	15	31	11	23
18.5K 00470	22	47	22	43	18.5	38	15	31
22K 00620	30	62	30	57	22	44	18.5	38
30K 00770	37	77	37	70	30	57	22	44
37K 00930	45	93	45	85	37	71	30	57
45K 01160	55	116	55	106	45	86	37	71
55K 01800	75/90	180	75	144	55	110	45	86
75K 02160	110	216	90	180	75	144	55	110
90K 02600	132	260	110	216	90	180	75	144
110K 03250	160	325	132	260	110	216	90	180
132K 03610	185	361	160	325	132	260	110	216
160K 04320	220	432	185	361	160	325	132	260
185K 04810	250	481	220	432	185	361	160	325
220K 05470	280	547	250	481	220	432	185	361
250K 06100	315	610	280	547	250	481	220	432
280K 06830	355	683	315	610	280	547	250	481
315K 07700	400	770	355	683	315	610	280	547
355K 08660	450	866	400	770	355	683	315	610
400K 09620	500	962	450	866	400	770	355	683
450K 10940	560	1094	500	962	450	866	400	770
500K 12120	630	1212	560	1094	500	962	450	866

## Extensive lineup

### •Standard model **FR - A 8 2 0 - 0.4K - 1**

Symbol	Voltage class	Symbol	Structure, functionality	Symbol <sup>*)</sup>	Description	Symbol	Type <sup>*)</sup>	Symbol	Circuit board coating (IEC60721-3-3 3C2/3S2 compatible)	Plated conductor
2	200 V class	0	Standard model	0.4K to 280K	Inverter ND rated capacity (kW)	-1	FM	None	Without	Without
4	400 V class			00023 to 06830	Inverter SLD rated current (A)	-2	CA	-60	With	Without
								-06 <sup>*)</sup>	With	With

	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K
Three-phase 200V class FR-A820-□ <sup>*)</sup>	00046	00077	00105	00167	00250	00340	00490	00630	00770	00930	01250	01540	01870	02330	03160	03800	04750
	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K
Three-phase 400V class FR-A840-□ <sup>*)</sup>	00023	00038	00052	00083	00126	00170	00250	00310	00380	00470	00620	00770	00930	01160	01800	02160	02600
	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
	110K	132K	160K	185K	220K	250K	280K										
	03250	03610	04320	04810	05470	06100	06830										
	●	●	●	●	●	●	●										

### •Separated converter type

[ Inverter ]

### **FR - A 8 4 2 - 315K - 1**

Symbol	Voltage class	Symbol	Structure, functionality	Symbol <sup>*)</sup>	Description	Symbol	Type <sup>*)</sup>	Symbol	Circuit board coating (IEC60721-3-3 3C2/3S2 compatible)	Plated conductor
4	400 V class	2	Separated converter type	315K to 500K	Inverter ND rated capacity (kW)	-1	FM	None	Without	Without
				07700 to 12120	Inverter SLD rated current (A)	-2	CA	-60	With	Without
								-06	With	With

Three-phase 400V class FR-A842-□ <sup>*)</sup>	315K	355K	400K	450K	500K
	07700	08660	09620	10940	12120
	●	●	●	●	●

### •Converter unit

### **FR - CC2 - H 315K - 60**

Symbol	Voltage class	Symbol	Description	Symbol	Circuit board coating (IEC60721-3-3 3C2/3S2 compatible)	Plated conductor
H	400 V class	315K to 630K	Applicable motor capacity (kW)	-60	With	Without
				-06	With	With

Three-phase 400V class FR-CC2-H□ (with a built-in DC reactor)	315K	355K	400K	450K	500K	560K	630K
	●	●	●	●	●	●	●

### •IP55 compatible model

### **FR - A 8 4 6 - 7.5K - 1 - 60 C3**

Symbol	Voltage class	Symbol <sup>*)</sup>	Description	Symbol	Type <sup>*)</sup>	Symbol	Circuit board coating (IEC60721-3-3 3C2/3S2 compatible)	Plated conductor	Symbol	EMC filter
4	400 V class	0.4K to 132K	Inverter ND rated capacity (kW)	-1	FM	-60	With	Without	C2	Built-in C2 filter
		00023 to 03610	Inverter SLD rated current (A)	-2	CA	-06	With	With	C3	Built-in C3 filter

Symbol	Structure, functionality
6	IP55 compatible model

	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K
Three-phase 400V class FR-A846-□ (with a built-in DC reactor)	00023	00038	00052	00083	00126	00170	00250	00310	00380	00470	00620	00770	00930	01160	01800	02160	02600
	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
	110K	132K															
	03250	03610															
	●	●															

\*1: Models can be alternatively indicated with the inverter rated current (SLD rating).

(IP55 compatible models have LD and ND rating types only. However, the SLD rated current of standard models is used to represent the model.)

\*2: Specification differs by the type as follows.

Symbol	Type	Motor output	Built-in EMC filter	Initial setting		
				Control logic	Rated frequency	Base frequency voltage (Pr.19)
-1	FM	Terminal FM (pulse train output) Terminal AM (analog voltage output (0 to 10 VDC))	OFF	Sink logic	60 Hz	9999 (same as the power supply voltage)
-2	CA	Terminal CA (analog current output (0 to 20 mA)) Terminal AM (analog voltage output (0 to 10 VDC))	ON	Source logic	50 Hz	8888 (95% of the power supply voltage)

\*3: Available for the 5.5K or higher.

\*4: For using the 75K or higher inverter and a 75 kW or higher motor, always install a DC reactor (FR-HEL), which is available as an option.

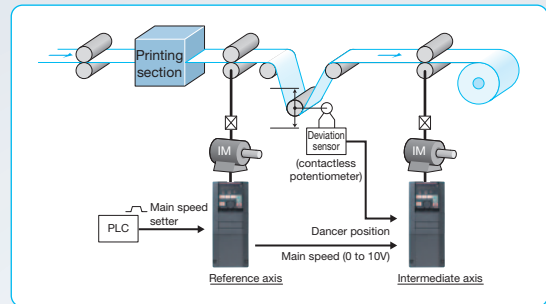
\*5: Always install the converter unit (FR-CC2). (Not required when a high power factor converter (FR-HC2) is used.)

●: Released model

## Application example

# BEST SUITED FOR EVERY MACHINE

### Line Control (Winding and Unwinding)



Material tension is kept constant by employing speed control and torque control to eliminate slack and uneven winding. By using a motor with the speed ratio most appropriate for the machine, the inverter capacity can be downsized.

#### Typical industries

Textile industry

Steel industry

Pulp, paper, paper products manufacturing industries

### Dancer control **NEW**

The dancer control detects the dancer roll positions and performs PID operation to keep the sheet tension constant.

### Traverse function **NEW**

The traverse function, used for the traverse axis of spinning machine, prevents uneven winding or collapsing.

### Torque accuracy

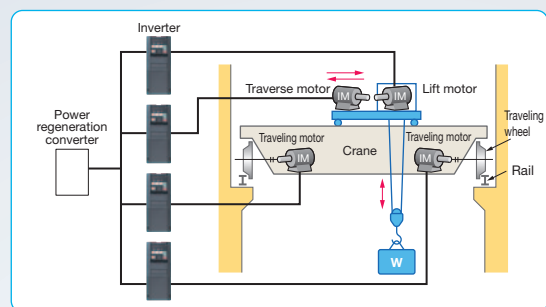
	Real sensorless vector control	Vector control
Torque control range	1 : 20	1 : 50
Absolute torque accuracy*1	±20%	±10%*3
Repetitive torque accuracy*2	±10%	±5%*3

\*1: Difference between the actual torque and the torque command

\*2: Fluctuation between the average of the actual torque and the actual measured torque (repeatability of the torque)

\*3: When online auto tuning (adaptive magnetic flux observer) enabled

### Cranes



Relentless operation is possible with HD rating when lifting. And when traveling, vibrations applied to objects being conveyed are suppressed with anti-sway control, facilitating efficient operation.

#### Typical industries

Lumber, wood product manufacturing industries

Steel industry

Warehousing

Water transportation

Textile industry

Metal products manufacturing

### High torque at low speed

[Starting torque] ■ Real sensorless vector control 200% (ND rating)

■ Vector control 200% (ND rating)  
(150% of initial setting for the 5.5K and higher)

[Zero-speed torque] ■ Vector control: 200% (Select HD rating.)

### PLC function **NEW**

By employing synchronous operation for gate-type cranes, positional displacement of both axes is corrected during travel, achieving highly accurate control without using an external controller.

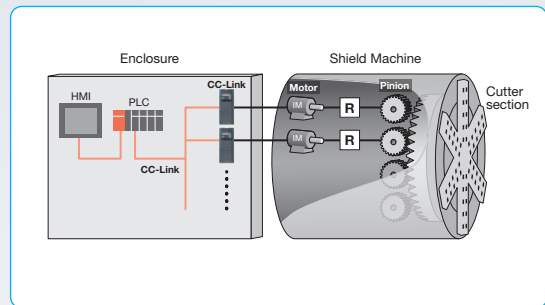
### Anti-sway control **NEW**

When an object is moved by a crane, swinging at the time of stopping is suppressed on the crane's transverse axis or traveling axis.

This control cuts down the tact time and facilitates efficient operation.



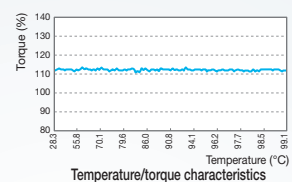
## Shield Machines



Inverters can be used to provide high starting torque for digging, and for transferring earth and sand after digging. A lineup of products compatible with the IP55 protective structure is available as a separate series.

### Real sensorless vector control

Motors are controlled without encoders, which are susceptible to hazardous environment. Use of such motors naturally provides higher reliability. Torque accuracy has also improved because the temperature is better controlled.



### Typical industries

Construction industry

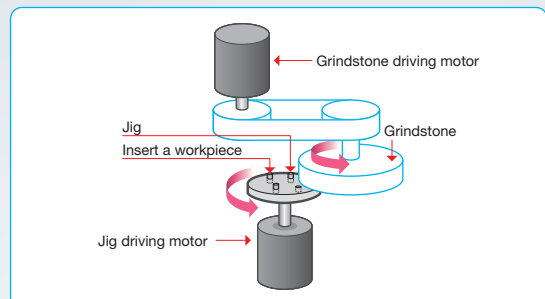
### Drop control

This function balances the load between motors when using multiple inverters.

### CC-Link communication

CC-Link communication enables a programmable controller or a GOT to control multiple inverters. Furthermore, wiring is minimized using a single CC-Link cable.

## Machine Tools



The rotation speed can be set according to the material being processed. Stable high-speed rotation is also possible.

### High-speed operation

[Operating frequency] ■ V/F control 590 Hz  
 ■ Vector control 400 Hz  
 ■ Real sensorless vector control 400 Hz

### Typical industries

Metal products manufacturing

### Torque limit function

This is effective in preventing machine damage (tool damage prevention, etc.) due to sudden disturbance torque.

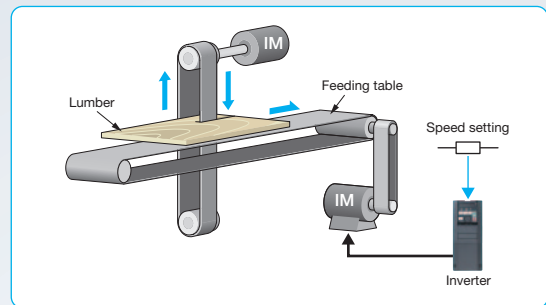
### Orientation control (vector control)

The inverter can adjust the stop position (Orientation control) using a position detector (encoder) attached to a place such as the main shaft of the machine.

## Application example

# BEST SUITED FOR EVERY MACHINE

### Wood Processing Machines



Even when processing areas of varying hardness such as lumber knots, processing time delays are suppressed by minimizing reductions in motor speed.

#### Typical industries

Lumber, wood product manufacturing industries

Forestry

### Real sensorless vector control, vector control

Improved speed response to sudden load fluctuations when compared with the previous model (FR-A700).

[Response speed]

■ Real sensorless vector control 50 Hz\*1 (A700: 20 Hz)

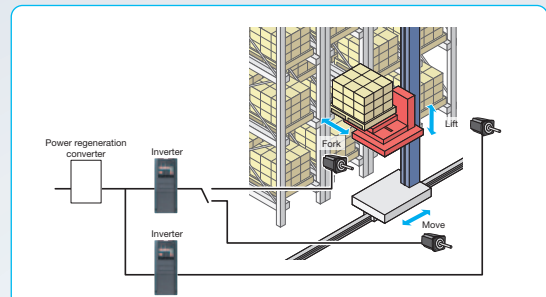
■ Vector control 130 Hz (A700: 50 Hz)

\*1: At 3.7 kW with no load. Differs depending on the load conditions and motor capacity.

### Torque limiting function

This function is effective in preventing machine damage (tool damage, etc.) due to sudden disturbance torque.

### Conveyance



The new series offers a wealth of functionality suited to applications such as high-accuracy conveyance and target position stoppage, which contributes to reduction in tact time.

#### Typical industries

Steel industry

Metal products manufacturing

Lumber, wood product manufacturing industries

Textile industry

Water transportation, fishing industry

Warehousing

### PM sensorless vector control

Multiple axes are strictly controlled to run at the same speed without using a driving belt. This control method provides driving accurate enough for transporting glass substrates without damaging them. Simple positioning control is also available.

(when high frequency superposition control selected in combination with MM-CF)

### Increased magnetic excitation deceleration **NEW**

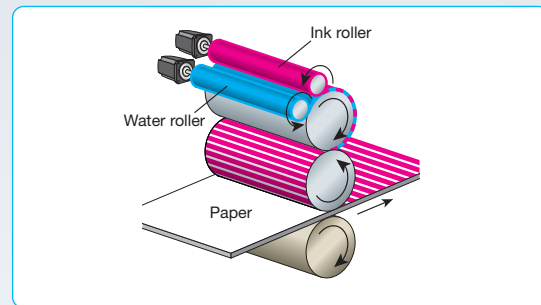
Deceleration time can be reduced without a brake resistor.

Tact time can be eliminated at conveyor lines, etc.

### PLC function **NEW**

When a few sensors are used to check the presence of goods on a conveyor and the arrival of such goods, the inverter can directly receive such signals from the sensors for the PLC control.

## Printing Machines



The highly-accurate speed control minimizes color unevenness and displaced prints.

### Typical industries

Printing and related industries

## Speed control

	Real sensorless vector control	Vector control	PM sensorless vector control
Speed response	50 Hz*1	130 Hz	50 Hz
Speed control range	1:200 (when power drive at 0.3 Hz to 60 Hz)	1:1500 (both driving/regeneration*2)	1:1000*3 (when HD rating selected)

\*1: At 3.7 kW with no load. Differs depending on the load conditions and motor capacity.

\*2: If using regeneration unit (option) during regeneration

\*3: When high frequency superposition control selected in combination with the MM-CF

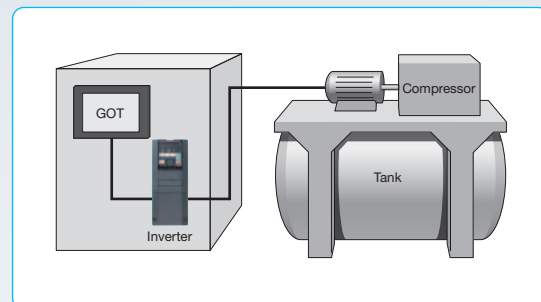
## PM sensorless vector control

The speed fluctuations of the ink roller axis and water roller axis are minimized to eliminate print unevenness.

[Speed fluctuation ratio]  $\pm 0.05\%$  (Digital input)

"No encoder" means less trouble and higher reliability.

## Compressors



The PM sensorless vector control is useful in generating high starting torque. By using this control method with an IPM motor, much power can be saved.

### Typical industries

Steel industry

Metal products manufacturing

Lumber, wood product manufacturing industries

Textile industry

Water transportation, fishing industry

Warehousing

## PM sensorless vector control

Smooth operation is possible even at start-up under high load.

[Starting torque] 1.5 kW or lower: 200%, 2.0 kW or higher: 150%

When high frequency superposition control selected in combination with MM-CF

The use of a highly-efficient IPM motor cuts down the required power. This small motor also makes the machine small.

## PID control

Pressure can be automatically adjusted by converting signals from the encoder to inverter input signals and feeding them back.



## FREELY CONTROL MACHINES

The PLC function will help you to provide the control sequence best suited for the machine specifications.

### 1 Inverter operation sequence customized for the machine

- A set of operations (operation at different signal inputs, signal and monitor outputs at different inverter status, etc.) can be freely programmed in accordance with the machine specifications. For example, a shutter opening/closing can be performed based on a signal from a sensor, or based on the opening/closing times. Control programs can be created in sequence ladders using the inverter setup software (FR Configurator2).

### 2 Realizes the decentralized control

- The control of the whole system is decentralized to inverters that manage their subordinating devices individually.
- A group of dedicated sequence programs is created and saved in each inverter. The master controller no longer has to process all the sequence programs, and the decentralized system accepts program changes more flexibly.

### 3 Automatic operation in accordance with the time

- With the real-time clock, automatic operation can be performed at certain times (when the optional LCD operation panel (FR-LU08) is used).

### 4 Useful functions

- **User parameter**  
Up to 50 parameters, which are linked with the data registers, can be saved. The variables (data registers) used in the PLC function can be saved as inverter parameters. Furthermore, parameter settings can be saved in the EEPROM of inverter. When results of calculation using the PLC function are saved in the parameters, the data can be retained after the power is turned OFF.
- **User initiated fault**  
Inverter output can be shut off under conditions other than those of the existing protective functions. Up to five specific fault-initiating conditions can be set to activate a protective function and shut off the inverter output.
- **Monitored item for the user**  
Special register values can be displayed for monitoring on the operation panel. Arbitrary data designated by the user such as results of calculation using the PLC function can be displayed.
- **Inverter parameter read/write**  
Parameter settings can be changed using sequence programs. The acceleration/deceleration patterns can also be set with sequence programs to be changed at certain operation statuses. You can choose RAM or EEPROM to save the parameter settings. When the settings are changed frequently, choose RAM.
- **PID function**  
Two different loops of PID inverter operations can be pre-set, and those can be controlled using sequence programs.
- **Inverter operation lock**  
The inverter operation can be restricted for the command sources other than the sequence programs.

## PLC function

Item	Description
I/O	
General-purpose I/O	Sequence programs enable I/O signal transmission to/from the inverter and its plug-in options.
Analog I/O	Sequence programs enable reading of analog input values or analog output transmission by the inverter, and analog output transmission to the plug-in options.
Pulse train I/O	Sequence programs enable pulse train inputs (to terminal JOG) and pulse train outputs (from terminal F/C(FM)).
Inverter parameter read/write	Sequence programs enable inverter parameter write/read.
User parameter	Fifty user parameters (Pr.1150 to Pr.1199) are available and are linked with the data registers D206 to D255, which accept direct access by sequence programs.
CC-Link	A plug-in option (FR-A8NC) enables handling of remote registers as arbitrary data in the sequence programs.
Special function	
PID operation	Inverter's PID operations can be set (up to two loops).
User initiated fault	Up to five fault-initiating conditions can be set to activate a protective function.
Fault clear	The protective function occurring in the inverter can be reset.
Inverter operation lock	Inverters can start up while the PLC function is running.
Monitored item for the user	Desired data is displayable on the operation panel.

## Application example

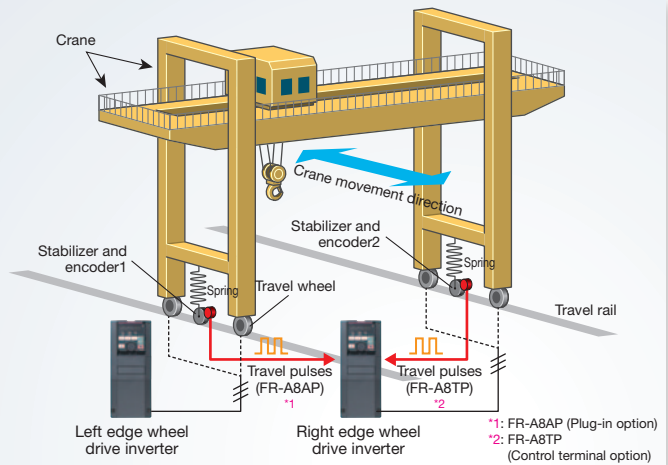
### Crane control



The traveled distance (total number of travel pulses) of each wheel is directly read from the encoder installed at the wheel. The pulses from the two wheels are then compared, and their speed is adjusted to synchronize the wheel positions. There is no need to use an external controller to offset speed, allowing high accuracy control.

#### User initiated fault

Up to five protective functions operating under specific conditions can be set. Protective functions can be triggered to block inverter output at such times as when positional displacements are not eliminated even after offsetting speed over a fixed period of time, or pulses from the PLGs on both wheels are not input.



### Conveyor control



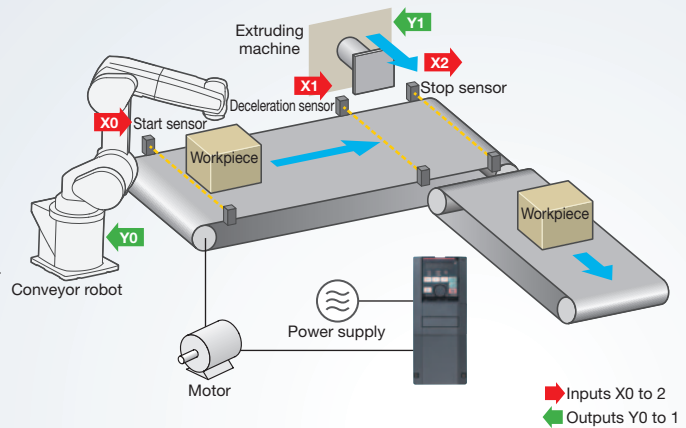
The workpiece positions detected by sensors are directly reported to the inverter, and the inverter sends out the operation commands to the conveyor robot and to the extruding machine. Whole control can be performed by an inverter, in accordance with the movement of its peripheral equipment.

#### Inverter parameter read/write

Changes can be made to inverter parameters from the sequence program. The acceleration/deceleration time and pattern can be set based on the type of workpiece.

#### Inverter operation lock

Operation is possible only when the sequence function is enabled. Changes to settings caused by operator error can be avoided.



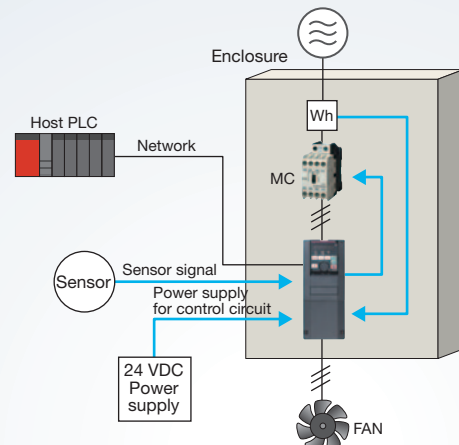
### Fan control



Signals sent via the enclosure (relay panel, etc.) such as input magnetic contactor signals, watt hour meter signals, and sensor signals can be read directly into the inverter and controlled. A fan can be controlled in accordance with the conditions without using relays, etc. Furthermore, by using an external 24 VDC power source for the control power supply, input machine signals can be turned ON and OFF regardless of whether there is an input power source. And by employing an external 24 VDC power supply for the control power, input machine signals can be turned ON and OFF, regardless of the existence of a main circuit power supply.

#### CC-Link

A plug-in option (FR-A8NC) enables handling of remote registers as arbitrary data in the sequence programs. A variety of equipment inside the factory can be centrally controlled with a CC-Link Network.



# DELIVERING A COMFORTABLE INVERTER

*From inverter startup to maintenance, this versatile software allows the user to specify settings easily at the computer.*

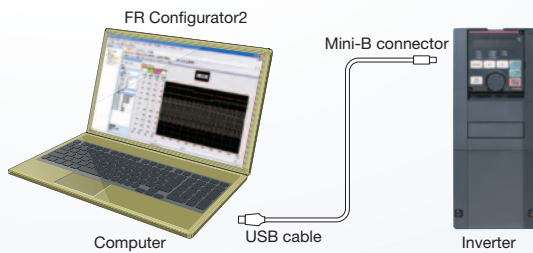
**[Compatible operating systems]**

Windows® 7, Windows® 8, Windows® 8.1/Pro/Enterprise (32-bit, 64-bit), Windows Vista® (32-bit), Windows® XP Professional SP3 or later, Windows® XP Home Edition SP3 or later



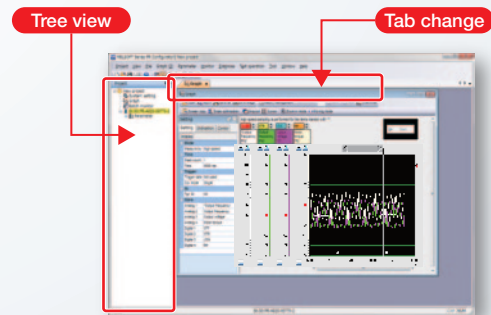
## Easy connection with a USB cable

A USB connector (Mini-B connector) is provided as standard. Easy connection to the computer without the need for a converter.



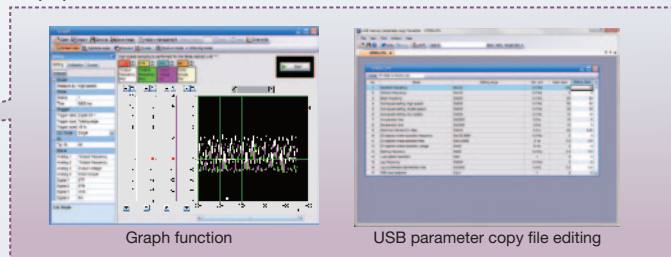
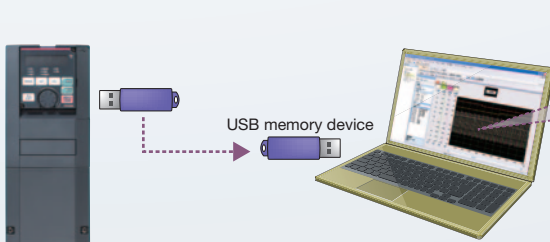
## Intuitive user interface

Connected inverters are displayed in tree view format. Windows for each function can be accessed by changing the tab for maximum efficiency.



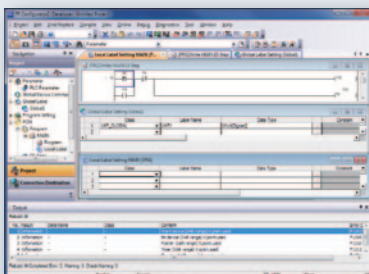
## Work can be carried out away from the equipment using a USB memory device

By loading trace data and parameter settings copied to a USB memory device into FR Configurator2, analysis and adjustments can be carried out with ease away from the equipment.



## Sequence control (Developer function)

The Developer function is used for creating sequence programs and writing them to the inverter to enable the use of the PLC function of the inverter.



**Free trial version Supported**

The function with the marking above is available in the free trial version (usable free of charge with limited functions). It can be downloaded at Mitsubishi Electric FA Global Website.

Function	Free trial version	Function	Free trial version
Parameter list	○	Convert	○
Diagnosis	○	Developer	×
Graph	×	USB memory parameter copy file edit	×
Batch monitor	×	Help	○
I/O terminal monitor	×		
Test operation	○		

○: Available, ×: Not available

The try-and-buy version (usable free of charge for a limited period of 20 days with the same functions as the release version) is also offered.

# OPERATING ENVIRONMENT

Features  
 Application Example  
 PLC Function  
 FR Configurator2  
 Connection  
 Examples  
 Standard  
 Specs  
 Outline  
 Dimensions  
 Terminal  
 Connection  
 Diagrams  
 Terminal  
 Specs  
 Operation  
 Panel  
 Parameter  
 List  
 Explanations  
 of  
 Parameters  
 Protective  
 Functions  
 Options  
 LVS/Cables  
 Precautions  
 Motors  
 Compatibility  
 Warranty  
 Inquiry

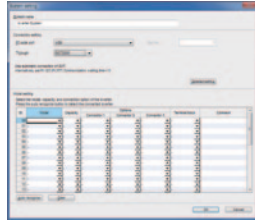


## 1 Efficient startup settings

### System settings

Free trial version Supported

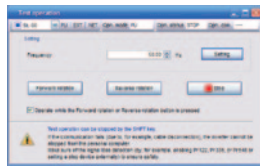
This sets the method used to connect the inverters and the computer. Automatic recognition of connected inverters can also be set. The station number, model, capacity, and plug-in options of the connected inverters can also be set manually.



### Test operation

Free trial version Supported

Operating commands, frequency settings, and the operating mode can be set for the selected inverter.



### Conversion function

Free trial version Supported

Parameters can be set with the parameter auto conversion function when renewing from the FR-A700 series or FR-A500 series (to be supported soon).

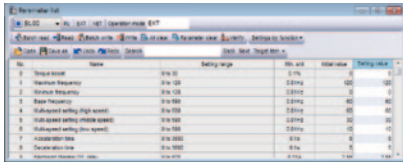


## 2 Perform pre-operation adjustments and checks during operation with ease

### Parameter list

Free trial version Supported

Parameters for selected station numbers can be displayed and changed.

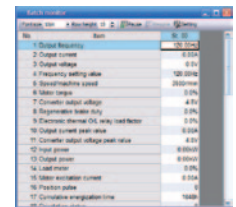


I/O signals can be assigned using settings by function.

### Batch monitor function

Multiple inverter monitor items can be monitored simultaneously.

With a terminal monitor, the ON/OFF status can be monitored.



### USB memory parameter copy file edit

Parameter settings (USB memory device parameter copy file) read from the inverter to a USB memory device can be edited.

### Offline auto tuning

Tuning is performed in wizard format after specifying necessary parameter settings.

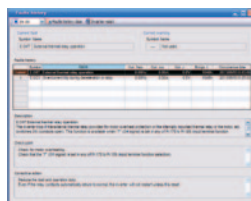


## 3 Easy-to-follow platform facilitates easy maintenance

### Diagnosis (faults history)

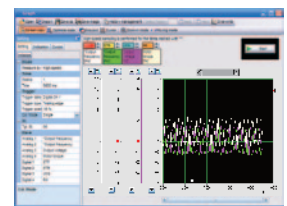
Free trial version Supported

Inverter faults history can be read and displayed together with the alarm occurrence time. Activating faults can be displayed, and inverters can also be reset.



### Graph function

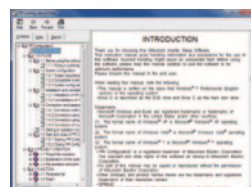
Inverter data can be sampled and displayed in a graphical format. Trace data can also be read and displayed in a graph.



### Help

Free trial version Supported

Displays the content of inverter and software instruction manuals.



### Life diagnosis [to be available soon]

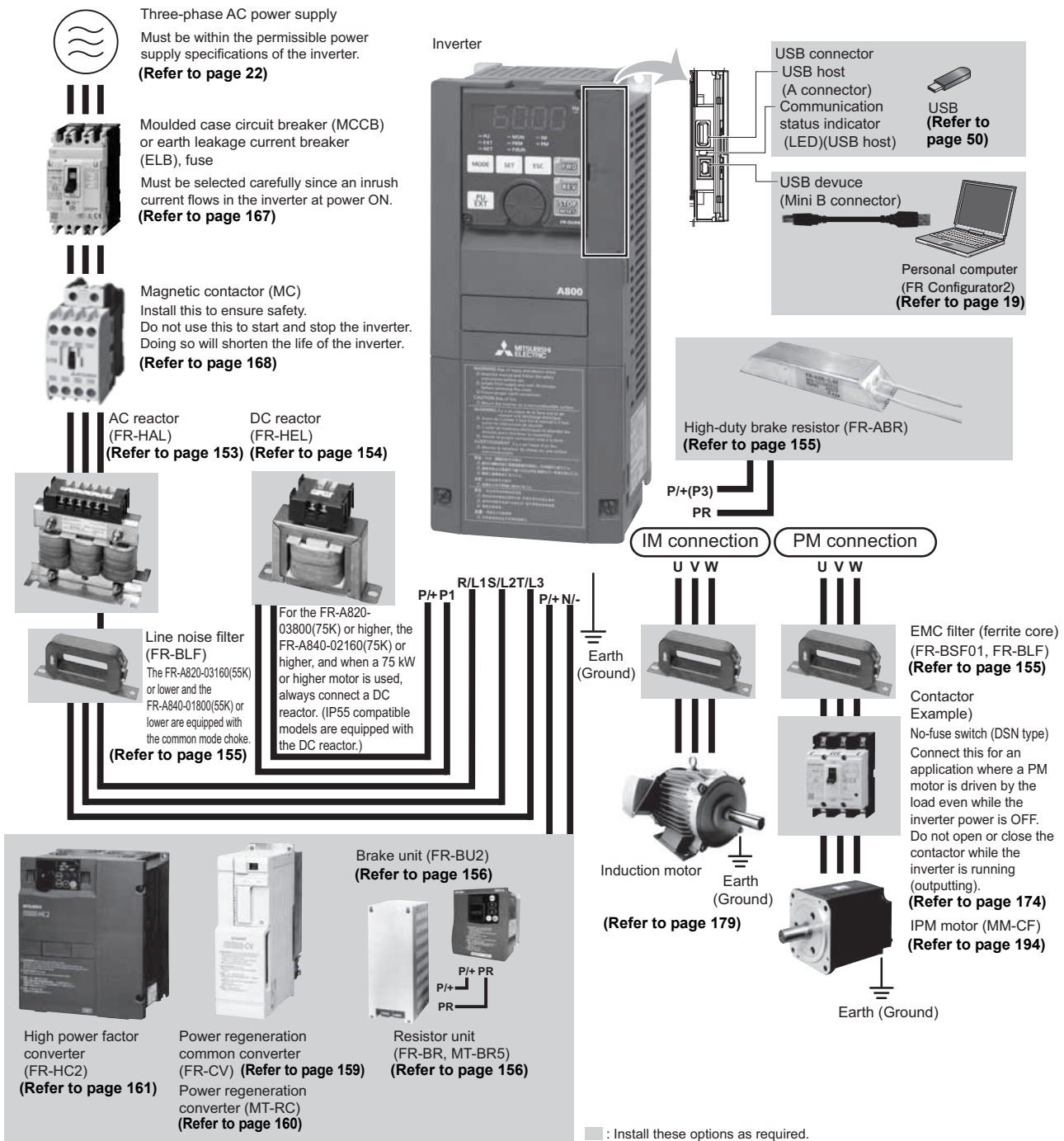
Free trial version Supported

Life information read from the inverter is displayed. Check marks appear in the life alarm fields of inverter parts that have exceeded their replacement schedule. Diagnosis results can also be output to a file.



# Connection Example

## ● Connection example for standard models



# Standard Specifications

## Rating (Standard model)

### ◆ 200 V class

Model FR-A820-[]		00046	00077	00105	00167	00250	00340	00490	00630	00770	00930	01250	01540	01870	02330	03160	03800	04750		
		0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K		
Applicable motor capacity (kW) *1	SLD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90/110	132		
	LD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110		
	ND (initial setting)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90		
	HD	0.2*2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75		
Rated capacity (kVA) *3	SLD	1.8	2.9	4	6.4	10	13	19	24	29	35	48	59	71	89	120	145	181		
	LD	1.6	2.7	3.7	5.8	8.8	12	17	22	27	32	43	53	65	81	110	132	165		
	ND (initial setting)	1.1	1.9	3	4.2	6.7	9.1	13	18	23	29	34	44	55	67	82	110	132		
	HD	0.6	1.1	1.9	3	4.2	6.7	9.1	13	18	23	29	34	44	55	67	82	110		
Rated current (A)	SLD	4.6	7.7	10.5	16.7	25	34	49	63	77	93	125	154	187	233	316	380	475		
	LD	4.2	7	9.6	15.2	23	31	45	58	70.5	85	114	140	170	212	288	346	432		
	ND (initial setting)	3	5	8	11	17.5	24	33	46	61	76	90	115	145	175	215	288	346		
	HD	1.5	3	5	8	11	17.5	24	33	46	61	76	90	115	145	175	215	288		
Output	Overload current rating *4	SLD 110% 60 s, 120% 3 s (inverse-time characteristics) at surrounding air temperature 40°C LD 120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 50°C ND (initial setting) 150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 50°C HD 200% 60 s, 250% 3 s (inverse-time characteristics) at surrounding air temperature 50°C																		
	Rated voltage *5	Three-phase 200 to 240 V																		
	Regenerative braking	Brake transistor	Built-in												FR-BU2 (Option)					
		Maximum brake torque*7	150% torque/3%ED *6				100% torque/3%ED *6			100% torque/2%ED *6			20% torque/continuous						10% torque/continuous	
	FR-ABR (when the option is used)	150% torque/10%ED			100% torque/10%ED						100% torque/6%ED						—			
Power supply	Rated input AC voltage/frequency	Three-phase 200 to 240 V 50 Hz/60 Hz																		
	Permissible AC voltage fluctuation	170 to 264 V 50 Hz/60 Hz																		
	Permissible frequency fluctuation	±5%																		
	Rated input current (A) *8	SLD	5.3	8.9	13.2	19.7	31.3	45.1	62.8	80.6	96.7	115	151	185	221	269	316	380	475	
		LD	5	8.3	12.2	18.3	28.5	41.6	58.2	74.8	90.9	106	139	178	207	255	288	346	432	
		ND (initial setting)	3.9	6.3	10.6	14.1	22.6	33.4	44.2	60.9	80	96.3	113	150	181	216	266	288	346	
HD		2.3	3.9	6.3	10.6	14.1	22.6	33.4	44.2	60.9	80	96.3	113	150	181	216	215	288		
Power supply capacity (kVA) *9	SLD	2	3.4	5	7.5	12	17	24	31	37	44	58	70	84	103	120	145	181		
	LD	1.9	3.2	4.7	7	11	16	22	29	35	41	53	68	79	97	110	132	165		
	ND (initial setting)	1.5	2.4	4	5.4	8.6	13	17	23	30	37	43	57	69	82	101	110	132		
	HD	0.9	1.5	2.4	4	5.4	8.6	13	17	23	30	37	43	57	69	82	82	110		
Protective structure (IEC 60529) *10	Enclose type (IP20)												Open type (IP00)							
Cooling system	Self-cooling			Forced air cooling																
Approx. mass (kg)	2.0	2.2	3.3	3.3	3.3	6.7	6.7	8.3	15	15	15	22	42	42	54	74	74			

\*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The 0.2 kW motor capacity is applicable under V/F control only.

\*3 The rated output capacity indicated assumes that the output voltage is 220 V for 200 V class.

\*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ .

\*6 Value for the built-in brake resistor

\*7 Value for the ND rating

\*8 The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor and cables) affects the rated input current.

\*9 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).

\*10 FR-DU08: IP40 (except for the PU connector section)

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal SpecsOperation Panel  
Parameter ListExplanations  
of  
ParametersProtective  
Functions

Options

LV/S/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



◆ 400 V class

Model FR-A840-[]		00023	00038	00052	00083	00126	00170	00250	00310	00380	00470	00620	00770	00930	01160	01800	02160	02600	03250	03610	04320	04810	05470	06100	06830	
		0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K	110K	132K	160K	185K	220K	250K	280K	
Applicable motor capacity (kW) *1	SLD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75/90	110	132	160	185	220	250	280	315	355	
	LD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	185	220	250	280	315	
	ND (initial setting)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	185	220	250	280	
	HD	0.2+2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	185	220	250	
Rated capacity (kVA) *3	SLD	1.8	2.9	4	6.3	10	13	19	24	29	36	47	59	71	88	137	165	198	248	275	329	367	417	465	521	
	LD	1.6	2.7	3.7	5.8	8.8	12	18	22	27	33	43	53	65	81	110	137	165	198	248	275	329	367	417	465	
	ND (initial setting)	1.1	1.9	3	4.6	6.9	9.1	13	18	24	29	34	43	54	66	84	110	137	165	198	248	275	329	367	417	
	HD	0.6	1.1	1.9	3	4.6	6.9	9.1	13	18	24	29	34	43	54	66	84	110	137	165	198	248	275	329	367	
Rated current (A)	SLD	2.3	3.8	5.2	8.3	12.6	17	25	31	38	47	62	77	93	116	180	216	260	325	361	432	481	547	610	683	
	LD	2.1	3.5	4.8	7.6	11.5	16	23	29	35	43	57	70	85	106	144	180	216	260	325	361	432	481	547	610	
	ND (initial setting)	1.5	2.5	4	6	9	12	17	23	31	38	44	57	71	86	110	144	180	216	260	325	361	432	481	547	
	HD	0.8	1.5	2.5	4	6	9	12	17	23	31	38	44	57	71	86	110	144	180	216	260	325	361	432	481	
Overload current rating *4	SLD	110% 60 s, 120% 3 s (inverse-time characteristics) at surrounding air temperature 40°C																								
	LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 50°C																								
	ND (initial setting)	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 50°C																								
	HD	200% 60 s, 250% 3 s (inverse-time characteristics) at surrounding air temperature 50°C																								
Rated voltage *5		Three-phase 380 to 500 V																								
Regenerative braking	Brake transistor	Built-in														FR-BU2(Optional)										
	Maximum brake torque *7	100% torque/2%ED *6										20% torque/continuous					10% torque/continuous									
	FR-ABR (when the option is used)	100% torque/10%ED							100% torque/6%ED							— *12										
Rated input AC voltage/frequency		Three-phase 380 to 500 V 50 Hz/60 Hz *11																								
Permissible AC voltage fluctuation		323 to 550 V 50 Hz/60 Hz																								
Permissible frequency fluctuation		±5%																								
Power supply	Rated input current (A) *8	SLD	3.2	5.4	7.8	10.9	16.4	22.5	31.7	40.3	48.2	58.4	76.8	97.6	115	141	180	216	260	325	361	432	481	547	610	683
		LD	3	4.9	7.3	10.1	15.1	22.3	31	38.2	44.9	53.9	75.1	89.7	106	130	144	180	216	260	325	361	432	481	547	610
		ND (initial setting)	2.3	3.7	6.2	8.3	12.3	17.4	22.5	31	40.3	48.2	56.5	75.1	91	108	134	144	180	216	260	325	361	432	481	547
		HD	1.4	2.3	3.7	6.2	8.3	12.3	17.4	22.5	31	40.3	48.2	56.5	75.1	91	108	110	144	180	216	260	325	361	432	481
	Power supply capacity (kVA) *9	SLD	2.5	4.1	5.9	8.3	12	17	24	31	37	44	59	74	88	107	137	165	198	248	275	329	367	417	465	521
		LD	2.3	3.7	5.5	7.7	12	17	24	29	34	41	57	68	81	99	110	137	165	198	248	275	329	367	417	465
		ND (initial setting)	1.7	2.8	4.7	6.3	9.4	13	17	24	31	37	43	57	69	83	102	110	137	165	198	248	275	329	367	417
		HD	1.1	1.7	2.8	4.7	6.3	9.4	13	17	24	31	37	43	57	69	83	84	110	137	165	198	248	275	329	367
Protective structure (IEC 60529) *10		Enclose type (IP20)												Open type (IP00)												
Cooling system		Self-cooling					Forced air cooling																			
Approx. mass (kg)		2.8	2.8	2.8	3.3	3.3	6.7	6.7	8.3	8.3	15	15	23	41	41	43	52	55	71	78	117	117	166	166	166	

- \*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.
- \*2 The 0.2 kW motor capacity is applicable under V/F control only.
- \*3 The rated output capacity indicated assumes that the output voltage is 440 V for 400 V class.
- \*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.
- \*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ .
- \*6 Value for the built-in brake resistor
- \*7 Value for the ND rating
- \*8 The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor and cables) affects the rated input current.
- \*9 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).
- \*10 FR-DU08: IP40 (except for the PU connector section)
- \*11 For the power voltage exceeding 480 V, set **Pr.977 Input voltage mode selection**. (For details, refer to ).
- \*12 The braking capability of the inverter built-in brake can be improved with a commercial brake resistor. For the details, please contact your sales representative.



## ● Rating (separated converter types)

### ◆ 400 V class

- Inverter

Model FR-A842-[ ]		07700	08660	09620	10940	12120	
		315K	355K	400K	450K	500K	
Applicable motor capacity (kW) *1	SLD	400	450	500	560	630	
	LD	355	400	450	500	560	
	ND (initial setting)	315	355	400	450	500	
	HD	280	315	355	400	450	
Output	Rated capacity (kVA) *2	SLD	587	660	733	834	924
		LD	521	587	660	733	834
		ND (initial setting)	465	521	587	660	733
		HD	417	465	521	587	660
	Rated current (A)	SLD	770	866	962	1094	1212
		LD	683	770	866	962	1094
		ND (initial setting)	610	683	770	866	962
		HD	547	610	683	770	866
	Overload current rating *3	SLD	110% 60 s, 120% 3 s (inverse-time characteristics) at surrounding air temperature 40°C				
		LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 50°C				
		ND (initial setting)	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 50°C				
		HD	200% 60 s, 250% 3 s (inverse-time characteristics) at surrounding air temperature 50°C				
Rated voltage *4		Three-phase 380 to 500 V					
Regenerative braking torque *5 (When the converter unit (FR-CC2) is used)		Maximum brake torque	10% torque/continuous				
Input power	DC power supply voltage		430 to 780 VDC				
	Control power supply auxiliary input		Single phase 380 to 500 V 50 Hz/60 Hz *7				
	Permissible control power supply auxiliary input fluctuation		Frequency $\pm 5\%$ , voltage $\pm 10\%$				
Protective structure (IEC 60529) *6		Open type (IP00)					
Cooling system		Forced air cooling					
Approx. mass (kg)		163	163	243	243	243	

\*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The rated output capacity indicated assumes that the output voltage is 440 V.

\*3 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*4 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ .

\*5 ND rating reference value

\*6 FR-DU08: IP40 (except for the PU connector section)

\*7 For the power voltage exceeding 480 V, set **Pr.977 Input voltage mode selection**.

- Converter unit (FR-CC2)

Model FR-CC2-H[ ]		315K	355K	400K	450K	500K	560K	630K
Applicable motor capacity (kW)		315	355	400	450	500	560	630
Output	Overload current rating *1	200% 60 s, 250% 3 s				150% 60 s, 200% 3 s	120% 60 s, 150% 3 s	110% 60 s, 120% 3 s
	Rated voltage *2	430 to 780 VDC *4						
Power supply	Rated input AC voltage/frequency		Three-phase 380 to 500 V 50 Hz/60 Hz					
	Permissible AC voltage fluctuation		Three-phase 323 to 550 V 50 Hz/60 Hz					
	Permissible frequency fluctuation		$\pm 5\%$					
	Rated input current (A)		610	683	770	866	962	1094
Power supply capacity (kVA) *3		465	521	587	660	733	833	924
Protective structure (IEC 60529)		Open type (IP00)						
Cooling system		Forced air cooling						
DC reactor		Built-in						
Approx. mass (kg)		210	213	282	285	288	293	294

\*1 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the converter unit and the inverter to return to or below the temperatures under 100% load.

\*2 The converter unit output voltage varies according to the input power supply voltage and the load. The maximum point of the voltage waveform at the converter unit output side is approximately the power supply voltage multiplied by  $\sqrt{2}$ .

\*3 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).

\*4 The permissible voltage imbalance ratio is 3% or less. (Imbalance ratio = (highest voltage between lines - average voltage between three lines) / average voltage between three lines  $\times 100$ )

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## ● Rating (IP55 compatible model)

### ◆ 400 V class

Model FR-A846-□		00023	00038	00052	00083	00126	00170	00250	00310	00380	00470	00620	00770	00930	01160	01800	02160	02600	03250	03610	
		0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K	15K	18.5K	22K	30K	37K	45K	55K	75K	90K	110K	132K	160
Applicable motor capacity (kW) *1	LD	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	
	ND (initial setting)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
Rated capacity (kVA) *2	LD	1.6	2.7	3.7	5.8	8.8	12	18	22	27	33	43	53	65	81	110	137	165	198	248	
	ND (initial setting)	1.1	1.9	3	4.6	6.9	9.1	13	18	24	29	34	43	54	66	84	110	137	165	198	248
Rated current (A)	LD	2.1	3.5	4.8	7.6	11.5	16	23	29	35	43	57	70	85	106	144	180	216	260	325	
	ND (initial setting)	1.5	2.5	4	6	9	12	17	23	31	38	44	57	71	86	110	144	180	216	260	325
Overload current rating *3	LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 40°C																			
	ND (initial setting)	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 40°C																			
Rated voltage *4		Three-phase 380 to 500 V																			
Regenerative braking *5		Maximum brake torque 10% torque/continuous																			
Rated input AC voltage/frequency		Three-phase 380 to 500 V 50 Hz/60 Hz *8																			
Permissible AC voltage fluctuation		323 to 550 V 50 Hz/60 Hz																			
Permissible frequency fluctuation		±5%																			
Rated input current (A) *6	LD	2.1	3.5	4.8	7.6	11.5	16	23	29	35	43	57	70	85	106	144	180	216	260	325	
	ND (initial setting)	1.5	2.5	4	6	9	12	17	23	31	38	44	57	71	86	110	144	180	216	260	325
Power supply capacity (kVA) *7	LD	1.6	2.7	3.7	5.8	9	12	18	22	27	33	43	53	65	81	110	137	165	198	248	
	ND (initial setting)	1.1	1.9	3	4.6	6.9	9	13	18	24	29	34	43	54	66	102	110	137	165	198	248
Protective structure	IEC 60529	Dust- and water-proof type (IP55) *10																			
	UL50	UL Type12 *9																			
Cooling system		Self cooling + internal fan							Forced-air-cooling + internal fan												
Approx. mass (kg)		15	15	15	15	16	17	26	26	27	27	59	60	63	64	147	150	153	189	193	193

\*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The rated output capacity indicated assumes that the output voltage is 440 V.

\*3 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*4 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ .

\*5 Value for the ND rating.

\*6 The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor and cables) affects the rated input current.

\*7 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).

\*8 For the power voltage exceeding 480 V, set **Pr.977 Input voltage mode selection**.

\*9 UL Type 12 Enclosure-Suitable for Installation in a Compartment Handling Conditioned Air (Plenum)

\*10 For compliance with IP55, remove the protective bushes and install the recommended cable glands.



● Common specifications

Control specifications	Control method		Soft-PWM control, high carrier frequency PWM control (selectable among V/F control, Advanced magnetic flux vector control, Real sensorless vector control, Optimum excitation control), vector control, and PM sensorless vector control	
	Output frequency range		0.2 to 590 Hz (The upper-limit frequency is 400 Hz under Advanced magnetic flux vector control, Real sensorless vector control, vector control, and PM sensorless vector control.)	
	Frequency setting resolution	Analog input	0.015 Hz/60 Hz (0 to 10 V/12 bits for terminals 2 and 4) 0.03 Hz/60 Hz (0 to 5 V/11 bits or 0 to 20 mA/approx. 11 bits for terminals 2 and 4, 0 to ±10 V/12 bits for terminal 1) 0.06 Hz/60 Hz (0 to ±5 V/11 bits for terminal 1)	
		Digital input	0.01 Hz	
	Frequency accuracy	Analog input	Within ±0.2% of the max. output frequency (25°C ± 10°C)	
		Digital input	Within 0.01% of the set output frequency	
	Voltage/frequency characteristics		Base frequency can be set from 0 to 590 Hz. Constant-torque/variable-torque pattern or adjustable 5 points V/F can be selected.	
	Starting torque *2		SLD Rating:120% 0.3 Hz, LD Rating:150% 0.3 Hz, ND Rating:200% 0.3 Hz*3, HD Rating:250% 0.3 Hz*3 (Real sensorless vector control, vector control)	
	Torque boost		Manual torque boost	
	Acceleration/deceleration time setting		0 to 3600 s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration mode, backlash countermeasures acceleration/deceleration can be selected.	
	DC injection brake (induction motor)		Operation frequency (0 to 120 Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable	
	Stall prevention operation level		Activation range of stall prevention operation (SLD rating: 0 to 120%, LD rating: 0 to 150%, ND rating: 0 to 220%, HD rating: 0 to 280%). Whether to use the stall prevention or not can be selected. (V/F control, Advanced magnetic flux vector control)	
Torque limit level		Torque limit value can be set (0 to 400% variable). (Real sensorless vector control, vector control, PM sensorless vector control)		
Operation specifications	Frequency setting signal	Analog input	Terminals 2 and 4: 0 to 10 V, 0 to 5 V, 4 to 20 mA (0 to 20 mA) are available. Terminal 1: -10 to +10 V, -5 to +5 V are available.	
		Digital input	Input using the setting dial of the operation panel or parameter unit Four-digit BCD or 16-bit binary (when used with option FR-A8AX)	
	Start signal		Forward and reverse rotation or start signal automatic self-holding input (3-wire input) can be selected.	
	Input signals (twelve terminals)		Low-speed operation command, Middle-speed operation command, High-speed operation command, Second function selection, Terminal 4 input selection, Jog operation selection, Selection of automatic restart after instantaneous power failure, flying start, Output stop, Start self-holding selection, Forward rotation command, Reverse rotation command, Inverter reset	
	Pulse train input		100 kpps	
	Operational functions		Maximum and minimum frequency settings, multi-speed operation, acceleration/deceleration pattern, thermal protection, DC injection brake, starting frequency, JOG operation, output stop (MRS), stall prevention, regeneration avoidance, increased magnetic excitation deceleration, DC feeding*4, frequency jump, rotation display, automatic restart after instantaneous power failure, electronic bypass sequence, remote setting, automatic acceleration/deceleration, intelligent mode, retry function, carrier frequency selection, fast-response current limit, forward/reverse rotation prevention, operation mode selection, slip compensation, droop control, load torque high-speed frequency control, speed smoothing control, traverse, auto tuning, applied motor selection, gain tuning, RS-485 communication, PID control, PID pre-charge function, easy dancer control, cooling fan operation selection, stop selection (deceleration stop/coasting), power-failure deceleration stop function, stop-on-contact control, PLC function, life diagnosis, maintenance timer, current average monitor, multiple rating, orientation control, speed control, torque control, position control, pre-excitation, torque limit, test run, 24 V power supply input for control circuit, safety stop function, anti-sway control	
	Output signal	Open collector output (five terminals) Relay output (two terminals)	Inverter running, Up to frequency, Instantaneous power failure/undervoltage, Overload warning, Output frequency detection, Fault Fault codes of the inverter can be output (4 bits) from the open collector.	
		Pulse train output (FM type)	50 kpps	
	For meter	Pulse train output (FM type)		Max. 2.4 kHz: one terminal (output frequency) The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection.</b>
		Current output (CA type)		Max. 20 mADC: one terminal (output current) The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection.</b>
Voltage output		Max. 10 VDC: one terminal (output voltage) The monitored item can be changed using <b>Pr.158 AM terminal function selection.</b>		
Operation panel (FR-DU08)	Operating status		Output frequency, Output current, Output voltage, Frequency setting value The monitored item can be changed using <b>Pr.52 Operation panel main monitor selection.</b>	
	Fault record		A fault record is displayed when a fault occurs. Past 8 fault records and the conditions immediately before the fault (output voltage/current/frequency/cumulative energization time/year/month/date/time) are saved.	
Protective/warning function	Protective function		Overcurrent trip during acceleration, Overcurrent trip during constant speed, Overcurrent trip during deceleration or stop, Regenerative overvoltage trip during acceleration, Regenerative overvoltage trip during constant speed, Regenerative overvoltage trip during deceleration or stop, Inverter overload trip, Motor overload trip, Heatsink overheat, Instantaneous power failure*4, Undervoltage*4, Input phase loss*4*5, Stall prevention stop, Loss of synchronism detection*5, Brake transistor alarm detection*6, Output side earth (ground) fault overcurrent, Output short circuit, Output phase loss, External thermal relay operation*5, PTC thermistor operation*5, Option fault, Communication option fault, Parameter storage device fault, PU disconnection, Retry count excess*5, Parameter storage device fault, CPU fault, Operation panel power supply short circuit/RS-485 terminals power supply short circuit, 24 VDC power fault, Abnormal output current detection*5, Inrush current limit circuit fault*4, Communication fault (inverter), Analog input fault, USB communication fault, Safety circuit fault, Overspeed occurrence*5, Speed deviation excess detection*5, Signal loss detection*5, Excessive position fault*5, Brake sequence fault*5, Encoder phase fault*5, 4 mA input fault*5, Pre-charge fault*5, PID signal fault*5, Option fault, Internal circuit fault*5, Internal circuit fault, Abnormal internal temperature*7, Magnetic pole position unknown*1	
	Warning function		Fan alarm, Stall prevention (overcurrent), Stall prevention (overvoltage), Regenerative brake pre-alarm*5*6, Electronic thermal relay function pre-alarm, PU stop, Speed limit indication*5, Parameter copy, Safety stop, Maintenance signal output*5, USB host error, Home position return setting error*5, Home position return uncompleted*5, Home position return parameter setting error*5, Operation panel lock*5, Password locked*5, Parameter write error, Copy operation error, 24 V external power supply operation, Internal fan alarm*7	

Features	Application Example PLC Function FR Configurator2
Connection Examples	Standard Speeds
Outline Dimensions	Terminal Connection Diagrams Terminal Specs
Operation Panel	Parameter List
Parameter List	Explanations of Parameters
Options	Protective Functions
LVS/Cables	Options
Precautions	Precautions
Motors	Motors
Compatibility	Compatibility
Warranty Inquiry	Warranty Inquiry

Environment	Surrounding air temperature	-10°C to +50°C (non-freezing) (LD, ND, HD ratings) -10°C to +40°C (non-freezing) (SLD rating, IP55 compatible model)
	Surrounding air humidity	95% RH or less (non-condensing) (With circuit board coating (conforming to IEC60721-3-3 3C2/3S2), IP55 compatible model) 90% RH or less (non-condensing) (Without circuit board coating)
	Storage temperature *8	-20°C to +65°C
	Atmosphere	Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt, etc.)
	Altitude/vibration	Maximum 1000 m above sea level *9, 5.9 m/s <sup>2</sup> *10 or less at 10 to 55 Hz (directions of X, Y, Z axes)

- \*1 Available only when a vector control compatible option is installed.
- \*2 For PM sensorless vector control, refer to **page 198**.
- \*3 In the initial setting of the FR-A820-00340(5.5K) or higher and the FR-A840-00170(5.5K) or higher, it is limited to 150% by the torque limit level.
- \*4 Enabled only for standard models and IP55 compatible models.
- \*5 This protective function is not available in the initial status.
- \*6 Enabled only for standard models.
- \*7 Available for the IP55 compatible model only.
- \*8 Temperature applicable for a short time, e.g. in transit.
- \*9 For the installation at an altitude above 1,000 m up to 2,500 m, derate the rated current 3% per 500 m.
- \*10 2.9m/s<sup>2</sup> or less for the FR-A840-04320(160K) or higher.

## ● PLC function specifications

Item		A800 PLC function specifications	
Control method		Repeated operation (by stored program)	
I/O control mode		Refresh	
Programming language		Relay symbolic language (ladder) Function block	
No. of instructions	Sequence instructions	25	
	Basic instructions	84	
	Application instructions	37	
Processing speed		Sequence instructions 1.9 μs to 12 μs/step*1	
Number of I/O device points		128 (input: 64 points, output: 64 points) 19 points built-in (input: 12 points, output: 7 points)*2 FR-A8AX (input: 16 points) FR-A8AY (output: 7 points) FR-A8AR (output: 3 points)	
Number of analog I/O points		3 input points built-in (Terminals 1, 2, and 4), FR-A8AZ: 1 input point (Terminal 6) 2 output points built-in (Terminals F/C(FM/CA) and AM), FR-A8AY: 2 output points (Terminals AM0 and AM1), FR-A8AZ: 1 output point (Terminal DA1)	
Pulse train I/O	Input	Terminal JOG maximum input pulse: 100k pulses/s *3	
	Output	Terminal FM maximum output pulse: 50k pulses/s *3	
Watchdog timer		10 to 2000 ms	
Program capacity		6K steps (24k bytes) (0 to 6144 steps can be set) Contained in one program	
Device	Internal relay (M)	128 (M0 to M127)	
	Latch relay (L)	Not used (Can be set with parameters but will not latch)*4	
	Timer (T)	Number of points	16 (T0 to T15)
		Specifications	100 ms timer: 0.1 to 3276.7 s can be set 10 ms timer: 0.01 to 327.67 s can be set 100 ms retentive timer: 0.1 to 3276.7 s can be set
	Counter (C)	Number of points	16 (C0 to C15)
		Specifications	Normal counter: Setting range 1 to 32767 Interrupt program counter: Not used
	Data register (D)	256 (D0 to D255)	
	Special relay (SM)	2048 (SM0 to SM2047) with limited functions	
Special register (SD)	2048 (SD0 to SD2047) with limited functions		

- \*1 The scan time is approximately 40 ms for 1K steps as inverter control is also performed in actual operations.
- \*2 The signals same as the ones assigned to the inverter I/O terminals are used.  
One point is always required for a sequence start (RUN/STOP).
- \*3 **Pr.291** Pulse train I/O selection must be set.
- \*4 There is no device latch function for power failures.  
Use the **Pr.1150 to Pr.1199 PLC function user parameters 1 to 50** (D206 to D255) to store device values in the EEPROM.

### NOTE

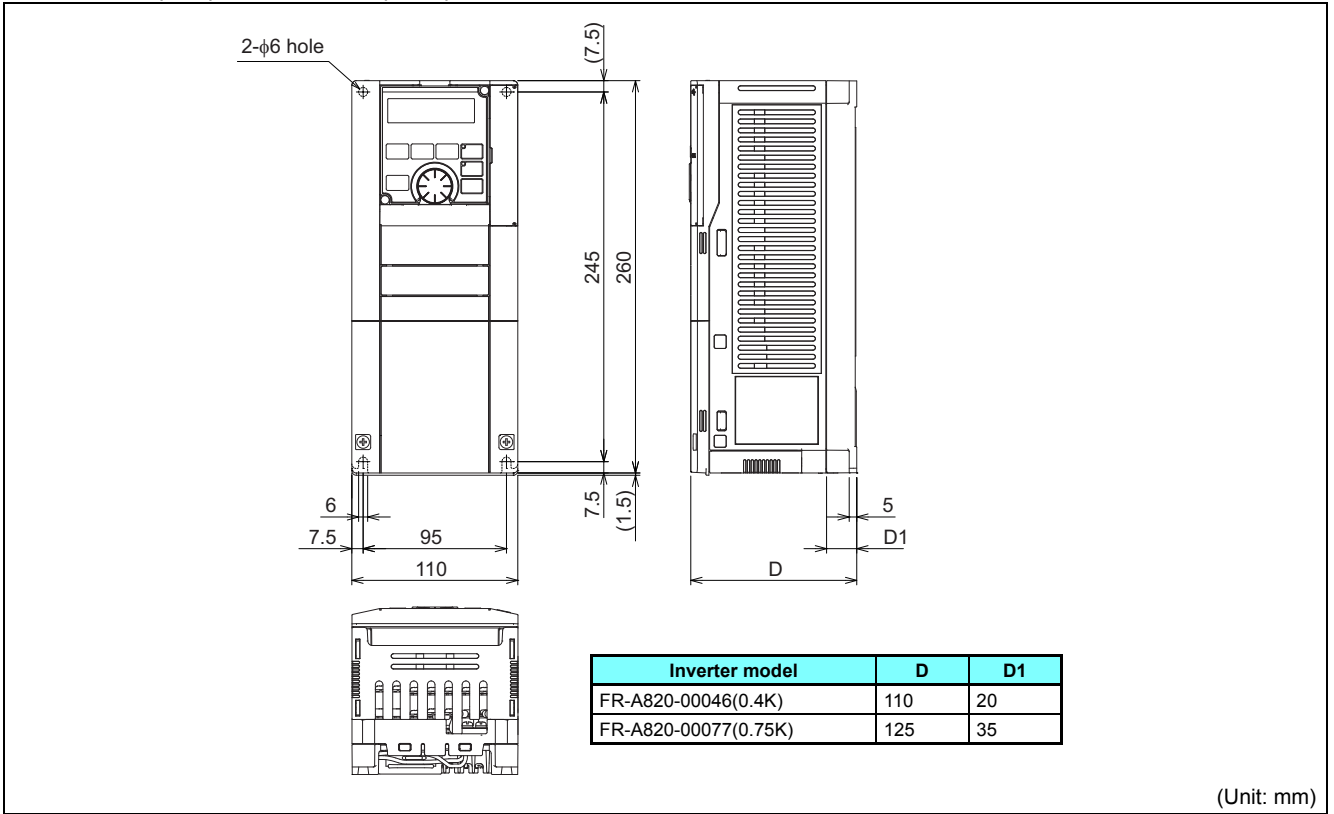
- There is no buffer memory.



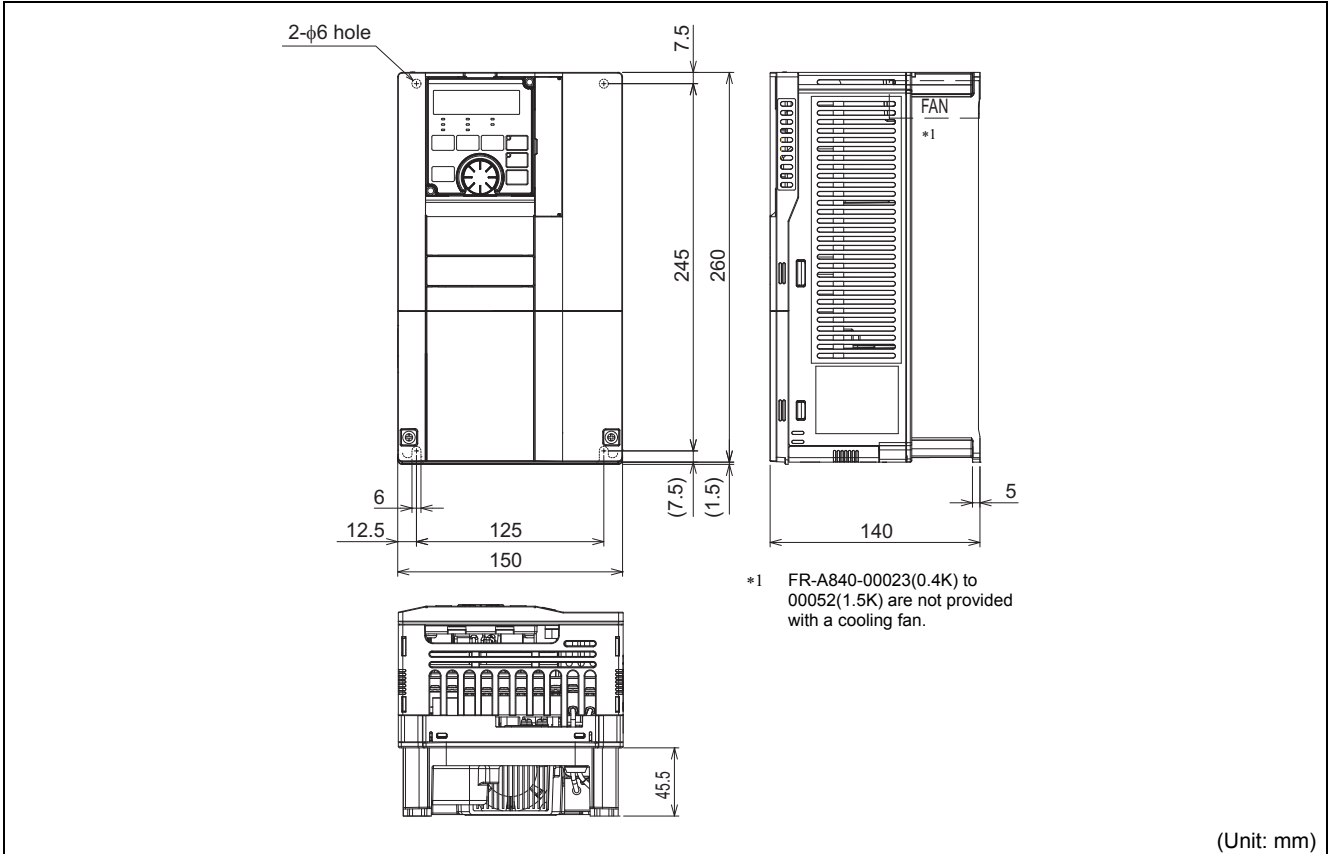
# Outline Dimension Drawings

## ● Standard model

FR-A820-00046(0.4K), FR-A820-00077(0.75K)



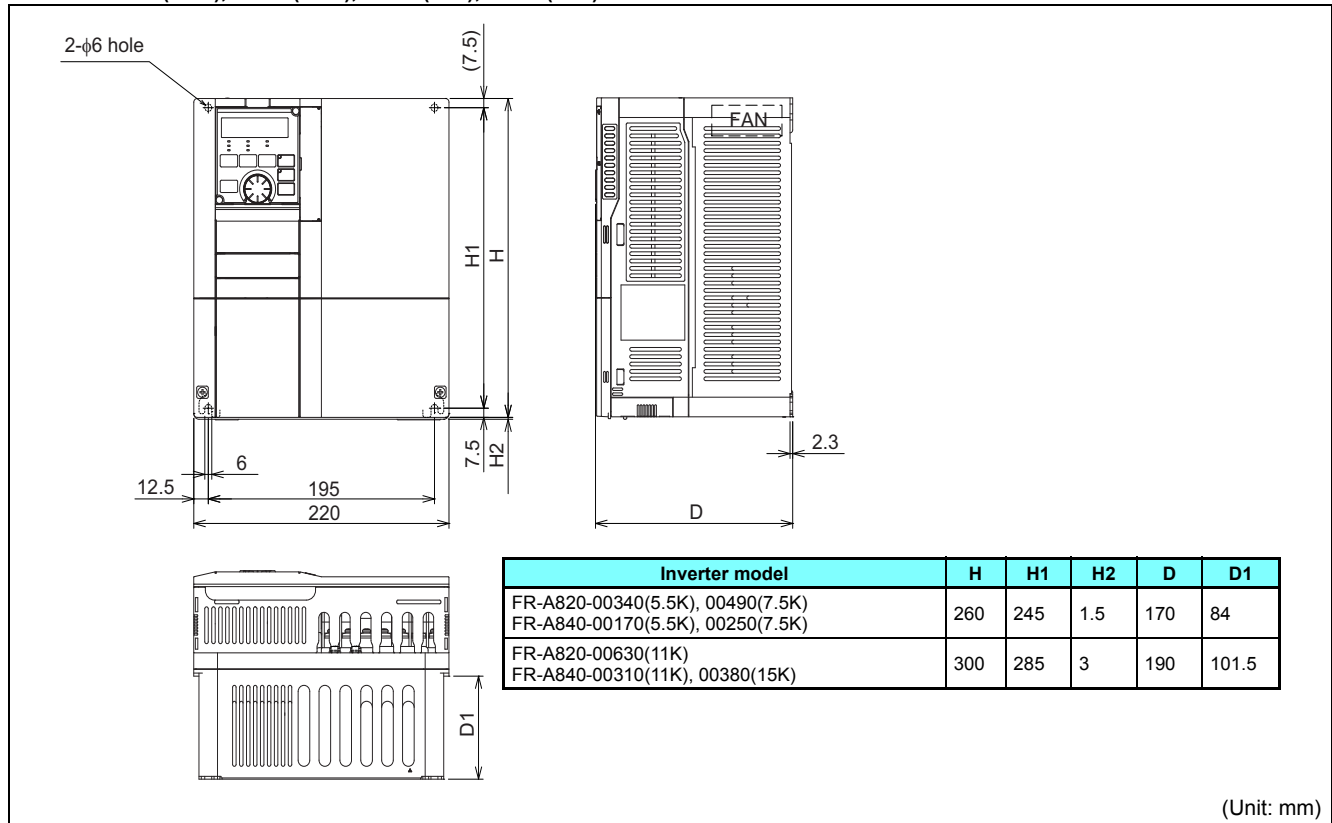
FR-A820-00105(1.5K), 00167(2.2K), 00250(3.7K)  
 FR-A840-00023(0.4K), 00038(0.75K), 00052(1.5K), 00083(2.2K), 00126(3.7K)



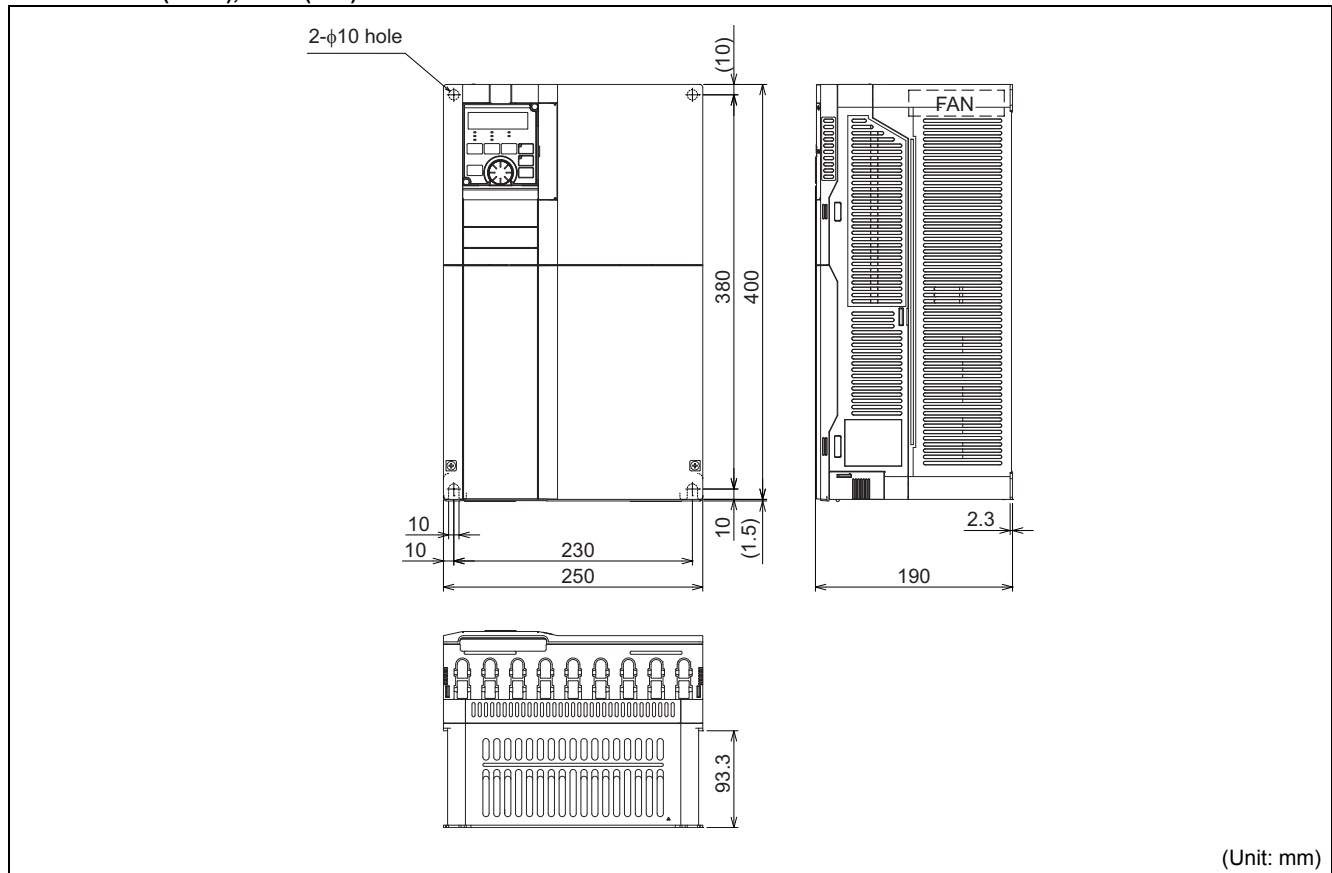
- Features
- Application Example  
PLC Function  
FR Configurator2
- Connection  
Examples
- Standard  
Specs
- Outline  
Dimensions**
- Terminal Connection  
Diagrams  
Terminal Specs
- Operation Panel
- Parameter List
- Explanations  
of  
Parameters
- Protective  
Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty  
Inquiry



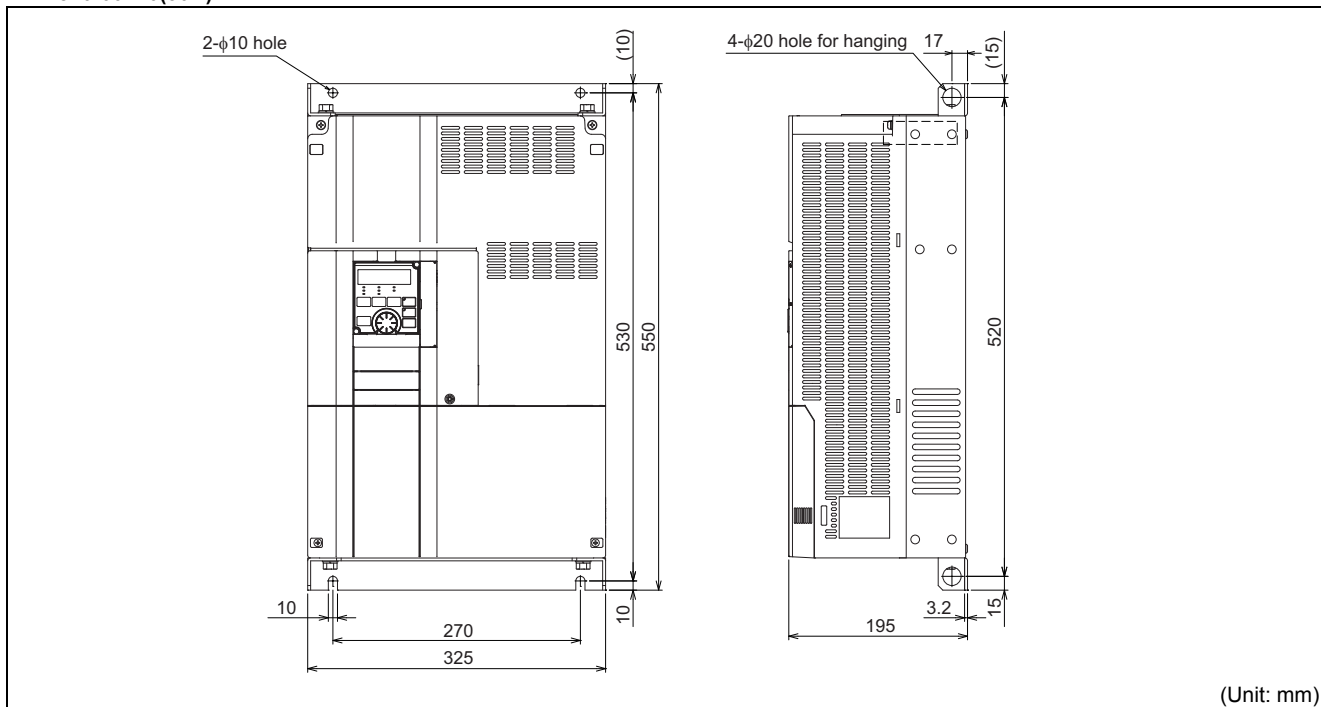
FR-A820-00340(5.5K), 00490(7.5K), 00630(11K)  
 FR-A840-00170(5.5K), 00250(7.5K), 00310(11K), 00380(15K)



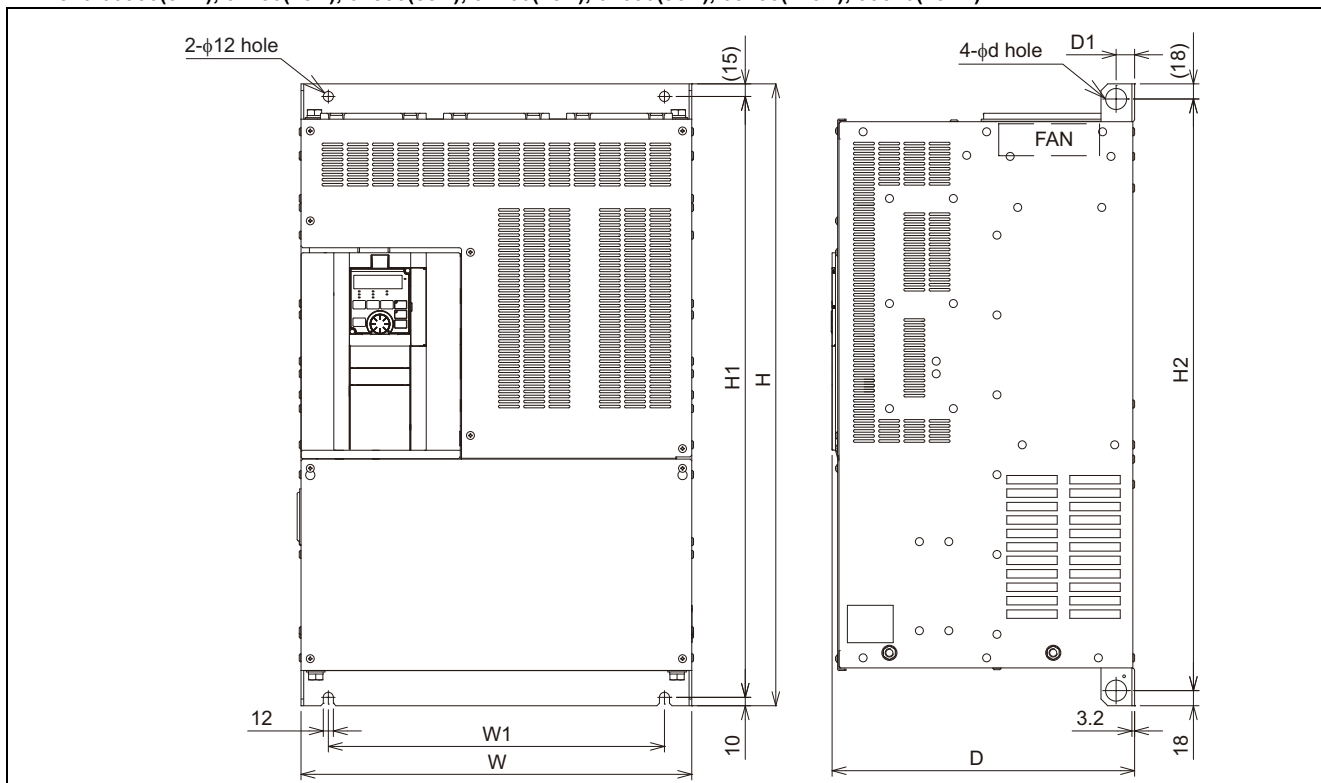
FR-A820-00770(15K), 00930(18.5K), 01250(22K)  
 FR-A840-00470(18.5K), 00620(22K)



FR-A820-01540(30K)  
FR-A840-00770(30K)



FR-A820-01870(37K), 02330(45K), 03160(55K), 03800(75K), 04750(90K)  
FR-A840-00930(37K), 01160(45K), 01800(55K), 02160(75K), 02600(90K), 03250(110K), 03610(132K)



Inverter model	W	W1	H	H1	H2	d	D	D1
FR-A820-01870(37K), 02330(45K) FR-A840-00930(37K), 01160(45K), 01800(55K)*1	435	380	550	525	514	25	250	24
FR-A820-03160(55K)*1	465	410	700	675	664	25	250	22
FR-A820-03800(75K)*1, 04750(90K)*1	465	400	740	715	704	24	360	22
FR-A840-02160(75K)*1, 02600(90K)*1	465	400	620	595	584	24	300	22
FR-A840-03250(110K)*1, 03610(132K)*1	465	400	740	715	704	25	360	22

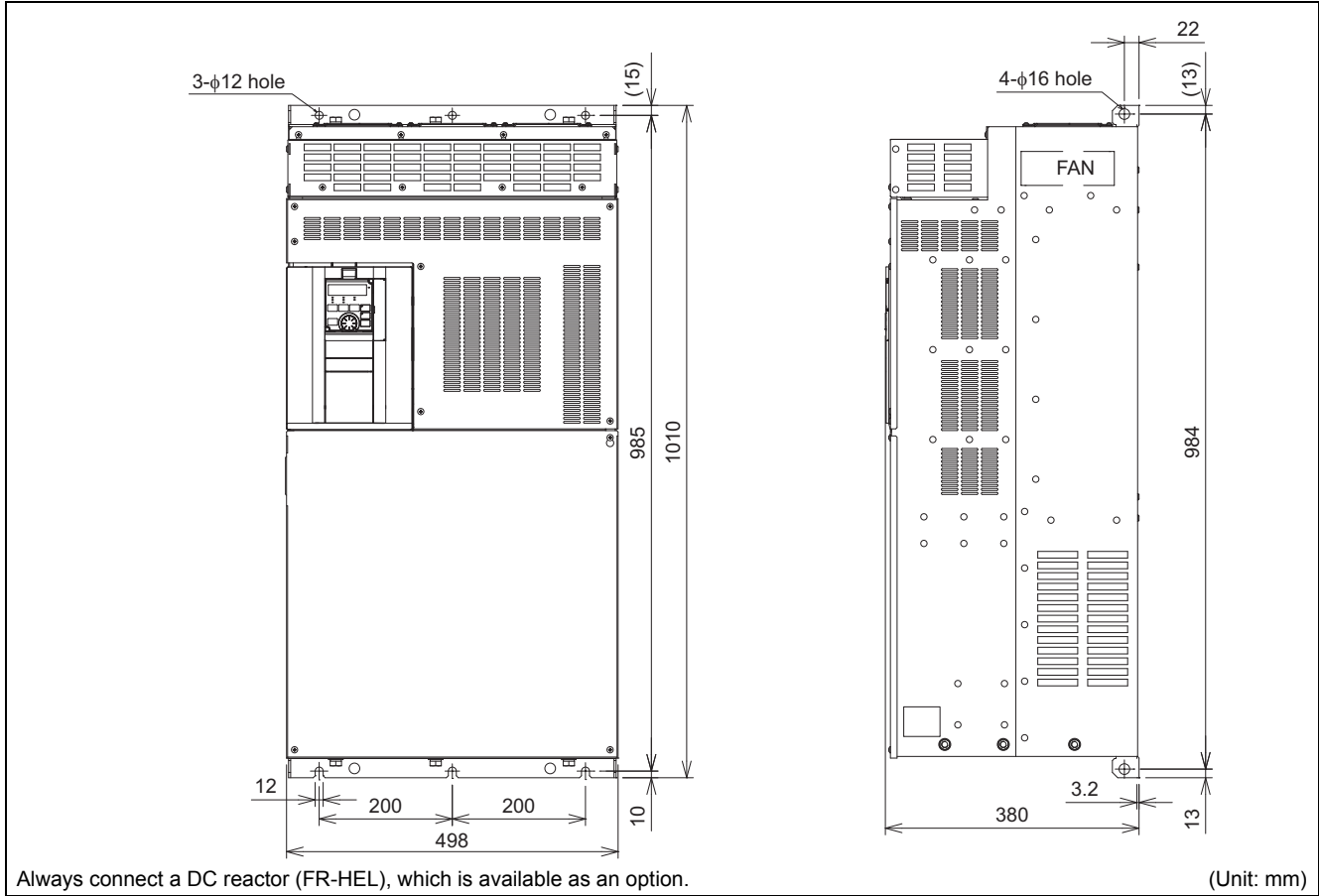
\*1 When using a motor with a capacity of 75 kW or higher, always connect a DC reactor (FR-HEL), which is available as an option.

(Unit: mm)

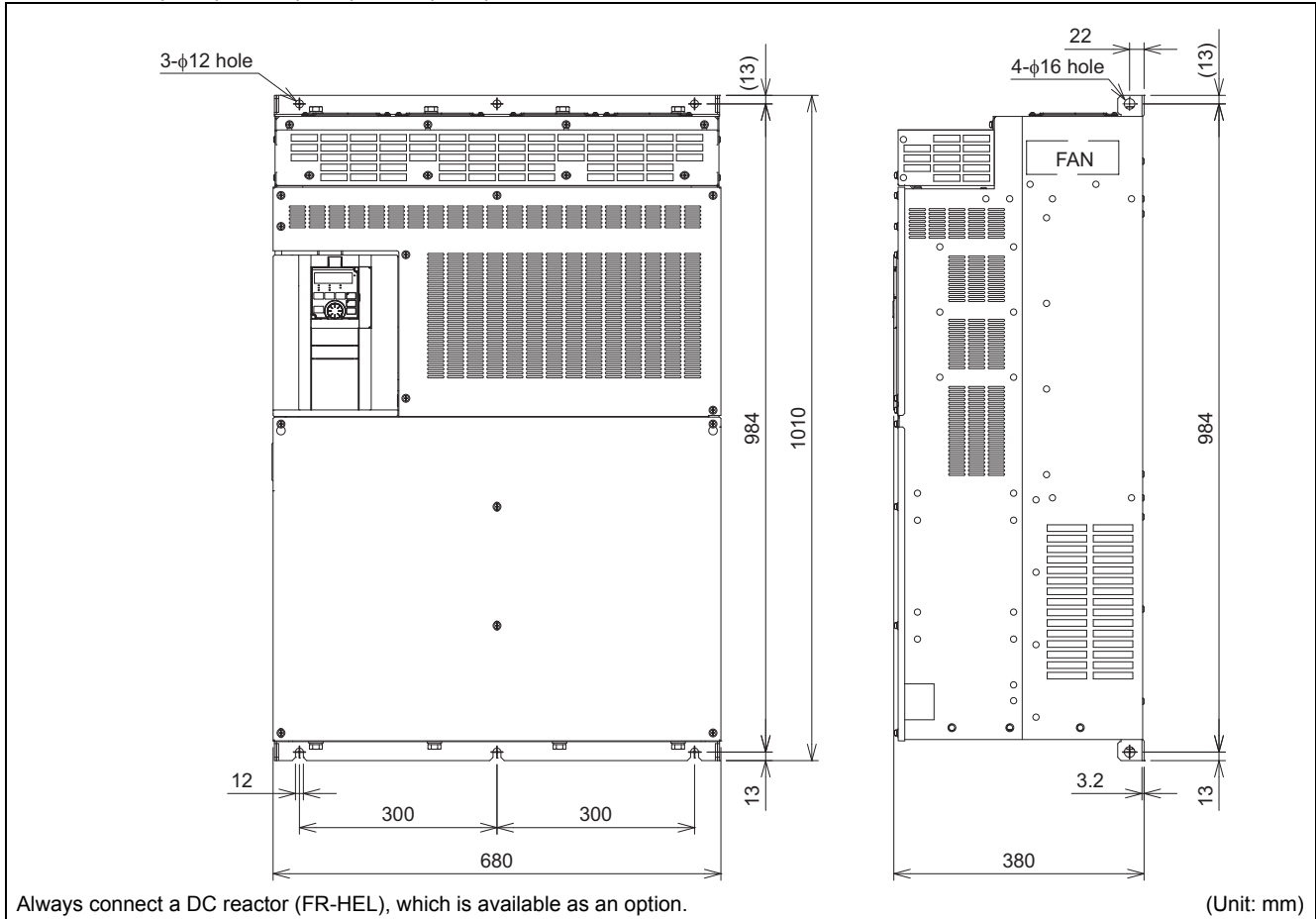
- Features
- Application Example  
PLC Function  
FR Configurator2
- Connection  
Examples
- Standard  
Specs
- Outline  
Dimensions**
- Terminal Connection  
Diagrams  
Terminal Specs
- Operation Panel
- Parameter List
- Explanations  
of  
Parameters
- Protective  
Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty  
Inquiry



**FR-A840-04320(160K), 04810(185K)**



**FR-A840-05470(220K), 06100(250K), 06830(280K)**



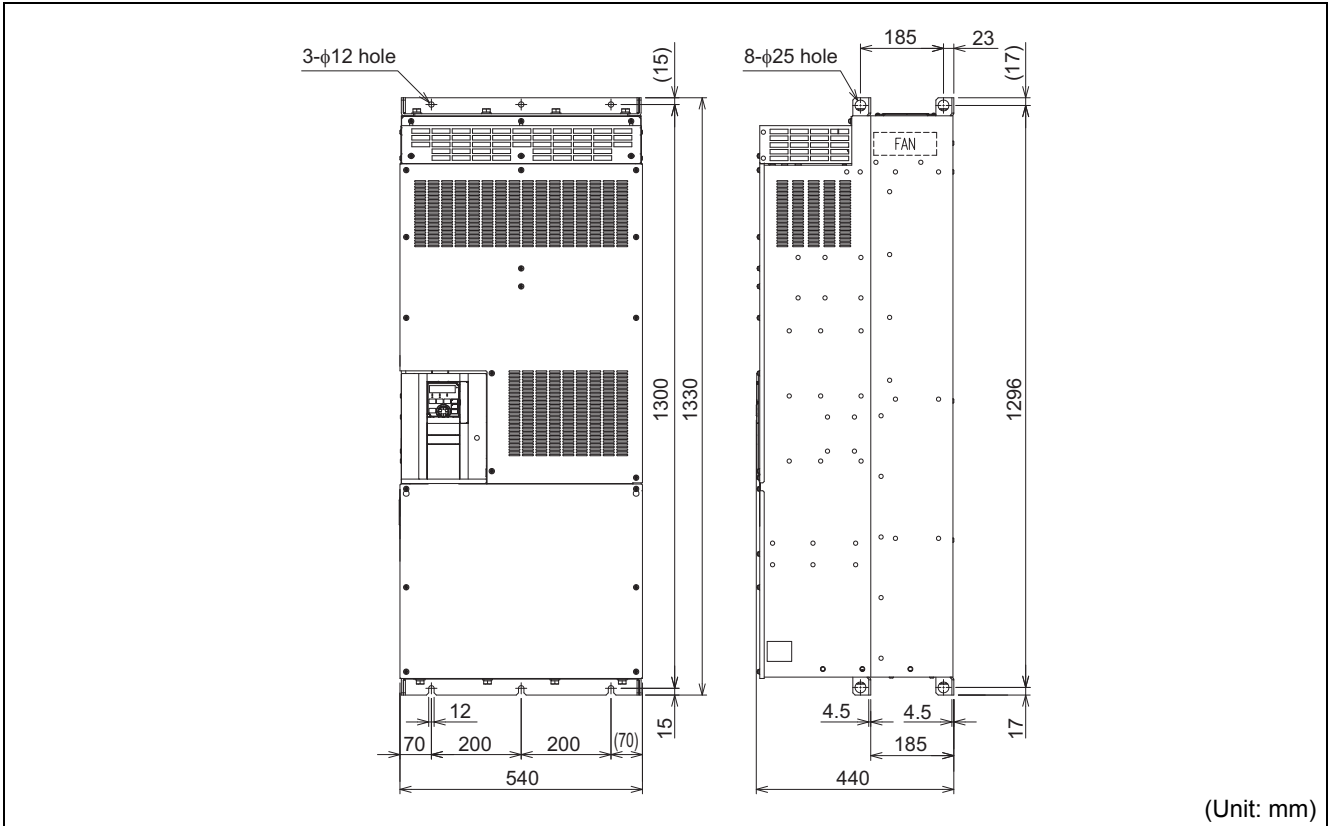




● Separated converter type

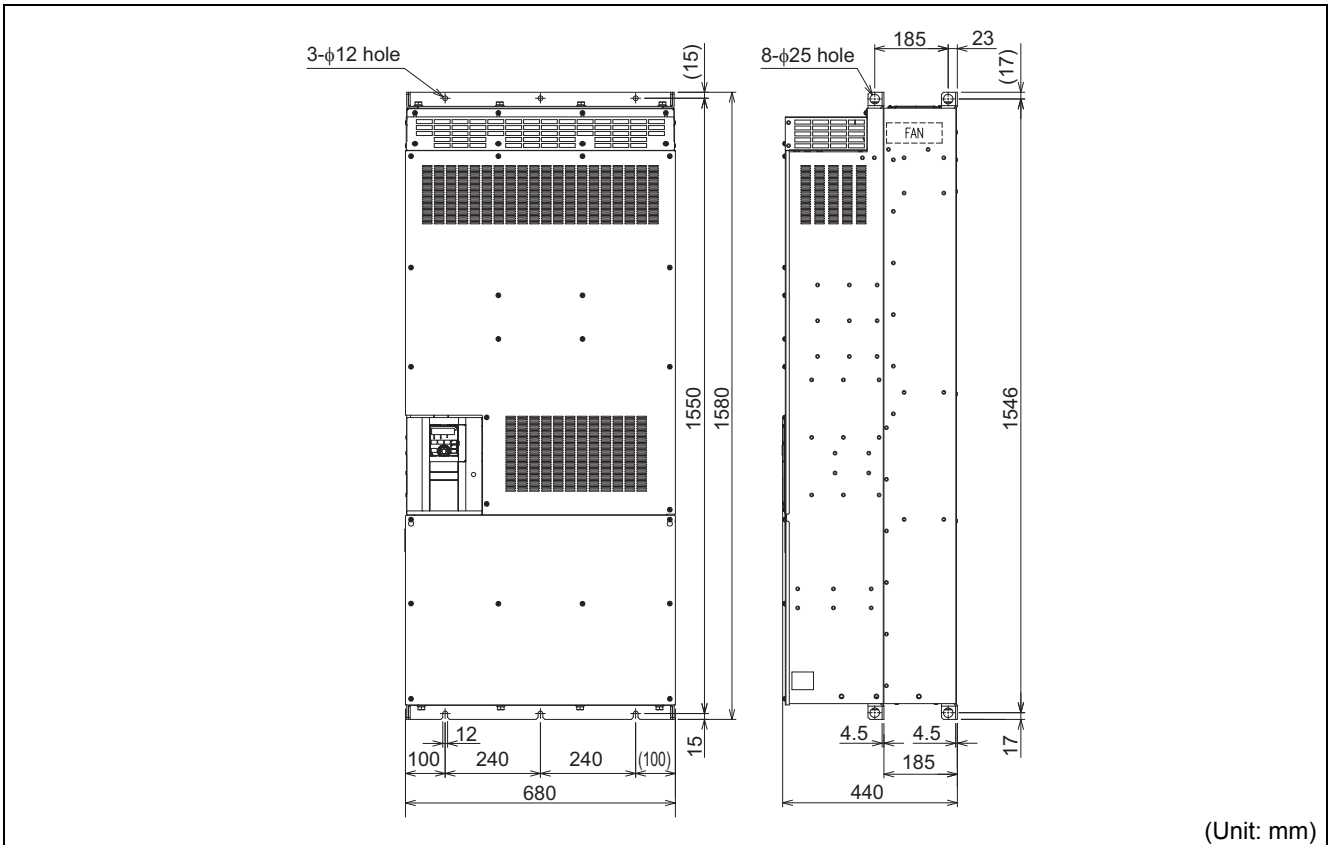
◆ Inverter

FR-A842-07700(315K), 08660(355K)



(Unit: mm)

FR-A842-09620(400K), 10940(450K), 12120(500K)



(Unit: mm)

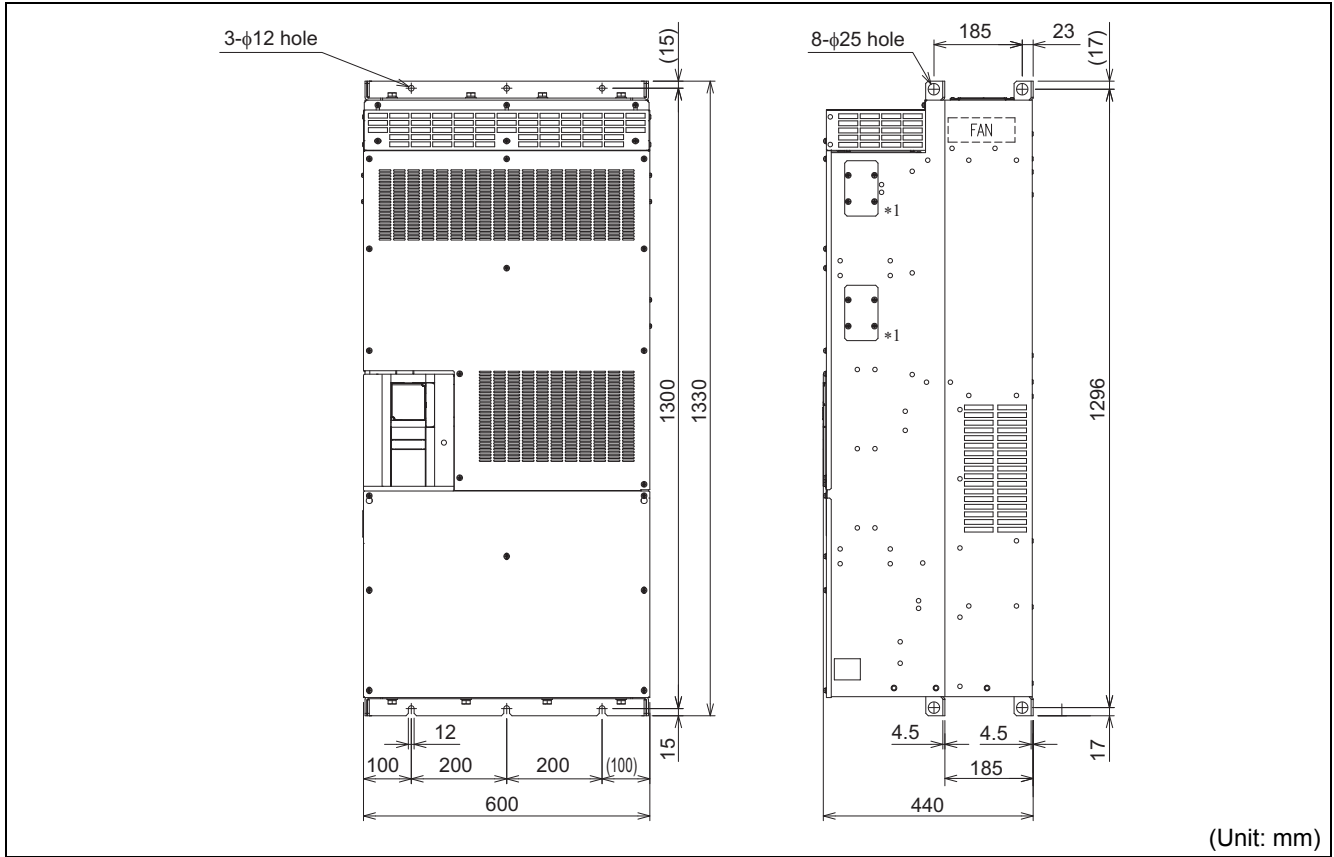
Features	Application Example PLC Function FR Configurator2	Connection Examples	Standard Specs	<b>Outline Dimensions</b>	Terminal Connection Diagrams Terminal Specs	Operation Panel	Parameter List	Explanations of Parameters	Protective Functions	Options	LVS/Cables	Precautions	Motors	Compatibility	Warranty Inquiry
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◆ Converter unit

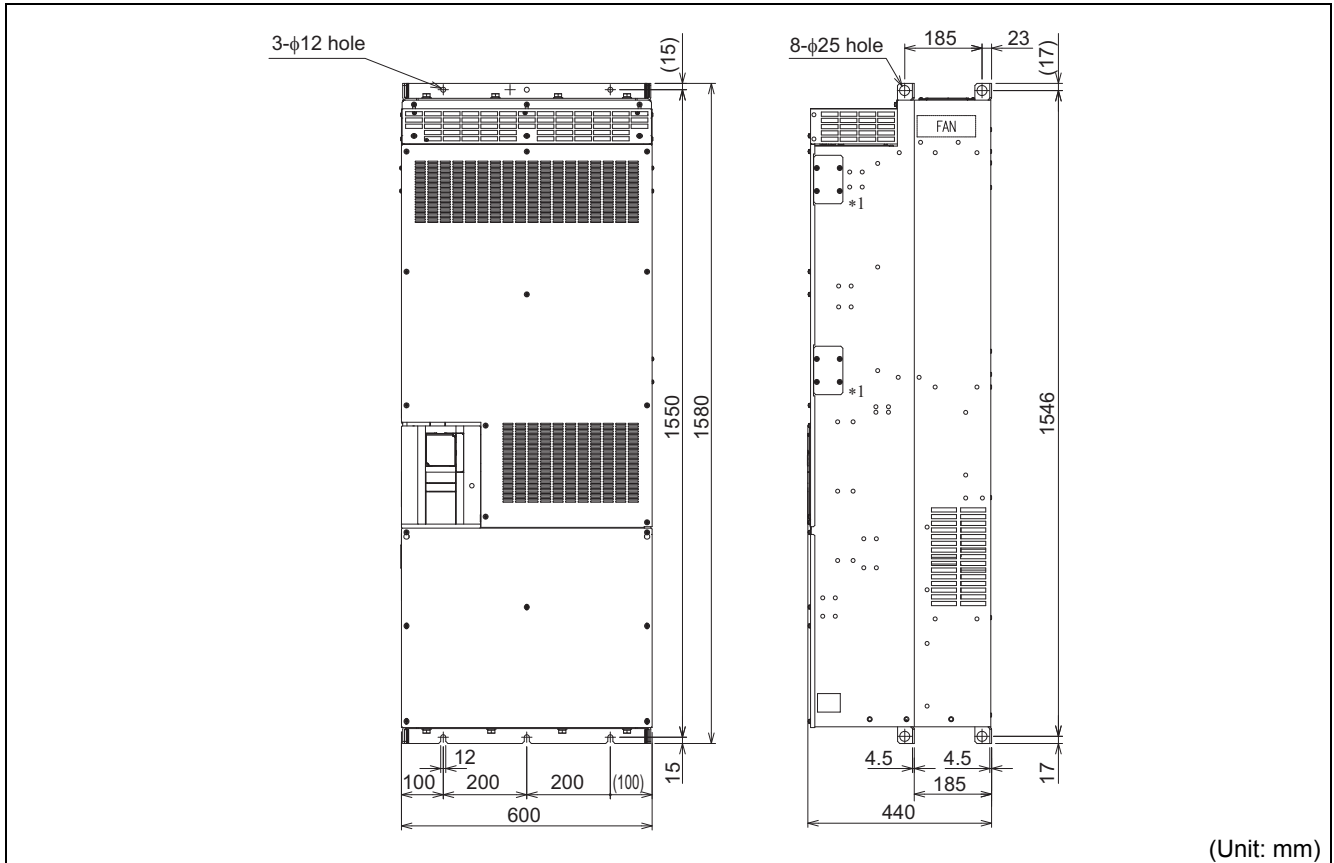
Equipped with a DC reactor.

FR-CC2-H315K, H355K



(Unit: mm)

FR-CC2-H400K, H450K, H500K, H560K, H630K



(Unit: mm)

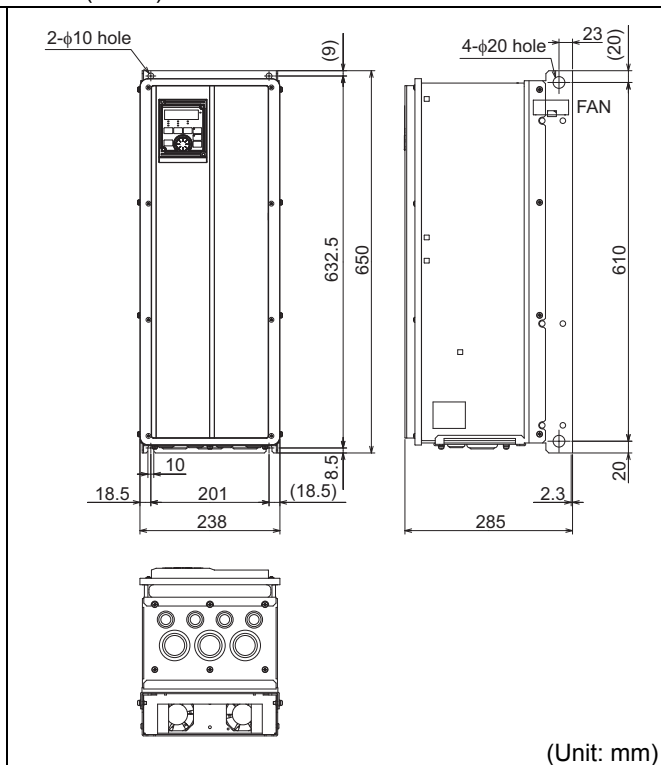
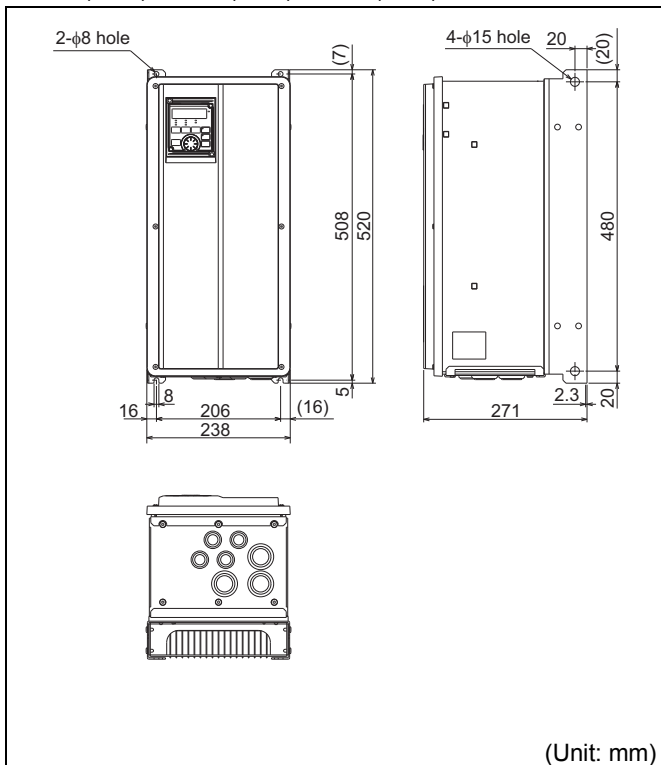
\*1 Do not remove the cover on the side of the converter unit.

● IP55 compatible model

Equipped with a DC reactor.

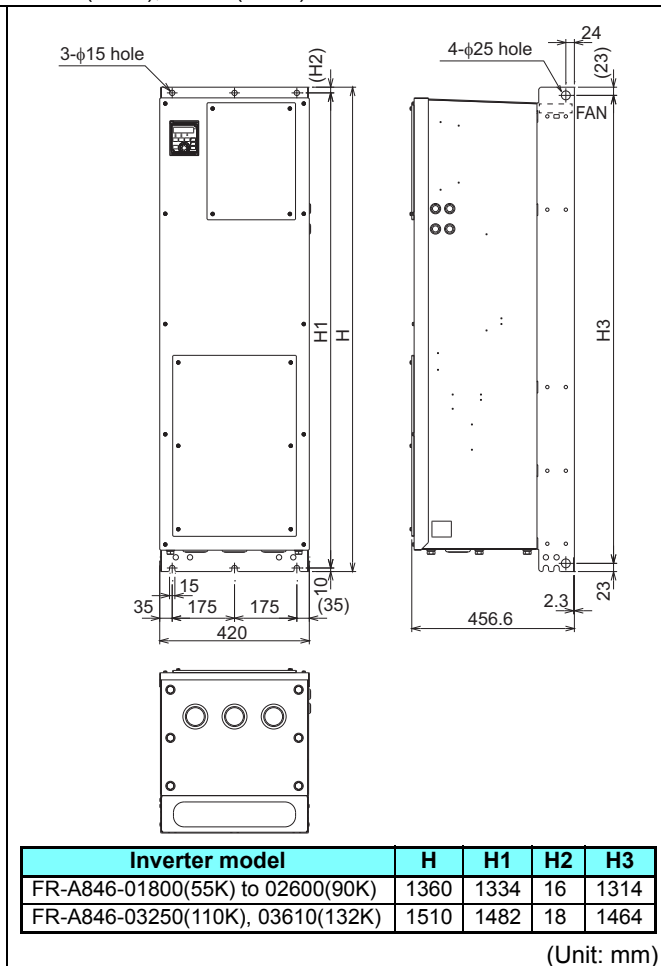
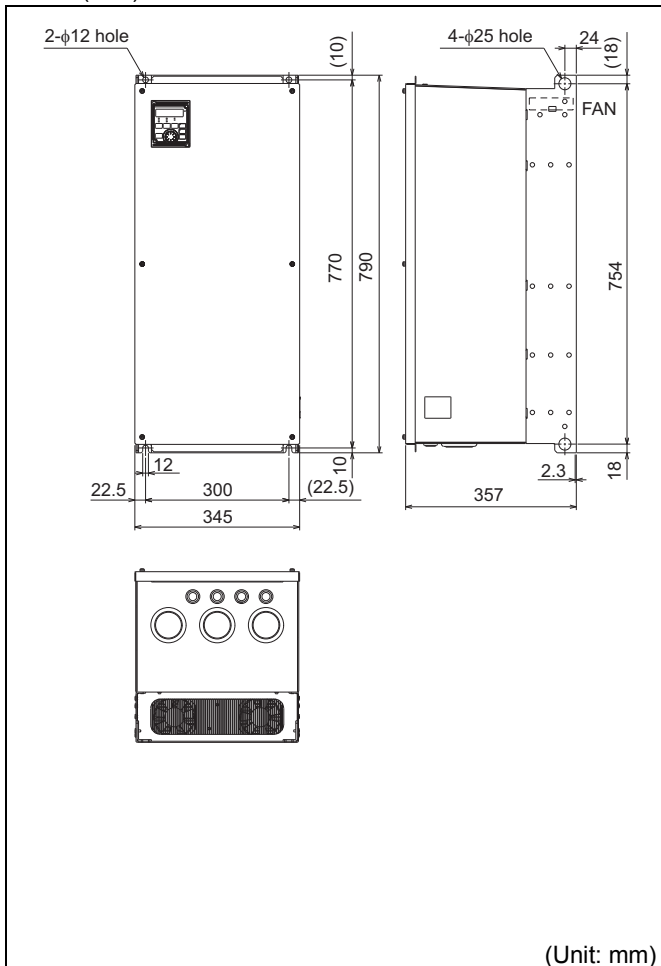
FR-A846-00023(0.4K), 00038(0.75K), 00052(1.5K),  
00083(2.2K), 00126(3.7K), 00170(5.5K)

FR-A846-00250(7.5K), 00310(11K), 00380(15K),  
00470(18.5K)



FR-A846-00620(22K), 00770(30K), 00930(37K),  
01160(45K)

FR-A846-01800(55K), 02160(75K), 02600(90K),  
03250(110K), 03610(132K)



Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

**Outline  
Dimensions**

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

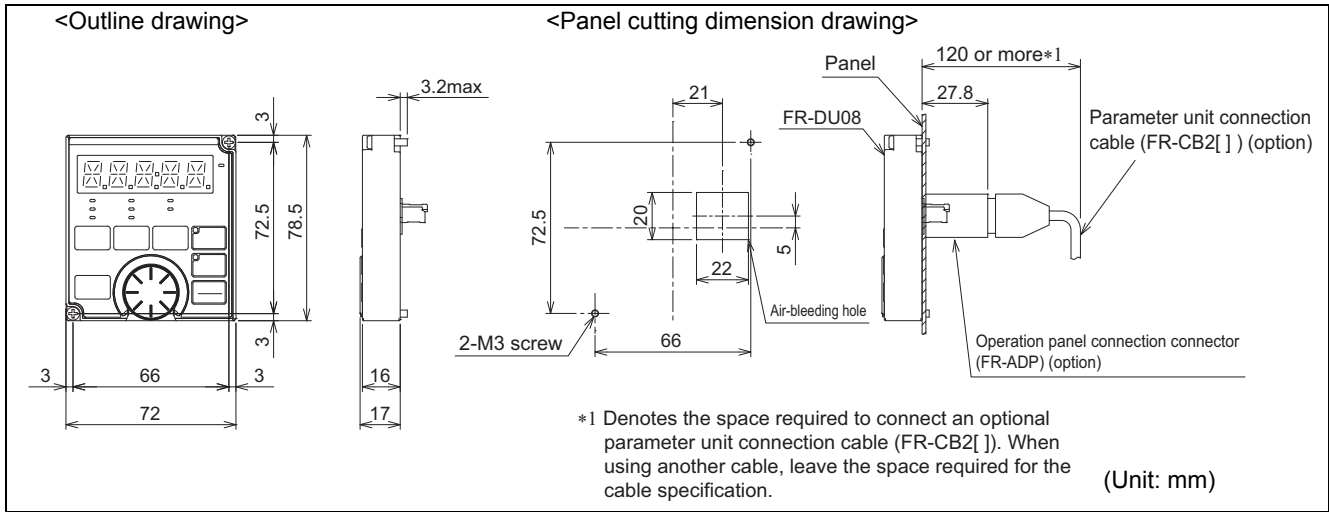
Motors

Compatibility

Warranty  
Inquiry



## ● Operation panel (FR-DU08)





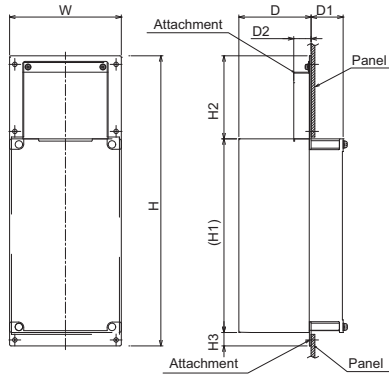
## Heatsink protrusion attachment procedure

When encasing the inverter or the converter unit in an enclosure, the heat generated in the enclosure can be greatly reduced by protruding the heatsink of the inverter or the converter unit. When installing the inverter in a compact enclosure, etc., this installation method is recommended. For the FR-A840-04320(160K) or higher, a heatsink can be protruded outside the enclosure without using an attachment.

### When using a heatsink protrusion attachment (FR-A8CN)

For the FR-A820-00105(1.5K) to FR-A820-04750(90K) and FR-A840-00023(0.4K) to FR-A840-03610(132K), a heatsink can be protruded outside the enclosure using a heatsink protrusion attachment (FR-A8CN). Refer to the instruction manual of the heatsink protrusion attachment (FR-A8CN) for details.

- Drawing after attachment installation (when used with the FR-A8CN)



Type	W	H	H1	H2	H3	D	D1	D2
FR-A8CN01	150	389.5	260	111.5	18	97	43	24.3
FR-A8CN02	245	408.5	260	116.5	32	86	84	21.3
FR-A8CN03	245	448.5	300	116.5	32	89	101	21.3
FR-A8CN04	280	554	400	113.5	32	96.7	93.3	40.6
FR-A8CN05	357	654	480	130	44	130.8	64.2	105
FR-A8CN06	478.2	650	465	145	40	96	154	55
FR-A8CN07	510.2	805	610	150	45	130	120	105
FR-A8CN08	510.2	845	650	150	45	176.5	183.5	40
FR-A8CN09	510.2	725	530	150	45	152.3	147.7	65

(Unit: mm)

- Enclosure cut dimensions (when used with the FR-A8CN)

<p><b>FR-A8CN01</b></p>	<p><b>FR-A8CN02</b></p>	<p><b>FR-A8CN03</b></p>	<p><b>FR-A8CN04</b></p>
<p><b>FR-A8CN05</b></p>	<p><b>FR-A8CN06</b></p>	<p><b>FR-A8CN07</b></p>	
<p><b>FR-A8CN08</b></p>	<p><b>FR-A8CN09</b></p>		

For a compatibility table between the attachment and the inverter, refer to **page 152**.

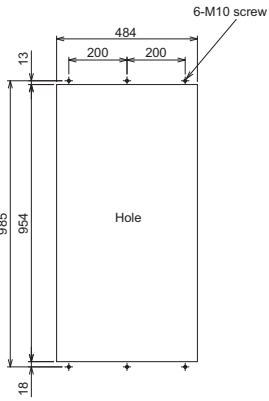
Features	Application Example PLC Function FR Configurator2
Connection Examples	Standard Specs
Dimensions	Outline
Terminal Connection Diagrams	Terminal Specs
Operation Panel	Parameter List
Explanations of Parameters	Protective Functions
Options	LVS/Cables
Precautions	Motors
Compatibility	Warranty Inquiry



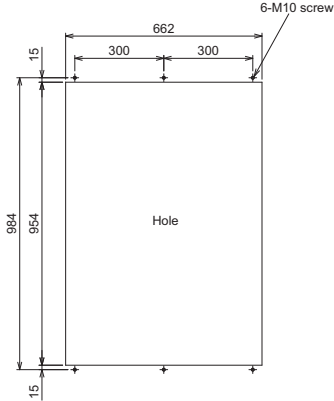
◆ **Heatsink protrusion for the FR-A840-04320(160K) or higher**

- Enclosure cutting  
Cut an enclosure according to the capacity of the inverter or the converter unit.

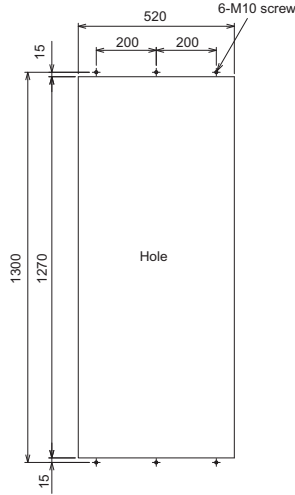
FR-A840-04320(160K)  
FR-A840-04810(185K)



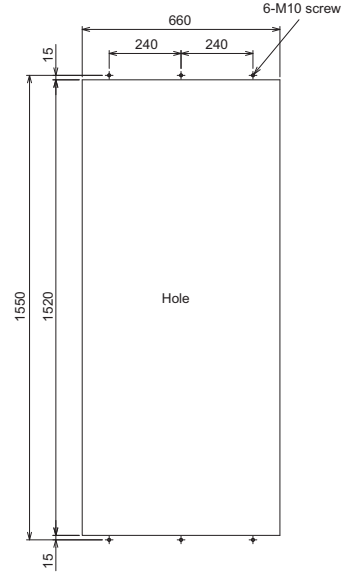
FR-A840-05470(220K)  
FR-A840-06100(250K)  
FR-A840-06830(280K)



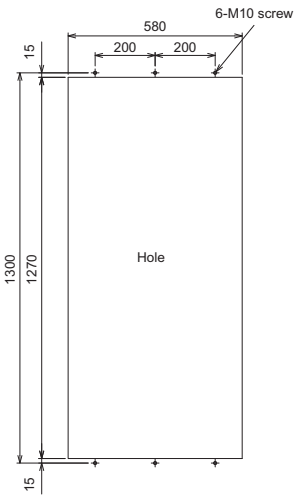
FR-A842-07700(315K)  
FR-A842-08660(355K)



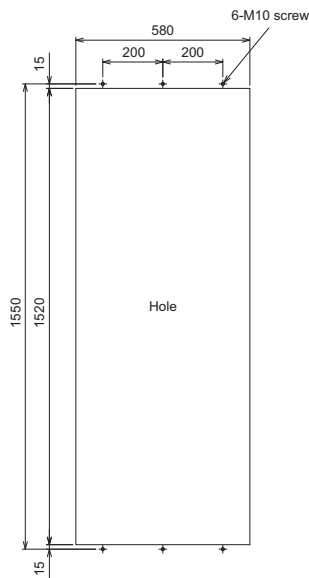
FR-A842-09620(400K)  
FR-A842-10940(450K)  
FR-A842-12120(500K)



FR-CC2-H315K  
FR-CC2-H355K



FR-CC2-H400K  
FR-CC2-H450K  
FR-CC2-H500K  
FR-CC2-H560K  
FR-CC2-H630K

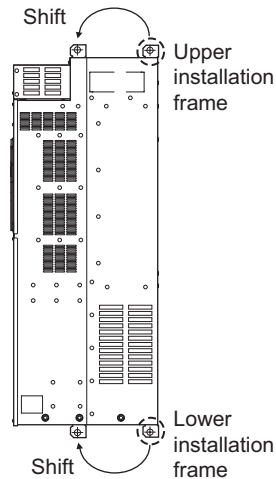


(Unit: mm)

- Shift and removal of a rear side installation frame

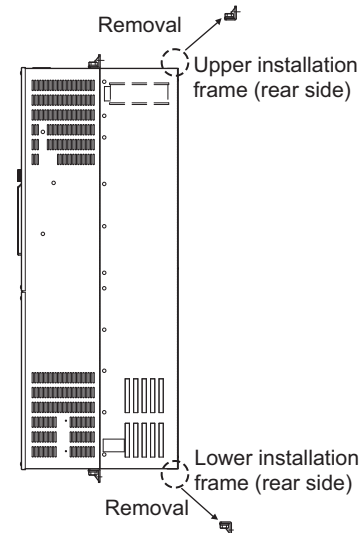
For the FR-A840-04320(160K) to FR-A840-06830(280K)

One installation frame is attached to each of the upper and lower parts of the inverter. Change the position of the rear side installation frame on the upper and lower sides of the inverter to the front side as shown below. When changing the installation frames, make sure that the installation orientation is correct.



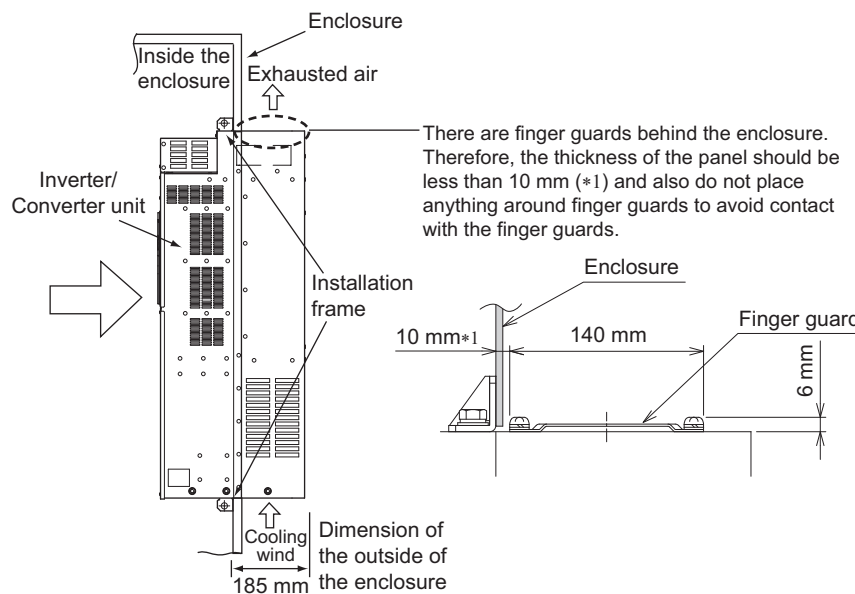
For the FR-A842-07700(315K) to FR-A842-12120(500K),  
FR-CC2-H315K to FR-CC2-H630K

Two installation frames are attached to each of the upper and lower parts of the inverter or the converter unit. Remove the rear side installation frame on the upper and lower sides of the inverter or the converter unit as shown below.



- Installation of the inverter or the converter unit

Push the inverter heatsink portion outside the enclosure and fix the enclosure and the inverter or the converter unit with upper and lower installation frame.



### NOTE

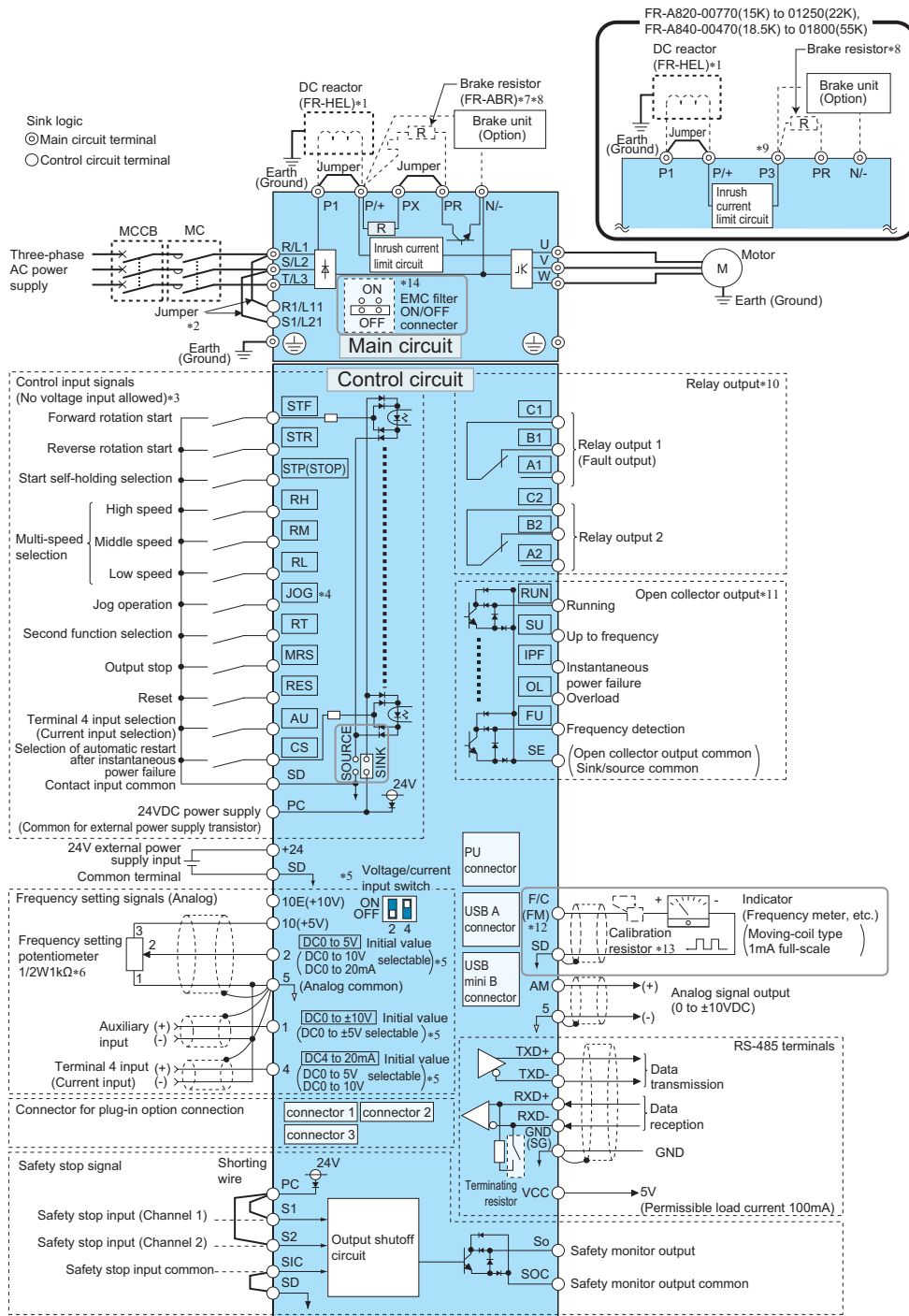
- Having a cooling fan, the cooling section which comes out of the enclosure cannot be used in the environment of water drops, oil, mist, dust, etc.
- Be careful not to drop screws, dust etc. into the inverter or the converter unit and the cooling fan section.
- The FR-A7CN heatsink protrusion attachment cannot be installed on the FR-A800 series.

Features	Application Example PLC Function FR Configurator2
Connection Examples	Standard Specs
Outline Dimensions	Terminal Connection Diagrams Terminal Specs
Operation Panel	Parameter List
Explanations of Parameters	Protective Functions
Options	LVS/Cables
Precautions	Warranty Inquiry

## Terminal Connection Diagram

● Standard models and IP55 compatible models

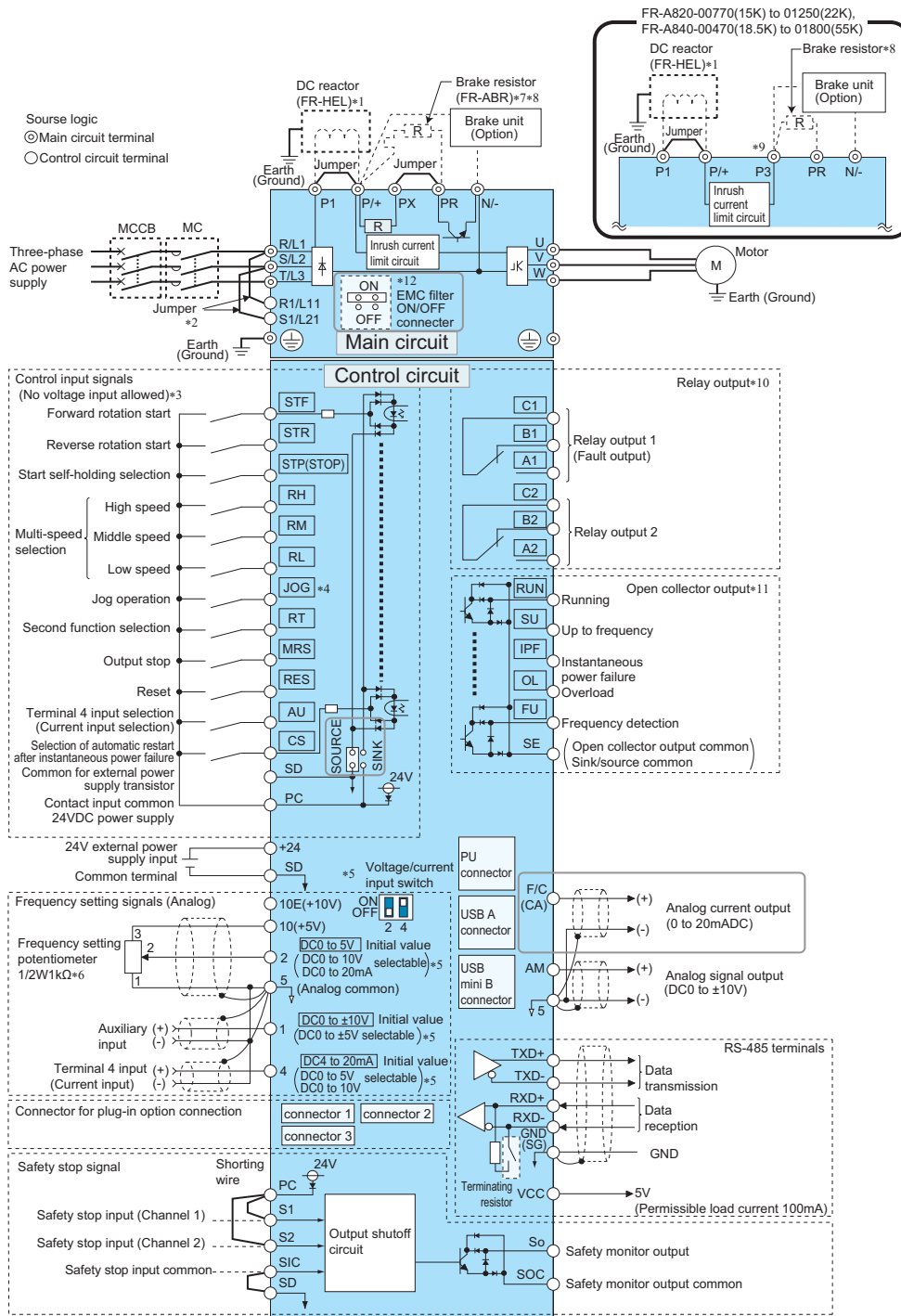
◆ FM type



- \*1 For the FR-A820-03800(75K) or higher, the FR-A840-02160(75K) or higher, and when a 75 kW or higher motor is used, always connect a DC reactor (FR-HEL), which is available as an option. (To select a DC reactor, refer to **page 22**, **page 179**, and select one according to the applicable motor capacity.) When connecting a DC reactor to the FR-A820-03160(55K) or lower or the FR-A840-01800(55K) or lower, remove the jumper across the terminals P1 and P/+ before connecting the DC reactor. The IP55 compatible model has a built-in DC reactor.
- \*2 When using separate power supply for the control circuit, remove the jumper between R1/L11 and S1/L21. IP55 compatible models do not have terminals R/L11, S/L21, and jumpers.
- \*3 The function of these terminals can be changed with the input terminal assignment (**Pr.178 to Pr.189**). (Refer to **page 116**.)
- \*4 Terminal JOG is also used as a pulse train input terminal. Use **Pr.291** to choose JOG or pulse.
- \*5 Terminal input specifications can be changed by analog input specification switchover (**Pr.73**, **Pr.267**). To input a voltage, set the voltage/current input switch OFF. To input a current, set the voltage/current input switch ON. (Refer to **page 104**.) It is recommended to use 2W1kΩ when the frequency setting signal is changed frequently.
- \*6 If connecting a brake resistor, remove the jumper between PR and PX (FR-A820-00046(0.4K) to 00490(7.5K), FR-A840-00023(0.4K) to 00250(7.5K)).
- \*7 Connect a brake resistor across terminals P/+ (P3) and PR. (The terminal PR is equipped in FR-A820-00046(0.4K) to 01250(22K), FR-A840-00023(0.4K) to 01800(55K).) Install a thermal relay to prevent overheating and damage of discharging resistors. (Refer to the Instruction Manual (Detailed).)
- \*8 Do not connect the DC power supply (under DC feeding mode) to terminal P3.
- \*9 The function of these terminals can be changed with the output terminal assignment (**Pr.195**, **Pr.196**). (Refer to **page 117**.)
- \*10 The function of these terminals can be changed with the output terminal assignment (**Pr.190 to Pr.194**). (Refer to **page 117**.)
- \*11 The terminal FM can be used to output pulse trains as open collector output by setting **Pr.291**.
- \*12 Not required when calibrating the scale with the operation panel.
- \*13 Do not change the initially set ON (enabled) position of the EMC filter ON/OFF connector in the case of the inverter with a built-in C2 filter (IP55 compatible model). The Class C2 compatibility condition is not satisfied with the EMC filter OFF. The FR-A846-00250(7.5K)-C2 to FR-A846-00470(18.5K)-C2 are not provided with the EMC filter ON/OFF connector. The EMC filter is always ON.



◆ CA type

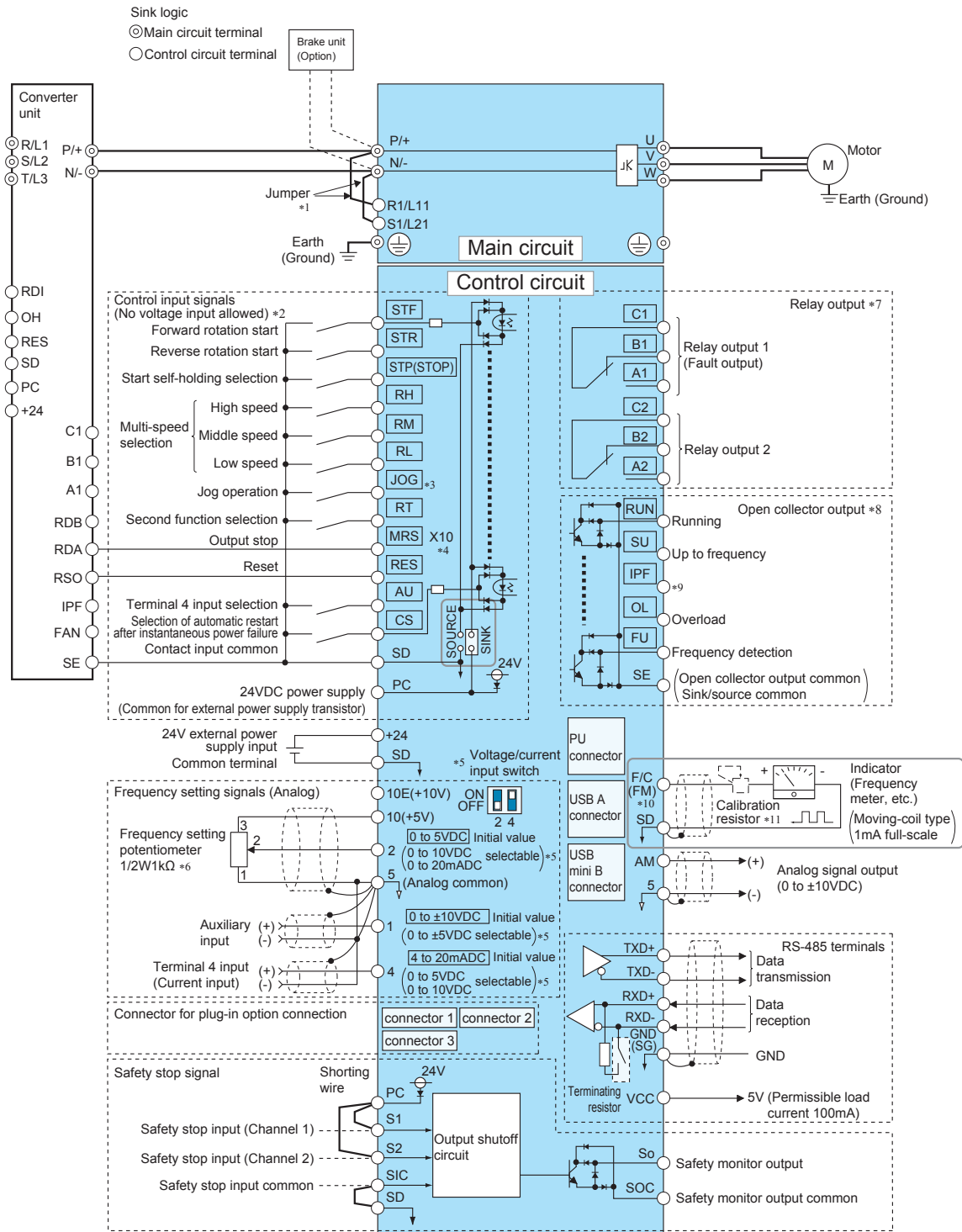


- \*1 For the FR-A820-03800(75K) or higher, the FR-A840-02160(75K) or higher, and when a 75 kW or higher motor is used, always connect a DC reactor (FR-HEL), which is available as an option. (To select a DC reactor, refer to **page 22**, **page 179**, and select one according to the applicable motor capacity.) When connecting a DC reactor to the FR-A820-03160(55K) or lower or the FR-A840-01800(55K) or lower, remove the jumper across the terminals P1 and P/+ before connecting the DC reactor. The IP55 compatible model has a built-in DC reactor.
- \*2 When using separate power supply for the control circuit, remove the jumper between R1/L11 and S1/L21. IP55 compatible models do not have terminals R/L11, S/L21, and jumpers.
- \*3 The function of these terminals can be changed with the input terminal assignment (**Pr.178 to Pr.189**). (Refer to **page 116**.)
- \*4 Terminal JOG is also used as a pulse train input terminal. Use **Pr.291** to choose JOG or pulse.
- \*5 Terminal input specifications can be changed by analog input specification switchover (**Pr.73**, **Pr.267**). To input a voltage, set the voltage/current input switch OFF. To input a current, set the voltage/current input switch ON. (Refer to **page 104**.)
- \*6 It is recommended to use 2W1kΩ when the frequency setting signal is changed frequently.
- \*7 If connecting a brake resistor, remove the jumper between PR and PX (FR-A820-00046(0.4K) to 00490(7.5K), FR-A840-00023(0.4K) to 00250(7.5K)).
- \*8 Connect a brake resistor across terminals P/+ (P3) and PR. (The terminal PR is equipped in FR-A820-00046(0.4K) to 01250(22K), FR-A840-00023(0.4K) to 01800(55K).) Install a thermal relay to prevent overheating and damage of discharging resistors. (Refer to the Instruction Manual (Detailed).)
- \*9 Do not connect the DC power supply (under DC feeding mode) to terminal P3.
- \*10 The function of these terminals can be changed with the output terminal assignment (**Pr.195**, **Pr.196**). (Refer to **page 117**.)
- \*11 The function of these terminals can be changed with the output terminal assignment (**Pr.190 to Pr.194**). (Refer to **page 117**.)
- \*12 Do not change the initially set ON (enabled) position of the EMC filter ON/OFF connector in the case of the inverter with a built-in C2 filter (IP55 compatible model). The Class C2 compatibility condition is not satisfied with the EMC filter OFF. The FR-A846-00250(7.5K)-C2 to FR-A846-00470(18.5K)-C2 are not provided with the EMC filter ON/OFF connector. The EMC filter is always ON.

Features	Application Example PLC Function FR Configurator2
Connection Examples	
Standard Specs	
Outline Dimensions	
Terminal Connection Diagrams	
Terminal Specs	
Operation Panel	
Parameter List	
Explanations of Parameters	
Protective Functions	
Options	
LVS/Cables	
Precautions	
Motors	
Compatibility	
Warranty Inquiry	

● Separated converter type

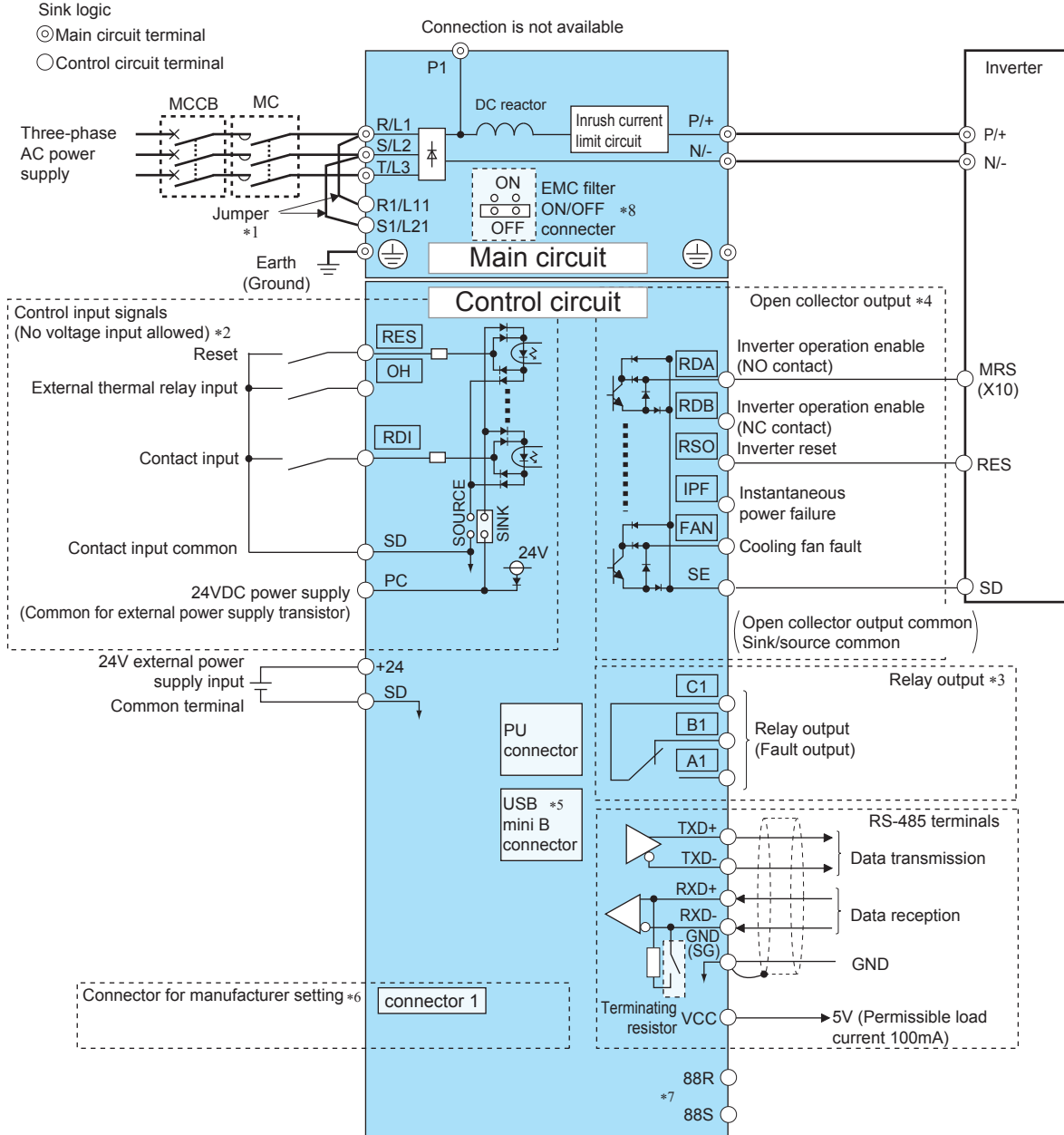
◆ Inverter (FM type)



- \*1 The terminals R1/L11 and S1/L21 are connected to the terminals P/+ and N/- with a jumper respectively. When using separate power supply for the control circuit, remove the jumpers from R1/L11 and S1/L21.
- \*2 The function of these terminals can be changed with the input terminal assignment (Pr.178 to Pr.189).
- \*3 Terminal JOG is also used as the pulse train input terminal. Use Pr.291 to choose JOG or pulse.
- \*4 The X10 signal (NC contact input specification) is assigned to the terminal MRS in the initial setting. Set Pr.599 = "0" to change the input specification of the X10 signal to NO contact.
- \*5 Terminal input specifications can be changed by analog input specification switchover (Pr.73, Pr.267). To input a voltage, set the voltage/current input switch OFF. To input a current, set the voltage/current input switch ON. Terminals 10 and 2 are also used as a PTC input terminal. (Pr.561)
- \*6 It is recommended to use 2 W 1 kΩ when the frequency setting signal is changed frequently.
- \*7 The function of these terminals can be changed with the output terminal assignment (Pr.195, Pr.196).
- \*8 The function of these terminals can be changed with the output terminal assignment (Pr.190 to Pr.194).
- \*9 No function is assigned in the initial setting. Use Pr.192 for function assignment.
- \*10 The terminal FM can be used to output pulse trains as open collector output by setting Pr.291.
- \*11 Not required when calibrating the scale with the operation panel.

## ● Converter unit (FR-CC2)

### ◆ When the sink logic is selected

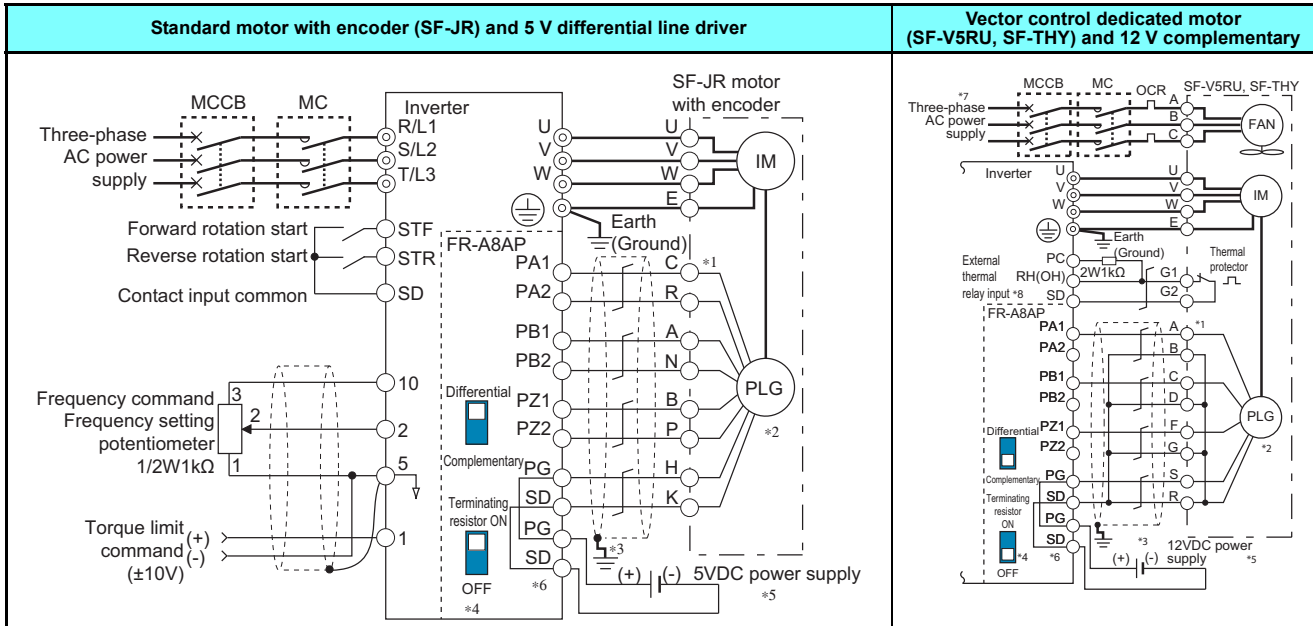


- \*1 When using separate power supply for the control circuit, remove the jumpers from R1/L11 and S1/L21.
- \*2 The function of these terminals can be changed with the input terminal assignment (Pr.178, Pr.187, Pr.189).
- \*3 The function of these terminals can be changed with the output terminal assignment (Pr.195).
- \*4 The function of these terminals can be changed with the output terminal assignment (Pr.190 to Pr.194).
- \*5 The connector is for manufacturer setting. Do not use.
- \*6 Plug-in options cannot be used.
- \*7 For manufacturer setting. Do not use.
- \*8 For the FR-CC2-H400K to H630K, two EMC filter ON/OFF connectors are provided.

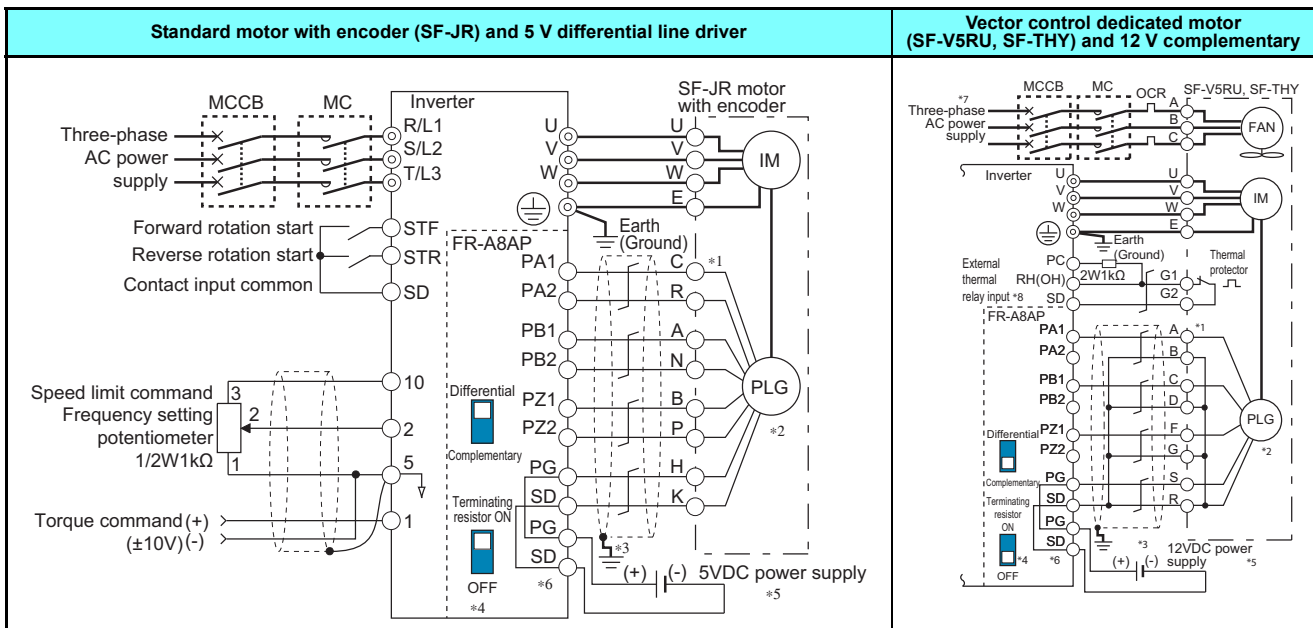
Features	Application Example PLC Function FR Configurator 2
Connection Examples	Standard Specs
Dimensions	Outline Dimensions
Terminal Connection Diagrams	Terminal Specs
Operation Panel	Parameter List
Parameter List	Explanations of Parameters
Options	Protective Functions
LVS/Cables	Options
Precautions	Options
Motors	Options
Compatibility	Options
Warranty Inquiry	Options

● Connection of motor with encoder (vector control) (when the sink logic is selected and the FR-A8AP is used)

◆ Speed control

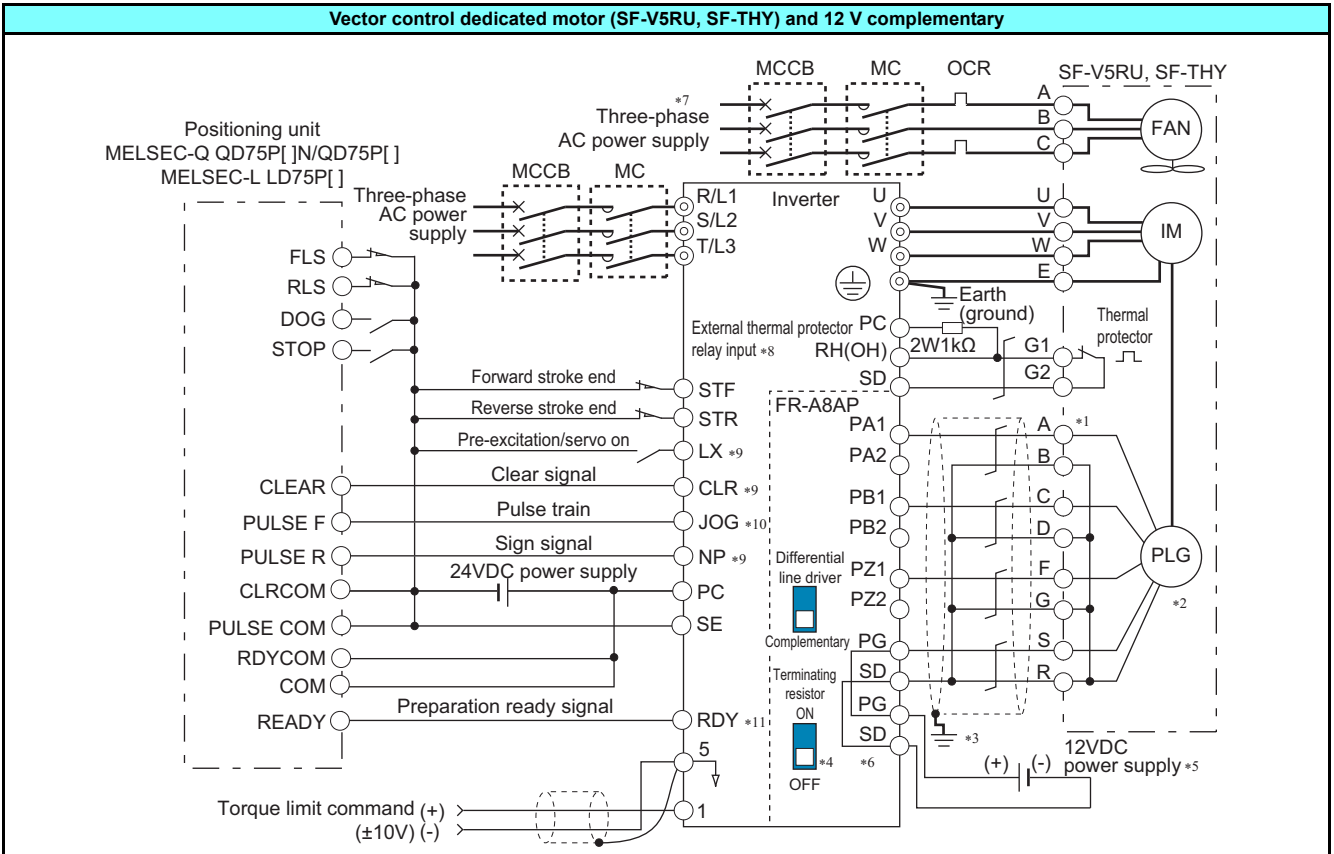


◆ Torque control

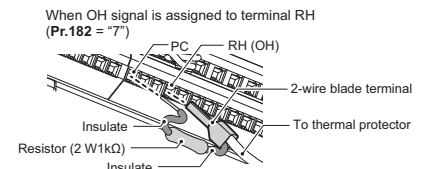




◆ Position control



- \*1 The pin number differs according to the encoder used.  
Speed, control, torque control, and position control by pulse train input are available with or without the Z-phase being connected.
- \*2 Connect the encoder so that there is no looseness between the motor and motor shaft. Speed ratio must be 1:1.
- \*3 Earth (ground) the shield of the encoder cable to the enclosure using a tool such as a P-clip. (Refer to the Instruction Manual (Detailed).)
- \*4 For the complementary, set the terminating resistor selection switch to OFF position. (Refer to the Instruction Manual (Detailed).)
- \*5 A separate power supply of 5 V/12 V/15 V/24 V is necessary according to the encoder power specification.  
When the encoder output is the differential line driver type, only 5 V can be input.
- \*6 Make the voltage of the external power supply the same as the encoder output voltage, and connect the external power supply across PG and SD.
- \*7 For terminal compatibility of the FR-JCBL, FR-V7CBL, and FR-A8AP, refer to the Instruction Manual (Detailed).
- \*8 Connect the recommended 2W1kΩ resistor between the terminal PC and OH. (Recommended product: MOS2C102J 2W1kΩ by KOA Corporation)  
Insert the input line and the resistor to a 2-wire blade terminal, and connect the blade terminal to the terminal OH.  
Insulate the lead wire of the resistor, for example by applying a contraction tube, and shape the wires so that the resistor and its lead wire will not touch other cables. Caulk the lead wire securely together with the thermal protector input line using a 2-wire blade terminal.  
(Do not subject the lead wire's bottom area to an excessive pressure.)  
To use a terminal as the terminal OH, assign the OH (external thermal O/L relay input) signal to an input terminal. (Set "7" in any of Pr.178 to Pr.189. For details, refer to page 116.)
- \*9 Assign the function using Pr.178 to Pr.184, Pr.187 to Pr.189 (input terminal function selection).
- \*10 When position control is selected, terminal JOG function is invalid and simple position pulse train input terminal becomes valid.
- \*11 Assign the function using Pr.190 to Pr.194 (output terminal function selection).




Features	Application Example	Connection Examples	Standard Specs	Outline Dimensions	Terminal Connection Diagrams	Operation Panel	Parameter List	Explanations of Parameters	Protective Functions	Options	LVS/Cables	Precautions	Motors	Compatibility	Warranty Inquiry
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# Terminal Specification Explanation

## ● Standard models, IP55 compatible models, and Separated converter type

indicates that terminal functions can be selected from Pr.178 to Pr.196 (I/O terminal function selection).

Terminal names and terminal functions are those of the factory set.

Type	Terminal Symbol	Terminal Name	Description			
Main circuit	R/L1, S/L2, T/L3*1	AC power input	Connect to the commercial power supply.			
	U, V, W	Inverter output	Connect a three-phase squirrel-cage motor or PM motor.			
	R1/L11, S1/L21*2	Power supply for control circuit	Connected to the AC power supply terminals R/L1 and S/L2. To retain alarm display and alarm output, apply external power to this terminal.			
	P/+, PR *1*2	Brake resistor connection	Connect an optional brake resistor across the terminals P/+ and PR. Remove the jumper across the terminals PR and PX for the inverter capacity that has the terminal PX. (FR-A820-00630(11K) or lower, FR-A840-00380(15K) or lower)			
	P3, PR *1*2	Brake resistor connection	Connect an optional brake resistor across the terminals P3 and PR. (FR-A820-00770(15K) to 01250(22K), FR-A840-00470(18.5K) to 01800(55K))			
	P/+, N/-	Brake unit connection	Connect the brake unit (FR-BU2), power regeneration common converter (FR-CV) or regeneration common converter (MT-RC) and high power factor converter (FR-HC2).			
	P3, N/-	Brake unit connection *3	Do not connect the DC power supply between terminals P3 and N/-. Use terminals P/+ and N/- for DC feeding. Connect the separated converter type to the terminals P/+ and N/- of the converter unit.			
	P/+, P1*1	DC reactor connection	Remove the jumper across terminals P/+P1 and connect a DC reactor. For the FR-A820-03800(75K) or higher, the FR-A840-02160(75K) or higher, and when a 75 kW or higher motor is used, always connect a DC reactor, which is available as an option.			
	PR, PX *1*2	Built-in brake circuit connection	When the jumper is connected across terminals PX and PR (initial status), the built-in brake circuit is valid. The built-in brake circuit is equipped in the FR-A820-00490(7.5K) or lower and FR-A840-00250(7.5K) or lower.			
			Earth (Ground)	For earthing (grounding) the inverter chassis. Must be earthed (grounded).		
Control circuit/input signal	Contact input	STF	Forward rotation start	Turn on the STF signal to start forward rotation and turn it off to stop.	When the STF and STR signals are turned on simultaneously, the stop command is given.	
		STR	Reverse rotation start	Turn on the STR signal to start reverse rotation and turn it off to stop.		
		STP (STOP)	Start self-holding selection	Turn on the STOP signal to self-hold the start signal.		
		RH, RM, RL	Multi-speed selection	Multi-speed can be selected according to the combination of RH, RM and RL signals.		
		JOG	Jog mode selection	Turn on the JOG signal to select Jog operation (initial setting) and turn on the start signal (STF or STR) to start Jog operation.		
			Pulse train input	JOG terminal can be used as pulse train input terminal. To use as pulse train input terminal, the Pr.291 setting needs to be changed. (maximum input pulse: 100k pulses/s)		
		RT	Second function selection	Turn on the RT signal to select second function selection. When the second function such as "Second torque boost" and "Second V/F (base frequency)" are set, turning on the RT signal selects these functions.		
		MRS	Output stop	Turn on the MRS signal (2 ms or more) to stop the inverter output. Use to shut off the inverter output when stopping the motor by electromagnetic brake.		
		MRS (X10)*8	Output stop (Inverter operation enable)	Connect to the terminal RDA of the converter unit (FR-CC2). When the RDA signal is turned OFF, the inverter output is shut off. The X10 signal (NC contact) is assigned to the terminal MRS in the initial setting. Use Pr.599 to change the specification to NO contact.		
		RES	Reset	Used to reset alarm output provided when protective circuit is activated. Turn on the RES signal for more than 0.1s, then turn it off. Recover about 1s after reset is cancelled.		
		AU	Terminal 4 input selection	Terminal 4 is made valid only when the AU signal is turned on. Turning the AU signal on makes terminal 2 invalid.		
		CS	Selection of automatic restart after instantaneous power failure	When the CS signal is left on, the inverter restarts automatically at power restoration. Note that restart setting is necessary for this operation. In the initial setting, a restart is disabled.		
		SD	Contact input common (sink)*4	Common terminal for the contact input terminal (sink logic) and terminal FM.		
			External transistor common (source)*5	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable current.		
			24 VDC power supply common	Common terminal for the 24 VDC power supply (terminal PC, terminal +24) Isolated from terminals 5 and SE.		
PC	External transistor common (sink)*4	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the sink logic to avoid malfunction by undesirable currents.				
	Contact input common (source)*5	Common terminal for contact input terminal (source logic).				
	24 VDC power supply	Can be used as 24 VDC 0.1 A power supply.				
Frequency setting	10E	Frequency setting power supply	When connecting a frequency setting potentiometer at an initial status, connect it to terminal 10.		10 VDC, permissible load current 10 mA	
	10		Change the input specifications of terminal 2 when connecting it to terminal 10E.		5 VDC, permissible load current 10 mA	
	2	Frequency setting (voltage)	Inputting 0 to 5 VDC (or 0 to 10 V, 4 to 20 mA) provides the maximum output frequency at 5 V (10 V, 20 mA) and makes input and output proportional. Use Pr.73 to switch from among input 0 to 5 VDC (initial setting), 0 to 10 VDC, and 4 to 20 mA. Set the voltage/current input switch in the ON position to select current input (0 to 20 mA).		Voltage input: Input resistance 10 kΩ ±1 kΩ Maximum permissible voltage 20 VDC Current input: Input resistance 245 Ω ±5 Ω Maximum permissible current 30 mA	
	4	Frequency setting (current)	Inputting 4 to 20 mADC (or 0 to 5 V, 0 to 10 V) provides the maximum output frequency at 20 mA and makes input and output proportional. This input signal is valid only when the AU signal is on (terminal 2 input is invalid). Use Pr.267 to switch from among input 4 to 20 mA (initial setting), 0 to 5 VDC, and 0 to 10 VDC. Set the voltage/current input switch in the OFF position to select voltage input (0 to 5 V/0 to 10 V). Use Pr.858 to switch terminal functions.			
	1	Frequency setting auxiliary	Inputting 0 to ±5 VDC or 0 to ±10 VDC adds this signal to terminal 2 or 4 frequency setting signal. Use Pr.73 to switch between input 0 to ±5 VDC and 0 to ±10 VDC (initial setting) input.		Input resistance 10 kΩ ±1 kΩ Maximum permissible voltage ±20 VDC	
5	Frequency setting common	Common terminal for frequency setting signal (terminal 2, 1 or 4) and analog output terminal AM, CA. Do not earth (ground).				
Thermistor	10	PTC thermistor input	For receiving PTC thermistor outputs.		Applicable PTC thermistor specification Overheat detection resistance: 500 Ω to 30 kΩ (Set by Pr.561)	
	2		When PTC thermistor is valid (Pr.561 ≠ "9999"), the terminal 2 is not available for frequency setting.			




Type	Terminal Symbol	Terminal Name	Description			
Control circuit/output signal	Power supply input	+24	24 V external power supply input	For connecting 24 V external power supply. If the 24 V external power supply is connected, power is supplied to the control circuit while the main power circuit is OFF.	Input voltage 23 to 25.5 VDC Input current 1.4 A or less	
		Relay	A1, B1, C1	Relay output 1 (alarm output)	1 changeover contact output indicates that the inverter protective function has activated and the output stopped. Alarm: discontinuity across B-C (continuity across A-C), Normal: continuity across B-C (discontinuity across A-C)	Contact capacity 230 VAC 0.3 A (power factor =0.4) 30 VDC 0.3 A
	A2, B2, C2		Relay output 2	1 changeover contact output		
	Open collector	RUN	Inverter running	Switched low when the inverter output frequency is equal to or higher than the starting frequency (initial value 0.5 Hz). Switched high during stop or DC injection brake operation.	Alarm code (4 bit) output (Refer to page 106.)	Permissible load 24 VDC (maximum 27 VDC) 0.1 A (The voltage drop is 2.8 V at maximum while the signal is ON.) LOW is when the open collector output transistor is ON (conducted). HIGH is when the transistor is OFF (not conducted).
		SU	Up to frequency	Switched low when the output frequency reaches within the range of ±10% (initial value) of the set frequency. Switched high during acceleration/deceleration and at a stop.		
		OL	Overload alarm	Switched low when stall prevention is activated by the stall prevention function. Switched high when stall prevention is cancelled.		
		IPF	Instantaneous power failure	Switched low when an instantaneous power failure and under voltage protections are activated.		
		IPF *8	Open collector output	No function is assigned in the initial setting. The function can be assigned setting Pr.192.		
		FU	Frequency detection	Switched low when the inverter output frequency is equal to or higher than the preset detected frequency and high when less than the preset detected frequency.		
		SE	Open collector output common	Common terminal for terminals RUN, SU, OL, IPF, FU		
	Pulse	FM *6	For meter	Output item: output frequency (initial setting), permissible load current 2 mA, For full scale 1440 pulses/s	Signals can be output from the open collector terminals by setting Pr.291. (maximum output pulse: 50kpulses/s)	
			NPN open collector output	Select one e.g. output frequency from monitor items. (The signal is not output during an inverter reset.) The output signal is proportional to the magnitude of the corresponding monitoring item.		
	Analog	AM	Analog voltage output	The output signal is proportional to the magnitude of the corresponding monitoring item. Use Pr.55, Pr.56, and Pr.866 to set full scales for the monitored output frequency, output current, and torque.	Output item: output frequency (initial setting), output signal 0 to ±10 VDC, permissible load current 1 mA (load impedance 10 kΩ or more), resolution 8 bit	
CA *7		Analog current output	Output item: output frequency (initial setting), Load impedance 200 Ω to 450 Ω Output signal 0 to 20 mADC			
Communication	—	PU connector	With the PU connector, communication can be made through RS-485. (1:1 connection only) • Conforming standard: EIA-485(RS-485) • Transmission format: Multi-drop link	• Communication speed: 4800 to 115200 bps • Wiring length: 500 m		
	RS-485 terminals	TXD+, TXD-	Inverter transmission terminal	With the RS-485 terminals, communication can be made through RS-485. • Conforming standard: EIA-485(RS-485) • Transmission format: Multi-drop link		
		RXD+, RXD-	Inverter reception terminal			
		GND (SG)	Earth (Ground)		• Communication speed: 300 to 115200 bps • Overall extension: 500 m	
—	USB A connector	A connector (receptacle). A USB memory device enables parameter copies and the trace function.	Interface: Conforms to USB1.1 (USB2.0 full-speed compatible). Transmission speed: 12 Mbps			
—	USB B connector	Mini B connector (receptacle). Connected to a personal computer via USB to enable setting, monitoring, test operations of the inverter by FR Configurator2.				
Safety stop signal	S1	Safety stop input (Channel 1)	The terminals S1 and S2 are used for the safety stop input signal for the safety relay module. The terminals S1 and S2 are used at the same time (dual channel). Inverter output is shutdown by shortening/opening between terminals S1 and SIC, or between S2 and SIC.	Input resistance 4.7 kΩ Input current 4 to 6 mADC (with 24 VDC input)		
	S2	Safety stop input (Channel 2)	In the initial status, terminals S1 and S2 are shorted with the terminal PC by shorting wires. The terminal SIC is shorted with the terminal SD. Remove the shorting wires and connect the safety relay module when using the safety stop function.			
	SIC	Safety stop input terminal common	Common terminal for terminals S1 and S2.	—		
	SO	Safety monitor output (open collector output)	Indicates the safety stop input signal status. Switched to LOW when the status is other than the internal safety circuit failure status. Switched to HIGH during the internal safety circuit failure status. (LOW is when the open collector output transistor is ON (conducted). HIGH is when the transistor is OFF (not conducted).) Refer to the Safety stop function instruction manual (BCN-A23228-001) when the signal is switched to HIGH while both terminals S1 and S2 are open.	Permissible load 24 VDC (maximum 27 VDC) 0.1 A (The voltage drop is 3.4 V at maximum while the signal is ON.)		
	SOC	Safety stop input terminal common	Common terminal for terminal SO.	—		

\*1 Terminals R/L1, S/L2, T/L3, PR, P3, P1, and PX are not provided in the separated converter type.  
 \*2 Terminals R1/L11, S1/L21, PR, P3, and PX are not provided for the IP55 compatible model.  
 \*3 Available for the FR-A820-00770(15K) to FR-A820-01250(22K), and the FR-A840-00470(18.5K) to FR-A840-01800(55K).  
 \*4 The sink logic is initially set for the FM-type inverter.  
 \*5 The source logic is initially set for the CA-type inverter.  
 \*6 Terminal FM is provided in the FM-type inverter.  
 \*7 Terminal CA is provided in the CA-type inverter.  
 \*8 Function and name of the separated converter type.

- Features
- Application Example
- FR Configurator2
- Connection Examples
- Standard Specs
- Outline Dimensions
- Terminal Connection Diagrams
- Operation Panel
- Parameter List
- Explanations of Parameters
- Protective Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty Inquiry

## ● Converter unit (FR-CC2)

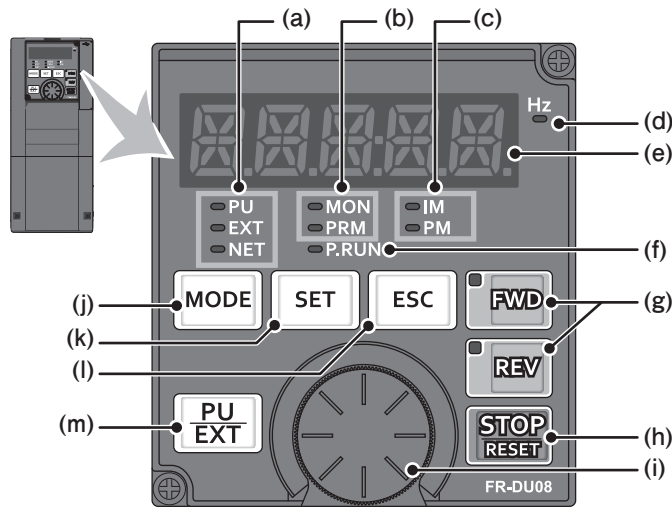
■ indicates that terminal functions can be selected from Pr.178, Pr.187, Pr.189 to Pr.195 (I/O terminal function selection). Terminal names and terminal functions are those of the factory set.

Type	Terminal Symbol	Terminal Name	Description			
Main circuit	R/L1, S/L2, T/L3	AC power input	Connect these terminals to the commercial power supply.			
	R1/L11, S1/L21	Power supply for the control circuit	Connected to the AC power supply terminals R/L1 and S/L2. To retain the fault display and fault output, remove the jumpers across terminals R/L1 and R1/L11 and across S/L2 and S1/L21 and supply external power to these terminals.			
	P/+, N/-	Inverter connection	Connect to terminals P/+ and N/- of the inverter.			
		Earth (ground)	For earthing (grounding) the converter unit chassis. This must be earthed (grounded).			
Control circuit/input signal	Contact input	RES	Reset	Use this signal to reset a fault output provided when a protective function is activated. Turn ON the RES signal for 0.1 s or longer, then turn it OFF. In the initial setting, reset is always enabled. By setting Pr.75, reset can be set enabled only at fault occurrence of the converter unit. The inverter recovers about 1 s after the reset is released.		
		OH	External thermal relay input	The external thermal relay input (OH) signal is used when using an external thermal relay or a thermal protector built into the motor to protect the motor from overheating. When the thermal relay is activated, the inverter trips by the external thermal relay operation (E.OHT).		
		RDI	Contact input	The function can be assigned by setting Pr.178.		
		SD	Contact input common (sink) (Initial setting)	Common terminal for contact input terminal (sink logic).		
			External transistor common (source)	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable current.		
		24 VDC power supply common	Common terminal for the 24 VDC power supply (terminal PC, terminal +24) Isolated from terminals 5 and SE.			
	PC	External transistor common (sink) (Initial setting)	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable current.			
		Contact input common (source)	Common terminal for contact input terminal (source logic).			
		24 VDC power supply common	Can be used as a 24 VDC 0.1 A power supply.			
	Power supply input	+24	24 V external power supply input	For connecting a 24 V external power supply. If a 24 V external power supply is connected, power is supplied to the control circuit while the main power circuit is OFF.		
	Control circuit/output signal	Relay	A1, B1, C1	Relay output 1 (fault output)	1 changeover contact output that indicates that the protective function of the converter unit has been activated and the outputs are stopped. Fault: discontinuity across B and C (continuity across A and C), Normal: continuity across Band C (discontinuity across A and C)	Contact capacity 230 VAC 0.3 A (power factor = 0.4) 30 VDC 0.3 A
			88R, 88S	For manufacturer setting. Do not use.		
Open collector		RDA	Inverter operation enable (NO contact)	Switched to LOW when the converter unit operation is ready. Assign the signal to the terminal MRS (X10) of the inverter. The inverter can be started when the RDA status is LOW.	Permissible load 24 VDC (maximum 27 VDC) 0.1 A (The voltage drop is 2.8 V at maximum while the signal is ON.) LOW is when the open collector output transistor is ON (conducted). HIGH is when the transistor is OFF (not conducted).	
		RDB	Inverter operation enable (NC contact)	Switched to LOW when a converter unit fault occurs or the converter is reset. The inverter can be started when the RDB status is HIGH.		
		RSO	Inverter reset	Switched to LOW when the converter is reset (RES-ON). Assign the signal to the terminal RES of the inverter. The inverter is reset when it is connected with the RSO status LOW.		
		IPF	Instantaneous power failure	Switched to LOW when an instantaneous power failure is detected.		
		FAN	Cooling fan fault	Switched to LOW when a cooling fan fault occurs.		
SE	Open collector output common	Common terminal for terminals RDA, RDB, RSO, IPF, FAN				
Communication	—		PU connector	With the PU connector, communication can be made through RS-485. (For connection on a 1:1 basis only) • Conforming standard: EIA-485 (RS-485) • Transmission format: Multidrop link • Communication speed: 4800 to 115200 bps • Wiring length: 500 m		
	RS-485 terminals	TXD+	Converter unit transmission terminal	The RS-485 terminals enable the communication by RS-485. • Conforming standard: EIA-485 (RS-485) • Transmission format: Multidrop link • Communication speed: 300 to 115200 bps • Overall length: 500 m		
		TXD-				
		RXD+	Converter unit reception terminal			
		RXD-				
GND (SG)	Earthing (grounding)					



# Operation Panel (FR-DU08(-01))

## ● Components of the operation panel



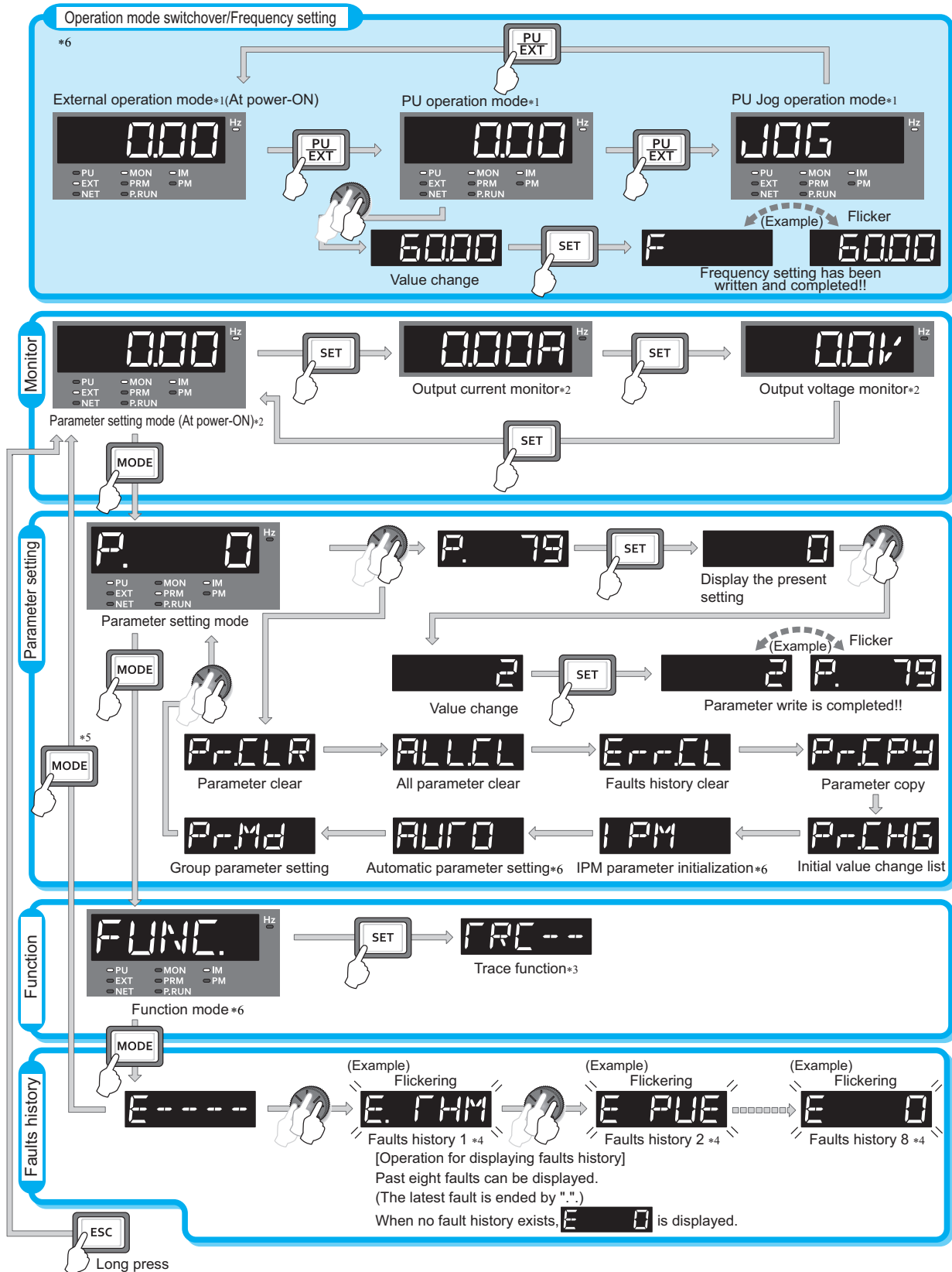
The operation panel of the inverter can be used for the converter unit.

No.	Component *1		Name	Description
(a)	FR-DU08	FR-DU08-01	Operation mode indicator *2	PU/HAND: ON to indicate the PU operation mode. EXT/AUTO: ON to indicate the External operation mode. (ON at power-ON in the initial setting.) NET: ON to indicate the Network operation mode. PU and EXT: ON to indicate the External/PU combined operation mode 1 or 2.
(b)			Operation panel status indicator	MON: ON to indicate the monitoring mode. Quickly flickers twice intermittently while the protective function is activated. PRM: ON to indicate the parameter setting mode.
(c)			Control motor indicator *2	IM: ON to indicate the induction motor control. PM: ON to indicate the PM sensorless vector control. The indicator flickers when test operation is selected.
(d)			Frequency unit indicator *2	ON to indicate frequency. (Flickers when the set frequency is displayed in the monitor.)
(e)			Monitor (5-digit LED)	Shows the frequency, parameter number, etc. (Using Pr.52, Pr.774 to Pr.776, the monitored item can be changed.)
(f)			PLC function indicator *2	ON to indicate that the PLC function is operating.
(g)			FWD key, REV key *2	FWD key: Starts forward rotation. The LED is lit during forward operation. REV key: Starts reverse rotation. The LED is lit during reverse operation. The LED flickers under the following conditions. • When the frequency command is not given even if the forward/reverse command is given. • When the frequency command is the starting frequency or lower. • When the MRS signal is being input.
(h)			STOP/RESET key	Stops the operation commands. Resets the inverter when the protection function is activated.
(i)			Setting dial	The setting dial of the Mitsubishi inverters. The setting dial is used to change the frequency and parameter settings. Press the setting dial to perform the following operations: • To display a set frequency in the monitoring mode (the setting can be changed using Pr.992.) • To display the present setting during calibration • To display a fault history number in the faults history mode
(j)			MODE key	Switches to different modes. Switches to the easy setting mode by pressing simultaneously with . Holding this key for 2 seconds locks the operation. The key lock is invalid when Pr.161="0 (initial setting)".
(k)			SET key	Enters each setting. If pressed during operation, the monitored  item changes. (Using Pr.52 and Pr.774-Pr.776, the monitored item can be changed.)
(l)			ESC key	Goes back to the previous display. Holding this key for a longer time changes the mode back to the monitor mode.
(m)	FR-DU08	FR-DU08-01	PU/EXT key *2	Switches between the PU operation mode, the PUJOG operation mode, and the External operation mode. Switches to the easy setting mode by pressing simultaneously with . Cancels the PU stop also.

\*1 The FR-DU08-01 is an operation panel for IP55 compatible models.  
\*2 Not available for the converter unit.

Features  
Application Example  
PLC Function  
FR Configurator2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LV5/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry

● Basic operation(FR-DU08)



\*1 For the details of operation modes, refer to **page 107**.

\*2 Monitored items can be changed.(Refer to **page 98**.)

\*3 For the details of the trace function, refer to **page 142**.

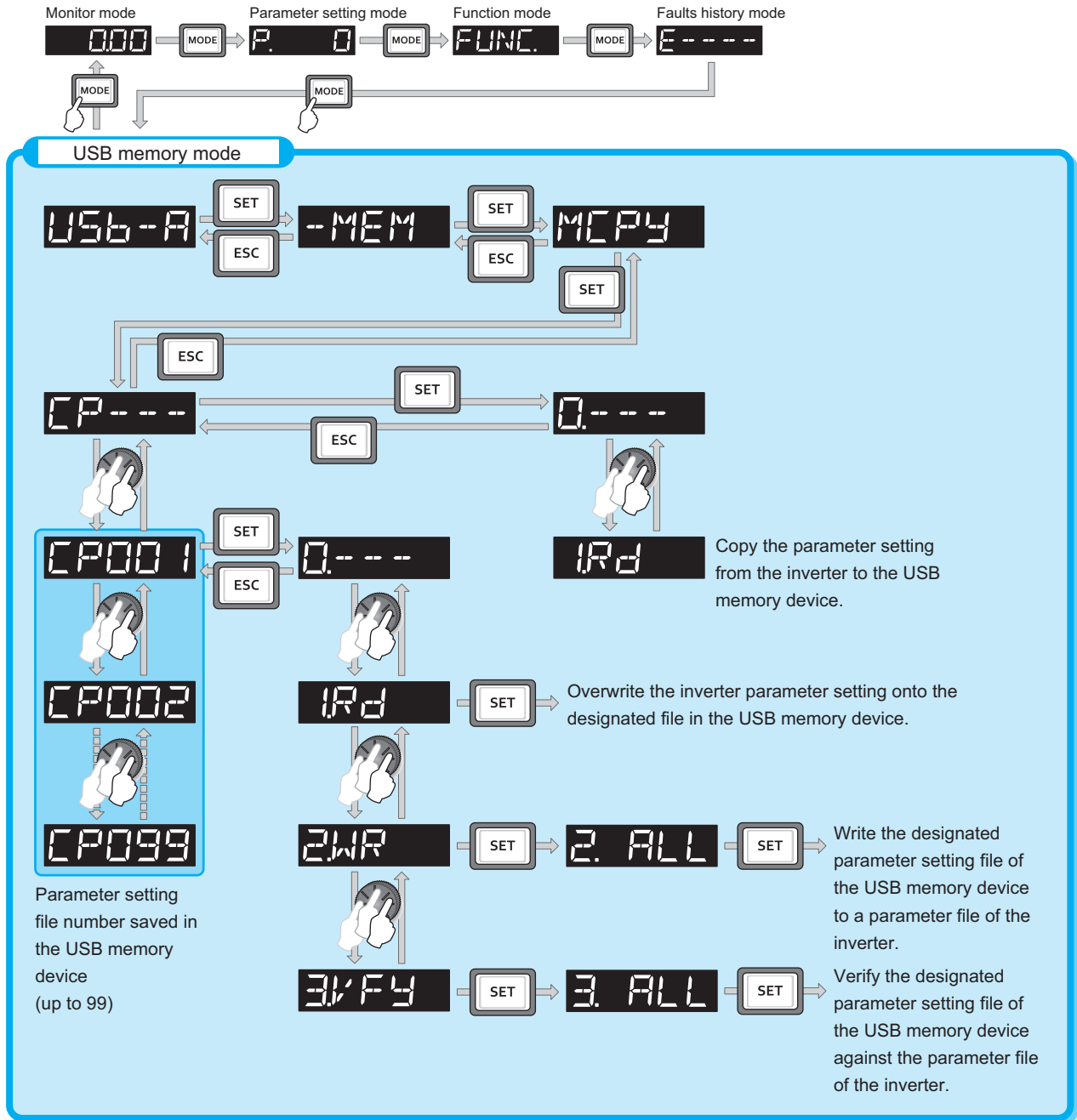
\*4 While a fault is displayed, the display shifts as follows by pressing **SET**: Output frequency at the fault → Output current → Output voltage → Energization time → Year → Month → Date → Time. (After Time, it goes back to a fault display.) Pressing the setting dial shows the fault history number.

\*5 The USB memory mode will appear if a USB memory device is connected. (Refer to **page 50**.)

\*6 Not available for the converter unit.

### ● Parameter copy to the USB memory device

Insert the USB memory in the inverter. The USB memory mode is displayed and USB memory operations are possible.



Features
Application Example PLC Function FR Configurator2
Connection Examples
Standard Specs
Outline Dimensions
Terminal Connection Diagrams Terminal Specs
<b>Operation Panel</b>
Parameter List
Explanations of Parameters
Protective Functions
Options
LVS/Cables
Precautions
Motors
Compatibility
Warranty Inquiry



## ● Group parameter display

Parameter numbers can be changed to grouped parameter numbers.  
Parameters are grouped by their functions. The related parameters can be set easily.

### (1) Changing to the grouped parameter numbers

Pr.MD setting value	Description
0	No change
1	Parameter display by parameter number
2	Parameter display by function group




### Operation

- Screen at power-ON  
The monitor display appears.
- Parameter setting mode  
Press **MODE** to choose the parameter setting mode. (The parameter number read previously appears.)
- Selecting the parameter number  
Turn  until **Pr.Md** (parameter display method) appears.  
Press **SET**. "0" (initial value) will appear.
- Changing to the group parameter display  
Turn  to change the set value to "2" (group parameter display). Press **SET** to select the group parameter setting. "2" and "Pr.Md" flicker alternately after the setting is completed.

### (2) Changing parameter settings in the group parameter display

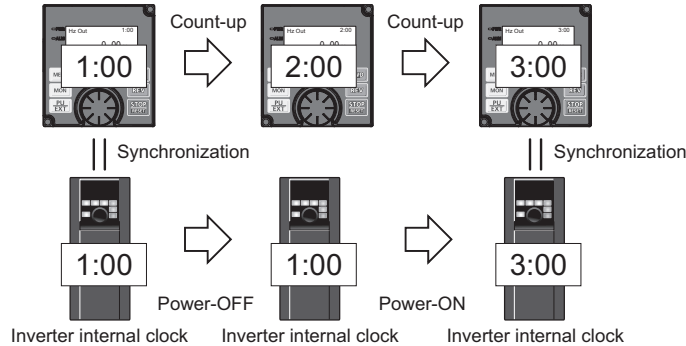
Changing example Change the **P.H400(Pr.1) Maximum frequency**.

### Operation

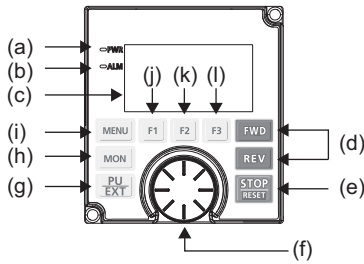
- Screen at power-ON  
The monitor display appears.
- Changing the operation mode  
Press **PU EXT** to choose the PU operation mode. [PU] indicator is lit.
- Parameter setting mode  
Press **MODE** to choose the parameter setting mode. (The parameter number read previously appears.)
- Parameter group selection  
Press **ESC** several times until **Pr0** appears.  
(No need to press **ESC** if the previously read parameter is one of **Pr CLR** to **Pr.Md**.) Skip this operation and proceed to step 5..)
- Parameter group selection  
Turn  until **Pr4** (protective function parameter 4) appears. Press **SET** to display **Pr4--** and make the group parameters of the protective function parameter 4 selectable.
- Parameter selection  
Turn  until **Pr400** (P.H400 Maximum frequency) appears. Press **SET** to read the present set value.  
"12000" (initial value) appears.
- Changing the setting value  
Turn  to change the set value to "6000". Press **SET** to enter the setting. "6000" and "Pr400" flicker alternately after the setting is completed.

# LCD operation panel (FR-LU08)

- The FR-LU08 is an optional operation panel adopting an LCD panel capable of displaying text and menus.
- Replacement with the operation panel (FR-DU08) and installation on the enclosure surface using a connection cable (FR-CB2) are possible. (To connect the FR-LU08, an optional operation panel connection connector (FR-ADP) is required.)
- Parameter settings for up to three inverters can be saved.
- When the FR-LU08 is connected to the inverter, the internal clock of the inverter can be synchronized with the clock of FRLU08. (Real time clock function)  
 With a battery (CR1216), the FR-LU08 time count continues even if the main power of the inverter is turned OFF. (The time count of the inverter internal clock does not continue when the inverter power is turned OFF.)



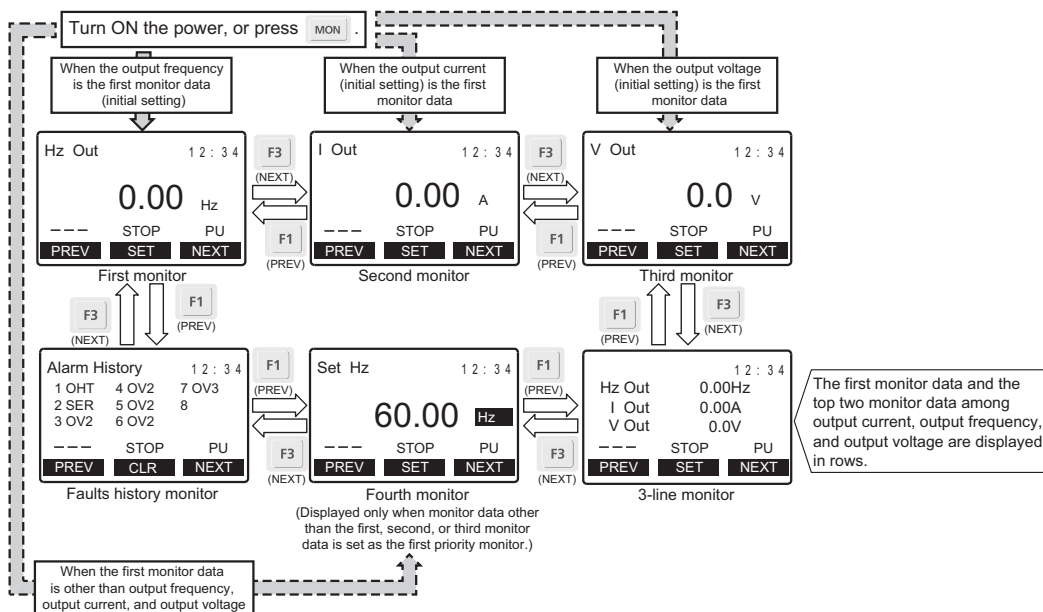
## ● Appearance and parts name



Symbol	Name	Description
a	Power lamp	ON when the power is turned ON.
b	Alarm lamp	ON when an inverter alarm occurs.
c	Monitor	Shows the frequency, parameter number, etc. (Using Pr.52, Pr.774 to Pr.776, the monitored item can be changed.)
d	FWD key, REV key	FWD key: Starts the forward operation. REV key: Starts the reverse operation.
e	STOP/RESET key	Used to stop operation commands. Used to reset the inverter when the protective function is activated.
f	Setting dial	The setting dial is used to change the frequency and parameter settings. Pressing the dial shows details of the faults history mode.
g	PU/EXT key	Switches between the PU mode, the PUJOG mode, and the External operation mode.
h	MON key	Shows the first monitored item.
i	MENU key	Displays the quick menu. Pressing the key while the quick menu is displayed displays the function menu.
j	Software key (F1)	Select a guidance displayed on the monitor.
k	Software key (F2)	
l	Software key (F3)	

## ● Switching the main monitor data

When Pr.52 Operation panel main monitor selection is set to "0", by pressing **F1 (PREV)** or **F3 (NEXT)** 6 types of monitor data are displayed in order.



Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



# Parameter List

## ● Inverter parameter list (by parameter number)

For simple variable-speed operation of the inverter, the initial value of the parameters may be used as they are. Set the necessary parameters to meet the load and operational specifications. Parameter setting, change and check can be made from the operation panel (FR-DU08).

### NOTE

- **Simple** indicates simple mode parameters. Use **Pr.160 User group read selection** to indicate the simple mode parameters only.
- Parameter setting may be restricted in some operating statuses. Use **Pr.77 Parameter write selection** to change the setting.

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Basic functions	0	G000	Torque boost <b>Simple</b>	0 to 30%	0.1%	6% *1 4% *1 3% *1 2% *1 1% *1		90	
	1	H400	Maximum frequency <b>Simple</b>	0 to 120 Hz	0.01 Hz	120 Hz *2 60 Hz *3		90	
	2	H401	Minimum frequency <b>Simple</b>	0 to 120 Hz	0.01 Hz	0 Hz		90	
	3	G001	Base frequency <b>Simple</b>	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	90	
	4	D301	Multi-speed setting (high speed) <b>Simple</b>	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	91	
	5	D302	Multi-speed setting (middle speed) <b>Simple</b>	0 to 590 Hz	0.01 Hz	30 Hz		91	
	6	D303	Multi-speed setting (low speed) <b>Simple</b>	0 to 590 Hz	0.01 Hz	10 Hz		91	
	7	F010	Acceleration time <b>Simple</b>	0 to 3600 s	0.1 s	5 s *4 15 s *5		91	
	8	F011	Deceleration time <b>Simple</b>	0 to 3600 s	0.1 s	5 s *4 15 s *5		91	
	9	H000 C103	Electronic thermal O/L relay <b>Simple</b> Rated motor current <b>Simple</b>	0 to 500 A 0 to 3600 A	0.01 A *2 0.1 A *3	Inverter rated current		92	
DC injection brake	10	G100	DC injection brake operation frequency	0 to 120 Hz, 9999	0.01 Hz	3 Hz		92	
	11	G101	DC injection brake operation time	0 to 10 s, 8888	0.1 s	0.5 s		92	
	12	G110	DC injection brake operation voltage	0 to 30%	0.1%	4% *6 2% *6 1% *6		92	
—	13	F102	Starting frequency	0 to 60 Hz	0.01 Hz	0.5 Hz		93	
—	14	G003	Load pattern selection	0 to 5	1	0		93	
Jog operation	15	D200	Jog frequency	0 to 590 Hz	0.01 Hz	5 Hz		93	
	16	F002	Jog acceleration/deceleration time	0 to 3600 s	0.1 s	0.5 s		93	
—	17	T720	MRS input selection	0, 2, 4	1	0		94	
—	18	H402	High speed maximum frequency	0 to 590 Hz	0.01 Hz	120 Hz *2 60 Hz *3		90	
—	19	G002	Base frequency voltage	0 to 1000 V, 8888, 9999	0.1 V	9999	8888	90	
Acceleration/ deceleration times	20	F000	Acceleration/deceleration reference frequency	1 to 590 Hz	0.01 Hz	60 Hz	50 Hz	91	
	21	F001	Acceleration/deceleration time increments	0, 1	1	0		91	
Stall prevention	22	H500	Stall prevention operation level (Torque limit level)	0 to 400%	0.1%	150%		94	
	23	H610	Stall prevention operation level compensation factor at double speed	0 to 200%, 9999	0.1%	9999		94	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Multi-speed setting	24 to 27	D304 to D307	Multi-speed setting (4 speed to 7 speed)	0 to 590 Hz, 9999	0.01 Hz	9999		91	
—	28	D300	Multi-speed input compensation selection	0, 1	1	0		91	
—	29	F100	Acceleration/deceleration pattern selection	0 to 6	1	0		95	
—	30	E300	Regenerative function selection	0 to 2, 10, 11, 20, 21, 100 to 102, 110, 111, 120, 121 *15	1	0		96	
				2, 10, 11, 102, 110, 111 *16	1	10			
				0, 2, 10, 20, 100, 102, 110, 120 *17	1	0			
Frequency jump	31	H420	Frequency jump 1A	0 to 590 Hz, 9999	0.01 Hz	9999		97	
	32	H421	Frequency jump 1B	0 to 590 Hz, 9999	0.01 Hz	9999		97	
	33	H422	Frequency jump 2A	0 to 590 Hz, 9999	0.01 Hz	9999		97	
	34	H423	Frequency jump 2B	0 to 590 Hz, 9999	0.01 Hz	9999		97	
	35	H424	Frequency jump 3A	0 to 590 Hz, 9999	0.01 Hz	9999		97	
	36	H425	Frequency jump 3B	0 to 590 Hz, 9999	0.01 Hz	9999		97	
—	37	M000	Speed display	0, 1 to 9998	1	0		97	
Frequency detection	41	M441	Up-to-frequency sensitivity	0 to 100%	0.1%	10%		97	
	42	M442	Output frequency detection	0 to 590 Hz	0.01 Hz	6 Hz		97	
	43	M443	Output frequency detection for reverse rotation	0 to 590 Hz, 9999	0.01 Hz	9999		97	
Second functions	44	F020	Second acceleration/deceleration time	0 to 3600 s	0.1 s	5 s		91	
	45	F021	Second deceleration time	0 to 3600 s, 9999	0.1 s	9999		91	
	46	G010	Second torque boost	0 to 30%, 9999	0.1%	9999		90	
	47	G011	Second V/F (base frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		90	
	48	H600	Second stall prevention operation level	0 to 400%	0.1%	150%		94	
	49	H601	Second stall prevention operation frequency	0 to 590 Hz, 9999	0.01 Hz	0 Hz		94	
	50	M444	Second output frequency detection	0 to 590 Hz	0.01 Hz	30 Hz		97	
51	H010 C203	Second electronic thermal O/L relay Rated second motor current	0 to 500 A, 9999 *2	0.01 A	9999		92		
			0 to 3600 A, 9999 *3	0.1 A					
Monitor functions	52	M100	Operation panel main monitor selection	0, 5 to 14, 17 to 20, 22 to 36, 38, 40 to 46, 50 to 57, 61, 62, 64, 67, 71 to 74, 87 to 98, 100	1	0		98	
	54	M300	FM/CA terminal function selection	1 to 3, 5 to 14, 17, 18, 21, 24, 32 to 34, 36, 46, 50, 52, 53, 61, 62, 67, 70, 87 to 90, 92, 93, 95, 97, 98	1	1		98	
	55	M040	Frequency monitoring reference	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	100	
	56	M041	Current monitoring reference	0 to 500 A *2 0 to 3600 A *3	0.01 A 0.1 A	Inverter rated current		100	
Automatic restart	57	A702	Restart coasting time	0, 0.1 to 30 s, 9999	0.1 s	9999		100	
	58	A703	Restart cushion time	0 to 60 s	0.1 s	1 s		100	
—	59	F101	Remote function selection	0 to 3, 11 to 13	1	0		102	
—	60	G030	Energy saving control selection	0, 4, 9	1	0		102	

Features	Application Example PLC Function FR Configurator2
Connection Examples	
Standard Specs	
Outline Dimensions	
Terminal Connection Diagrams	
Operation Panel	
Parameter List	
Explanations of Parameters	
Protective Functions	
Options	
LVS/Cables	
Precautions	
Motors	
Compatibility	
Warranty Inquiry	

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Automatic acceleration/deceleration	61	F510	Reference current	0 to 500 A, 9999 *2	0.01 A *2	9999		102	
				0 to 3600 A, 9999 *3	0.1 A *3				
	62	F511	Reference value at acceleration	0 to 400%, 9999	0.1%	9999		102	
	63	F512	Reference value at deceleration	0 to 400%, 9999	0.1%	9999		102	
	64	F520	Starting frequency for elevator mode	0 to 10 Hz, 9999	0.01 Hz	9999		102	
	65	H300	Retry selection	0 to 5	1	0		103	
	66	H611	Stall prevention operation reduction starting frequency	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	94	
Retry	67	H301	Number of retries at fault occurrence	0 to 10, 101 to 110	1	0		103	
	68	H302	Retry waiting time	0.1 to 600 s	0.1 s	1 s		103	
	69	H303	Retry count display erase	0	1	0		103	
	70 *18	G107	Special regenerative brake duty	0 to 100%	0.1%	0%		96	
	71	C100	Applied motor	0 to 6, 13 to 16, 20, 23, 24, 30, 33, 34, 40, 43, 44, 50, 53, 54, 70, 73, 74, 330, 333, 334, 8090, 8093, 8094, 9090, 9093, 9094	1	0		103	
	72	E600	PWM frequency selection	0 to 15 *2 0 to 6, 25 *3	1	2		104	
	73	T000	Analog input selection	0 to 7, 10 to 17	1	1		104	
	74	T002	Input filter time constant	0 to 8	1	1		105	
	75	-	Reset selection/disconnected PU detection/PU stop selection	0 to 3, 14 to 17 *2 0 to 3, 14 to 17, 100 to 103, 114 to 117 *3	1	14		105	
		E100	Reset selection	0, 1		0			
		E101	Disconnected PU detection			1			
		E102	PU stop selection						
	E107	Reset limit	0 *2 0, 1 *3	1	0				
	76	M510	Fault code output selection	0 to 2	1	0		106	
	77	E400	Parameter write selection	0 to 2	1	0		106	
	78	D020	Reverse rotation prevention selection	0 to 2	1	0		106	
	79	D000	Operation mode selection <i>Simple</i>	0 to 4, 6, 7	1	0		107	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting	
						FM	CA			
Motor constants	80	C101	Motor capacity	0.4 to 55 kW, 9999 *2	0.01 kW *2	9999		108		
				0 to 3600 kW, 9999 *3	0.1 kW *3					
	81	C102	Number of motor poles	2, 4, 6, 8, 10, 12, 9999	1	9999		108		
	82	C125	Motor excitation current	0 to 500 A, 9999 *2	0.01 A *2	9999		109		
				0 to 3600 A, 9999 *3	0.1 A *3					
	83	C104	Rated motor voltage	0 to 1000 V	0.1 V	9999		200 V *7	109	
								400 V *8		
	84	C105	Rated motor frequency	10 to 400 Hz, 9999	0.01 Hz	9999		109		
	89	G932	Speed control gain (Advanced magnetic flux vector)	0 to 200%, 9999	0.1%	9999		108		
	90	C120	Motor constant (R1)	0 to 50 Ω, 9999 *2	0.001 Ω *2	9999		109		
				0 to 400 mΩ, 9999 *3	0.01 mΩ *3					
	91	C121	Motor constant (R2)	0 to 50 Ω, 9999 *2	0.001 Ω *2	9999		109		
				0 to 400 mΩ, 9999 *3	0.01 mΩ *3					
	92	C122	Motor constant (L1)/d-axis inductance (Ld)	0 to 6000mH, 9999 *2	0.1 mH *2	9999		109		
				0 to 400mH, 9999 *3	0.01 mH *3					
93	C123	Motor constant (L2)/q-axis inductance (Lq)	0 to 6000mH, 9999 *2	0.1 mH *2	9999		109			
			0 to 400mH, 9999 *3	0.01 mH *3						
94	C124	Motor constant (X)	0 to 100%, 9999	0.1% *2	9999		109			
				0.01% *3						
95	C111	Online auto tuning selection	0 to 2	1	0		110			
96	C110	Auto tuning setting/status	0, 1, 11, 101	1	0		109			
Adjustable 5 points V/F	100	G040	V/F1 (first frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		110		
	101	G041	V/F1 (first frequency voltage)	0 to 1000 V	0.1 V	0 V		110		
	102	G042	V/F2 (second frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		110		
	103	G043	V/F2 (second frequency voltage)	0 to 1000 V	0.1 V	0 V		110		
	104	G044	V/F3 (third frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		110		
	105	G045	V/F3 (third frequency voltage)	0 to 1000 V	0.1 V	0 V		110		
	106	G046	V/F4 (fourth frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		110		
	107	G047	V/F4 (fourth frequency voltage)	0 to 1000 V	0.1 V	0 V		110		
	108	G048	V/F5 (fifth frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		110		
	109	G049	V/F5 (fifth frequency voltage)	0 to 1000 V	0.1 V	0 V		110		
Third functions	110	F030	Third acceleration/deceleration time	0 to 3600 s, 9999	0.1 s	9999		91		
	111	F031	Third deceleration time	0 to 3600 s, 9999	0.1 s	9999		91		
	112	G020	Third torque boost	0 to 30%, 9999	0.1%	9999		90		
	113	G021	Third V/F (base frequency)	0 to 590 Hz, 9999	0.01 Hz	9999		90		
	114	H602	Third stall prevention operation level	0 to 400%	0.1%	150%		94		
	115	H603	Third stall prevention operation frequency	0 to 590 Hz	0.01 Hz	0 Hz		94		
	116	M445	Third output frequency detection	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	97		
PU connector communication	117	N020	PU communication station number	0 to 31	1	0		111		
	119	-	PU communication stop bit length / data length	0, 1, 10, 11	1	1		111		
						0				
						1				
	120	N024	PU communication parity check	0 to 2	1	2		111		
	121	N025	Number of PU communication retries	0 to 10, 9999	1	1		111		
	122	N026	PU communication check time interval	0, 0.1 to 999.8 s, 9999	0.1 s	9999		111		
	123	N027	PU communication waiting time setting	0 to 150 ms, 9999	1 ms	9999		111		
	124	N028	PU communication CR/LF selection	0 to 2	1	1		111		

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
—	125	T022	Terminal 2 frequency setting gain frequency <i>Simple</i>	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	112	
—	126	T042	Terminal 4 frequency setting gain frequency <i>Simple</i>	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	112	
PID operation	127	A612	PID control automatic switchover frequency	0 to 590 Hz, 9999	0.01 Hz	9999		113	
	128	A610	PID action selection	0, 10, 11, 20, 21, 40 to 43, 50, 51, 60, 61, 70, 71, 80, 81, 90, 91, 100, 101, 1000, 1001, 1010, 1011, 2000, 2001, 2010, 2011	1	0		113	
	129	A613	PID proportional band	0.1 to 1000%, 9999	0.1%	100%		113	
	130	A614	PID integral time	0.1 to 3600 s, 9999	0.1 s	1 s		113	
	131	A601	PID upper limit	0 to 100%, 9999	0.1%	9999		113	
	132	A602	PID lower limit	0 to 100%, 9999	0.1%	9999		113	
	133	A611	PID action set point	0 to 100%, 9999	0.01%	9999		113	
	134	A615	PID differential time	0.01 to 10 s, 9999	0.01 s	9999		113	
Bypass	135	A000	Electronic bypass sequence selection	0, 1	1	0		114	
	136	A001	MC switchover interlock time	0 to 100 s	0.1 s	1 s		114	
	137	A002	Start waiting time	0 to 100 s	0.1 s	0.5 s		114	
	138	A003	Bypass selection at a fault	0, 1	1	0		114	
	139	A004	Automatic switchover frequency from inverter to bypass operation	0 to 60 Hz, 9999	0.01 Hz	9999		114	
Backlash measures	140	F200	Backlash acceleration stopping frequency	0 to 590 Hz	0.01 Hz	1 Hz		95	
	141	F201	Backlash acceleration stopping time	0 to 360 s	0.1 s	0.5 s		95	
	142	F202	Backlash deceleration stopping frequency	0 to 590 Hz	0.01 Hz	1 Hz		95	
	143	F203	Backlash deceleration stopping time	0 to 360 s	0.1 s	0.5 s		95	
—	144	M002	Speed setting switchover	0, 2, 4, 6, 8, 10, 12, 102, 104, 106, 108, 110, 112	1	4		97	
PU	145	E103	PU display language selection	0 to 7	1	—		114	
—	147	F022	Acceleration/deceleration time switching frequency	0 to 590 Hz, 9999	0.01 Hz	9999		91	
Current detection	148	H620	Stall prevention level at 0 V input	0 to 400%	0.1%	150%		94	
	149	H621	Stall prevention level at 10 V input	0 to 400%	0.1%	200%		94	
	150	M460	Output current detection level	0 to 400%	0.1%	150%		114	
	151	M461	Output current detection signal delay time	0 to 10 s	0.1 s	0 s		114	
	152	M462	Zero current detection level	0 to 400%	0.1%	5%		114	
	153	M463	Zero current detection time	0 to 10 s	0.01 s	0.5 s		114	
—	154	H631	Voltage reduction selection during stall prevention operation	0, 1, 10, 11	1	1		94	
—	155	T730	RT signal function validity condition selection	0, 10	1	0		115	
—	156	H501	Stall prevention operation selection	0 to 31, 100, 101	1	0		94	
—	157	M430	OL signal output timer	0 to 25 s, 9999	0.1 s	0 s		94	
—	158	M301	AM terminal function selection	1 to 3, 5 to 14, 17, 18, 21, 24, 32 to 34, 36, 46, 50, 52 to 54, 61, 62, 67, 70, 87 to 90, 91 to 98	1	1		98	
—	159	A005	Automatic switchover frequency range from bypass to inverter operation	0 to 10 Hz, 9999	0.01 Hz	9999		114	





Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
–	160	E440	User group read selection <i>Simple</i>	0, 1, 9999	1	0		115	
–	161	E200	Frequency setting/key lock operation selection	0, 1, 10, 11	1	0		115	
Automatic restart functions	162	A700	Automatic restart after instantaneous power failure selection	0 to 3, 10 to 13	1	0		100	
	163	A704	First cushion time for restart	0 to 20 s	0.1 s	0 s		100	
	164	A705	First cushion voltage for restart	0 to 100%	0.1%	0%		100	
	165	A710	Stall prevention operation level for restart	0 to 400%	0.1%	150%		100	
	Current detection	166	M433	Output current detection signal retention time	0 to 10 s, 9999	0.1 s	0.1 s		114
167		M464	Output current detection operation selection	0, 1, 10, 11	1	0		114	
–	168	E000	Parameter for manufacturer setting. Do not set.						
–		E080							
–	169	E001							
–		E081							
Cumulative monitor clear	170	M020							
	171	M030	Operation hour meter clear	0, 9999	1	9999		98	
User group	172	E441	User group registered display/batch clear	9999, (0 to 16)	1	0		115	
	173	E442	User group registration	0 to 1999, 9999	1	9999		115	
	174	E443	User group clear	0 to 1999, 9999	1	9999		115	
Input terminal function assignment	178	T700	STF terminal function selection	0 to 20, 22 to 28, 37, 42 to 48, 50 to 53, 60, 62, 64 to 74, 76 to 80, 87, 92 to 96, 9999	1	60		116	
	179	T701	STR terminal function selection	0 to 20, 22 to 28, 37, 42 to 48, 50 to 53, 61, 62, 64 to 74, 76 to 80, 87, 92 to 96, 9999	1	61		116	
	180	T702	RL terminal function selection	0 to 20, 22 to 28, 37, 42 to 48, 50 to 53, 62, 64 to 74, 76 to 80, 87, 92 to 96, 9999	1	0		116	
	181	T703	RM terminal function selection		1	1		116	
	182	T704	RH terminal function selection		1	2		116	
	183	T705	RT terminal function selection		1	3		116	
	184	T706	AU terminal function selection		1	4		116	
	185	T707	JOG terminal function selection		1	5		116	
	186	T708	CS terminal function selection		1	6		116	
	187	T709	MRS terminal function selection		1	24 *15*17 10 *16		116	
	188	T710	STOP terminal function selection		1	25		116	
189	T711	RES terminal function selection	1		62		116		

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Output terminal function assignment	190	M400	RUN terminal function selection	0 to 8, 10 to 20, 22, 25 to 28, 30 to 36, 38 to 57, 60, 61, 63, 64, 67, 68, 70, 79, 84, 85, 90 to 99, 100 to 108, 110 to 116, 120, 122, 125 to 128, 130 to 136, 138 to 157, 160, 161, 163, 164, 167, 168, 170, 179, 184, 185, 190 to 199, 200 to 208, 300 to 308, 9999	1	0		117	
	191	M401	SU terminal function selection		1	1		117	
	192	M402	IPF terminal function selection		1	2 *15*17 9999 *16		117	
	193	M403	OL terminal function selection		1	3		117	
	194	M404	FU terminal function selection		1	4		117	
	195	M405	ABC1 terminal function selection		1	99		117	
	196	M406	ABC2 terminal function selection		1	9999		117	
Multi-speed setting	232 to 239	D308 to D315	Multi-speed setting (8 speed to 15 speed)	0 to 590 Hz, 9999	0.01 Hz	9999		91	
—	240	E601	Soft-PWM operation selection	0, 1	1	1		104	
—	241	M043	Analog input display unit switchover	0, 1	1	0		112	
—	242	T021	Terminal 1 added compensation amount (terminal 2)	0 to 100%	0.1%	100%		104	
—	243	T041	Terminal 1 added compensation amount (terminal 4)	0 to 100%	0.1%	75%		104	
—	244	H100	Cooling fan operation selection	0, 1, 101 to 105	1	1		118	
Slip compensation	245	G203	Rated slip	0 to 50%, 9999	0.01%	9999		118	
	246	G204	Slip compensation time constant	0.01 to 10 s	0.01 s	0.5 s		118	
	247	G205	Constant-power range slip compensation selection	0, 9999	1	9999		118	
—	248	A006	Self power management selection	0 to 2	1	0		118	
—	249	H101	Earth (ground) fault detection at start	0, 1	1	0		118	
—	250	G106	Stop selection	0 to 100 s, 1000 to 1100 s, 8888, 9999	0.1 s	9999		118	
—	251	H200	Output phase loss protection selection	0, 1	1	1		119	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting	
						FM	CA			
Frequency compensation function	252	T050	Override bias	0 to 200%	0.1%	50%		104		
	253	T051	Override gain	0 to 200%	0.1%	150%		104		
—	254	A007	Main circuit power OFF waiting time	0 to 3600 s, 9999	1 s	600 s		118		
Life check	255	E700	Life alarm status display	(0 to 15)	1	0		119		
	256 *19	E701	Inrush current limit circuit life display	(0 to 100%)	1%	100%		119		
	257	E702	Control circuit capacitor life display	(0 to 100%)	1%	100%		119		
	258 *19	E703	Main circuit capacitor life display	(0 to 100%)	1%	100%		119		
	259 *19	E704	Main circuit capacitor life measuring	0, 1	1	0		119		
—	260	E602	PWM frequency automatic switchover	0, 1	1	1		104		
Power failure stop	261	A730	Power failure stop selection	0 to 2, 11, 12, 21, 22	1	0		119		
	262	A731	Subtracted frequency at deceleration start	0 to 20 Hz	0.01 Hz	3 Hz		119		
	263	A732	Subtraction starting frequency	0 to 590 Hz, 9999	0.01 Hz	60 Hz	50 Hz	119		
	264	A733	Power-failure deceleration time 1	0 to 3600 s	0.1 s	5 s		119		
	265	A734	Power-failure deceleration time 2	0 to 3600 s, 9999	0.1 s	9999		119		
	266	A735	Power failure deceleration time switchover frequency	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	119		
—	267	T001	Terminal 4 input selection	0 to 2	1	0		104		
—	268	M022	Monitor decimal digits selection	0, 1, 9999	1	9999		98		
—	269	E023	Parameter for manufacturer setting. Do not set.							
—	270	A200	Stop-on contact/load torque high-speed frequency control selection	0 to 3, 11, 13	1	0		120		
Load torque high speed frequency control	271	A201	High-speed setting maximum current	0 to 400%	0.1%	50%		120		
	272	A202	Middle-speed setting minimum current	0 to 400%	0.1%	100%		120		
	273	A203	Current averaging range	0 to 590 Hz, 9999	0.01 Hz	9999		120		
	274	A204	Current averaging filter time constant	1 to 4000	1	16		120		
Stop-on contact control	275	A205	Stop-on contact excitation current low-speed multiplying factor	50 to 300%, 9999	0.1%	9999		121		
	276	A206	PWM carrier frequency at stop-on contact	0 to 9, 9999 *2 0 to 4, 9999 *3	1	9999		121		
Brake sequence function	278	A100	Brake opening frequency	0 to 30 Hz	0.01 Hz	3 Hz		121		
	279	A101	Brake opening current	0 to 400%	0.1%	130%		121		
	280	A102	Brake opening current detection time	0 to 2 s	0.1 s	0.3 s		121		
	281	A103	Brake operation time at start	0 to 5 s	0.1 s	0.3 s		121		
	282	A104	Brake operation frequency	0 to 30 Hz	0.01 Hz	6 Hz		121		
	283	A105	Brake operation time at stop	0 to 5 s	0.1 s	0.3 s		121		
	284	A106	Deceleration detection function selection	0, 1	1	0		121		
	285	A107 H416	Overspeed detection frequency Speed deviation excess detection frequency	0 to 30 Hz, 9999	0.01 Hz	9999		121, 123		
Droop control	286	G400	Droop gain	0 to 100%	0.1%	0%		123		
	287	G401	Droop filter time constant	0 to 1 s	0.01 s	0.3 s		123		
	288	G402	Droop function activation selection	0 to 2, 10, 11	1	0		123		
—	289	M431	Inverter output terminal filter	5 to 50 ms, 9999	1 ms	9999		117		
—	290	M044	Monitor negative output selection	0 to 7	1	0		98		

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
—	291	D100	Pulse train I/O selection	[FM Type] 0, 1, 10, 11, 20, 21, 100 [CA Type] 0, 1	1	0	124		
—	292	A110 F500	Automatic acceleration/ deceleration	0, 1, 3, 5 to 8, 11	1	0	102		
—	293	F513	Acceleration/deceleration separate selection	0 to 2	1	0	102		
—	294	A785	UV avoidance voltage gain	0 to 200%	0.1%	100%	119		
—	295	E201	Frequency change increment amount setting	0, 0.01, 0.1, 1, 10	0.01	0	115		
Password function	296	E410	Password lock level	0 to 6, 99, 100 to 106, 199, 9999	1	9999	124		
	297	E411	Password lock/unlock	(0 to 5), 1000 to 9998, 9999	1	9999	124		
—	298	A711	Frequency search gain	0 to 32767, 9999	1	9999	109		
—	299	A701	Rotation direction detection selection at restarting	0, 1, 9999	1	0	100		
RS-485 communication	331	N030	RS-485 communication station number	0 to 31 (0 to 247)	1	0	111		
	332	N031	RS-485 communication speed	3, 6, 12, 24, 48, 96, 192, 384, 576, 768, 1152	1	96	111		
	333	-	RS-485 communication stop bit length / data length	0, 1, 10, 11	1	1	111		
		N032	PU communication data length	0, 1	1	0			
		N033	PU communication stop bit length	0, 1	1	1			
	334	N034	RS-485 communication parity check selection	0 to 2	1	2	111		
	335	N035	RS-485 communication retry count	0 to 10, 9999	1	1	111		
	336	N036	RS-485 communication check time interval	0 to 999.8 s, 9999	0.1 s	0 s	111		
	337	N037	RS-485 communication waiting time setting	0 to 150 ms, 9999	1 ms	9999	111		
	338	D010	Communication operation command source	0, 1	1	0	125		
	339	D011	Communication speed command source	0 to 2	1	0	125		
	340	D001	Communication startup mode selection	0 to 2, 10, 12	1	0	107		
	341	N038	RS-485 communication CR/LF selection	0 to 2	1	1	111		
342	N001	Communication EEPROM write selection	0, 1	1	0	111			
343	N080	Communication error count	-	1	0	111			



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Orientation control	350 *9	A510	Stop position command selection	0, 1, 9999	1	9999		125	
	351 *9	A526	Orientation speed	0 to 30 Hz	0.01 Hz	2 Hz		125	
	352 *9	A527	Creep speed	0 to 10 Hz	0.01 Hz	0.5 Hz		125	
	353 *9	A528	Creep switchover position	0 to 16383	1	511		125	
	354 *9	A529	Position loop switchover position	0 to 8191	1	96		125	
	355 *9	A530	DC injection brake start position	0 to 255	1	5		125	
	356 *9	A531	Internal stop position command	0 to 16383	1	0		125	
	357 *9	A532	Orientation in-position zone	0 to 255	1	5		125	
	358 *9	A533	Servo torque selection	0 to 13	1	1		125	
	359 *11	C141	Encoder rotation direction	0, 1, 100, 101	1	1		125	
	360 *9	A511	16-bit data selection	0 to 127	1	0		125	
	361 *9	A512	Position shift	0 to 16383	1	0		125	
	362 *9	A520	Orientation position loop gain	0.1 to 100	0.1	1		125	
	363 *9	A521	Completion signal output delay time	0 to 5 s	0.1 s	0.5 s		125	
	364 *9	A522	Encoder stop check time	0 to 5 s	0.1 s	0.5 s		125	
	365 *9	A523	Orientation limit	0 to 60 s, 9999	1 s	9999		125	
366 *9	A524	Recheck time	0 to 5 s, 9999	0.1 s	9999		125		
Encoder feedback	367 *9	G240	Speed feedback range	0 to 590 Hz, 9999	0.01 Hz	9999		126	
	368 *9	G241	Feedback gain	0 to 100	0.1	1		126	
	369 *10	C140	Number of encoder pulses	0 to 4096	1	1024		126	
	374	H800	Overspeed detection level	0 to 590 Hz, 9999	0.01 Hz	9999		126	
	376 *11	C148	Encoder signal loss detection enable/disable selection	0, 1	1	0		126	
S-pattern acceleration/ deceleration C	380	F300	Acceleration S-pattern 1	0 to 50%	1%	0%		95	
	381	F301	Deceleration S-pattern 1	0 to 50%	1%	0%		95	
	382	F302	Acceleration S-pattern 2	0 to 50%	1%	0%		95	
	383	F303	Deceleration S-pattern 2	0 to 50%	1%	0%		95	
Pulse train input	384	D101	Input pulse division scaling factor	0 to 250	1	0		124	
	385	D110	Frequency for zero input pulse	0 to 590 Hz	0.01 Hz	0 Hz		124	
	386	D111	Frequency for maximum input pulse	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	124	
Orientation control	393 *9	A525	Orientation selection	0 to 2, 10 to 12	1	0		125	
	394 *9	A540	Number of machine side gear teeth	0 to 32767	1	1		125	
	395 *9	A541	Number of motor side gear teeth	0 to 32767	1	1		125	
	396 *9	A542	Orientation speed gain (P term)	0 to 1000	1	60		125	
	397 *9	A543	Orientation speed integral time	0 to 20 s	0.001 s	0.333 s		125	
	398 *9	A544	Orientation speed gain (D term)	0 to 100	0.1	1		125	
	399 *9	A545	Orientation deceleration ratio	0 to 1000	1	20		125	
PLC function	414	A800	PLC function operation selection	0 to 2	1	0		126	
	415	A801	Inverter operation lock mode setting	0, 1	1	0		126	
	416	A802	Pre-scale function selection	0 to 5	1	0		126	
	417	A803	Pre-scale setting value	0 to 32767	1	1		126	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Position control	419	B000	Position command source selection	0, 2	1	0		127, 128	
	420	B001	Command pulse scaling factor numerator (electronic gear numerator)	1 to 32767	1	1		128	
	421	B002	Command pulse multiplication denominator (electronic gear denominator)	1 to 32767	1	1		128	
	422	B003	Position control gain	0 to 150 sec <sup>-1</sup>	1 sec <sup>-1</sup>	25 sec <sup>-1</sup>		129	
	423	B004	Position feed forward gain	0 to 100%	1%	0%		129	
	424	B005	Position command acceleration/ deceleration time constant	0 to 50 s	0.001 s	0 s		128	
	425	B006	Position feed forward command filter	0 to 5 s	0.001 s	0 s		129	
	426	B007	In-position width	0 to 32767 pulse	1 pulse	100 pulse		129	
	427	B008	Excessive level error	0 to 400K pulse, 9999	1K pulse	40K pulse		129	
	428	B009	Command pulse selection	0 to 5	1	0		128	
	429	B010	Clear signal selection	0, 1	1	1		128	
	430	B011	Pulse monitor selection	0 to 5, 12, 13, 100 to 105, 112, 113, 1000 to 1005, 1012, 1013, 1100 to 1105, 1112, 1113, 8888, 9999	1	9999		128	
—	446	B012	Model position control gain	0 to 150 sec <sup>-1</sup>	1 sec <sup>-1</sup>	25 sec <sup>-1</sup>		129	
Second motor constants	450	C200	Second applied motor	0, 1, 3 to 6, 13 to 16, 20, 23, 24, 30, 33, 34, 40, 43, 44, 50, 53, 54, 70, 73, 74, 330, 333, 334, 8093, 8094, 9090, 9093, 9094, 9999	1	9999		103	
	451	G300	Second motor control method selection	0 to 6, 10 to 14, 20, 100 to 106, 110 to 114, 9999	1	9999		108	
	453	C201	Second motor capacity	0.4 to 55 kW, 9999 *2 0 to 3600 kW, 9999 *3	0.01 kW *2 0.1 kW *3	9999		108	
	454	C202	Number of second motor poles	2, 4, 6, 8, 10, 12, 9999	1	9999		108	
	455	C225	Second motor excitation current	0 to 500 A, 9999 *2 0 to 3600 A, 9999 *3	0.01 A *2 0.1 A *3	9999		109	
	456	C204	Rated second motor voltage	0 to 1000 V	0.1 V	200 V *7 400 V *8		109	
	457	C205	Rated second motor frequency	10 to 400 Hz, 9999	0.01 Hz	9999		109	
	458	C220	Second motor constant (R1)	0 to 50 Ω, 9999 *2 0 to 400 mΩ, 9999 *3	0.001 Ω *2 0.01 mΩ *3	9999		109	
	459	C221	Second motor constant (R2)	0 to 50 Ω, 9999 *2 0 to 400 mΩ, 9999 *3	0.001 Ω *2 0.01 mΩ *3	9999		109	
	460	C222	Second motor constant (L1) / d-axis inductance (Ld)	0 to 6000mH, 9999 *2 0 to 400mH, 9999 *3	0.1 mH *2 0.01 mH *3	9999		109	
	461	C223	Second motor constant (L2) / q-axis inductance (Lq)	0 to 6000mH, 9999 *2 0 to 400mH, 9999 *3	0.1 mH *2 0.01 mH *3	9999		109	
	462	C224	Second motor constant (X)	0 to 100%, 9999	0.1% *2 0.01% *3	9999		109	
	463	C210	Second motor auto tuning setting/ status	0, 1, 11, 101	1	0		109	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Simple position control	464	B020	Digital position control sudden stop deceleration time	0 to 360 s	0.1 s	0 s		127	
	465	B021	First target position lower 4 digits	0 to 9999	1	0		127	
	466	B022	First target position upper 4 digits	0 to 9999	1	0		127	
	467	B023	Second target position lower 4 digits	0 to 9999	1	0		127	
	468	B024	Second target position upper 4 digits	0 to 9999	1	0		127	
	469	B025	Third target position lower 4 digits	0 to 9999	1	0		127	
	470	B026	Third target position upper 4 digits	0 to 9999	1	0		127	
	471	B027	Fourth target position lower 4 digits	0 to 9999	1	0		127	
	472	B028	Fourth target position upper 4 digits	0 to 9999	1	0		127	
Simple position control	473	B029	Fifth target position lower 4 digits	0 to 9999	1	0		127	
	474	B030	Fifth target position upper 4 digits	0 to 9999	1	0		127	
	475	B031	Sixth target position lower 4 digits	0 to 9999	1	0		127	
	476	B032	Sixth target position upper 4 digits	0 to 9999	1	0		127	
	477	B033	Seventh target position lower 4 digits	0 to 9999	1	0		127	
	478	B034	Seventh target position upper 4 digits	0 to 9999	1	0		127	
	479	B035	Eighth target position lower 4 digits	0 to 9999	1	0		127	
	480	B036	Eighth target position upper 4 digits	0 to 9999	1	0		127	
	481	B037	Ninth target position lower 4 digits	0 to 9999	1	0		127	
	482	B038	Ninth target position upper 4 digits	0 to 9999	1	0		127	
	483	B039	Tenth target position lower 4 digits	0 to 9999	1	0		127	
	484	B040	Tenth target position upper 4 digits	0 to 9999	1	0		127	
	485	B041	Eleventh target position lower 4 digits	0 to 9999	1	0		127	
	486	B042	Eleventh target position upper 4 digits	0 to 9999	1	0		127	
	487	B043	Twelfth target position lower 4 digits	0 to 9999	1	0		127	
	488	B044	Twelfth target position upper 4 digits	0 to 9999	1	0		127	
	489	B045	Thirteenth target position lower 4 digits	0 to 9999	1	0		127	
	490	B046	Thirteenth target position upper 4 digits	0 to 9999	1	0		127	
	491	B047	Fourteenth target position lower 4 digits	0 to 9999	1	0		127	
	492	B048	Fourteenth target position upper 4 digits	0 to 9999	1	0		127	
493	B049	Fifteenth target position lower 4 digits	0 to 9999	1	0		127		
494	B050	Fifteenth target position upper 4 digits	0 to 9999	1	0		127		
Remote output	495	M500	Remote output selection	0, 1, 10, 11	1	0		129	
	496	M501	Remote output data 1	0 to 4095	1	0		129	
	497	M502	Remote output data 2	0 to 4095	1	0		129	
—	498	A804	PLC function flash memory clear	0, 9696 (0 to 9999)	1	0		126	
—	502	N013	Stop mode selection at communication error	0 to 3	1	0		126	
Maintenance	503	E710	Maintenance timer 1	0 (1 to 9998)	1	0		130	
	504	E711	Maintenance timer 1 warning output set time	0 to 9998, 9999	1	9999		130	
—	505	M001	Speed setting reference	1 to 590 Hz	0.01 Hz	60 Hz	50 Hz	97	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
S-pattern acceleration/ deceleration D	516	F400	S-pattern time at a start of acceleration	0.1 to 2.5 s	0.1 s	0.1 s		95	
	517	F401	S-pattern time at a completion of acceleration	0.1 to 2.5 s	0.1 s	0.1 s		95	
	518	F402	S-pattern time at a start of deceleration	0.1 to 2.5 s	0.1 s	0.1 s		95	
	519	F403	S-pattern time at a completion of deceleration	0.1 to 2.5 s	0.1 s	0.1 s		95	
—	522	G105	Output stop frequency	0 to 590 Hz, 9999	0.01 Hz	9999		130	
—	539	N002	MODBUS RTU communication check time interval	0 to 999.8 s, 9999	0.1 s	9999		111	
USB	547	N040	USB communication station number	0 to 31	1	0		130	
	548	N041	USB communication check time interval	0 to 999.8 s, 9999	0.1 s	9999		130	
Communication	549	N000	Protocol selection	0, 1	1	0		111	
	550	D012	NET mode operation command source selection	0, 1, 9999	1	9999		125	
	551	D013	PU mode operation command source selection	1 to 3, 9999	1	9999		125	
—	552	H429	Frequency jump range	0 to 30 Hz, 9999	0.01 Hz	9999		97	
PID control	553	A603	PID deviation limit	0 to 100%, 9999	0.1%	9999		113	
	554	A604	PID signal operation selection	0 to 3, 10 to 13	1	0		113	
Current average value monitor	555	E720	Current average time	0.1 to 1 s	0.1 s	1 s		130	
	556	E721	Data output mask time	0 to 20 s	0.1 s	0 s		130	
	557	E722	Current average value monitor signal output reference current	0 to 500 A*2 0 to 3600 A*3	0.01 A *2 0.1 A *3	Inverter rated current		130	
—	560	A712	Second frequency search gain	0 to 32767, 9999	1	9999		109	
—	561	H020	PTC thermistor protection level	0.5 to 30 kΩ, 9999	0.01 kΩ	9999		92	
—	563	M021	Energization time carrying-over times	(0 to 65535)	1	0		98	
—	564	M031	Operating time carrying-over times	(0 to 65535)	1	0		98	
Second motor constants	569	G942	Second motor speed control gain	0 to 200%, 9999	0.1%	9999		108	
Multiple rating	570	E301	Multiple rating setting	0 to 3 *15*16	1	2		131	
				1, 2 *17					
—	571	F103	Holding time at a start	0 to 10 s, 9999	0.1 s	9999		93	
—	573	A680 T052	4 mA input check selection	1 to 4, 9999	1	9999		131	
—	574	C211	Second motor online auto tuning	0 to 2	1	0		110	
PID control	575	A621	Output interruption detection time	0 to 3600 s, 9999	0.1 s	1 s		113	
	576	A622	Output interruption detection level	0 to 590 Hz	0.01 Hz	0 Hz		113	
	577	A623	Output interruption cancel level	900 to 1100%	0.1%	1000%		113	
Traverse function	592	A300	Traverse function selection	0 to 2	1	0		131	
	593	A301	Maximum amplitude amount	0 to 25%	0.1%	10%		131	
	594	A302	Amplitude compensation amount during deceleration	0 to 50%	0.1%	10%		131	
	595	A303	Amplitude compensation amount during acceleration	0 to 50%	0.1%	10%		131	
	596	A304	Amplitude acceleration time	0.1 to 3600 s	0.1 s	5 s		131	
	597	A305	Amplitude deceleration time	0.1 to 3600 s	0.1 s	5 s		131	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
–	598 *20	H102	Undervoltage level	350 to 430 V, 9999	0.1 V	9999		131	
–	599	T721	X10 terminal input selection	0, 1	1	0 *15*17 1 *16		96	
Electronic thermal O/L relay	600	H001	First free thermal reduction frequency 1	0 to 590 Hz, 9999	0.01 Hz	9999		92	
	601	H002	First free thermal reduction ratio 1	1 to 100%	1%	100%		92	
	602	H003	First free thermal reduction frequency 2	0 to 590 Hz, 9999	0.01 Hz	9999		92	
	603	H004	First free thermal reduction ratio 2	1 to 100%	1%	100%		92	
	604	H005	First free thermal reduction frequency 3	0 to 590 Hz, 9999	0.01 Hz	9999		92	
–	606	T722	Power failure stop external signal input selection	0, 1	1	1		119	
–	607	H006	Motor permissible load level	110 to 250%	1%	150%		92	
–	608	H016	Second motor permissible load level	110 to 250%, 9999	1%	9999		92	
PID control	609	A624	PID set point/deviation input selection	1 to 5	1	2		113	
	610	A625	PID measured value input selection	1 to 5	1	3		113	
–	611	F003	Acceleration time at a restart	0 to 3600 s, 9999	0.1 s	9999		100	
Cumulative pulse monitor	635 *9	M610	Cumulative pulse clear signal selection	0 to 3	1	0		128	
	636 *9	M611	Cumulative pulse division scaling factor	1 to 16384	1	1		128	
	637 *9	M612	Control terminal option-Cumulative pulse division scaling factor	1 to 16384	1	1		128	
	638 *9	M613	Cumulative pulse storage	0 to 3	1	0		128	
Brake sequence function	639	A108	Brake opening current selection	0, 1	1	0		121	
	640	A109	Brake operation frequency selection	0, 1	1	0		121	
	641	A130	Second brake sequence operation selection	0, 7, 8, 9999	1	0		121	
	642	A120	Second brake opening frequency	0 to 30 Hz	0.01 Hz	3 Hz		121	
	643	A121	Second brake opening current	0 to 400%	0.1%	130%		121	
	644	A122	Second brake opening current detection time	0 to 2 s	0.1 s	0.3 s		121	
	645	A123	Second brake operation time at start	0 to 5 s	0.1 s	0.3 s		121	
	646	A124	Second brake operation frequency	0 to 30 Hz	0.01 Hz	6 Hz		121	
	647	A125	Second brake operation time at stop	0 to 5 s	0.1 s	0.3 s		121	
	648	A126	Second deceleration detection function selection	0, 1	1	0		121	
	650	A128	Second brake opening current selection	0, 1	1	0		121	
Speed smoothing control	653	G410	Speed smoothing control	0 to 200%	0.1%	0%		132	
	654	G411	Speed smoothing cutoff frequency	0 to 120 Hz	0.01 Hz	20 Hz		132	
Analog remote output function	655	M530	Analog remote output selection	0, 1, 10, 11	1	0		132	
	656	M531	Analog remote output 1	800 to 1200%	0.1%	1000%		132	
	657	M532	Analog remote output 2	800 to 1200%	0.1%	1000%		132	
	658	M533	Analog remote output 3	800 to 1200%	0.1%	1000%		132	
	659	M534	Analog remote output 4	800 to 1200%	0.1%	1000%		132	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LV/S/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Increased magnetic excitation deceleration	660	G130	Increased magnetic excitation deceleration operation selection	0, 1	1	0		133	
	661	G131	Magnetic excitation increase rate	0 to 40%, 9999	0.1%	9999		133	
	662	G132	Increased magnetic excitation current level	0 to 300%	0.1%	100%		133	
—	663	M060	Control circuit temperature signal output level	0 to 100°C	1°C	0°C		133	
—	665	G125	Regeneration avoidance frequency gain	0 to 200%	0.1%	100%		139	
—	668	A786	Power failure stop frequency gain	0 to 200%	0.1%	100%		119	
—	673	G060	SF-PR slip amount adjustment operation selection	2, 4, 6, 9999	1	9999		133	
—	674	G061	SF-PR slip amount adjustment gain	0 to 500%	0.1%	100%		133	
Second droop control	679	G420	Second droop gain	0 to 100%, 9999	0.1%	9999		123	
	680	G421	Second droop filter time constant	0 to 1 s, 9999	0.01 s	9999		123	
	681	G422	Second droop function activation selection	0 to 2, 10, 11, 9999	1	9999		123	
	682	G423	Second droop break point gain	0.1 to 100%, 9999	0.1%	9999		123	
	683	G424	Second droop break point torque	0.1 to 100%, 9999	0.1%	9999		123	
—	684	C000	Tuning data unit switchover	0, 1	1	0		109	
Maintenance	686	E712	Maintenance timer 2	0 (1 to 9998)	1	0		130	
	687	E713	Maintenance timer 2 warning output set time	0 to 9998, 9999	1	9999		130	
	688	E714	Maintenance timer 3	0 (1 to 9998)	1	0		130	
	689	E715	Maintenance timer 3 warning output set time	0 to 9998, 9999	1	9999		130	
—	690	H881	Deceleration check time	0 to 3600 s, 9999	0.1 s	1 s		133	
Electronic thermal O/L relay	692	H011	Second free thermal reduction frequency 1	0 to 590 Hz, 9999	0.01 Hz	9999		92	
	693	H012	Second free thermal reduction ratio 1	1 to 100%	1%	100%		92	
	694	H013	Second free thermal reduction frequency 2	0 to 590 Hz, 9999	0.01 Hz	9999		92	
	695	H014	Second free thermal reduction ratio 2	1 to 100%	1%	100%		92	
	696	H015	Second free thermal reduction frequency 3	0 to 590 Hz, 9999	0.01 Hz	9999		92	
—	699	T740	Input terminal filter	5 to 50 ms, 9999	1 ms	9999		116	





Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Motor constants	702	C106	Maximum motor frequency	0 to 400 Hz, 9999	0.01 Hz	9999		109	
	706	C130	Induced voltage constant (phi f)	0 to 5000 mV/(rad/s), 9999	0.1 mV/(rad/s)	9999		109	
	707	C107	Motor inertia (integer)	10 to 999, 9999	1	9999		109	
	711	C131	Motor Ld decay ratio	0 to 100%, 9999	0.1%	9999		109	
	712	C132	Motor Lq decay ratio	0 to 100%, 9999	0.1%	9999		109	
	717	C182	Starting resistance tuning compensation	0 to 200%, 9999	0.1%	9999		109	
	721	C185	Starting magnetic pole position detection pulse width	0 to 6000 μs, 10000 to 16000 μs, 9999	1 μs	9999		109	
	724	C108	Motor inertia (exponent)	0 to 7, 9999	1	9999		109	
	725	C133	Motor protection current level	100 to 500%, 9999	0.1%	9999		109	
	738	C230	Second motor induced voltage constant (phi f)	0 to 5000 mV/(rad/s), 9999	0.1 mV/(rad/s)	9999		109	
	739	C231	Second motor Ld decay ratio	0 to 100%, 9999	0.1%	9999		109	
	740	C232	Second motor Lq decay ratio	0 to 100%, 9999	0.1%	9999		109	
	741	C282	Second starting resistance tuning compensation	0 to 200%, 9999	0.1%	9999		109	
	742	C285	Second motor magnetic pole position detection pulse width	0 to 6000 μs, 10000 to 16000 μs, 9999	1 μs	9999		109	
	743	C206	Second motor maximum frequency	0 to 400 Hz, 9999	0.01 Hz	9999		109	
	744	C207	Second motor inertia (integer)	10 to 999, 9999	1	9999		109	
745	C208	Second motor inertia (exponent)	0 to 7, 9999	1	9999		109		
746	C233	Second motor protection current level	100 to 500%, 9999	0.1%	9999		109		
—	747	G350	Second motor low-speed range torque characteristic selection	0, 9999	1	9999		134	
PID control	753	A650	Second PID action selection	0, 10, 11, 20, 21, 50, 51, 60, 61, 70, 71, 80, 81, 90, 91, 100, 101, 1000, 1001, 1010, 1011, 2000, 2001, 2010, 2011	1	0		113	
	754	A652	Second PID control automatic switchover frequency	0 to 590 Hz, 9999	0.01 Hz	9999		113	
	755	A651	Second PID action set point	0 to 100%, 9999	0.01%	9999		113	
	756	A653	Second PID proportional band	0.1 to 1000%, 9999	0.1%	100%		113	
	757	A654	Second PID integral time	0.1 to 3600 s, 9999	0.1 s	1 s		113	
	758	A655	Second PID differential time	0.01 to 10 s, 9999	0.01 s	9999		113	
PID pre-charge function	759	A600	PID unit selection	0 to 43, 9999	1	9999		113	
	760	A616	Pre-charge fault selection	0, 1	1	0		134	
	761	A617	Pre-charge ending level	0 to 100%, 9999	0.1%	9999		134	
	762	A618	Pre-charge ending time	0 to 3600 s, 9999	0.1 s	9999		134	
	763	A619	Pre-charge upper detection level	0 to 100%, 9999	0.1%	9999		134	
	764	A620	Pre-charge time limit	0 to 3600 s, 9999	0.1 s	9999		134	
	765	A656	Second pre-charge fault selection	0, 1	1	0		134	
	766	A657	Second pre-charge ending level	0 to 100%, 9999	0.1%	9999		134	
	767	A658	Second pre-charge ending time	0 to 3600 s, 9999	0.1 s	9999		134	
	768	A659	Second pre-charge upper detection level	0 to 100%, 9999	0.1%	9999		134	
	769	A660	Second pre-charge time limit	0 to 3600 s, 9999	0.1 s	9999		134	
Monitor function	774	M101	Operation panel monitor selection 1	1 to 3, 5 to 14, 17 to 20, 22 to 36, 38, 40 to 46, 50 to 57, 61, 62, 64, 67, 71 to 74, 87 to 98, 100, 9999	1	9999		98	
	775	M102	Operation panel monitor selection 2		1	9999		98	
	776	M103	Operation panel monitor selection 3		1	9999		98	
—	777	A681 T053	4 mA input check operation frequency	0 to 590 Hz, 9999	0.01 Hz	9999		131	
—	778	A682 T054	4 mA input check filter	0 to 10 s	0.01 s	0 s		131	

Features

Application Example  
PLC Function  
FR Configurator 2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
—	779	N014	Operation frequency during communication error	0 to 590 Hz, 9999	0.01 Hz	9999		111	
—	788	G250	Low speed range torque characteristic selection	0, 9999	1	9999		134	
—	791	F070	Acceleration time in low-speed range	0 to 3600 s, 9999	0.1 s	9999		91	
—	792	F071	Deceleration time in low-speed range	0 to 3600 s, 9999	0.1 s	9999		91	
—	799	M520	Pulse increment setting for output power	0.1, 1, 10, 100, 1000 kWh	0.1 kWh	1 kWh		134	
—	800	G200	Control method selection	0 to 6, 9 to 14, 20, 100 to 106, 109 to 114	1	20		108	
—	802	G102	Pre-excitation selection	0, 1	1	0		92	
Torque command	803	G210	Constant output range torque characteristic selection	0, 1, 10, 11	1	0		95, 135	
	804	D400	Torque command source selection	0, 1, 3 to 6	1	0		95, 135	
	805	D401	Torque command value (RAM)	600 to 1400%	1%	1000%		95, 135	
	806	D402	Torque command value (RAM, EEPROM)	600 to 1400%	1%	1000%		95, 135	
Speed limit	807	H410	Speed limit selection	0 to 2	1	0		135	
	808	H411	Forward rotation speed limit/speed limit	0 to 400 Hz	0.01 Hz	60 Hz	50 Hz	135	
	809	H412	Reverse rotation speed limit/reverse-side speed limit	0 to 400 Hz, 9999	0.01 Hz	9999		135	
Torque limit	810	H700	Torque limit input method selection	0 to 2	1	0		95	
	811	D030	Set resolution switchover	0, 1, 10, 11	1	0		95, 97	
	812	H701	Torque limit level (regeneration)	0 to 400%, 9999	0.1%	9999		95	
	813	H702	Torque limit level (3rd quadrant)	0 to 400%, 9999	0.1%	9999		95	
	814	H703	Torque limit level (4th quadrant)	0 to 400%, 9999	0.1%	9999		95	
	815	H710	Torque limit level 2	0 to 400%, 9999	0.1%	9999		95	
	816	H720	Torque limit level during acceleration	0 to 400%, 9999	0.1%	9999		95	
Easy gain tuning	817	H721	Torque limit level during deceleration	0 to 400%, 9999	0.1%	9999		95	
	818	C112	Easy gain tuning response level setting	1 to 15	1	2		136	
Adjustment function	819	C113	Easy gain tuning selection	0 to 2	1	0		136	
	820	G211	Speed control P gain 1	0 to 1000%	1%	60%		136	
	821	G212	Speed control integral time 1	0 to 20 s	0.001 s	0.333 s		136	
	822	T003	Speed setting filter 1	0 to 5 s, 9999	0.001 s	9999		105	
	823 *9	G215	Speed detection filter 1	0 to 0.1 s	0.001 s	0.001 s		136	
	824	G213	Torque control P gain 1 (current loop proportional gain)	0 to 500%	1%	100%		136	
	825	G214	Torque control integral time 1 (current loop integral time)	0 to 500 ms	0.1 ms	5 ms		136	
	826	T004	Torque setting filter 1	0 to 5 s, 9999	0.001 s	9999		105	
	827	G216	Torque detection filter 1	0 to 0.1 s	0.001 s	0 s		136	
	828	G224	Model speed control gain	0 to 1000%	1%	60%		137	
	830	G311	Speed control P gain 2	0 to 1000%, 9999	1%	9999		136	
	831	G312	Speed control integral time 2	0 to 20 s, 9999	0.001 s	9999		136	
	832	T005	Speed setting filter 2	0 to 5 s, 9999	0.001 s	9999		105	
	833 *9	G315	Speed detection filter 2	0 to 0.1 s, 9999	0.001 s	9999		136	
	834	G313	Torque control P gain 2	0 to 500%, 9999	1%	9999		136	
	835	G314	Torque control integral time 2	0 to 500 ms, 9999	0.1 ms	9999		136	
836	T006	Torque setting filter 2	0 to 5 s, 9999	0.001 s	9999		105		
837	G316	Torque detection filter 2	0 to 0.1 s, 9999	0.001 s	9999		136		



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Torque bias	840	G230	Torque bias selection	0 to 3, 24, 25, 9999	1	9999		137	
	841	G231	Torque bias 1	600 to 1400%, 9999	1%	9999		137	
	842	G232	Torque bias 2	600 to 1400%, 9999	1%	9999		137	
	843	G233	Torque bias 3	600 to 1400%, 9999	1%	9999		137	
	844	G234	Torque bias filter	0 to 5s, 9999	0.001 s	9999		137	
	845	G235	Torque bias operation time	0 to 5s, 9999	0.01 s	9999		137	
	846	G236	Torque bias balance compensation	0 to 10 V, 9999	0.1 V	9999		137	
	847	G237	Fall-time torque bias terminal 1 bias	0 to 400%, 9999	1%	9999		137	
Additional function	848	G238	Fall-time torque bias terminal 1 gain	0 to 400%, 9999	1%	9999		137	
	849	T007	Analog input offset adjustment	0 to 200%	0.1%	100%		105	
	850	G103	Brake operation selection	0 to 2	1	0		92	
	851 *12	C240	Control terminal option-Number of encoder pulses	0 to 4096	1	2048		125	
	852 *12	C241	Control terminal option-Encoder rotation direction	0, 1, 100, 101	1	1		125	
	853 *9	H417	Speed deviation time	0 to 100 s	0.1 s	1 s		123	
	854	G217	Excitation ratio	0 to 100%	1%	100%		138	
	855 *12	C248	Control terminal option-Signal loss detection enable/disable selection	0, 1	1	0		126	
	858	T040	Terminal 4 function assignment	0, 1, 4, 9999	1	0		138	
	859	C126	Torque current/Rated PM motor current	0 to 500 A, 9999 *2 0 to 3600 A, 9999 *3	0.01 A *2 0.1 A *3	9999		109	
	860	C226	Second motor torque current/Rated PM motor current	0 to 500 A, 9999 *2 0 to 3600 A, 9999 *3	0.01 A *2 0.1 A *3	9999		109	
	862 *9	C242	Encoder option selection	0, 1	1	0		125	
	863 *12	M600	Control terminal option-Encoder pulse division ratio	1 to 32767	1	1		138	
	864	M470	Torque detection	0 to 400%	0.1%	150%		138	
	865	M446	Low speed detection	0 to 590 Hz	0.01 Hz	1.5 Hz		97	
Indication function	866	M042	Torque monitoring reference	0 to 400%	0.1%	150%		100	
–	867	M321	AM output filter	0 to 5 s	0.01 s	0.01 s		140	
–	868	T010	Terminal 1 function assignment	0 to 6, 9999	1	0		138	
–	869	M334	Current output filter	0 to 5 s	0.01 s	–	0.02 s	140	
–	870	M440	Speed detection hysteresis	0 to 5 Hz	0.01 Hz	0 Hz		97	
Protective Functions	872 *19	H201	Input phase loss protection selection	0, 1	1	0		119	
	873 *13	H415	Speed limit	0 to 400 Hz	0.01 Hz	20 Hz		123	
	874	H730	OLT level setting	0 to 400%	0.1%	150%		95	
	875	H030	Fault definition	0, 1	1	0		138	
–	876 *12	H022	Thermal protector input	0, 1	1	1		92	
Control system functions	877	G220	Speed feed forward control/model adaptive speed control selection	0 to 2	1	0		137	
	878	G221	Speed feed forward filter	0 to 1 s	0.01 s	0 s		137	
	879	G222	Speed feed forward torque limit	0 to 400%	0.1%	150%		137	
	880	C114	Load inertia ratio	0 to 200 times	0.1	7		137	
	881	G223	Speed feed forward gain	0 to 1000%	1%	0%		137	
Regeneration avoidance function	882	G120	Regeneration avoidance operation selection	0 to 2	1	0		139	
	883	G121	Regeneration avoidance operation level	300 to 800 V	0.1V	DC380 V *7 DC760 V *8		139	
	884	G122	Regeneration avoidance at deceleration detection sensitivity	0 to 5	1	0		139	
	885	G123	Regeneration avoidance compensation frequency limit value	0 to 590 Hz, 9999	0.01 Hz	6 Hz		139	
	886	G124	Regeneration avoidance voltage gain	0 to 200%	0.1%	100%		139	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Free parameters	888	E420	Free parameter 1	0 to 9999	1	9999		139	
	889	E421	Free parameter 2	0 to 9999	1	9999		139	
Energy saving monitor	891	M023	Cumulative power monitor digit shifted times	0 to 4, 9999	1	9999		98, 139	
	892	M200	Load factor	30 to 150%	0.1%	100%		139	
	893	M201	Energy saving monitor reference (motor capacity)	0.1 to 55 kW *2 0 to 3600 kW *3	0.01 kW *2 0.1 kW *3	Inverter rated capacity		139	
	894	M202	Control selection during commercial power-supply operation	0 to 3	1	0		139	
	895	M203	Power saving rate reference value	0, 1, 9999	1	9999		139	
	896	M204	Power unit cost	0 to 500, 9999	0.01	9999		139	
	897	M205	Power saving monitor average time	0 to 1000 h, 9999	1 h	9999		139	
	898	M206	Power saving cumulative monitor clear	0, 1, 10, 9999	1	9999		139	
	899	M207	Operation time rate (estimated value)	0 to 100%, 9999	0.1%	9999		139	
Calibration parameters	C0 (900) *14	M310	FM/CA terminal calibration	-	-	-		140	
	C1 (901) *14	M320	AM terminal calibration	-	-	-		140	
	C2 (902) *14	T200	Terminal 2 frequency setting bias frequency	0 to 590 Hz	0.01 Hz	0 Hz		112	
	C3 (902) *14	T201	Terminal 2 frequency setting bias	0 to 300%	0.1%	0%		112	
	125 (903) *14	T202	Terminal 2 frequency setting gain frequency	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	112	
	C4 (903) *14	T203	Terminal 2 frequency setting gain	0 to 300%	0.1%	100%		112	
	C5 (904) *14	T400	Terminal 4 frequency setting bias frequency	0 to 590 Hz	0.01 Hz	0 Hz		112	
	C6 (904) *14	T401	Terminal 4 frequency setting bias	0 to 300%	0.1%	20%		112	
	126 (905) *14	T402	Terminal 4 frequency setting gain frequency	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	112	
	C7 (905) *14	T403	Terminal 4 frequency setting gain	0 to 300%	0.1%	100%		112	
	C12 (917) *14	T100	Terminal 1 bias frequency (speed)	0 to 590 Hz	0.01 Hz	0 Hz		112	
	C13 (917) *14	T101	Terminal 1 bias (speed)	0 to 300%	0.1%	0%		112	
	C14 (918) *14	T102	Terminal 1 gain frequency (speed)	0 to 590 Hz	0.01 Hz	60 Hz	50 Hz	112	
	C15 (918) *14	T103	Terminal 1 gain (speed)	0 to 300%	0.1%	100%		112	
	C16 (919) *14	T110	Terminal 1 bias command (torque)	0 to 400%	0.1%	0%		112	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Calibration parameters	C17 (919) *14	T111	Terminal 1 bias (torque)	0 to 300%	0.1%	0%		112	
	C18 (920) *14	T112	Terminal 1 gain command (torque)	0 to 400%	0.1%	150%		112	
	C19 (920) *14	T113	Terminal 1 gain (torque)	0 to 300%	0.1%	100%		112	
	C8 (930) *14	M330	Current output bias signal	0 to 100%	0.1%	-	0%	140	
	C9 (930) *14	M331	Current output bias current	0 to 100%	0.1%	-	0%	140	
	C10 (931) *14	M332	Current output gain signal	0 to 100%	0.1%	-	100%	140	
	C11 (931) *14	M333	Current output gain current	0 to 100%	0.1%	-	100%	140	
	C38 (932) *14	T410	Terminal 4 bias command (torque)	0 to 400%	0.1%	0%		112	
	C39 (932) *14	T411	Terminal 4 bias (torque)	0 to 300%	0.1%	20%		112	
	C40 (933) *14	T412	Terminal 4 gain command (torque)	0 to 400%	0.1%	150%		112	
	C41 (933) *14	T413	Terminal 4 gain (torque)	0 to 300%	0.1%	100%		112	
	C42 (934) *14	A630	PID display bias coefficient	0 to 500, 9999	0.01	9999		113	
	C43 (934) *14	A631	PID display bias analog value	0 to 300%	0.1%	20%		113	
	C44 (935) *14	A632	PID display gain coefficient	0 to 500, 9999	0.01	9999		113	
	C45 (935) *14	A633	PID display gain analog value	0 to 300%	0.1%	100%		113	
-	977	E302	Input voltage mode selection	0, 1	1	0		140	
-	989	E490	Parameter copy alarm release	10 *2 100 *3	1	10 *2 100 *3		140	
PU	990	E104	PU buzzer control	0, 1	1	1		141	
	991	E105	PU contrast adjustment	0 to 63	1	58		141	
Monitor function	992	M104	Operation panel setting dial push monitor selection	0 to 3, 5 to 14, 17 to 20, 22 to 36, 38, 40 to 46, 50 to 57, 61, 62, 64, 67, 71 to 74, 87 to 98, 100	1	0		98	
Droop control	994	G403	Droop break point gain	0.1 to 100%, 9999	0.1%	9999		123	
	995	G404	Droop break point torque	0.1 to 100%	0.1%	100%		123	
-	997	H103	Fault initiation	0 to 255, 9999	1	9999		141	
-	998	E430	PM parameter initialization <i>Simple</i>	0, 3003, 3103, 8009, 8109, 9009, 9109	1	0		196	
-	999	E431	Automatic parameter setting <i>Simple</i>	1, 2, 10, 11, 12, 13, 20, 21, 9999	1	9999		141	
-	1000	E108	Parameter for manufacturer setting. Do not set.						

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
—	1002	C150	Lq tuning target current adjustment coefficient	50 to 150%, 9999	0.1%	9999		109	
Additional function	1003	G601	Notch filter frequency	0, 8 to 1250 Hz	1 Hz	0		142	
	1004	G602	Notch filter depth	0 to 3	1	0		142	
	1005	G603	Notch filter width	0 to 3	1	0		142	
Clock function	1006	E020	Clock (year)	2000 to 2099	1	2000		142	
	1007	E021	Clock (month, day)	1/1 to 12/31	1	101		142	
	1008	E022	Clock (hour, minute)	0:00 to 23:59	1	0		142	
—	1015	A607	Integral stop selection at limited frequency	0, 1, 10, 11	1	0		113	
—	1016	H021	PTC thermistor protection detection time	0 to 60 s	1 s	0 s		92	
—	1018	M045	Monitor with sign selection	0, 9999	1	9999		98	
Trace function	1020	A900	Trace operation selection	0 to 4	1	0		142	
	1021	A901	Trace mode selection	0 to 2	1	0		142	
	1022	A902	Sampling cycle	0 to 9	1	2		142	
	1023	A903	Number of analog channels	1 to 8	1	4		142	
	1024	A904	Sampling auto start	0, 1	1	0		142	
	1025	A905	Trigger mode selection	0 to 4	1	0		142	
	1026	A906	Number of sampling before trigger	0 to 100%	1%	90%		142	
	1027	A910	Analog source selection (1ch)	1 to 3, 5 to 14, 17 to 20, 22 to 24, 32 to 36, 40 to 42, 46, 52 to 54, 61, 62, 64, 67, 71 to 74, 87 to 98, 201 to 213, 222 to 227, 230 to 232, 235 to 238	1	201		142	
	1028	A911	Analog source selection (2ch)			202		142	
	1029	A912	Analog source selection (3ch)			203		142	
	1030	A913	Analog source selection (4ch)			204		142	
	1031	A914	Analog source selection (5ch)			205		142	
	1032	A915	Analog source selection (6ch)			206		142	
	1033	A916	Analog source selection (7ch)			207		142	
	1034	A917	Analog source selection (8ch)			208		142	
	1035	A918	Analog trigger channel	1 to 8	1	1		142	
	1036	A919	Analog trigger operation selection	0, 1	1	0		142	
	1037	A920	Analog trigger level	600 to 1400	1	1000		142	
	1038	A930	Digital source selection (1ch)	1 to 255	1	1		142	
	1039	A931	Digital source selection (2ch)			2		142	
	1040	A932	Digital source selection (3ch)			3		142	
1041	A933	Digital source selection (4ch)	4			142			
1042	A934	Digital source selection (5ch)	5			142			
1043	A935	Digital source selection (6ch)	6			142			
1044	A936	Digital source selection (7ch)	7			142			
1045	A937	Digital source selection (8ch)	8			142			
1046	A938	Digital trigger channel	1 to 8	1	1		142		
1047	A939	Digital trigger operation selection	0, 1	1	0		142		
—	1048	E106	Display-off waiting time	0 to 60 min	1 min	0 min		142	
—	1049	E110	USB host reset	0, 1	1	0		143	



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Anti-sway control	1072	A310	DC brake judgment time for anti-sway control operation	0 to 10 s	0.1 s	3 s		143	
	1073	A311	Anti-sway control operation selection	0, 1	1	0		143	
	1074	A312	Anti-sway control frequency	0.05 to 3 Hz, 9999	0.001 Hz	1 Hz		143	
	1075	A313	Anti-sway control depth	0 to 3	1	0		143	
	1076	A314	Anti-sway control width	0 to 3	1	0		143	
	1077	A315	Rope length	0.1 to 50 m	0.1 m	1 m		143	
	1078	A316	Trolley weight	1 to 50000 kg	1 kg	1 kg		143	
1079	A317	Load weight	1 to 50000 kg	1 kg	1 kg		143		
—	1103	F040	Deceleration time at emergency stop	0 to 3600 s	0.1 s	5 s		143	
Monitor function	1106	M050	Torque monitor filter	0 to 5 s, 9999	0.01 s	9999		98	
	1107	M051	Running speed monitor filter	0 to 5 s, 9999	0.01 s	9999		98	
	1108	M052	Excitation current monitor filter	0 to 5 s, 9999	0.01 s	9999		98	
—	1113	H414	Speed limit method selection	0 to 2, 10, 9999	1	0		135	
—	1114	D403	Torque command reverse selection	0, 1	1	1		135	
—	1115	G218	Speed control integral term clear time	0 to 9998 ms	1 ms	0 s		136	
—	1116	G206	Constant output range speed control P gain compensation	0 to 100%	0.1%	0%		136	
—	1117	G261	Speed control P gain 1 (per-unit system)	0 to 300, 9999	0.01	9999		136	
—	1118	G361	Speed control P gain 2 (per-unit system)	0 to 300, 9999	0.01	9999		136	
—	1119	G262	Model speed control gain (per-unit system)	0 to 300, 9999	0.01	9999		137	
—	1121	G260	Per-unit speed control reference frequency	0 to 400 Hz	0.01 Hz	120 Hz *2	136, 137		
						60 Hz *3			
PID control	1134	A605	PID upper limit manipulated value	0 to 100%	0.1%	100%		113	
	1135	A606	PID lower limit manipulated value	0 to 100%	0.1%	100%		113	
	1136	A670	Second PID display bias coefficient	0 to 500, 9999	0.01	9999		113	
	1137	A671	Second PID display bias analog value	0 to 300%	0.1%	20%		113	
	1138	A672	Second PID display gain coefficient	0 to 500, 9999	0.01	9999		113	
	1139	A673	Second PID display gain analog value	0 to 300%	0.1%	100%		113	
	1140	A664	Second PID set point/deviation input selection	1 to 5	1	2		113	
	1141	A665	Second PID measured value input selection	1 to 5	1	3		113	
	1142	A640	Second PID unit selection	0 to 43, 9999	1	9999		113	
	1143	A641	Second PID upper limit	0 to 100%, 9999	0.1%	9999		113	
	1144	A642	Second PID lower limit	0 to 100%, 9999	0.1%	9999		113	
	1145	A643	Second PID deviation limit	0 to 100%, 9999	0.1%	9999		113	
	1146	A644	Second PID signal operation selection	0 to 3, 10 to 13	1	0		113	
	1147	A661	Second output interruption detection time	0 to 3600 s, 9999	0.1 s	1 s		113	
1148	A662	Second output interruption detection level	0 to 590 Hz	0.01 Hz	0 Hz		113		
1149	A663	Second output interruption cancel level	900 to 1100%	0.1%	1000%		113		
PLC function	1150 to 1199	A810 to A859	PLC function user parameters 1 to 50	0 to 65535	1	0		126	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
—	1220	B100	Parameter for manufacturer setting.						
Simple position control	1221	B101	Start command edge detection selection	0, 1	1	0		127	
	1222	B120	First positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1223	B121	First positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1224	B122	First positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1225	B123	First positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1226	B124	Second positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1227	B125	Second positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1228	B126	Second positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1229	B127	Second positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1230	B128	Third positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1231	B129	Third positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1232	B130	Third positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1233	B131	Third positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1234	B132	Fourth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1235	B133	Fourth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1236	B134	Fourth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1237	B135	Fourth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1238	B136	Fifth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1239	B137	Fifth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1240	B138	Fifth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1241	B139	Fifth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1242	B140	Sixth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1243	B141	Sixth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1244	B142	Sixth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
1245	B143	Sixth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127		
1246	B144	Seventh positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127		
1247	B145	Seventh positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127		
1248	B146	Seventh positioning dwell time	0 to 20000 ms	1 ms	0 ms		127		
1249	B147	Seventh positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127		
1250	B148	Eighth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127		
1251	B149	Eighth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127		
1252	B150	Eighth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127		
1253	B151	Eighth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127		
1254	B152	Ninth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127		



Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Simple position control	1255	B153	Ninth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1256	B154	Ninth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1257	B155	Ninth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1258	B156	Tenth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1259	B157	Tenth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1260	B158	Tenth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1261	B159	Tenth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1262	B160	Eleventh positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1263	B161	Eleventh positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1264	B162	Eleventh positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1265	B163	Eleventh positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1266	B164	Twelfth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1267	B165	Twelfth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1268	B166	Twelfth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1269	B167	Twelfth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1270	B168	Thirteenth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1271	B169	Thirteenth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1272	B170	Thirteenth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1273	B171	Thirteenth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1274	B172	Fourteenth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1275	B173	Fourteenth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1276	B174	Fourteenth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1277	B175	Fourteenth positioning sub-function	0, 1, 10, 11, 100, 101, 110, 111	1	10		127	
	1278	B176	Fifteenth positioning acceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1279	B177	Fifteenth positioning deceleration time	0.01 to 360 s	0.01 s	5 s		127	
	1280	B178	Fifteenth positioning dwell time	0 to 20000 ms	1 ms	0 ms		127	
	1281	B179	Fifteenth positioning sub-function	0, 10, 100, 110	1	10		127	
	1282	B180	Home position return method selection	0 to 6	1	4		127	
	1283	B181	Home position return speed	0 to 30 Hz	0.01 Hz	2 Hz		127	
	1284	B182	Home position return creep speed	0 to 10 Hz	0.01 Hz	0.5 Hz		127	
1285	B183	Home position shift amount lower 4 digits	0 to 9999	1	0		127		
1286	B184	Home position shift amount upper 4 digits	0 to 9999	1	0		127		
1287	B185	Travel distance after proximity dog ON lower 4 digits	0 to 9999	1	2048		127		
1288	B186	Travel distance after proximity dog ON upper 4 digits	0 to 9999	1	0		127		
1289	B187	Home position return stopper torque	0 to 200%	0.1%	40%		127		

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value		Refer to page	Customer setting
						FM	CA		
Simple position control	1290	B188	Home position return stopper waiting time	0 to 10 s	0.1 s	0.5 s		127	
	1292	B190	Position control terminal input selection	0, 1	1	0		127	
	1293	B191	Roll feeding mode selection	0, 1	1	0		127	
	1294	B192	Position detection lower 4 digits	0 to 9999	1	0		129	
	1295	B193	Position detection upper 4 digits	0 to 9999	1	0		129	
	1296	B194	Position detection selection	0 to 2	1	0		129	
	1297	B195	Position detection hysteresis width	0 to 32767	1	0		129	
—	1298	B013	Second position control gain	0 to 150 s <sup>-1</sup>	1 s <sup>-1</sup>	25 s <sup>-1</sup>		129	
—	1299	G108	Second pre-excitation selection	0, 1	1	0		92	
—	1300 to 1343, 1350 to 1359	N500 to N543, N550 to N559	Communication option parameters. For details, refer to the Instruction Manual of the option.						
Clear parameters	Pr.CLR	Parameter clear	(0), 1	1	0		140		
	ALL.CL	All parameter clear	(0), 1	1	0		140		
	Err.CL	Fault history clear	(0), 1	1	0		140		
—	Pr.CPY	Parameter copy	(0), 1 to 3	1	0		140		
—	Pr.CHG	Initial value change list	—	1	0		140		
—	IPM	IPM initialization	0, 3003	1	0		196		
—	AUTO	Automatic parameter setting	—	—	—		141		
—	Pr.MD	Group parameter setting	(0), 1, 2	1	0		51		

- \*1 Differ according to capacities.  
6%: FR-A820-00077(0.75K) or lower, FR-A840-00038(0.75K) or lower  
4%: FR-A820-00105(1.5K) to FR-A820-00250(3.7K), FR-A840-00052(1.5K) to FR-A840-00126(3.7K)  
3%: FR-A820-00340(5.5K), FR-A820-00490(7.5K), FR-A840-00170(5.5K), FR-A840-00250(7.5K)  
2%: FR-A820-00630(11K) to FR-A820-03160(55K), FR-A840-00310(11K) to FR-A840-01800(55K)  
1%: FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher
- \*2 The setting range or initial value for the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower.
- \*3 The setting range or initial value for the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher.
- \*4 The initial value for the FR-A820-00490(7.5K) or lower and FR-A840-00250(7.5K) or lower.
- \*5 The initial value for the FR-A820-00630(11K) or higher and FR-A840-00310(11K) or higher.
- \*6 Differ according to capacities.  
4%: FR-A820-00490(7.5K) or lower, FR-A840-00250(7.5K) or lower  
2%: FR-A820-00630(11K) to FR-A820-03160(55K), FR-A840-00310(11K) to FR-A840-01800(55K)  
1%: FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher
- \*7 The value for the 200 V class.
- \*8 The value for the 400 V class.
- \*9 The setting is available only when a vector control compatible option is installed.
- \*10 The setting is available only when the FR-A8AP is installed.
- \*11 The setting is available only when the FR-A8AP or the FR-A8APR is installed.
- \*12 The setting is available only when the FR-A8TP is installed.
- \*13 The setting is available only when the FR-A8AP or the FR-A8TP is installed.
- \*14 The parameter number in parentheses is the one for use with the LCD operation panel and the parameter unit.
- \*15 The setting range or initial value for the standard model.
- \*16 The setting range or initial value for the separated converter type.
- \*17 The setting range or initial value for the IP55 compatible model.
- \*18 The setting is available for the standard model only.
- \*19 The setting is available only for standard models and IP55 compatible models.
- \*20 The setting is available only with the 400 V class.



## ● Inverter parameter list (by function group)

### ◆ E: Environment setting parameters

Parameters that set the inverter operation characteristics.

Pr. group	Pr.	Name	Refer to page
E000	168	Parameter for manufacturer setting. Do not set.	
E001	169	Parameter for manufacturer setting. Do not set.	
E020	1006	Clock (year)	142
E021	1007	Clock (month, day)	142
E022	1008	Clock (hour, minute)	142
E023	269	Parameter for manufacturer setting. Do not set.	
E080	168	Parameter for manufacturer setting. Do not set.	
E081	169	Parameter for manufacturer setting. Do not set.	
E100	75	Reset selection	105
E101	75	Disconnected PU detection	105
E102	75	PU stop selection	105
E103	145	PU display language selection	114
E104	990	PU buzzer control	141
E105	991	PU contrast adjustment	141
E106	1048	Display-off waiting time	142
E107	75	Reset limit	105
E108	1000	Parameter for manufacturer setting. Do not set.	
E110	1049	USB host reset	143
E200	161	Frequency setting/key lock operation selection	115
E201	295	Frequency change increment amount setting	115
E300	30	Regenerative function selection	96
E301	570	Multiple rating setting	131
E302	977	Input voltage mode selection	140
E400	77	Parameter write selection	106
E410	296	Password lock level	124
E411	297	Password lock/unlock	124
E420	888	Free parameter 1	139
E421	889	Free parameter 2	139
E430	998	PM parameter initialization <i>Simple</i>	196
E431	999	Automatic parameter setting <i>Simple</i>	141
E440	160	User group read selection <i>Simple</i>	115
E441	172	User group registered display/batch clear	115
E442	173	User group registration	115
E443	174	User group clear	115
E490	989	Parameter copy alarm release	140
E600	72	PWM frequency selection	104
E601	240	Soft-PWM operation selection	104
E602	260	PWM frequency automatic switchover	104
E700	255	Life alarm status display	119
E701	256 *8	Inrush current limit circuit life display	119
E702	257	Control circuit capacitor life display	119
E703	258 *8	Main circuit capacitor life display	119
E704	259 *8	Main circuit capacitor life measuring	119
E710	503	Maintenance timer 1	130
E711	504	Maintenance timer 1 warning output set time	130
E712	686	Maintenance timer 2	130
E713	687	Maintenance timer 2 warning output set time	130
E714	688	Maintenance timer 3	130
E715	689	Maintenance timer 3 warning output set time	130

Pr. group	Pr.	Name	Refer to page
E720	555	Current average time	130
E721	556	Data output mask time	130
E722	557	Current average value monitor signal output reference current	130

### ◆ F: Setting of acceleration/deceleration time and acceleration/deceleration pattern

Parameters that set the motor acceleration/deceleration characteristics.

Pr. group	Pr.	Name	Refer to page
F000	20	Acceleration/deceleration reference frequency	91
F001	21	Acceleration/deceleration time increments	91
F002	16	Jog acceleration/deceleration time	93
F003	611	Acceleration time at a restart	100
F010	7	Acceleration time <i>Simple</i>	91
F011	8	Deceleration time <i>Simple</i>	91
F020	44	Second acceleration/deceleration time	91
F021	45	Second deceleration time	91
F022	147	Acceleration/deceleration time switching frequency	91
F030	110	Third acceleration/deceleration time	91
F031	111	Third deceleration time	91
F040	1103	Deceleration time at emergency stop	143
F070	791	Acceleration time in low-speed range	91
F071	792	Deceleration time in low-speed range	91
F100	29	Acceleration/deceleration pattern selection	95
F101	59	Remote function selection	102
F102	13	Starting frequency	93
F103	571	Holding time at a start	93
F200	140	Backlash acceleration stopping frequency	95
F201	141	Backlash acceleration stopping time	95
F202	142	Backlash deceleration stopping frequency	95
F203	143	Backlash deceleration stopping time	95
F300	380	Acceleration S-pattern 1	95
F301	381	Deceleration S-pattern 1	95
F302	382	Acceleration S-pattern 2	95
F303	383	Deceleration S-pattern 2	95
F400	516	S-pattern time at a start of acceleration	95
F401	517	S-pattern time at a completion of acceleration	95
F402	518	S-pattern time at a start of deceleration	95
F403	519	S-pattern time at a completion of deceleration	95
F500	292	Automatic acceleration/deceleration	102
F510	61	Reference current	102
F511	62	Reference value at acceleration	102
F512	63	Reference value at deceleration	102
F513	293	Acceleration/deceleration separate selection	102
F520	64	Starting frequency for elevator mode	102

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

### ◆ D: Operation command and frequency command

Parameters that specify the inverter's command source, and parameters that set the motor driving frequency and torque.

Pr. group	Pr.	Name	Refer to page
D000	79	Operation mode selection <i>Simple</i>	107
D001	340	Communication startup mode selection	107
D010	338	Communication operation command source	125
D011	339	Communication speed command source	125
D012	550	NET mode operation command source selection	125
D013	551	PU mode operation command source selection	125
D020	78	Reverse rotation prevention selection	106
D030	811	Set resolution switchover	95, 97
D100	291	Pulse train I/O selection	124
D101	384	Input pulse division scaling factor	124
D110	385	Frequency for zero input pulse	124
D111	386	Frequency for maximum input pulse	124
D200	15	Jog frequency	93
D300	28	Multi-speed input compensation selection	91
D301	4	Multi-speed setting (high speed) <i>Simple</i>	91
D302	5	Multi-speed setting (middle speed) <i>Simple</i>	91
D303	6	Multi-speed setting (low speed) <i>Simple</i>	91
D304 to D307	24 to 27	Multi-speed setting (4 speed to 7 speed)	91
D308 to D315	232 to 239	Multi-speed setting (8 speed to 15 speed)	91
D400	804	Torque command source selection	95, 135
D401	805	Torque command value (RAM)	95, 135
D402	806	Torque command value (RAM, EEPROM)	95, 135
D403	1114	Torque command reverse selection	135

### ◆ H: Protective function parameter

Parameters to protect the motor and the inverter.

Pr. group	Pr.	Name	Refer to page
H000	9	Electronic thermal O/L relay <i>Simple</i>	92
H001	600	First free thermal reduction frequency 1	92
H002	601	First free thermal reduction ratio 1	92
H003	602	First free thermal reduction frequency 2	92
H004	603	First free thermal reduction ratio 2	92
H005	604	First free thermal reduction frequency 3	92
H006	607	Motor permissible load level	92
H010	51	Second electronic thermal O/L relay	92
H011	692	Second free thermal reduction frequency 1	92
H012	693	Second free thermal reduction ratio 1	92
H013	694	Second free thermal reduction frequency 2	92
H014	695	Second free thermal reduction ratio 2	92
H015	696	Second free thermal reduction frequency 3	92
H016	608	Second motor permissible load level	92
H020	561	PTC thermistor protection level	92

Pr. group	Pr.	Name	Refer to page
H021	1016	PTC thermistor protection detection time	92
H022	876 *4	Thermal protector input	92
H030	875	Fault definition	138
H100	244	Cooling fan operation selection	118
H101	249	Earth (ground) fault detection at start	118
H102	598 *9	Undervoltage level	131
H103	997	Fault initiation	141
H200	251	Output phase loss protection selection	119
H201	872 *8	Input phase loss protection selection	119
H300	65	Retry selection	103
H301	67	Number of retries at fault occurrence	103
H302	68	Retry waiting time	103
H303	69	Retry count display erase	103
H400	1	Maximum frequency <i>Simple</i>	90
H401	2	Minimum frequency <i>Simple</i>	90
H402	18	High speed maximum frequency	90
H410	807	Speed limit selection	135
H411	808	Forward rotation speed limit/speed limit	135
H412	809	Reverse rotation speed limit/reverse-side speed limit	135
H414	1113	Speed limit method selection	135
H415	873 *5	Speed limit	123
H416	285	Speed deviation excess detection frequency	121, 123
H417	853 *1	Speed deviation time	123
H420	31	Frequency jump 1A	97
H421	32	Frequency jump 1B	97
H422	33	Frequency jump 2A	97
H423	34	Frequency jump 2B	97
H424	35	Frequency jump 3A	97
H425	36	Frequency jump 3B	97
H429	552	Frequency jump range	97
H500	22	Stall prevention operation level (Torque limit level)	94
H501	156	Stall prevention operation selection	94
H600	48	Second stall prevention operation level	94
H601	49	Second stall prevention operation frequency	94
H602	114	Third stall prevention operation level	94
H603	115	Third stall prevention operation frequency	94
H610	23	Stall prevention operation level compensation factor at double speed	94
H611	66	Stall prevention operation reduction starting frequency	94
H620	148	Stall prevention level at 0 V input	94
H621	149	Stall prevention level at 10 V input	94
H631	154	Voltage reduction selection during stall prevention operation	94
H700	810	Torque limit input method selection	95
H701	812	Torque limit level (regeneration)	95
H702	813	Torque limit level (3rd quadrant)	95
H703	814	Torque limit level (4th quadrant)	95
H710	815	Torque limit level 2	95
H720	816	Torque limit level during acceleration	95
H721	817	Torque limit level during deceleration	95
H730	874	OLT level setting	95
H800	374	Overspeed detection level	126
H881	690	Deceleration check time	133

### ◆ M: Monitor display and monitor output signal

Parameters regarding the inverter's operating status. These parameters are used to set the monitors and output signals.

Pr. group	Pr.	Name	Refer to page
M000	37	Speed display	97
M001	505	Speed setting reference	97
M002	144	Speed setting switchover	97
M020	170	Watt-hour meter clear	98
M021	563	Energization time carrying-over times	98
M022	268	Monitor decimal digits selection	98
M023	891	Cumulative power monitor digit shifted times	98, 139
M030	171	Operation hour meter clear	98
M031	564	Operating time carrying-over times	98
M040	55	Frequency monitoring reference	100
M041	56	Current monitoring reference	100
M042	866	Torque monitoring reference	100
M043	241	Analog input display unit switchover	112
M044	290	Monitor negative output selection	98
M045	1018	Monitor with sign selection	98
M050	1106	Torque monitor filter	98
M051	1107	Running speed monitor filter	98
M052	1108	Excitation current monitor filter	98
M060	663	Control circuit temperature signal output level	133
M100	52	Operation panel main monitor selection	98
M101	774	Operation panel monitor selection 1	98
M102	775	Operation panel monitor selection 2	98
M103	776	Operation panel monitor selection 3	98
M104	992	Operation panel setting dial push monitor selection	98
M200	892	Load factor	139
M201	893	Energy saving monitor reference (motor capacity)	139
M202	894	Control selection during commercial power-supply operation	139
M203	895	Power saving rate reference value	139
M204	896	Power unit cost	139
M205	897	Power saving monitor average time	139
M206	898	Power saving cumulative monitor clear	139
M207	899	Operation time rate (estimated value)	139
M300	54	FM/CA terminal function selection	98
M301	158	AM terminal function selection	98
M310	C0 (900) *6	FM/CA terminal calibration	140
M320	C1 (901) *6	AM terminal calibration	140
M321	867	AM output filter	140
M330	C8 (930) *6	Current output bias signal	140
M331	C9 (930) *6	Current output bias current	140
M332	C10 (931) *6	Current output gain signal	140
M333	C11 (931) *6	Current output gain current	140
M334	869	Current output filter	140

Pr. group	Pr.	Name	Refer to page
M400	190	RUN terminal function selection	117
M401	191	SU terminal function selection	117
M402	192	IPF terminal function selection	117
M403	193	OL terminal function selection	117
M404	194	FU terminal function selection	117
M405	195	ABC1 terminal function selection	117
M406	196	ABC2 terminal function selection	117
M430	157	OL signal output timer	94
M431	289	Inverter output terminal filter	117
M433	166	Output current detection signal retention time	114
M440	870	Speed detection hysteresis	97
M441	41	Up-to-frequency sensitivity	97
M442	42	Output frequency detection	97
M443	43	Output frequency detection for reverse rotation	97
M444	50	Second output frequency detection	97
M445	116	Third output frequency detection	97
M446	865	Low speed detection	97
M460	150	Output current detection level	114
M461	151	Output current detection signal delay time	114
M462	152	Zero current detection level	114
M463	153	Zero current detection time	114
M464	167	Output current detection operation selection	114
M470	864	Torque detection	138
M500	495	Remote output selection	129
M501	496	Remote output data 1	129
M502	497	Remote output data 2	129
M510	76	Fault code output selection	106
M520	799	Pulse increment setting for output power	134
M530	655	Analog remote output selection	132
M531	656	Analog remote output 1	132
M532	657	Analog remote output 2	132
M533	658	Analog remote output 3	132
M534	659	Analog remote output 4	132
M600	863 *4	Control terminal option-Encoder pulse division ratio	138
M610	635 *1	Cumulative pulse clear signal selection	128
M611	636 *1	Cumulative pulse division scaling factor	128
M612	637 *1	Control terminal option-Cumulative pulse division scaling factor	128
M613	638 *1	Cumulative pulse storage	128

### ◆ T: Multi-function input terminal parameters

Parameters for the input terminals where inverter commands are received through.

Pr. group	Pr.	Name	Refer to page
T000	73	Analog input selection	104
T001	267	Terminal 4 input selection	104
T002	74	Input filter time constant	105
T003	822	Speed setting filter 1	105
T004	826	Torque setting filter 1	105
T005	832	Speed setting filter 2	105
T006	836	Torque setting filter 2	105
T007	849	Analog input offset adjustment	105
T010	868	Terminal 1 function assignment	138
T021	242	Terminal 1 added compensation amount (terminal 2)	104
T022	125	Terminal 2 frequency setting gain frequency <i>Simple</i>	112

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Pr. group	Pr.	Name	Refer to page
T040	858	Terminal 4 function assignment	138
T041	243	Terminal 1 added compensation amount (terminal 4)	104
T042	126	Terminal 4 frequency setting gain frequency <i>Simple</i>	112
T050	252	Override bias	104
T051	253	Override gain	104
T052	573	4 mA input check selection	131
T053	777	4 mA input check operation frequency	131
T054	778	4 mA input check filter	131
T100	C12 (917) *6	Terminal 1 bias frequency (speed)	112
T101	C13 (917) *6	Terminal 1 bias (speed)	112
T102	C14 (918) *6	Terminal 1 gain frequency (speed)	112
T103	C15 (918) *6	Terminal 1 gain (speed)	112
T110	C16 (919) *6	Terminal 1 bias command (torque)	112
T111	C17 (919) *6	Terminal 1 bias (torque)	112
T112	C18 (920) *6	Terminal 1 gain command (torque)	112
T113	C19 (920) *6	Terminal 1 gain (torque)	112
T200	C2 (902) *6	Terminal 2 frequency setting bias frequency	112
T201	C3 (902) *6	Terminal 2 frequency setting bias	112
T202	125 (903) *6	Terminal 2 frequency setting gain frequency	112
T203	C4 (903) *6	Terminal 2 frequency setting gain	112
T400	C5 (904) *6	Terminal 4 frequency setting bias frequency	112
T401	C6 (904) *6	Terminal 4 frequency setting bias	112
T402	126 (905) *6	Terminal 4 frequency setting gain frequency	112
T403	C7 (905) *6	Terminal 4 frequency setting gain	112
T410	C38 (932) *6	Terminal 4 bias command (torque)	112

Pr. group	Pr.	Name	Refer to page
T411	C39 (932) *6	Terminal 4 bias (torque)	112
T412	C40 (933) *6	Terminal 4 gain command (torque)	112
T413	C41 (933) *6	Terminal 4 gain (torque)	112
T700	178	STF terminal function selection	116
T701	179	STR terminal function selection	116
T702	180	RL terminal function selection	116
T703	181	RM terminal function selection	116
T704	182	RH terminal function selection	116
T705	183	RT terminal function selection	116
T706	184	AU terminal function selection	116
T707	185	JOG terminal function selection	116
T708	186	CS terminal function selection	116
T709	187	MRS terminal function selection	116
T710	188	STOP terminal function selection	116
T711	189	RES terminal function selection	116
T720	17	MRS input selection	94
T721	599	X10 terminal input selection	96
T722	606	Power failure stop external signal input selection	119
T730	155	RT signal function validity condition selection	115
T740	699	Input terminal filter	116

#### ◆ C: Motor constant parameters

Parameters for the applied motor setting.

Pr. group	Pr.	Name	Refer to page
C000	684	Tuning data unit switchover	109
C100	71	Applied motor	103
C101	80	Motor capacity	108
C102	81	Number of motor poles	108
C103	9	Rated motor current <i>Simple</i>	92
C104	83	Rated motor voltage	109
C105	84	Rated motor frequency	109
C106	702	Maximum motor frequency	109
C107	707	Motor inertia (integer)	109
C108	724	Motor inertia (exponent)	109
C110	96	Auto tuning setting/status	109
C111	95	Online auto tuning selection	110
C112	818	Easy gain tuning response level setting	136
C113	819	Easy gain tuning selection	136
C114	880	Load inertia ratio	137
C120	90	Motor constant (R1)	109
C121	91	Motor constant (R2)	109
C122	92	Motor constant (L1)/d-axis inductance (Ld)	109
C123	93	Motor constant (L2)/q-axis inductance (Lq)	109
C124	94	Motor constant (X)	109
C125	82	Motor excitation current	109
C126	859	Torque current/Rated PM motor current	109
C130	706	Induced voltage constant (phi f)	109
C131	711	Motor Ld decay ratio	109
C132	712	Motor Lq decay ratio	109
C133	725	Motor protection current level	109
C140	369 *2	Number of encoder pulses	126
C141	359 *3	Encoder rotation direction	125





Pr. group	Pr.	Name	Refer to page
C148	376 *3	Encoder signal loss detection enable/disable selection	126
C150	1002	Lq tuning target current adjustment coefficient	109
C182	717	Starting resistance tuning compensation	109
C185	721	Starting magnetic pole position detection pulse width	109
C200	450	Second applied motor	103
C201	453	Second motor capacity	108
C202	454	Number of second motor poles	108
C203	51	Rated second motor current	92
C204	456	Rated second motor voltage	109
C205	457	Rated second motor frequency	109
C206	743	Second motor maximum frequency	109
C207	744	Second motor inertia (integer)	109
C208	745	Second motor inertia (exponent)	109
C210	463	Second motor auto tuning setting/status	109
C211	574	Second motor online auto tuning	110
C220	458	Second motor constant (R1)	109
C221	459	Second motor constant (R2)	109
C222	460	Second motor constant (L1) / d-axis inductance (Ld)	109
C223	461	Second motor constant (L2) / q-axis inductance (Lq)	109
C224	462	Second motor constant (X)	109
C225	455	Second motor excitation current	109
C226	860	Second motor torque current/Rated PM motor current	109
C230	738	Second motor induced voltage constant (phi f)	109
C231	739	Second motor Ld decay ratio	109
C232	740	Second motor Lq decay ratio	109
C233	746	Second motor protection current level	109
C240	851 *4	Control terminal option-Number of encoder pulses	125
C241	852 *4	Control terminal option-Encoder rotation direction	125
C242	862 *1	Encoder option selection	125
C248	855 *4	Control terminal option-Signal loss detection enable/disable selection	125
C282	741	Second starting resistance tuning compensation	109
C285	742	Second motor magnetic pole detection pulse width	109

### ◆ A: Application parameters

Parameters to set a specific application.

Pr. group	Pr.	Name	Refer to page
A000	135	Electronic bypass sequence selection	114
A001	136	MC switchover interlock time	114
A002	137	Start waiting time	114
A003	138	Bypass selection at a fault	114
A004	139	Automatic switchover frequency from inverter to bypass operation	114
A005	159	Automatic switchover frequency range from bypass to inverter operation	114
A006	248	Self power management selection	118
A007	254	Main circuit power OFF waiting time	118
A100	278	Brake opening frequency	121
A101	279	Brake opening current	121
A102	280	Brake opening current detection time	121
A103	281	Brake operation time at start	121
A104	282	Brake operation frequency	121
A105	283	Brake operation time at stop	121

Pr. group	Pr.	Name	Refer to page
A106	284	Deceleration detection function selection	121
A107	285	Overspeed detection frequency	121, 123
A108	639	Brake opening current selection	121
A109	640	Brake operation frequency selection	121
A110	292	Automatic acceleration/deceleration	102
A120	642	Second brake opening frequency	121
A121	643	Second brake opening current	121
A122	644	Second brake opening current detection time	121
A123	645	Second brake operation time at start	121
A124	646	Second brake operation frequency	121
A125	647	Second brake operation time at stop	121
A126	648	Second deceleration detection function selection	121
A128	650	Second brake opening current selection	121
A129	651	Second brake operation frequency selection	121
A130	641	Second brake sequence operation selection	121
A200	270	Stop-on contact/load torque high-speed frequency control selection	120
A201	271	High-speed setting maximum current	120
A202	272	Middle-speed setting minimum current	120
A203	273	Current averaging range	120
A204	274	Current averaging filter time constant	120
A205	275	Stop-on contact excitation current low-speed multiplying factor	121
A206	276	PWM carrier frequency at stop-on contact	121
A300	592	Traverse function selection	131
A301	593	Maximum amplitude amount	131
A302	594	Amplitude compensation amount during deceleration	131
A303	595	Amplitude compensation amount during acceleration	131
A304	596	Amplitude acceleration time	131
A305	597	Amplitude deceleration time	131
A310	1072	DC brake judgment time for anti-sway control operation	143
A311	1073	Anti-sway control operation selection	143
A312	1074	Anti-sway control frequency	143
A313	1075	Anti-sway control depth	143
A314	1076	Anti-sway control width	143
A315	1077	Rope length	143
A316	1078	Trolley weight	143
A317	1079	Load weight	143
A510	350 *1	Stop position command selection	125
A511	360 *1	16-bit data selection	125
A512	361 *1	Position shift	125
A520	362 *1	Orientation position loop gain	125
A521	363 *1	Completion signal output delay time	125
A522	364 *1	Encoder stop check time	125
A523	365 *1	Orientation limit	125
A524	366 *1	Recheck time	125
A525	393 *1	Orientation selection	126
A526	351 *1	Orientation speed	125
A527	352 *1	Creep speed	125
A528	353 *1	Creep switchover position	125
A529	354 *1	Position loop switchover position	125
A530	355 *1	DC injection brake start position	125
A531	356 *1	Internal stop position command	125
A532	357 *1	Orientation in-position zone	125
A533	358 *1	Servo torque selection	125

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LV/S/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



Pr. group	Pr.	Name	Refer to page
A540	394 *1	Number of machine side gear teeth	125
A541	395 *1	Number of motor side gear teeth	125
A542	396 *1	Orientation speed gain (P term)	126
A543	397 *1	Orientation speed integral time	126
A544	398 *1	Orientation speed gain (D term)	126
A545	399 *1	Orientation deceleration ratio	126
A600	759	PID unit selection	113
A601	131	PID upper limit	113
A602	132	PID lower limit	113
A603	553	PID deviation limit	113
A604	554	PID signal operation selection	113
A605	1134	PID upper limit manipulated value	113
A606	1135	PID lower limit manipulated value	113
A607	1015	Integral stop selection at limited frequency	113
A610	128	PID action selection	113
A611	133	PID action set point	113
A612	127	PID control automatic switchover frequency	113
A613	129	PID proportional band	113
A614	130	PID integral time	113
A615	134	PID differential time	113
A616	760	Pre-charge fault selection	134
A617	761	Pre-charge ending level	134
A618	762	Pre-charge ending time	134
A619	763	Pre-charge upper detection level	134
A620	764	Pre-charge time limit	134
A621	575	Output interruption detection time	113
A622	576	Output interruption detection level	113
A623	577	Output interruption cancel level	113
A624	609	PID set point/deviation input selection	113
A625	610	PID measured value input selection	113
A630	C42 (934) *6	PID display bias coefficient	113
A631	C43 (934) *6	PID display bias analog value	113
A632	C44 (935) *6	PID display gain coefficient	113
A633	C45 (935) *6	PID display gain analog value	113
A640	1142	Second PID unit selection	113
A641	1143	Second PID upper limit	113
A642	1144	Second PID lower limit	113
A643	1145	Second PID deviation limit	113
A644	1146	Second PID signal operation selection	113
A650	753	Second PID action selection	113
A651	755	Second PID action set point	113
A652	754	Second PID control automatic switchover frequency	113
A653	756	Second PID proportional band	113
A654	757	Second PID integral time	113
A655	758	Second PID differential time	113
A656	765	Second pre-charge fault selection	134
A657	766	Second pre-charge ending level	134
A658	767	Second pre-charge ending time	134
A659	768	Second pre-charge upper detection level	134

Pr. group	Pr.	Name	Refer to page
A660	769	Second pre-charge time limit	134
A661	1147	Second output interruption detection time	113
A662	1148	Second output interruption detection level	113
A663	1149	Second output interruption cancel level	113
A664	1140	Second PID set point/deviation input selection	113
A665	1141	Second PID measured value input selection	113
A670	1136	Second PID display bias coefficient	113
A671	1137	Second PID display bias analog value	113
A672	1138	Second PID display gain coefficient	113
A673	1139	Second PID display gain analog value	113
A680	573	4 mA input check selection	131
A681	777	4 mA input check operation frequency	131
A682	778	4 mA input check filter	131
A700	162	Automatic restart after instantaneous power failure selection	100
A701	299	Rotation direction detection selection at restarting	100
A702	57	Restart coasting time	100
A703	58	Restart cushion time	100
A704	163	First cushion time for restart	100
A705	164	First cushion voltage for restart	100
A710	165	Stall prevention operation level for restart	100
A711	298	Frequency search gain	109
A712	560	Second frequency search gain	109
A730	261	Power failure stop selection	119
A731	262	Subtracted frequency at deceleration start	119
A732	263	Subtraction starting frequency	119
A733	264	Power-failure deceleration time 1	119
A734	265	Power-failure deceleration time 2	119
A735	266	Power failure deceleration time switchover frequency	119
A785	294	UV avoidance voltage gain	119
A786	668	Power failure stop frequency gain	119
A800	414	PLC function operation selection	126
A801	415	Inverter operation lock mode setting	126
A802	416	Pre-scale function selection	126
A803	417	Pre-scale setting value	126
A804	498	PLC function flash memory clear	126
A810 to A859	1150 to 1199	PLC function user parameters 1 to 50	126
A900	1020	Trace operation selection	142
A901	1021	Trace mode selection	142
A902	1022	Sampling cycle	142
A903	1023	Number of analog channels	142
A904	1024	Sampling auto start	142
A905	1025	Trigger mode selection	142
A906	1026	Number of sampling before trigger	142
A910	1027	Analog source selection (1ch)	142
A911	1028	Analog source selection (2ch)	142
A912	1029	Analog source selection (3ch)	142
A913	1030	Analog source selection (4ch)	142
A914	1031	Analog source selection (5ch)	142
A915	1032	Analog source selection (6ch)	142

Pr. group	Pr.	Name	Refer to page
A916	1033	Analog source selection (7ch)	142
A917	1034	Analog source selection (8ch)	142
A918	1035	Analog trigger channel	142
A919	1036	Analog trigger operation selection	142
A920	1037	Analog trigger level	142
A930	1038	Digital source selection (1ch)	142
A931	1039	Digital source selection (2ch)	142
A932	1040	Digital source selection (3ch)	142
A933	1041	Digital source selection (4ch)	142
A934	1042	Digital source selection (5ch)	142
A935	1043	Digital source selection (6ch)	142
A936	1044	Digital source selection (7ch)	142
A937	1045	Digital source selection (8ch)	142
A938	1046	Digital trigger channel	142
A939	1047	Digital trigger operation selection	142

### ◆ B: Position control parameters

Parameters for the position control setting.

Pr. group	Pr.	Name	Refer to page
B000	419	Position command source selection	127, 128
B001	420	Command pulse scaling factor numerator (electronic gear numerator)	128
B002	421	Command pulse multiplication denominator (electronic gear denominator)	128
B003	422	Position control gain	129
B004	423	Position feed forward gain	129
B005	424	Position command acceleration/ deceleration time constant	128
B006	425	Position feed forward command filter	129
B007	426	In-position width	129
B008	427	Excessive level error	129
B009	428	Command pulse selection	128
B010	429	Clear signal selection	128
B011	430	Pulse monitor selection	128
B012	446	Model position control gain	128
B013	1298	Second position control gain	129
B020	464	Digital position control sudden stop deceleration time	127
B021	465	First target position lower 4 digits	127
B022	466	First target position upper 4 digits	127
B023	467	Second target position lower 4 digits	127
B024	468	Second target position upper 4 digits	127
B025	469	Third target position lower 4 digits	127
B026	470	Third target position upper 4 digits	127
B027	471	Fourth target position lower 4 digits	127
B028	472	Fourth target position upper 4 digits	127
B029	473	Fifth target position lower 4 digits	127
B030	474	Fifth target position upper 4 digits	127
B031	475	Sixth target position lower 4 digits	127
B032	476	Sixth target position upper 4 digits	127
B033	477	Seventh target position lower 4 digits	127
B034	478	Seventh target position upper 4 digits	127
B035	479	Eighth target position lower 4 digits	127
B036	480	Eighth target position upper 4 digits	127
B037	481	Ninth target position lower 4 digits	127
B038	482	Ninth target position upper 4 digits	127
B039	483	Tenth target position lower 4 digits	127

Pr. group	Pr.	Name	Refer to page
B040	484	Tenth target position upper 4 digits	127
B041	485	Eleventh target position lower 4 digits	127
B042	486	Eleventh target position upper 4 digits	127
B043	487	Twelfth target position lower 4 digits	127
B044	488	Twelfth target position upper 4 digits	127
B045	489	Thirteenth target position lower 4 digits	127
B046	490	Thirteenth target position upper 4 digits	127
B047	491	Fourteenth target position lower 4 digits	127
B048	492	Fourteenth target position upper 4 digits	127
B049	493	Fifteenth target position lower 4 digits	127
B050	494	Fifteenth target position upper 4 digits	127
B100	1220	Parameter for manufacturer setting.	
B101	1221	Start command edge detection selection	127
B120	1222	First positioning acceleration time	127
B121	1223	First positioning deceleration time	127
B122	1224	First positioning dwell time	127
B123	1225	First positioning sub-function	127
B124	1226	Second positioning acceleration time	127
B125	1227	Second positioning deceleration time	127
B126	1228	Second positioning dwell time	127
B127	1229	Second positioning sub-function	127
B128	1230	Third positioning acceleration time	127
B129	1231	Third positioning deceleration time	127
B130	1232	Third positioning dwell time	127
B131	1233	Third positioning sub-function	127
B132	1234	Fourth positioning acceleration time	127
B133	1235	Fourth positioning deceleration time	127
B134	1236	Fourth positioning dwell time	127
B135	1237	Fourth positioning sub-function	127
B136	1238	Fifth positioning acceleration time	127
B137	1239	Fifth positioning deceleration time	127
B138	1240	Fifth positioning dwell time	127
B139	1241	Fifth positioning sub-function	127
B140	1242	Sixth positioning acceleration time	127
B141	1243	Sixth positioning deceleration time	127
B142	1244	Sixth positioning dwell time	127
B143	1245	Sixth positioning sub-function	127
B144	1246	Seventh positioning acceleration time	127
B145	1247	Seventh positioning deceleration time	127
B146	1248	Seventh positioning dwell time	127
B147	1249	Seventh positioning sub-function	127
B148	1250	Eighth positioning acceleration time	127
B149	1251	Eighth positioning deceleration time	127
B150	1252	Eighth positioning dwell time	127
B151	1253	Eighth positioning sub-function	127
B152	1254	Ninth positioning acceleration time	127
B153	1255	Ninth positioning deceleration time	127
B154	1256	Ninth positioning dwell time	127
B155	1257	Ninth positioning sub-function	127
B156	1258	Tenth positioning acceleration time	127
B157	1259	Tenth positioning deceleration time	127

Features  
Application Example  
PLC Function  
FR Configurator2  
Connection  
Examples  
Standard  
Specs  
Outline  
Dimensions  
Terminal Connection  
Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations  
of  
Parameters  
Protective  
Functions  
Options  
LV/S/Cables  
Precautions  
Motors  
Compatibility  
Warranty  
Inquiry

Pr. group	Pr.	Name	Refer to page
B158	1260	Tenth positioning dwell time	127
B159	1261	Tenth positioning sub-function	127
B160	1262	Eleventh positioning acceleration time	127
B161	1263	Eleventh positioning deceleration time	127
B162	1264	Eleventh positioning dwell time	127
B163	1265	Eleventh positioning sub-function	127
B164	1266	Twelfth positioning acceleration time	127
B165	1267	Twelfth positioning deceleration time	127
B166	1268	Twelfth positioning dwell time	127
B167	1269	Twelfth positioning sub-function	127
B168	1270	Thirteenth positioning acceleration time	127
B169	1271	Thirteenth positioning deceleration time	127
B170	1272	Thirteenth positioning dwell time	127
B171	1273	Thirteenth positioning sub-function	127
B172	1274	Fourteenth positioning acceleration time	127
B173	1275	Fourteenth positioning deceleration time	127
B174	1276	Fourteenth positioning dwell time	127
B175	1277	Fourteenth positioning sub-function	127
B176	1278	Fifteenth positioning acceleration time	127
B177	1279	Fifteenth positioning deceleration time	127
B178	1280	Fifteenth positioning dwell time	127
B179	1281	Fifteenth positioning sub-function	127
B180	1282	Home position return method selection	127
B181	1283	Home position return speed	127
B182	1284	Home position return creep speed	127
B183	1285	Home position shift amount lower 4 digits	127
B184	1286	Home position shift amount upper 4 digits	127
B185	1287	Travel distance after proximity dog ON lower 4 digits	127
B186	1288	Travel distance after proximity dog ON upper 4 digits	127
B187	1289	Home position return stopper torque	127
B188	1290	Home position return stopper waiting time	127
B190	1292	Position control terminal input selection	127
B191	1293	Roll feeding mode selection	127
B192	1294	Position detection lower 4 digits	129
B193	1295	Position detection upper 4 digits	129
B194	1296	Position detection selection	129
B195	1297	Position detection hysteresis width	129

#### ◆ N: Operation via communication and its settings

Parameters for communication operation. These parameters set the communication specifications and operation.

Pr. group	Pr.	Name	Refer to page
N000	549	Protocol selection	111
N001	342	Communication EEPROM write selection	111
N002	539	MODBUS RTU communication check time interval	111
N013	502	Stop mode selection at communication error	126

Pr. group	Pr.	Name	Refer to page
N014	779	Operation frequency during communication error	111
N020	117	PU communication station number	111
N021	118	PU communication speed	111
N022	119	PU communication data length	111
N023	119	PU communication stop bit length	111
N024	120	PU communication parity check	111
N025	121	Number of PU communication retries	111
N026	122	PU communication check time interval	111
N027	123	PU communication waiting time setting	111
N028	124	PU communication CR/LF selection	111
N030	331	RS-485 communication station number	111
N031	332	RS-485 communication speed	111
N032	333	PU communication data length	111
N033	333	PU communication stop bit length	111
N034	334	RS-485 communication parity check selection	111
N035	335	RS-485 communication retry count	111
N036	336	RS-485 communication check time interval	111
N037	337	RS-485 communication waiting time setting	111
N038	341	RS-485 communication CR/LF selection	111
N040	547	USB communication station number	130
N041	548	USB communication check time interval	130
N080	343	Communication error count	111
N500 to N543, N550 to N559	1300 to 1343, 1350 to 1359	Communication option parameters. For details, refer to the Instruction Manual of the option.	

#### ◆ G: Control Parameters

Parameters for motor control.

Pr. group	Pr.	Name	Refer to page
G000	0	Torque boost <i>Simple</i>	90
G001	3	Base frequency <i>Simple</i>	90
G002	19	Base frequency voltage	90
G003	14	Load pattern selection	93
G010	46	Second torque boost	90
G011	47	Second V/F (base frequency)	90
G020	112	Third torque boost	90
G021	113	Third V/F (base frequency)	90
G030	60	Energy saving control selection	102
G040	100	V/F1 (first frequency)	110
G041	101	V/F1 (first frequency voltage)	110
G042	102	V/F2 (second frequency)	110
G043	103	V/F2 (second frequency voltage)	110
G044	104	V/F3 (third frequency)	110
G045	105	V/F3 (third frequency voltage)	110
G046	106	V/F4 (fourth frequency)	110
G047	107	V/F4 (fourth frequency voltage)	110
G048	108	V/F5 (fifth frequency)	110
G049	109	V/F5 (fifth frequency voltage)	110
G060	673	SF-PR slip amount adjustment operation selection	133
G061	674	SF-PR slip amount adjustment gain	133
G100	10	DC injection brake operation frequency	92
G101	11	DC injection brake operation time	92
G102	802	Pre-excitation selection	92
G103	850	Brake operation selection	92



Pr. group	Pr.	Name	Refer to page
G105	522	Output stop frequency	130
G106	250	Stop selection	118
G107	70 *7	Special regenerative brake duty	96
G108	1299	Second pre-excitation selection	92
G110	12	DC injection brake operation voltage	92
G120	882	Regeneration avoidance operation selection	139
G121	883	Regeneration avoidance operation level	139
G122	884	Regeneration avoidance at deceleration detection sensitivity	139
G123	885	Regeneration avoidance compensation frequency limit value	139
G124	886	Regeneration avoidance voltage gain	139
G125	665	Regeneration avoidance frequency gain	139
G130	660	Increased magnetic excitation deceleration operation selection	133
G131	661	Magnetic excitation increase rate	133
G132	662	Increased magnetic excitation current level	133
G200	800	Control method selection	108
G203	245	Rated slip	118
G204	246	Slip compensation time constant	118
G205	247	Constant-power range slip compensation selection	118
G206	1116	Constant output range speed control P gain compensation	136
G210	803	Constant output range torque characteristic selection	95, 135
G211	820	Speed control P gain 1	136
G212	821	Speed control integral time 1	136
G213	824	Torque control P gain 1 (current loop proportional gain)	136
G214	825	Torque control integral time 1 (current loop integral time)	136
G215	823 *1	Speed detection filter 1	136
G216	827	Torque detection filter 1	136
G217	854	Excitation ratio	138
G218	1115	Speed control integral term clear time	136
G220	877	Speed feed forward control/model adaptive speed control selection	137
G221	878	Speed feed forward filter	137
G222	879	Speed feed forward torque limit	137
G223	881	Speed feed forward gain	137
G224	828	Model speed control gain	137
G230	840	Torque bias selection	137
G231	841	Torque bias 1	137
G232	842	Torque bias 2	137
G233	843	Torque bias 3	137
G234	844	Torque bias filter	137
G235	845	Torque bias operation time	137
G236	846	Torque bias balance compensation	137
G237	847	Fall-time torque bias terminal 1 bias	137
G238	848	Fall-time torque bias terminal 1 gain	137
G240	367 *1	Speed feedback range	126
G241	368 *1	Feedback gain	126
G250	788	Low speed range torque characteristic selection	134
G260	1121	Per-unit speed control reference frequency	136, 137
G261	1117	Speed control P gain 1 (per-unit system)	136
G262	1119	Model speed control gain (per-unit system)	137
G300	451	Second motor control method selection	108
G311	830	Speed control P gain 2	136
G312	831	Speed control integral time 2	136
G313	834	Torque control P gain 2	136

Pr. group	Pr.	Name	Refer to page
G314	835	Torque control integral time 2	136
G315	833 *1	Speed detection filter 2	136
G316	837	Torque detection filter 2	136
G350	747	Second motor low-speed range torque characteristic selection	134
G361	1118	Speed control P gain 2 (per-unit system)	136
G400	286	Droop gain	123
G401	287	Droop filter time constant	123
G402	288	Droop function activation selection	123
G403	994	Droop break point gain	123
G404	995	Droop break point torque	123
G410	653	Speed smoothing control	132
G411	654	Speed smoothing cutoff frequency	132
G420	679	Second droop gain	123
G421	680	Second droop filter time constant	123
G422	681	Second droop function activation selection	123
G423	682	Second droop break point gain	123
G424	683	Second droop break point torque	123
G601	1003	Notch filter frequency	142
G602	1004	Notch filter depth	142
G603	1005	Notch filter width	142
G932	89	Speed control gain (Advanced magnetic flux vector)	108
G942	569	Second motor speed control gain	108

- \*1 The setting is available only when a vector control compatible option is installed.
- \*2 The setting is available only when the FR-A8AP is installed.
- \*3 The setting is available only when the FR-A8AP or the FR-A8APR is installed.
- \*4 The setting is available only when the FR-A8TP is installed.
- \*5 The setting is available only when the FR-A8AP or the FR-A8TP is installed.
- \*6 The parameter number in parentheses is the one for use with the LCD operation panel and the parameter unit.
- \*7 Setting can be made only for the standard model.
- \*8 Setting can be made only for the standard model and the IP55 compatible model.
- \*9 The setting is available only with the 400 V class.

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



## ● Converter unit parameter list (by parameter number)

Set the necessary parameters to meet the load and operational specifications. Parameter setting, change and check can be performed from the operation panel (FR-DU08).

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value	Customer setting					
—	30	E300	Reset selection during power supply to main circuit	0, 100	1	0						
Automatic restart	57	A702	Restart selection	0, 9999	1	9999						
	65	H300	Retry selection	0 to 4	1	0						
Retry	67	H301	Number of retries at fault occurrence	0 to 10, 101 to 110	1	0						
	68	H302	Retry waiting time	0.1 to 600 s	0.1 s	1 s						
	69	H303	Retry count display erase	0	1	0						
—	75	—	Reset selection/disconnected PU detection/reset limit	14 to 17, 114 to 117	1	14						
		E100	Reset selection	0, 1		0						
		E101	Disconnected PU detection									
		E107	Reset limit									
—	77	E400	Parameter write selection	1, 2	1	2						
PU connector communication	117	N020	PU communication station number	0 to 31	1	0						
	118	N021	PU communication speed	48, 96, 192, 384, 576, 768, 1152	1	192						
	119	—	PU communication stop bit length / data length	0, 10	1	1						
		N022	PU communication data length	0, 1		0						
		N023	PU communication stop bit length	0, 1		1						
	120	N024	PU communication parity check	0 to 2	1	2						
	121	N025	Number of PU communication retries	0 to 10, 9999	1	1						
	122	N026	PU communication check time interval	0, 0.1 to 999.8 s, 9999	0.1 s	9999						
	123	N027	PU communication waiting time setting	0 to 150 ms, 9999	1 ms	9999						
	124	N028	PU communication CR/LF selection	0 to 2	1	1						
—	161	E200	Key lock operation selection	0, 10	1	0						
—	168	E000	Parameter for manufacturer setting.									
		E080										
—	169	E001										
		E081										
Cumulative monitor clear	170	M020						Watt-hour meter clear	0, 10, 9999	1	9999	
	Input terminal function assignment	178						T700	RDI terminal function selection	7, 62, 9999	1	9999
187		T709	OH terminal function selection	7								
189		T711	RES terminal function selection	62								
Output terminal function assignment	190	M400	RDB terminal function selection	2, 8, 11, 17, 25, 26, 64, 68, 90, 94, 95, 98, 99, 102, 108, 111, 125, 126, 164, 168, 190, 194, 195, 198, 199, 206, 207, 209, 210, 214, 306, 307, 309, 310, 9999	1	111						
	191	M401	RDA terminal function selection		1	11						
	192	M402	IPF terminal function selection		1	2						
	193	M403	RSO terminal function selection		1	209						
	194	M404	FAN terminal function selection		1	25						
	195	M405	ABC1 terminal function selection		1	99						
—	248	A006	Self power management selection	0 to 2	1	0						





Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value	Customer setting	
Life check	255	E700	Life alarm status display	(0 to 15)	1	0		
	256	E701	Inrush current limit circuit life display	(0 to 100%)	1%	100%		
	257	E702	Control circuit capacitor life display	(0 to 100%)	1%	100%		
—	261	A730	Power failure stop selection	0, 1, 2, 21, 22	1	0		
—	268	M022	Monitor decimal digits selection	0, 1, 9999	1	9999		
—	269	E023	Parameter for manufacturer setting. Do not set.					
—	290	M044	Monitor negative output selection	0, 2, 4, 6	1	0		
Password function	296	E410	Password lock level	0 to 3, 5, 6, 100 to 103, 105, 106, 9999	1	9999		
	297	E411	Password lock/unlock	(0 to 5), 1000 to 9998, 9999	1	9999		
RS-485 communication	331	N030	RS-485 communication station number	0, 31 (0, 247)	1	0		
	332	N031	RS-485 communication speed	3, 6, 12, 24, 48, 96, 192, 384, 576, 768, 1152	1	96		
	333	—	RS-485 communication stop bit length / data length	0, 1, 10, 11	1	1		
		N032	RS-485 communication data length	0, 1	1	0		
	N033	RS-485 communication stop bit length	0, 1	1	1			
	334	N034	RS-485 communication parity check selection	0 to 2	1	2		
	335	N035	RS-485 communication retry count	0 to 10, 9999	1	1		
	336	N036	RS-485 communication check time interval	0 to 999.8 s, 9999	0.1 s	0 s		
	337	N037	RS-485 communication waiting time setting	0 to 150 ms, 9999	1 ms	9999		
	341	N038	RS-485 communication CR/LF selection	0 to 2	1	1		
342	N001	Communication EEPROM write selection	0, 1	1	0			
343	N080	Communication error count	—	1	0			
Maintenance	503	E710	Maintenance timer 1	0 (1 to 9998)	1	0		
	504	E711	Maintenance timer 1 warning output set time	0 to 9998, 9999	1	9999		
—	539	N002	MODBUS RTU communication check time interval	0 to 999.8 s, 9999	0.1 s	9999		
Communication	549	N000	Protocol selection	0, 1	1	0		
—	563	M021	Energization time carrying-over times	(0 to 65535)	1	0		
—	598	H102	Undervoltage level	350 to 430 V, 9999	0.1 V	9999		
—	663	M060	Control circuit temperature signal output level	0 to 100°C	1°C	0°C		
Maintenance	686	E712	Maintenance timer 2	0 (1 to 9998)	1	0		
	687	E713	Maintenance timer 2 warning output set time	0 to 9998, 9999	1	9999		
	688	E714	Maintenance timer 3	0 (1 to 9998)	1	0		
	689	E715	Maintenance timer 3 warning output set time	0 to 9998, 9999	1	9999		
Monitor function	774	M101	Operation panel monitor selection 1	2, 8, 13, 20, 25, 43, 44, 55, 62, 98, 9999	1	9999		
	775	M102	Operation panel monitor selection 2		1	9999		
	776	M103	Operation panel monitor selection 3		1	9999		
Protective Functions	872	H201	Input phase loss protection selection	0, 1	1	0		
	—	876	T723	OH input selection	0 to 2	1	0	

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

Function	Pr.	Pr. group	Name	Setting range	Minimum setting increments	Initial value	Customer setting
Free parameters	888	E420	Free parameter 1	0 to 9999	1	9999	
	889	E421	Free parameter 2	0 to 9999	1	9999	
Energy saving monitor	891	M023	Cumulative power monitor digit shifted times	0, 4, 9999	1	9999	
PU	990	E104	PU buzzer control	0, 1	1	1	
Monitor function	992	M104	Operation panel setting dial push monitor selection	2, 8, 13, 20, 25, 43, 44, 55, 62, 98	1	8	
—	997	H103	Fault initiation	0 to 255, 9999	1	9999	
Clock function	1006	E020	Clock (year)	2000 to 2099	1	2000	
	1007	E021	Clock (month, day)	1/1 to 12/31	1	101	
	1008	E022	Clock (hour, minute)	0:00 to 23:59	1	0	
—	1048	E106	Display-off waiting time	0 to 60 min	1 min	0	
Clear parameters	Pr.CLR		Parameter clear	(0), 1	1	0	
	ALL.CL		All parameter clear	(0), 1	1	0	
	Err.CL		Fault history clear	(0), 1	1	0	
—	Pr.CPY		Parameter copy	(0), 1 to 3	1	0	
—	Pr.CHG		Initial value change list	—	1	0	
—	Pr.MD		Group parameter setting	(0), 1, 2	1	0	

# Explanations of Parameters

The following marks are used to show the applicable control method: **V/F** for V/F control, **Magnetic flux** for Advanced magnetic flux vector control, **Sensorless** for Real sensorless vector control, **Vector** for vector control, and **PM** for PM sensorless vector control. (Parameters without any mark are valid for all controls.)

**Pr.**.....denotes parameter numbers, and **GROUP**.....denotes group parameter numbers.

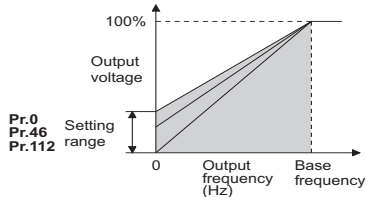
Connection diagrams appear with the control logic of the input terminals as sink logic, unless otherwise specified.

## Manual torque boost **V/F**

Pr.	GROUP	Name	Pr.	GROUP	Name
0	G000	Torque boost	46	G010	Second torque boost
112	G020	Third torque boost			

Voltage drop in the low-frequency range can be compensated, improving reduction of the motor torque in the low-speed range.

- Motor torque in the low-frequency range can be adjusted according to the load, in order to increase the motor torque at start.
- The RT and X9 signals enable the switching between 3 types of torque boost.
- Available during V/F control.

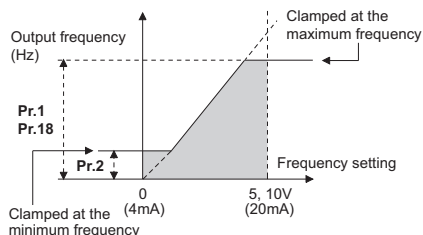


## Limiting the output frequency (maximum/minimum frequency)

Pr.	GROUP	Name	Pr.	GROUP	Name
1	H400	Maximum frequency	2	H401	Minimum frequency
18	H402	High speed maximum frequency			

Motor speed can be limited.

- Clamp the upper and lower limits of the output frequency.
- To operate at a frequency higher than 120 Hz, adjust the maximum output frequency with **Pr.18**. (If a frequency is set in **Pr.18**, the **Pr.1** setting automatically changes to the frequency set in **Pr.18**. Also, if a frequency is set in **Pr.1**, the **Pr.18** setting automatically changes to the frequency set in **Pr.1**.)
- During position control under vector control, the maximum frequency is valid for the speed command calculated considering the droop pulses. The lower frequency limit is disabled.

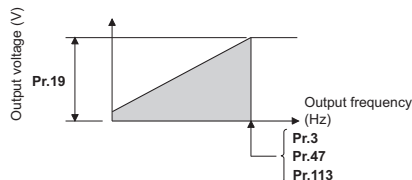


## Base frequency, voltage **V/F**

Pr.	GROUP	Name	Pr.	GROUP	Name
3	G001	Base frequency	19	G002	Base frequency voltage
47	G011	Second V/F (base frequency)	113	G021	Third V/F (base frequency)

Use this function to adjust the inverter outputs (voltage, frequency) to match with the motor rating.

- When operating a standard motor, generally set the rated frequency of the motor in **Pr.3 Base frequency**. When running the motor using commercial power supply-inverter switch-over operation, set **Pr.3** to the same value as the power supply frequency.
- When you want to change the base frequency when switching multiple motors with one inverter, etc., use the **Pr.47 Second V/F (base frequency)** and **Pr.113 Third V/F (base frequency)**.
- Set the rated voltage (rated motor voltage, etc.) to the **Pr.19 Base frequency voltage**.
- Available during V/F control.

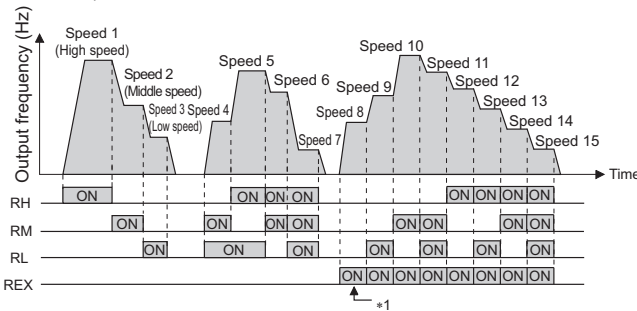


## Multi-speed setting operation

Pr.	GROUP	Name	Pr.	GROUP	Name
4	D301	Multi-speed setting (high speed)	5	D302	Multi-speed setting (middle speed)
6	D303	Multi-speed setting (low speed)	24	D304	Multi-speed setting (speed 4)
25	D305	Multi-speed setting (speed 5)	26	D306	Multi-speed setting (speed 6)
27	D307	Multi-speed setting (speed 7)	28	D300	Multi-speed input compensation selection
232	D308	Multi-speed setting (speed 8)	233	D309	Multi-speed setting (speed 9)
234	D310	Multi-speed setting (speed 10)	235	D311	Multi-speed setting (speed 11)
236	D312	Multi-speed setting (speed 12)	237	D313	Multi-speed setting (speed 13)
238	D314	Multi-speed setting (speed 14)	239	D315	Multi-speed setting (speed 15)

Use these parameters to change among pre-set operation speeds with contact signals. The speeds are pre-set with parameters. Any speed can be selected by simply turning ON/OFF the contact signals (RH, RM, RL, and REX signals).

- The inverter operates at the frequency set in **Pr.4** when RH signal is ON, **Pr.5** when RM signal is ON and **Pr.6** when RL signal is ON.
- The frequency from 4th speed to 15th speed can be set in accordance with the combination of the RH, RM, RL, and REX signals. Set the running frequencies in **Pr.24** to **Pr.27** and **Pr.232** to **Pr.239**. (In the initial status, 4th speed to 15th speed are invalid.)



\*1 Operates at the frequency set in **Pr.6** when RH, RM, or RL is OFF and REX is ON while **Pr.232 Multi-speed setting (speed 8) = "9999"**.

- Speed (frequency) can be compensated for the multi-speed setting and the remote setting by inputting the frequency setting compensation signal (terminals 1, 2).

Pr.28 setting	Description
0 (initial value)	Without compensation
1	With compensation

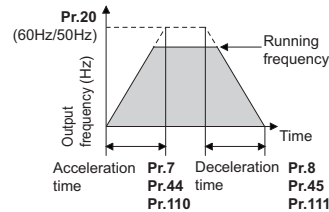
## Acceleration/deceleration time

Pr.	GROUP	Name	Pr.	GROUP	Name
7	F010	Acceleration time	8	F011	Deceleration time
20	F000	Acceleration/ deceleration reference frequency	21	F001	Acceleration/ deceleration time increments
44	F020	Second acceleration/ deceleration time	45	F021	Second deceleration time
110	F030	Third acceleration/ deceleration time	111	F031	Third deceleration time
147	F022	Acceleration/ deceleration time switching frequency	791	F070	Acceleration time in low-speed range
792	F071	Deceleration time in low-speed range			

The following parameters are used to set motor acceleration/ deceleration time.

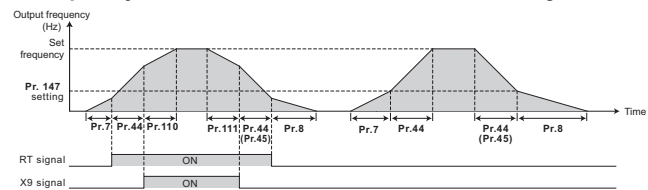
Set a larger value for a slower acceleration/deceleration, and a smaller value for a faster acceleration/deceleration.

- Use **Pr.7 Acceleration time** to set the acceleration time required to reach **Pr.20 Acceleration/deceleration reference frequency** from a stop status.
- Use **Pr.8 Deceleration time** to set the deceleration time required to reach a stop status from **Pr.20 Acceleration/deceleration reference frequency**.

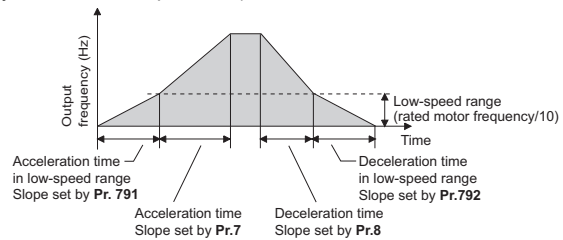


Pr.21 setting	Description
0 (initial value)	Increment: 0.1 s Set the increment for the acceleration/deceleration time setting.
1	Increment: 0.01 s

- Pr.44** and **Pr.45** are valid when the RT signal is ON or when the output frequency is equal to or higher than the frequency set in **Pr.147 Acceleration/deceleration time switching frequency**. **Pr.110** and **Pr.111** are valid when the X9 signal is ON.



- If torque is required in the low-speed range (less than 10% of the rated motor frequency) under PM sensorless vector control, set the **Pr.791 Acceleration time in low-speed range** and **Pr.792 Deceleration time in low-speed range** settings higher than the **Pr.7 Acceleration time** and **Pr.8 Deceleration time** settings so that the mild acceleration/deceleration is performed in the low-speed range. (Enabled especially under the current synchronization operation.)



## Overheat protection of the motor (electronic thermal O/L relay)

Pr.	GROUP	Name	Pr.	GROUP	Name
9	H000	Electronic thermal O/L relay	51	H010	Second electronic thermal O/L relay
561	H020	PTC thermistor protection level	600	H001	First free thermal reduction frequency 1
601	H002	First free thermal reduction ratio 1	602	H003	First free thermal reduction frequency 2
603	H004	First free thermal reduction ratio 2	604	H005	First free thermal reduction frequency 3
607	H006	Motor permissible load level	608	H016	Second motor permissible load level
692	H011	Second free thermal reduction frequency 1	693	H012	Second free thermal reduction ratio 1
694	H013	Second free thermal reduction frequency 2	695	H014	Second free thermal reduction ratio 2
696	H015	Second free thermal reduction frequency 3	876	H022	Thermal protector input
1016	H021	PTC thermistor protection detection time			

Set the current for the electronic thermal O/L relay to protect the motor from overheating. Such a setting will provide the optimum protective characteristic considering the low cooling capability of the motor during low-speed operation.

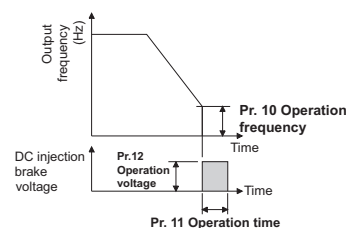
- This function detects the overload (overheat) of the motor and trips the inverter by stopping the operation of the transistor at the inverter output side.
- Set the rated motor current (A) in **Pr.9**. (If the motor has both 50 Hz and 60 Hz ratings and the **Pr.3 Base frequency** is set to 60 Hz, set to 1.1 times the 60 Hz rated motor current.
- Set "0" in **Pr.9** to avoid activating the electronic thermal relay function; for example, when using an external thermal relay for the motor. (Note that the output transistor protection of the inverter is enabled. (E.THT))
- Mitsubishi constant-torque motor  
Set one of "1, 13 to 18, 50, 53, or 54" in **Pr.71**. (This setting will enable the 100% constant-torque characteristic in the low-speed range.)
- When using an IPM motor (MM-CF), perform IPM parameter initialization to automatically set the rated current of the IPM motor.
- The outputs from the PTC thermistor built into the motor can be input to the terminals 2 and 10. When the input from the PTC thermistor reaches the resistance value set in **Pr.561**, PTC thermistor operation (E.PTC) will be activated to shut off the inverter outputs.
- When the PTC thermistor protection level setting is used, use **Pr.1016** to set the time from when the resistance of the PTC thermistor reaches the protection level until the protective function (E.PTC) is activated.
- The activation level of the electronic thermal O/L relay **Pr.600** to **Pr.604** (**Pr.692** to **Pr.696**) can be varied according to the thermal characteristic of the motor.
- While the RT signal is ON, the setting values of **Pr.51** and **Pr.692** to **Pr.696** are referred to provide thermal protection. Use the electronic thermal O/L relay function to drive two motors of different current ratings by one inverter. (To rotate two motors at once, use an external thermal relay.)
- To change the operational characteristic of the electronic thermal O/L relay, set the permissible load level in **Pr.607** or **Pr.608** according to the motor characteristics.
- Use **Pr.876** to set valid/invalid status of terminal OH function when the FR-A8TP is installed.

## DC injection brake, zero speed control, and servo lock

Pr.	GROUP	Name	Pr.	GROUP	Name
10	G100	DC injection brake operation frequency	11	G101	DC injection brake operation time
12	G110	DC injection brake operation voltage	802	G102	Pre-excitation selection
850	G103	Brake operation selection	1299	G108	Second pre-excitation selection

When stopping a motor, DC injection brake is applied to adjust the braking torque and timing to stop the motor.

- By setting the frequency to operate the DC injection brake (zero speed control and servo lock) to **Pr.10 DC injection brake operation frequency**, the DC injection brake (zero speed control and servo lock) will operate when it reaches this frequency at the time of deceleration.



- Set the time applying the DC injection brake (zero speed control and servo lock) to **Pr.11 DC injection brake operation time**.
- Pr.12 DC injection brake operation voltage** will set the percent against the power supply voltage. (Not used at the time of zero speed control or servo lock)
- Under Real sensorless vector control, **Pr.850** can be used to select DC injection brake (setting value "0", initial value), zero speed control (setting value "1"), or magnetic flux decay output shutoff (setting value "2").
- When speed control is selected under vector control or PM sensorless vector control, pre-excitation braking operation by the LX signal can either be zero speed control or servo lock control. Pre-excitation is valid at LX signal ON.

Pr.802 (Pr.1299) Setting value	Braking operation	Description
0 (initial value)	Zero speed control	It will try to maintain 0 r/min so the motor shaft will not rotate even when a load is applied. However, it will not return to its original position when the shaft moves due to external force.
1	Servo lock	It will try to maintain the position of the motor shaft even if a load is applied. When the shaft moves due to external force, it will return to its original position after the external force is removed.

- For the vector control and PM sensorless vector control, set the frequency at where the zero speed control or servo lock control activates (**Pr.10**) and the operating period of the control (**Pr.11**). Use **Pr.802** to select whether the zero speed control or servo lock control. During vector control, the initial value of **Pr.10** is automatically set to 0.5 Hz.
- Turning ON the RT signal enables the second pre-excitation selection.

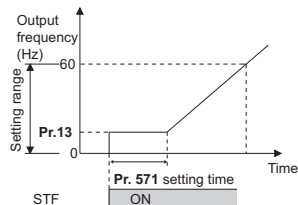


## Starting frequency and start-time hold function

V/F Magnetic flux Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
13	F102	Starting frequency	571	F103	Holding time at a start

The starting frequency can be set and the starting frequency can be held for a certain period of time. Set these functions when starting torque is needed or the motor drive at start needs smoothing.



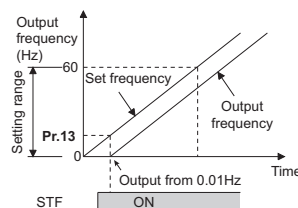
## Minimum frequency at motor start and start-time hold function

PM

Pr.	GROUP	Name	Pr.	GROUP	Name
13	F102	Starting frequency	571	F103	Holding time at a start

Set the frequency where the PM motor starts running.

- When setting a frequency with analog input, set the deadband in the low-speed range to eliminate noise and offset deviation.
- When the low-speed range high-torque characteristic function is enabled (Pr.788 = "9999"), the frequency level of 0.01 Hz is held for the time period of Pr.571 after turning ON the start signal.

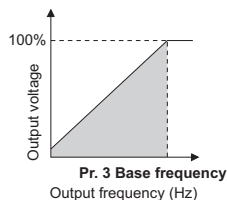


## V/F patterns for various applications

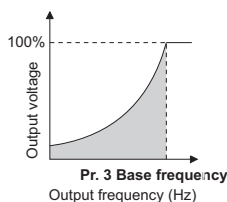
V/F

Pr.	GROUP	Name
14	G003	Load pattern selection

Optimal output characteristics (V/F characteristics) for application or load characteristics can be selected. Available during V/F control.



- Constant-torque load application (setting "0", initial value)**  
The output voltage will change linearly against the output frequency at the base frequency or lower. Set this parameter when driving a load that has constant load torque even when the rotation speed is changed, such as a conveyor, dolly, or roll drive.



- Variable-torque load applications (setting value "1")**  
The output voltage will change in square curve against the output frequency at the base frequency or lower. Set this parameter when driving a load with load torque change proportionally against the square of the rotation speed, such as a fan or pump.

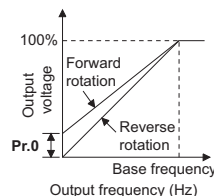
- Vertical lift load applications (setting value "2, 3")

Set "2" for a vertical lift load that is in power driving at forward rotation and in regenerative driving at reverse rotation.

Pr.0 Torque boost is valid during forward rotation, and torque boost is automatically changed to "0%" during reverse rotation. Set "3" for the counterweight system, etc. that is in power driving at reverse rotation and in regenerative driving at forward rotation, according to the load weight.

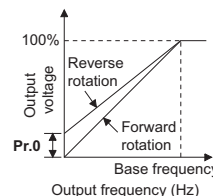
Pr.14 = 2

For vertical lift loads  
At forward rotation boost...Pr.0 setting  
At reverse rotation boost...0%



Pr.14 = 3

For vertical lift loads  
At forward rotation boost...0%  
At reverse rotation boost...Pr.0 setting



- Switching applied load selection with a terminal (setting value "4, 5")

The RT and X17 signals enable the switching between the constant-torque load operation and lift operation.

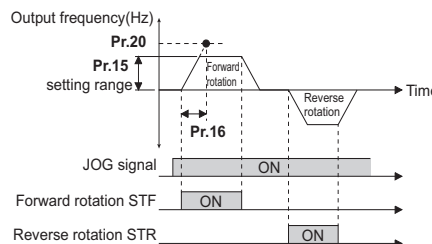
Pr.14 Setting value	RT(X17) signal	output characteristic
4	ON	For constant-torque load (same as the setting value "0")
	OFF	For lift, boost at reverse rotation 0% (same as the setting value "2")
5	ON	For constant-torque load (same as the setting value "0")
	OFF	For lift, boost at reverse rotation 0% (same as the setting value "3")

## JOG operation

Pr.	GROUP	Name	Pr.	GROUP	Name
15	D200	Jog frequency	16	F002	Jog acceleration/ deceleration time

The frequency and acceleration/deceleration time for JOG operation can be set. JOG operation is possible in both External operation and PU.

JOG operation can be used for conveyor positioning, test operation, etc.

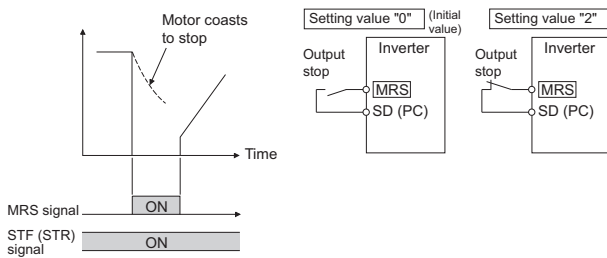


## Inverter output shutoff signal

Pr.	GROUP	Name
17	T720	MRS input selection

The inverter output can be shut off with the MRS signal. The logic of the MRS signal can also be selected.

When **Pr.17**="4", the MRS signal from an external terminal is selected as the normally closed (NC contact) input, and the MRS signal (output stop) via communication as the normally open (NO contact) input.



- Pr. 18** ➔ Refer to the page on Pr.1
- Pr. 19** ➔ Refer to the page on Pr.3
- Pr. 20, 21** ➔ Refer to the page on Pr.7

## Stall prevention operation



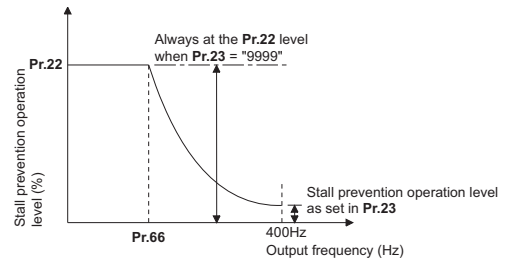
Pr.	GROUP	Name	Pr.	GROUP	Name
22	H500	Stall prevention operation level	23	H610	Stall prevention operation level compensation factor at double speed
48	H600	Second stall prevention operation level	49	H601	Second stall prevention operation frequency
66	H611	Stall prevention operation reduction starting frequency	114	H602	Third stall prevention operation level
115	H603	Third stall prevention operation frequency	148	H620	Stall prevention level at 0 V input
149	H621	Stall prevention level at 10 V input	154	H631	Voltage reduction selection during stall prevention operation
156	H501	Stall prevention operation selection	157	M430	OL signal output timer
858	T040	Terminal 4 function assignment	868	T010	Terminal 1 function assignment

This function monitors the output current and automatically changes the output frequency to prevent the inverter from tripping due to overcurrent, overvoltage, etc. It can also limit the stall prevention and fast-response current limit operation during acceleration/ deceleration and power/regenerative driving.

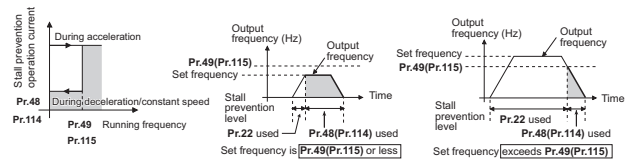
This function is disabled during Real sensorless vector control, vector control and PM sensorless vector control.

- **Stall prevention**  
If the output current exceeds the stall prevention operation level, the output frequency of the inverter is automatically changed to reduce the output current. Also the second and third stall prevention functions can limit the output frequency range in which the stall prevention function is enabled.
- **Fast-response current limit**  
If the current exceeds the limit value, the output of the inverter is shut off to prevent an overcurrent.

- For **Pr.22**, set the ratio of the output current to the inverter rated current at which the stall prevention operation will be activated. Normally, this should be set at 150% (initial value). For the FR-A820-00250(3.7K) or lower and FR-A840-00126(3.7K) or lower, when the control method is changed from V/F control or Advanced magnetic flux vector control to Real sensorless vector control, or vector control, the **Pr.22** setting changes from 150% (initial value) to 200%.
- To set the stall prevention operation level with the analog signal via the terminal 1 (terminal 4), set **Pr.868 (Pr.858)**="4". Use **Pr.148** and **Pr.149** to adjust gain and bias for the analog signals.
- When operating at the rated motor frequency or higher, acceleration may not be made because the motor current does not increase. Also, when operating in the high-frequency range, the current flowing to the locked motor becomes less than the rated output current of the inverter; and even if the motor is stopped, the protective function will not operate (OL). In a case like this, the stall prevention level can be reduced in the high-frequency range to improve the motor's operating characteristics. This is useful when operating up to the high speed range, such as when using a centrifuge. Normally, set **Pr.66** to 60 Hz, and **Pr.23** to 100%.
- When **Pr.23**="9999" (initial value), the stall prevention operation level is constant at the **Pr.22** level up to 590 Hz.



- By setting **Pr.49**="9999" and turning ON the RT signal, **Pr.48** will be enabled.
- To enable **Pr.114**, set **Pr.115**≠ "0" and turn ON the X9 signal.
- Use **Pr.48 (Pr.114)** to set the stall prevention operation level applicable in the range between 0 Hz and the frequency set in **Pr.49(Pr.115)**.



Pr.49 setting	Pr.115 setting	Operation
0 (initial value)		The second (third) stall prevention function disabled.
0.01 Hz to 590 Hz		The second (third) stall prevention function operates according to the frequency.
9999	Setting not available	The second stall prevention function operates according to the RT signal. RT signal ON: stall level <b>Pr.48</b> RT signal OFF: stall level <b>Pr.22</b>

- Use **Pr.154** to further suppress the activation of the protective function (E.OCC, E.OV[]) during stall prevention operation.
- Use **Pr.156** to suppress the stall prevention operation and the fast-response current limit in accordance with the operating status.
- When Real sensorless vector control, vector control or PM sensorless vector control is selected using **Pr.800**, **Pr.22** serves as the torque limit level.

- Features
- Application Example
- PLC Function
- FR Configurator2
- Connection Examples
- Standard Specs
- Outline Dimensions
- Terminal Connection Diagrams
- Terminal Specs
- Operation Panel
- Parameter List
- Parameters
- Explanations of Parameters
- Protective Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty Inquiry

## Setting the torque limit level under speed control

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
22	H500	Stall prevention operation level (Torque limit level)	157	M430	OL signal output timer
803	G210	Constant output range torque characteristic selection	804	D400	Torque command source selection
805	D401	Torque command value (RAM)	806	D402	Torque command value (RAM, EEPROM)
810	H700	Torque limit input method selection	811	D030	Set resolution switchover
812	H701	Torque limit level (regeneration)	813	H702	Torque limit level (3rd quadrant)
814	H703	Torque limit level (4th quadrant)	815	H710	Torque limit level 2
816	H720	Torque limit level during acceleration	817	H721	Torque limit level during deceleration
858	T040	Terminal 4 function assignment	868	T010	Terminal 1 function assignment
874	H730	OLT level setting			

During speed control under Real sensorless vector control, vector control and PM sensorless vector control, the output torque is limited to prevent it from exceeding a specified value.

- The torque limit level can be set in a range of 0 to 400% using **Pr.22**. When the TL signal is ON, the torque limit level 2 (**Pr.815**) is enabled.
- The torque limit level can be selected by setting it with a parameter, or by using analog input terminals (terminals 1, 4). Also, the torque limit level at forward rotation (power driving/regenerative driving) and reverse rotation (power driving/regenerative driving) can be set individually.

Pr.	Setting range	Description
810	0 (initial value)	Torque limit by parameter setting
	1	Torque limit using the analog signals input to the terminals 1 and 4.
	2	Torque limit by communication options
812	0 to 400%	Set the torque limit level for forward rotation regenerative driving.
	9999 (initial value)	Limit using <b>Pr.22</b> or the analog terminal values.
813	0 to 400%	Set the torque limit level for reverse rotation power driving.
	9999 (initial value)	Limit using <b>Pr.22</b> or the analog terminal values.
814	0 to 400%	Set the torque limit level for reverse rotation regenerative driving.
	9999 (initial value)	Limit using <b>Pr.22</b> or the analog terminal values.

- When inputting an analog signal from the terminal 1 (4) to set the torque limit level, set **Pr.810**="1" or **Pr.868 (Pr.858)**="4".
- The torque limit value can be input using a communication option (FR-A8NC or FR-A8NCE).
- Use **Pr.816** and **Pr.817** to set the torque limit value during acceleration/deceleration.
- For the torque limit operation during Real sensorless vector control and vector control, use **Pr.803** to change the torque characteristic in the low-speed range and in the constant output range.

Pr.803 setting	Torque characteristic in low-speed range	Torque characteristic in constant-outpu range
0 (initial value)	Torque rise *1	Constant motor output
1	Constant torque	Constant torque
10	Constant torque	Constant motor output
11	Torque rise *1	Constant torque

\*1 This function is only available under Real sensorless vector control.

- The inverter can be set to trip at activation of torque limit operation and stalling of the motor. Use **Pr.874** to set the output torque where the protective function activates.

- Use **Pr.811** to change the parameter setting increment for the torque limit setting from 0.1% to 0.01%.
- If **Pr.800** is used to select V/F control or Advanced magnetic flux vector control, the **Pr.22** setting operates as the stall prevention operation level.

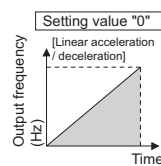
**Pr.24 to 28** Refer to the page on Pr.4.

## Acceleration/deceleration pattern and backlash measures

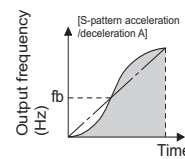
Pr.	GROUP	Name	Pr.	GROUP	Name
29	F100	Acceleration/deceleration pattern selection	140	F200	Backlash acceleration stopping frequency
141	F201	Backlash acceleration stopping time	142	F202	Backlash deceleration stopping frequency
143	F203	Backlash deceleration stopping time	380	F300	Acceleration S-pattern 1
381	F301	Deceleration S-pattern 1	382	F302	Acceleration S-pattern 2
383	F303	Deceleration S-pattern 2	516	F400	S-pattern time at a start of acceleration
517	F401	S-pattern time at a completion of acceleration	518	F402	S-pattern time at a start of deceleration
519	F403	S-pattern time at a completion of deceleration			

The acceleration/deceleration pattern can be set according to the application.

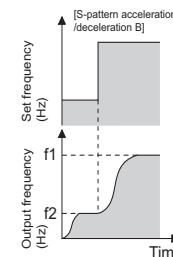
In addition, the backlash measures, which stop acceleration/deceleration at certain frequency or time set in parameters during acceleration/deceleration, can be set.



- Linear acceleration/deceleration (setting value "0", initial value)  
When the frequency is changed for acceleration, deceleration, etc. during inverter operation, the output frequency is changed linearly (linear acceleration/deceleration) to reach the set frequency without straining the motor and inverter.

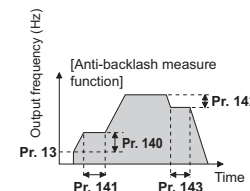


- S-pattern acceleration/deceleration A (setting value "1")  
For the main shaft of a machine, etc. Use this when quick acceleration/deceleration is required to reach a high-speed area equal to or higher than the base frequency.



- S-pattern acceleration/deceleration B (setting value "2")  
This is useful for preventing stacks from collapsing on a conveyor, etc. S-pattern acceleration/deceleration B can reduce the impact during acceleration/deceleration by accelerating/decelerating in an S-pattern from the present frequency (f2) to the target frequency (f1).

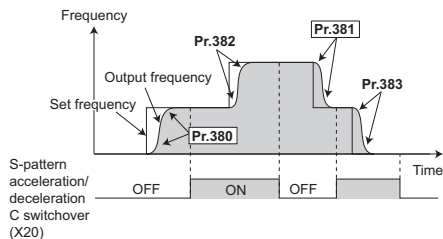
- Backlash measures (setting value "3", **Pr.140 to Pr.143**)  
To avoid backlash, acceleration/deceleration is temporarily stopped. Set the acceleration/deceleration stopping frequency and time in **Pr.140 to Pr.143**.





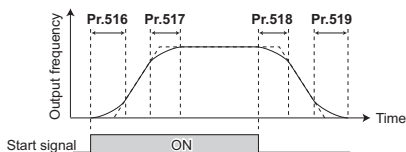
- S-pattern acceleration/deceleration C (setting value "4", **Pr.380** to **Pr.383**)

The acceleration/deceleration curve is switched by the S-pattern acceleration/deceleration C switchover (X20) signal. Set the ratio (%) of time for drawing an S-shape in **Pr.380** to **Pr.383** with the acceleration time as 100%.

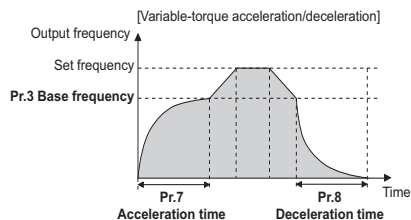


- S-pattern acceleration/deceleration D (setting value "5", **Pr.516** to **Pr.519**)

Set the time required for S-pattern operation part of S-pattern acceleration/deceleration with **Pr.516** to **Pr.519**.



- Variable-torque acceleration/deceleration (**Pr.29**="6")  
This function is useful for variable-torque load such as a fan or blower to accelerate/decelerate in short time. In areas where output frequency > base frequency, the speed accelerates/decelerates linearly.



## Selecting the regenerative brake and DC feeding

Pr.	GROUP	Name	Pr.	GROUP	Name
30	E300	Regenerative function selection	70	G107	Special regenerative brake duty
599	T721	X10 terminal input selection			

- By using the optional high-duty brake resistor (FR-ABR) or the brake unit (FR-BU2, BU, FR-BU), the regenerative brake duty can be increased for the operation with frequent starts and stops.
- The power regeneration common converter (FR-CV 55K or lower) or power regeneration converter (MT-RC 75K or higher) is used for the continuous operation in the regenerative status. To further suppress harmonics or improve the power factor, use a high power factor converter (FR-HC2).
- For standard models and IP55 compatible models, it is possible to choose between the DC feeding mode 1, which will operate with DC power supply (terminals P and N), and DC feeding mode 2, which will normally operate in AC power supply (terminals R, S, and T) and operate in DC power supply (terminal P and N), such as batteries, at the time of power failure.

- Standard model  
For FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower

Regeneration unit	Power supply to the inverter	Pr.30 setting value	Pr.70 setting value
When the built-in brake, Brake unit (FR-BU2, BU, FR-BU *1)	R, S, T	0 (initial value), 100	Brake duty differs according to the capacity.
	P, N	10, 110	
	R, S, T/P, N	20, 120	
High-duty brake resistor (FR-ABR)	R, S, T	1, 101	10%*3 6%*4
	P, N	11, 111	
	R, S, T/P, N	21, 121	
High power factor converter (FR-HC2), Power regeneration common converter (FR-CV)	P, N	2, 102	0% (initial value)

FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher

Regeneration unit	Power supply to the inverter	Pr.30 setting value	Pr.70 setting value
No regenerative function	R, S, T	0 (initial value), 100	—
	P, N	10, 110	
	R, S, T/P, N	20, 120	
Brake unit (FR-BU2*2)	R, S, T	1, 101	0% (initial value)
	P, N	11, 111	
	R, S, T/P, N	21, 121	
Power regeneration converter (MT-RC)	R, S, T	1, 101	0% (initial value)
High power factor converter (FR-HC2)	P, N	2, 102	—

- Separated converter type

Regeneration unit	Power supply to the inverter	Pr.30 setting value
No regenerative function (FR-CC2)	P, N	10 (initial value), 110
Brake unit (FR-CC2+FR-BU2*2)	P, N	11, 111
High power factor converter (FR-HC2)	P, N	2, 102

- IP55 compatible model

Regeneration unit	Power supply to the inverter	Pr.30 setting value
Brake unit (FR-BU2, BU, FR-BU*1)	R, S, T	0 (initial value), 100
	P, N	10, 110
	R, S, T/P, N	20, 120
High power factor converter (FR-HC2), Power regeneration common converter (FR-CV)	P, N	2, 102

- \*1 Used in combination with GZG, GRZG, or FR-BR.
- \*2 Used in combination with MT-BR5
- \*3 Setting for the FR-A820-00490(7.5K) or lower and FR-A840-00250(7.5K) or lower
- \*4 Setting for the FR-A820-00630(11K) or higher and FR-A840-00310(11K) or higher

- When set to **Pr.599** = "1", X10 signal can be changed to normally closed (NC contact) input specification.

Features  
Application Example  
PLC Function  
FR Configurator2  
Connection  
Examples  
Standard  
Specs  
Outline  
Dimensions  
Terminal  
Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations  
of  
Parameters  
Protective  
Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty  
Inquiry

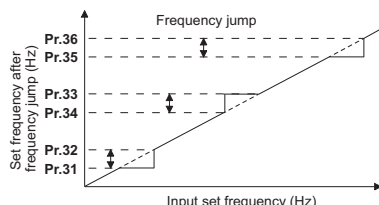




## Avoiding machine resonance points (frequency jump)

Pr.	GROUP	Name	Pr.	GROUP	Name
31	H420	Frequency jump 1A	32	H421	Frequency jump 1B
33	H422	Frequency jump 2A	34	H423	Frequency jump 2B
35	H424	Frequency jump 3A	36	H425	Frequency jump 3B
552	H429	Frequency jump range			

When it is desired to avoid resonance attributable to the natural frequency of a mechanical system, these parameters allow resonant frequencies to be jumped.



- Up to three areas can be set, with the jump frequencies set to either the top or bottom point of each area.
- The frequency jumps 1A, 2A, 3A can be set and operation is performed at these frequencies in the jump areas.
- At the initial setting "9999", frequency jumps are not performed.
- During acceleration/deceleration, the running frequency within the set area is valid.
- A total of six jump areas can be set **Pr.552** by setting the common jump range for the frequencies set in **Pr.31** to **Pr.36**.

## Speed display and speed setting

Pr.	GROUP	Name	Pr.	GROUP	Name
37	M000	Speed display	144	M002	Speed setting switchover
505	M001	Speed setting reference	811	D030	Set resolution switchover

The monitor display unit and the frequency setting on PU(FR-DU08/FR-PU07) can be switched to motor speed and machine speed.

- The setting increment for each monitor is determined by the combination of **Pr.37** and **Pr.144**. (The initial values are shown within the thick lines.)
- Use **Pr.811** to change the increment for the running speed monitor and speed setting monitor (r/min) from 1 r/min to 0.1 r/min.
- Changing the number of motor poles using **Pr.81** Number of motor poles will change the **Pr.144** setting value.

Pr.37 setting value	Pr.144 setting value	Output frequency monitor	Set frequency monitor	Running speed monitor	Frequency setting parameter setting
0 (initial value)	0	0.01 Hz	0.01 Hz	1 r/min *1*2	0.01 Hz
	2 to 12	0.01 Hz	0.01 Hz	1 r/min *1*2	0.01 Hz
	102 to 112	1 r/min *1*2	1 r/min *1*2	1 r/min *1*2	1 r/min *1
1 to 9998	0	0.01 Hz	0.01 Hz	1 (machine speed) *1	0.01 Hz
	2 to 12	1 (machine speed) *1	1 (machine speed) *1	1 (machine speed) *1	1 (machine speed) *1
	102 to 112	0.01 Hz	0.01 Hz	1 r/min *1*2	0.01 Hz

\*1 Conversion formula to the motor speed r/min  
 $\text{Frequency} \times 120 / \text{number of motor poles (Pr.144)}$   
 Conversion formula to machine speed  
 $\text{Pr.37} \times \text{Frequency} / \text{Pr.505}$   
 For **Pr.144** in the above formula, the value is "Pr.144 - 100" when "102 to 110" is set in **Pr.144**; and the value is "4" when **Pr.37**=0 and **Pr.144**=0.

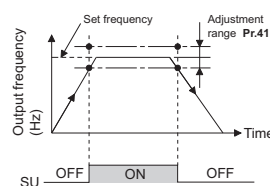
\*2 Use **Pr.811** to change the increment from 1 r/min to 0.1 r/min.

## Output frequency detection

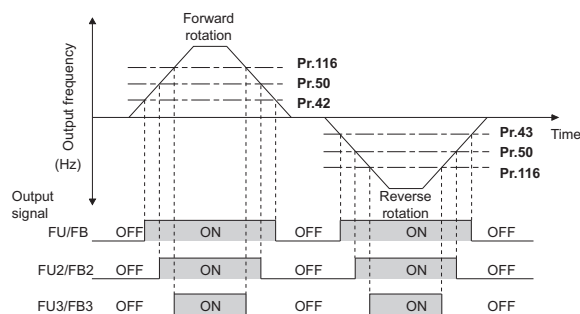
Pr.	GROUP	Name	Pr.	GROUP	Name
41	M441	Up-to-frequency sensitivity	42	M442	Output frequency detection
43	M443	Output frequency detection for reverse rotation	50	M444	Second output frequency detection
116	M445	Third output frequency detection	865	M446	Low speed detection
870	M400	Speed detection hysteresis			

The output frequency of the inverter is detected to output as an output signal.

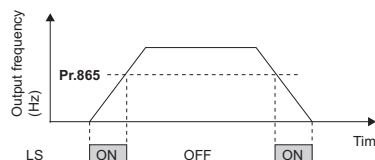
- The **Pr.41** value can be adjusted within the range  $\pm 1\%$  to  $\pm 100\%$  considering the set frequency as 100%.
- This parameter can be used to check whether the set frequency has been reached, and provide signals such as the operation start signal for related equipment.



- Output frequency detection signal (FU, FB) is output when the output frequency reaches the **Pr.42** setting or higher. This function can be used for electromagnetic brake operation, open signal, etc.
- Frequency detection dedicated to reverse rotation can also be set by setting the detection frequency to **Pr.43**. This is useful for changing the timing of the electromagnetic brake for forward rotation (lifting) and reverse rotation (lowering) in operations such as a lift operation.
- When outputting a frequency detection signal separately from the FU (FB) signal, set the detection frequency in **Pr.50** or **Pr.116**. When the output frequency reaches the **Pr.50** setting or higher, the FU2 (FB2) signal is output (when it reaches the **Pr.116** setting or higher, the FU3 (FB3) signal is output).



- During Real sensorless vector control and vector control, FU (FU2, FU3) signal is output when the output frequency reaches the specified speed, and FB (FB2, FB3) signal is output when the actual motor speed (estimated actual rotations per minute) reaches the specified speed. (Output timings of FU and FB signals are the same under V/F control, Advanced magnetic flux vector control, and encoder feedback control.)
- During Real sensorless vector control, vector control, and PM sensorless vector control, the LS signal is output when the output frequency drops to **Pr.865** or lower. During inverter operation, signals are output by the following conditions.





- Pr.** 44 to 45 ➤ Refer to the page on Pr.7
- Pr.** 46 ➤ Refer to the page on Pr.0
- Pr.** 47 ➤ Refer to the page on Pr.3
- Pr.** 48 to 49 ➤ Refer to the page on Pr.22
- Pr.** 50 ➤ Refer to the page on Pr.41
- Pr.** 51 ➤ Refer to the page on Pr.9

## Monitor display selection

Pr.	GROUP	Name	Pr.	GROUP	Name
52	M100	Operation panel main monitor selection	54	M300	FM/CA terminal function selection
158	M301	AM terminal function selection	170	M020	Watt-hour meter clear
171	M030	Operation hour meter clear	268	M022	Monitor decimal digits selection
290	M044	Monitor negative output selection	563	M021	Energization time carrying-over times
564	M031	Operating time carrying-over times	774	M101	Operation panel monitor selection 1
775	M102	Operation panel monitor selection 2	776	M103	Operation panel monitor selection 3
891	M023	Cumulative power monitor digit shifted times	992	M104	Operation panel setting dial push monitor selection
1018	M045	Monitor with sign selection	1106	M050	Torque monitor filter
1107	M051	Running speed monitor filter	1108	M052	Excitation current monitor filter

Use **Pr.52, Pr.774 to Pr.776, Pr.992** to select a monitored item to be displayed on the operation panel (FR-DU08) and parameter unit (FR-PU07).

Refer to the following table and set the monitor to be displayed. (The items with — are not available for monitoring. The circle in the display/output column denotes availability of the minus sign display/output.)

Monitored item	Unit	Pr.52, Pr.774 to Pr.776, Pr.992		Pr.54 (FM/CA) Pr.158 (AM) setting value	Terminal FM, CA, AM full-scale value	Minus (-) display/output *14
		DU	PU			
Output frequency/Rotation speed*10	0.01 Hz *9	1/0/100	1	—	Pr.55	○*15
Output current*6*7*10	0.01 A/0.1 A *5	2/0/100	2	—	Pr.56	—
Output voltage*6*10	0.1 V	3/0/100	3	—	200 V class: 400 V 400 V class: 800 V	—
Fault or alarm indication	—	0/100	—	—	—	—
Frequency setting value/speed setting	0.01 Hz *9	5	*1	5	Pr.55	—
Running speed	1 (r/min)	6	*1	6	Setting value of Pr.55 converted by Pr.37 and Pr.144.	○*15
Motor torque	0.1%	7	*1	7	Pr.866	○
Converter output voltage*6	0.1 V	8	*1	8	200 V class: 400 V 400 V class: 800 V	—
Regenerative brake duty*13	0.1%	9	*1	9	Brake duty determined by Pr.30 and Pr.70	—
Electronic thermal O/L relay load factor	0.1%	10	*1	10	Electronic thermal O/L relay (100%)	—
Output current peak value*6	0.01 A/0.1 A *5	11	*1	11	Pr.56	—
Converter output voltage peak value*6	0.1 V	12	*1	12	200 V class: 400 V 400 V class: 800 V	—
Input power	0.01 kW/0.1 kW *5	13	*1	13	Rated inverter power × 2	—
Output power*7	0.01 kW/0.1 kW *5	14	*1	14	Rated inverter power × 2	—

Monitored item	Unit	Pr.52, Pr.774 to Pr.776, Pr.992		Pr.54 (FM/CA) Pr.158 (AM) setting value	Terminal FM, CA, AM full-scale value	Minus (-) display/output *14
		DU	PU			
Load meter	0.1%	17	17	—	Pr.866	—
Motor excitation current*6	0.01 A/0.1 A *5	18	18	—	Pr.56	—
Position pulse	—	19	—	—	—	—
Cumulative energization time*2	1 h	20	—	—	—	—
Reference voltage output	—	—	21	—	—	—
Orientation status*8	1	22	—	—	—	—
Actual operation time*2*3	1 h	23	—	—	—	—
Motor load factor	0.1%	24	24	200%	—	—
Cumulative power*6	0.01 kWh/0.1 kWh*4*5	25	—	—	—	—
Position command	1	26	—	—	—	○
Position command (upper digits)	1	27	—	—	—	○
Current position	1	28	—	—	—	○
Current position (upper digits)	1	29	—	—	—	○
Droop pulse	1	30	—	—	—	○
Droop pulse (upper digits)	1	31	—	—	—	○
Torque command	0.1%	32	32	Pr.866	—	○
Torque current command	0.1%	33	33	Pr.866	—	○
Motor output	0.01 kW/0.1 kW *5	34	34	Rated motor capacity	—	—
Feedback pulse*8	—	35	—	—	—	—
Torque monitor (driving/regenerative polarity switching)	0.1%	36	36	Pr.866	—	○
Trace status	1	38	—	—	—	—
PLC function user monitor 1	Increment set in SD1215	40	—	—	—	—
PLC function user monitor 2	—	41	—	—	—	—
PLC function user monitor 3	—	42	—	—	—	—
Station number (RS-485 terminals)	1	43	—	—	—	—
Station number (PU)	1	44	—	—	—	—
Station number (CC-Link)	1	45	—	—	—	—
Motor temperature*8	1°C	46	46	Pr.751	—	○
Energy saving effect	Changeable by parameter setting	50	50	Inverter capacity	—	—
Cumulative energy saving	—	51	—	—	—	—
PID set point	0.1%	52	52	100%	—	—
PID measured value	0.1%	53	53	100%	—	—
PID deviation	0.1%	54	54*11	100%	—	○
Input terminal status	—	55	*1	—	—	—
Output terminal status	—	—	*1	—	—	—
Option input terminal status*8	—	56	—	—	—	—
Option output terminal status*8	—	57	—	—	—	—
Option input terminal status 1 (for communication)*8	—	—*12	—*12	—	—	—
Option input terminal status 2 (for communication)*8	—	—*12	—*12	—	—	—



Monitored item	Unit	Pr.52, Pr.774 to Pr.776, Pr.992		Pr.54 (FM/CA) Pr.158 (AM) setting value	Terminal FM, CA, AM full-scale value	Minus (-) display/output *14
		DU	PU			
Option output terminal status 1 (for communication)*8	—	—*12		—*12	—	
Motor thermal load factor	0.1%	61		61	Motor thermal activation level (100%)	
Inverter thermal load factor	0.1%	62		62	Inverter thermal activation level (100%)	
PTC thermistor resistance	0.01 kΩ	64		—	—	
PID measured value 2	0.1%	67		67	100%	
PLC function analog output	0.1%	—		70	100%	○
Cumulative pulse*8	—	71		—	—	○*16
Cumulative pulse overflow times*8	—	72		—	—	○*16
Cumulative pulse (control terminal option)*8	—	73		—	—	○*16
Cumulative pulse overflow times (control terminal option)*8	—	74		—	—	○*16
32-bit cumulative power (lower 16 bits)	1 kWh	—*12		—*12	—	
32-bit cumulative power (upper 16 bits)	1 kWh	—*12		—*12	—	
32-bit cumulative power (lower 16 bits)	0.01 kWh/0.1 kWh *5	—*12		—*12	—	
32-bit cumulative power (upper 16 bits)	0.01 kWh/0.1 kWh *5	—*12		—*12	—	
Remote output value 1	0.1%	87		87	1000%	
Remote output value 2	0.1%	88		88	1000%	
Remote output value 3	0.1%	89		89	1000%	○
Remote output value 4	0.1%	90		90	1000%	
PID manipulated variable	0.1%	91		91*11	100%	○
Second PID set point	0.1%	92		92	100%	
Second PID measured value	0.1%	93		93	100%	
Second PID deviation	0.1%	94		94*11	100%	○
Second PID measured value 2	0.1%	95		95	100%	
Second PID manipulated variable	0.1%	96		96*11	100%	○
Dancer main speed setting	0.01 Hz	97		97	Pr.55	
Control circuit temperature	1°C	98		98	100°C	○

- \*1 To display the monitored items from the frequency setting value to the output terminal status on a parameter unit (FR-PU07), select "other monitor".
- \*2 The cumulative energization time and actual operation time are accumulated from 0 to 65535 hours, then cleared, and accumulated again from 0.
- \*3 The actual operation time does not increase if the cumulative running time before power OFF is less than an hour.
- \*4 When using the parameter unit (FR-PU07), "kW" is displayed
- \*5 Differs according to capacities. (FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower/FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher)
- \*6 Since the voltage and current displays on the operation panel (FR-DU08) are shown in four digits, a monitor value of more than "9999" is displayed as "----".

- \*7 When the output current is less than the specified current level (5% of the inverter rated current), the output current is monitored as 0 A. Therefore, the monitored value of an output current and output power may be displayed as "0" when using a much smaller-capacity motor compared to the inverter or in other instances that cause the output current to fall below the specified value.
- \*8 Available when the option is connected.
- \*9 When Pr.37="1 to 9998" or Pr.144="2 to 12, 102 to 112", 1 increment is used. (Refer to page 97)
- \*10 The monitored values are retained even if an inverter fault occurs. Resetting will clear the retained values.
- \*11 Can be set for the AM (Pr.158) only.
- \*12 Can be set or monitored only via communication.
- \*13 The setting is available for the standard model only.
- \*14 Setting Pr.290 ≠ 0 enables the display/output with a minus sign.
- \*15 Setting Pr.1018 = 0 enables the display/output with a minus sign.
- \*16 Negative values are not displayed on the operation panel. The values "-1 to -32767" are displayed as "65535 to 32769" on the operation panel.

- Pr.774 sets the output frequency monitor, Pr.775 sets the output current monitor, and Pr.776 sets the monitor description to be displayed at the output voltage monitor position. When Pr.774 to Pr.776="9999" (initial value), the Pr.52 setting value is used. (For the monitor display sequence, refer to page 49.)
- Digits in the cumulative power monitor can be shifted to the right by the number set in Pr.891.
- Writing "0" in Pr.170 clears the cumulative power monitor.
- Pr.563 allows the user to check how many times the cumulative energization time monitor has exceeded 65535 h. Pr.564 allows the use to check how many times the actual operation time monitor has exceeded 65535 h.
- Writing "0" in Pr.171 clears the actual operation time monitor.

Pr.268 setting	Description
9999 (initial value)	No function
0	When monitoring with the first or second decimal place (0.1 increments or 0.01 increments), the 0.1 decimal place or lower is dropped to display an integral value (1 increments). The monitor value equal to or smaller than 0.99 is displayed as 0.
1	When monitoring with the second decimal place (0.01 increments), the 0.01 decimal place is dropped and the monitor displays the first decimal place (0.1 increments). When monitoring with the first decimal place, the display will not change.

- When Pr.52="100", the set frequency is displayed during stop, and output frequency is displayed during running. (LED of Hz flickers during stop and is lit during operation.)

Pr.52	0		100	
	Operating status	During running/stop	During stop	Running
Output frequency	Output frequency	Set frequency	Output frequency	
Output current	Output current			
Output voltage	Output voltage			
Fault or alarm indication	Fault or alarm indication			

- The monitored item to be displayed at the operation panel (FR-DU08)'s setting dial push can be selected with Pr.992.

Pr.992	0		100	
	Operating status	During running/stop	During stop	Running
Monitor displayed by the setting dial push	Set frequency (PU direct-in frequency)	Set frequency	Output frequency	

- Pr.290 enables minus-sign outputs via the terminal AM (analog voltage output) or the communication. It also enables the minus-sign display on the operation panel (FR-DU08).

Pr.290 setting	Minus-sign output from terminal AM	Minus-sign display on operation panel	Minus-sign output via communication
0 (initial value)	-	-	-
1	Output with minus sign	-	-
2	-	Displayed with minus sign.	-
3	Output with minus sign	Displayed with minus sign.	-
4	-	-	Output with minus sign
5	Output with minus sign	-	Output with minus sign
6	-	Displayed with minus sign.	Output with minus sign
7	Output with minus sign	Displayed with minus sign.	Output with minus sign

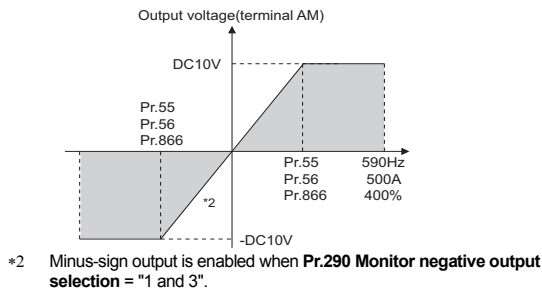
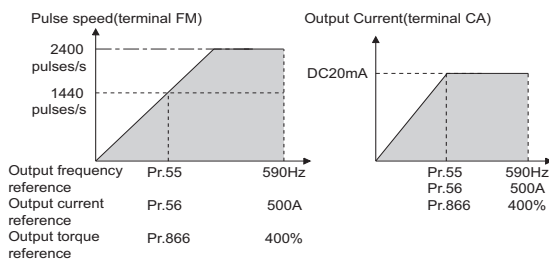
### Reference for monitor value output from terminal FM/CA, AM

Pr.	GROUP	Name	Pr.	GROUP	Name
55	M040	Frequency monitoring reference	56	M041	Current monitoring reference
866	M042	Torque monitoring reference			

Full scales can be set for the values output from the terminal FM/CA and AM.

Monitor*1	Reference parameter	Initial value
Frequency	Pr.55	FM type, 60 Hz CA type 50 Hz
Current	Pr.56	Inverter rated current
torque	Pr.866	150%

\*1 For the monitored item names, refer to the page on Pr.52.



### Automatic restart after instantaneous power failure with an induction motor

V/F Magnetic flux Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
57	A702	Restart coasting time	58	A703	Restart cushion time
162	A700	Automatic restart after instantaneous power failure selection	163	A704	First cushion time for restart
164	A705	First cushion voltage for restart	165	A710	Stall prevention operation level for restart
299	A701	Rotation direction detection selection at restarting	611	F003	Acceleration time at a restart

The inverter can be restarted without stopping the motor in the following conditions:

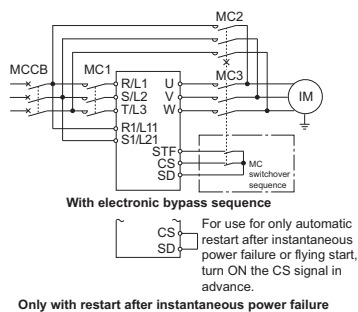
- When switching from commercial power supply operation over to inverter operation
- When an instantaneous power failure occurs during inverter operation
- When the motor is coasting at start

Pr.	Setting range	Description	
162	0 (initial value)	Frequency search only performed at the first start	
	1	Reduced voltage start only at the first start (no frequency search)	
	2	PLG Encoder detection frequency search	
	3	Frequency search only performed at the first start (reduced impact restart)	
	10	Frequency search at every start	
	11	Reduced voltage start at every start (no frequency search)	
	12	Encoder detection frequency search at every start	
	13	Frequency search at every start (reduced impact restart)	
	299	0 (initial value)	Without rotation direction detection
		1	With rotation direction detection
		9999	When Pr.78 Reverse rotation prevention selection = "0", with rotation direction detection Pr.78 Reverse rotation prevention selection = "1, 2", without rotation direction detection
	57	0	Coasting time differs according to the inverter capacity.*1
		0.1 to 30s	Set the waiting time for the inverter to perform a restart after the power lost by an instantaneous power failure restores.
	9999 (initial value)	No restart	
58	0 to 60 s	Set the voltage cushion time for restart.	
163	0 to 20 s	Set the voltage cushion time for restart.	
164	0 to 100%	Set a value considering the load amount (moment of inertia, torque).	
165	0 to 400%	Set the stall prevention level at restart considering the inverter rated current as 100%.	
611	0 to 3600 s	Set the acceleration time that takes to reach Pr.20 Acceleration/deceleration reference frequency setting at a restart.	
	9999 (initial value)	Normal acceleration time setting (settings like Pr.7 ) is applied as the acceleration time for restart.	

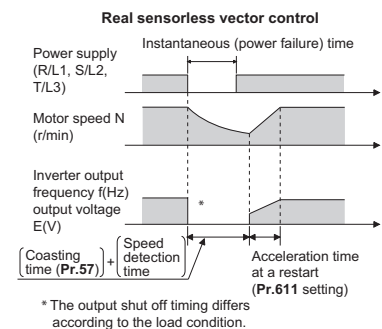
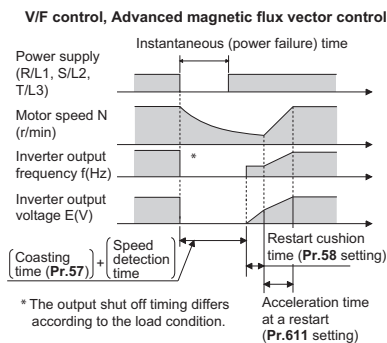
\*1 The coasting time when Pr.57="0" is as shown below. (When Pr.162 is set to the initial value and the ND rating is selected.)  
FR-A820-00105(1.5K) or lower and, FR-A840-00052(1.5K) or lower: 0.5s  
FR-A820-00167(2.2K) to FR-A820-00490(7.5K) and  
FR-A840-00083(2.2K) to FR-A840-00250(7.5K): 1 s  
FR-A820-00630(11K) to FR-A820-03160(55K) and  
FR-A840-00310(11K) to FR-A840-01800(55K): 3.0 s  
FR-A820-03800(75K) or higher and, FR-A840-02160(75K) or higher : 5.0 s

Features  
Application Example  
FR Configurator2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry

<Connection diagram>

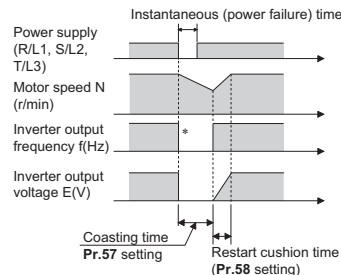


- Pr.162="0 (initial value), 3, 10, or 13", the motor speed is detected at power restoration to start the motor smoothly.
- During encoder feedback control with Pr.162 = "2 or 12" or during vector control, the motor starts at power restoration based on the motor speed and rotation direction detected by the encoder. (This operation is available when a vector control compatible option is installed.)
- Setting Pr.162 = "3, 13" will lead to better-absorbed impacts and smoother motor start. (Reduced impact restart) than the Pr.162 = "0, 10" setting does. (Offline auto tuning)  
Under Real sensorless vector control, the reduced impact restart is applied, independently of the Pr.162 setting.
- The encoder also detects the rotation direction during reverse rotation so that the inverter can re-start smoothly. (Pr.299 Rotation direction detection selection at restarting to enable/disable the rotation direction detection)



- When Pr.162 = "1" or "11", automatic restart operation is performed in a reduced voltage system, where the voltage is gradually risen with the output frequency unchanged from prior to an instantaneous power failure independently of the coasting speed of the motor.  
During Real sensorless vector control, the output frequency and voltage before an instantaneous power failure are output. (The Pr.58 setting is disabled.)

V/F control, Advanced magnetic flux vector control



### Automatic restart after instantaneous power failure with a PM motor

Pr.	GROUP	Name	Pr.	GROUP	Name
57	A702	Restart coasting time	162	A700	Automatic restart after instantaneous power failure selection
611	F003	Acceleration time at a restart			

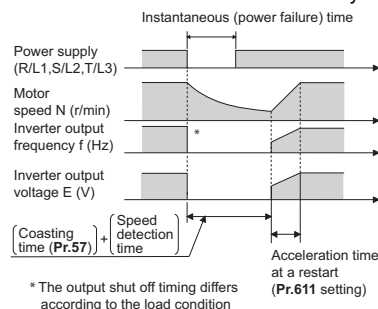
While using an IPM motor MM-CF, the inverter can be restarted without stopping the motor.  
By enabling the automatic restart after instantaneous power failure function in the following conditions, the motor can be restarted.

- When an instantaneous power failure occurs during inverter operation
- When the motor is coasting at start

Pr.	Setting range	Description
57	0	No waiting time
	0.1 to 30 s	Set the waiting time for the inverter to perform a restart after the power lost by an instantaneous power failure restores.
	9999 (initial value)	No restart
162	0 (initial value), 1, 2, 3	Frequency search only performed at the first start
	10, 11, 12, 13	Frequency search at every start
611	0 to 3600 s	Set the acceleration time that takes to reach Pr.20 Acceleration/deceleration reference frequency at a restart.
	9999 (initial value)	Standard acceleration time (for example, Pr.7) s applied as the acceleration time at restart.

#### ◆ Selection for the automatic restart (Pr.162)

The motor speed is detected (frequency search) at power restoration to start the motor smoothly.  
The encoder also detects the rotation direction during reverse rotation so that the inverter can re-start smoothly.





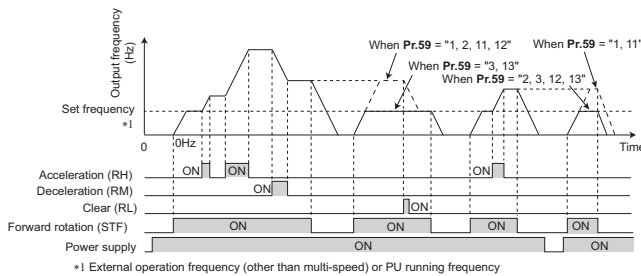
## Remote setting function

Pr.	GROUP	Name
59	F101	Remote function selection

Even if the operation panel is located away from the enclosure, contact signals can be used to perform continuous variable-speed operation, without using analog signals.

By simply setting this parameter, the acceleration, deceleration and setting clear functions of the remote speed setter (FR-FK) become available.

Pr.59 setting	Description		
	RH, RM, RL signal function	Frequency setting storage	Deceleration to the frequency lower than the set frequency
0 (initial value)	Multi-speed setting	-	Not available
1	Remote setting	With	
2	Remote setting	Not used	
3	Remote setting	Not used (Turning STF/STR OFF clears remotely set frequency.)	
11	Remote setting	With	Available
12	Remote setting	Not used	
13	Remote setting	Not used (Turning STF/STR OFF clears remotely set frequency.)	



## Energy saving control selection



Pr.	GROUP	Name
60	G030	Energy saving control selection

Inverter will perform energy saving control automatically even when the detailed parameter settings are made.

It is appropriate for an application such as a fan or pump.

Pr.60 setting	Description
0 (initial value)	Normal operation
4	Energy saving operation*1 With the energy saving operation, the inverter will automatically control the output voltage so the inverter output power during the constant-speed operation will become minimal. (Available during V/F control)
9	Optimum excitation control*1 The Optimum excitation control is a control method to decide the output voltage by controlling the excitation current so the efficiency of the motor is maximized. (Available during V/F control or Advanced magnetic flux vector control)

\*1 Output current may increase slightly with the energy saving operation or the Optimum excitation control since the output voltage is controlled.

## Automatic acceleration/deceleration



Pr.	GROUP	Name	Pr.	GROUP	Name
61	F510	Reference current	62	F511	Reference value at acceleration
63	F512	Reference value at deceleration	64	F520	Starting frequency for elevator mode
292	F500	Automatic acceleration/deceleration	293	F513	Acceleration/deceleration separate selection

The inverter can be operated with the auto-adjusted parameters.

- Without setting the acceleration/deceleration time or the V/F pattern, the inverter can be operated as if the appropriate value is set to each parameter. This function is useful for operating the inverter without setting detailed parameters.
- Even if automatic acceleration/deceleration has been selected, inputting the JOG signal, RT signal (second function selection), or X9 signal (third function selection) during an inverter stop will switch to the normal operation and give priority to JOG operation, second function selection or third function selection. After the motor is started by the automatic acceleration/deceleration, none of JOG, RT, or X9 signal is accepted.

Pr.292 setting	Operation		Automatic setting Pr.
0 (initial value normal operation)	-		-
1 (shortest acceleration/deceleration)	Without brake resistor or the brake unit	Set this parameter to accelerate/decelerate the motor at the shortest time. (Stall prevention operation level 150%)	Pr.7, Pr.8
11 (shortest acceleration/deceleration)	With brake resistor, brake unit		
3 (optimum acceleration/deceleration)	Optimal operation that fully uses the inverter's capability is performed.		Pr.0, Pr.7, Pr.8
5 (lift mode)	Stall prevention operation level 150%	The inverter output voltage is controlled so that enough torque is provided during power driving and regenerative driving.	Pr.0, Pr.13, Pr.19
6 (lift mode 2)	Stall prevention operation level 180%		
7 (Brake sequence mode 1)	With machine brake opening completion signal	In this operation mode, operation timing signals of the mechanical brake are output from the inverter, such as for lift application.	-
8 (Brake sequence mode 2)	Without machine brake opening completion signal		

- Pr.61 to Pr.63 can be used to change the reference current for the shortest acceleration/deceleration and the optimal acceleration/deceleration operation.
- Use Pr.64 to set the starting frequency for the lift operation.
- Acceleration/deceleration times can be individually calculated. Such a setting can be enabled/disabled for the shortest acceleration/deceleration operation and the optimum acceleration/deceleration.

Pr.293 setting	Description
0 (initial value)	Both the acceleration and deceleration times are calculated.
1	Only the acceleration time is calculated.
2	Only the deceleration time is calculated.



## Retry function

Pr.	GROUP	Name	Pr.	GROUP	Name
65	H300	Retry selection	67	H301	Number of retries at fault occurrence
68	H302	Retry waiting time	69	H303	Retry count display erase

This function allows the inverter to reset itself and restart at activation of the protective function (fault indication). The retry generating faults can be also selected.

When the automatic restart after instantaneous power failure function is selected (**Pr.57 Restart coasting time** ≠ 9999), the restart operation is also performed after a retry operation as well as after an instantaneous power failure.

- Using **Pr.65**, you can select the fault that will cause a retry. "●" indicates the faults selected for retry.

Retry target Fault indication	Pr.65 setting					
	0	1	2	3	4	5
E.OC1	●	●		●	●	●
E.OC2	●	●		●	●	
E.OC3	●	●		●	●	●
E.OV1	●		●	●	●	
E.OV2	●		●	●	●	
E.OV3	●		●	●	●	
E.THM	●					
E.THT	●					
E.IPF	●				●	
E.UVT	●				●	
E.BE	●				●	
E.GF	●				●	
E.OHT	●				●	
E.OLT	●				●	
E.OPT	●				●	
E.OP1	●				●	
E.PE	●				●	
E.MB1	●				●	
E.MB2	●				●	
E.MB3	●				●	
E.MB4	●				●	
E.MB5	●				●	
E.MB6	●				●	
E.MB7	●				●	
E.OS	●				●	
E.OSD	●				●	
E.PTC	●				●	
E.CDO	●				●	
E.SER	●				●	
E.USB	●				●	
E.ILF	●				●	
E.PID	●				●	
E.PCH	●				●	
E.SOT	●	●		●	●	●
E.LCI	●				●	

- For **Pr.67**, set the number of retries at a fault occurrence.

Pr.67 setting	Description
0 (initial value)	No retry function
1 to 10	Set the number of retries at fault occurrence. A fault output is not provided during the retry operation.
101 to 110	Set the number of retries at fault occurrence. (The setting value minus 100 is the number of retries.) A fault output is provided during the retry operation.

- For **Pr.68**, set the waiting time (0.1 to 600 s) from a protective function activation to a retry.
- By reading **Pr.69**, the number of successful restarts made by retries can be obtained.

**Pr.66** ➤ Refer to the page on Pr.22

**Pr.67 to 69** ➤ Refer to the page on Pr.65

**Pr.70** ➤ Refer to the page on Pr.30

## Applicable motor

Pr.	GROUP	Name	Pr.	GROUP	Name
71	C100	Applied motor	450	C200	Second applied motor

Setting of the applied motor selects the thermal characteristic appropriate for the motor. When using a constant-torque or PM motor, the electronic thermal O/L relay is set according to the used motor.

Pr.71	Pr.450	Applied motor	Setting increment for motor constant	Operational characteristic of the electronic thermal O/L relay			
				Standard	Constant-torque	PM	
0 (Pr.71 initial value)		Standard motor (such as SF-JR)	Ω, mΩ, mH, %, A, mV	○			
1		Constant-torque motor (SF-JRCA, etc.) SF-V5RU (except for 1500 r/min series)			○		
2	—	Standard motor (such as SF-JR) Adjustable 5 points V/F (Refer to page 110)		○			
20		Mitsubishi standard motor (SF-JR 4P 1.5kW or lower)			○		
30		Vector control dedicated motor SF-V5RU (1500 r/min series) SF-THY			○		
40		Mitsubishi high-efficiency motor SF-HR		○			
50		Mitsubishi constant-torque motor SF-HRCA			○		
70		Mitsubishi high-performance energy-saving motor SF-PR			○		
330*1		IPM motor MM-CF				○	
8090		IPM motor (other than MM-CF)			○		
9090		SPM motor			○		
3, 4		Standard motor (such as SF-JR)		Internal data	○		
13, 14		Constant-torque motor (SF-JRCA, etc.) SF-V5RU (except for 1500 r/min series)				○	
23, 24		Mitsubishi standard motor (other than SF-JR 4P 1.5kW)				○	
33, 34		Vector control dedicated motor SF-V5RU (1500 r/min series) SF-THY			○		
43, 44		Mitsubishi high-efficiency motor SF-HR	○				
53, 54		Mitsubishi constant-torque motor SF-HRCA			○		
73, 74		Mitsubishi high-performance energy-saving motor SF-PR			○		
333, 334*1		IPM motor MM-CF				○	
8093, 8094		IPM motor (other than MM-CF)			○		
9093, 9094		SPM motor			○		
5		Standard motor	Ω, mΩ, A	○			
15		Constant-torque motor			○		
6		Standard motor		○			
16		Constant-torque motor			○		
—	9999 (initial value)	No second applied motor					

\*1 The setting is available for FR-A820-00630(11K) or lower.

- When initial values are set in **Pr.0** and **Pr.12**, the **Pr.0** and **Pr.12** settings are automatically changed by changing the **Pr.71** setting.

## Carrier frequency and Soft-PWM selection

Pr.	GROUP	Name	Pr.	GROUP	Name
72	E600	PWM frequency selection	240	E601	Soft-PWM operation selection
260	E602	PWM frequency automatic switchover			

The motor sound can be changed.

Pr.	Setting range	Description
72	0 to 15*1	The PWM carrier frequency can be changed. The setting displayed is in [kHz]. Note that 0 indicates 0.7 kHz, 15 indicates 14.5 kHz, and 25 indicates 2.5 kHz. (When using an optional sine wave filter, set "25".)
	0 to 6, 25*2	
240	0	Soft-PWM disabled
	1 (initial value)	Soft-PWM enabled
260	0	PWM carrier frequency automatic reduction function disabled (for the LD, ND, or HD rating)
	1 (initial value)	PWM carrier frequency automatic reduction function enabled

- \*1 The setting range for the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower.
- \*2 The setting range for the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher.

- Under Real sensorless vector control, vector control, and PM sensorless vector control, the following carrier frequencies are used. (For the control method and fast-response operation selection, refer to **Pr.800 Control method selection** refer to **page 108**)

Pr.72 setting	Carrier frequency (kHz)		
	Real sensorless vector control, vector control	PM sensorless vector control	fast-response operation selection
0 to 5	2	6*3	4
6, 7	6*4	6	
8, 9	10*4	10	
10 to 13	14*4	14	
14, 15			

- \*3 When low-speed range high-torque characteristic is disabled (Pr.788="0"), 2 kHz is used.
- \*4 In the low-speed range (3 Hz or lower) under Real sensorless vector control, the carrier frequency is automatically changed to 2 kHz. (For FR-A820-00490(7.5K) or lower and FR-A840-00250(7.5K) or lower)

- PWM carrier frequency automatic reduction function (Pr.260) Setting Pr.260="1 (initial value)" will enable the PWM carrier frequency auto-reduction function. If a heavy load is continuously applied while the inverter carrier frequency is set to 3 kHz or higher (Pr.72 ≥ "3"), the carrier frequency is automatically reduced to prevent occurrence of the inverter overload trip (electronic thermal O/L relay function) (E.THT). The carrier frequency is reduced to as low as 2 kHz. (Motor noise increases, but not to the point of failure.)
- When the PWM carrier frequency automatic reduction function is used, the operation with the carrier frequency set to 3 kHz or higher (Pr.72 ≥ "3") automatically reduces the carrier frequency for heavy-load operation as shown below.

Pr.260 setting	Pr.570 setting	Carrier frequency automatic reduction operation	
		FR-A820-04750(90K) or lower, FR-A840-02600(90K) or lower	FR-A840-03250(110K) or higher
1	0 (SLD), 1 (LD)	Continuous operation with the 85% or higher inverter rated current reduces the carrier frequency automatically.	Continuous operation with the 85% or higher inverter rated current reduces the carrier frequency automatically.
	2 (ND), 3 (HD)	Operation with the 150% or higher inverter rated current for the ND rating reduces the carrier frequency automatically.	Continuous operation with the 85% or higher inverter rated current reduces the carrier frequency automatically.
0	0 (SLD)	Continuous operation with the 85% or higher inverter rated current reduces the carrier frequency automatically.	Without carrier frequency automatic reduction (Perform continuous operation with the carrier frequency set to 2 kHz or lower or with less than 85% of the rated inverter current.)
	1 (LD)	Without carrier frequency automatic reduction (Perform continuous operation with the carrier frequency set to 2 kHz or lower or with less than 85% of the rated inverter current.)	Without carrier frequency automatic reduction (Perform continuous operation with the carrier frequency set to 2 kHz or lower or with less than 85% of the rated inverter current.)
	2 (ND), 3 (HD)	Without carrier frequency automatic reduction	Without carrier frequency automatic reduction

- In the low-speed range (about 10 Hz or lower), the carrier frequency may be automatically lowered. Motor noise increases, but not to the point of failure.

## Analog input selection

Pr.	GROUP	Name	Pr.	GROUP	Name
73	T000	Analog input selection	267	T001	Terminal 4 input selection
242	T021	Terminal 1 added compensation amount (terminal 2)	243	T041	Terminal 1 added compensation amount (terminal 4)
252	T050	Override bias	253	T051	Override gain

The analog input terminal specifications, the override function, and the function to switch forward/reverse rotation by the input signal polarity can be set.

Concerning the terminals 2 and 4 used for analog input, the voltage input (0 to 5 V, 0 to 10 V) and current input (0 to 20 mA) are selectable. To input a voltage (0 to 5 V/ 0 to 10 V), set the voltage/current input switch OFF. To input a current (0 to 20 mA), set the voltage/current input switch ON and change the parameters (Pr.73, Pr.267).

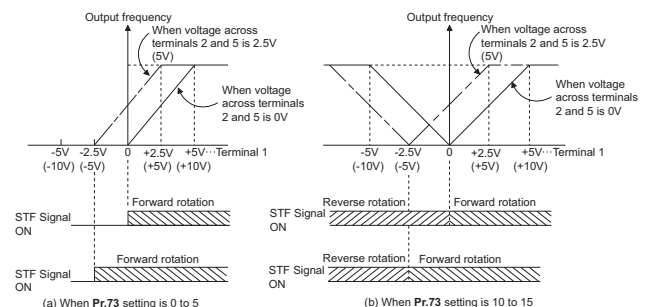
Addition compensation or fixed ratio analog compensation (override) with terminal 2 set to auxiliary input is applicable to the multi-speed operation or terminal 2/terminal 4 speed setting signal (main speed). (Bold frame indicates the main speed setting.)

Pr.73 setting	Terminal 2 input	Switch 1	Terminal 1 input	Compensation input terminal compensation method	Polarity reversible
0	0 to 10 V	OFF	0 to ±10 V	Terminal 1 Addition compensation	Not applied (state in which a negative polarity frequency command signal is not accepted)
1 (initial value)	0 to 5 V	OFF	0 to ±10 V		
2	0 to 10 V	OFF	0 to ±5 V		
3	0 to 5 V	OFF	0 to ±5 V	Terminal 2 Override	Applied
4	0 to 10 V	OFF	0 to ±10 V		
5	0 to 5 V	OFF	0 to ±5 V	Terminal 1 Addition compensation	Applied
6	0 to 20 mA	ON	0 to ±10 V		
7	0 to 20 mA	ON	0 to ±5 V		
10	0 to 10 V	OFF	0 to ±10 V		
11	0 to 5 V	OFF	0 to ±10 V		
12	0 to 10 V	OFF	0 to ±5 V		
13	0 to 5 V	OFF	0 to ±5 V		
14	0 to 10 V	OFF	0 to ±10 V	Terminal 2 Override	Applied
15	0 to 5 V	OFF	0 to ±5 V		
16	0 to 20 mA	ON	0 to ±10 V	Terminal 1 Addition compensation	Applied
17	0 to 20 mA	ON	0 to ±5 V		

- Turning ON the Terminal 4 input selection (AU) signal sets terminal 4 to the main speed.
- Set the Pr.267 and voltage/current input switch setting according to the table below.

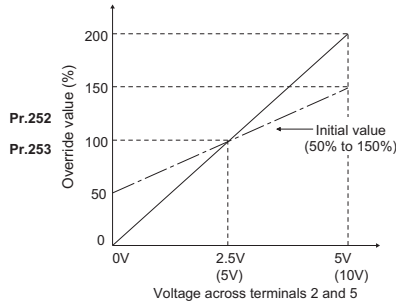
Pr.267 setting	Terminal 4 input	Switch 2
0 (initial value)	4 to 20 mA	ON
1	0 to 5 V	OFF
2	0 to 10 V	OFF

- Addition compensation (Pr.242, Pr.243) A compensation signal is addable to the main speed setting for such as synchronous or continuous speed control operation.



Terminal 1 (frequency setting auxiliary input) is added to the terminal 2 or 4 main speed setting signal.

- Override function (**Pr.252, Pr.253**)  
When the override setting is selected, terminal 1 or 4 is set to the main speed setting, and terminal 2 is set to the override signal. (If the main speed of terminal 1 or 4 is not input, the compensation by terminal 2 is disabled.)



- When **Pr.868 (Pr.858) = "4"**, the terminal 1 (terminal 4) values are set to the stall prevention operation level.

## Analog input responsiveness and noise elimination

Pr.	GROUP	Name	Pr.	GROUP	Name
74	T002	Input filter time constant	822	T003	Speed setting filter 1
826	T004	Torque setting filter 1	832	T005	Speed setting filter 2
836	T006	Torque setting filter 2	849	T007	Analog input offset adjustment

The frequency command/torque command response level and stability are adjustable by using the analog input (terminals 1, 2, and 4) signal.

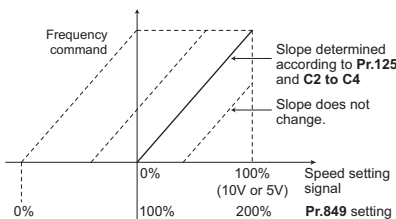
- **Pr.74** is effective to eliminate noise on the frequency setting circuit.  
Increase the filter time constant if steady operation cannot be performed due to noise, etc.  
A larger setting results in slower response. (The time constant can be between 0 and 8, which are about 5 ms to 1 s.)
- Set the primary delay filter time constant to the external speed command (analog input command) by using **Pr.822** or **Pr.832**. Set a larger time constant when delaying the speed command tracking or the analog input voltage is unstable.
- Set the primary delay filter time constant to the external torque command (analog input command) by using **Pr.826** or **Pr.836**. Set a larger time constant when delaying the torque command tracking or the analog input voltage is unstable.
- Set a value other than "9999" in **Pr.832** and **Pr.836**, which are enabled when the RT signal is ON.
- Setting **Pr.849** will offset the analog speed input (terminal2) and avoid the occurrence of a frequency command due to noise when the 0-speed command is given.

The offset voltage is positive when  $100\% < \text{Pr.849}$  and negative when  $\text{Pr.849} < 100\%$ . The detailed calculation of the offset voltage is as described below:

Offset voltage [V] =

$$\text{Voltage at the time of } 100\% (5 \text{ V or } 10 \text{ V} \times 1) \times (\text{Pr.849} - 100) / 100$$

\*1 It depends on the **Pr.73** setting.



## Reset selection/disconnected PU detection/PU stop selection

Pr.	GROUP	Name
75	E100	Reset selection
	E101	Disconnected PU detection
	E102	PU stop selection
	E107	Reset limit
	-	Reset selection/ disconnected PU detection/ PU stop selection

The reset input acceptance, disconnected PU (FR-DU08/FR-PU07) connector detection function and PU stop function can be selected.

Pr.75 setting	Reset selection	Disconnected PU detection	PU stop selection
0, 100	Reset input always enabled	Operation continues even when PU is disconnected.	Decelerates to a stop when  is input in PU operation mode only.
1, 101	Reset input enabled only when protective function activated		
2, 102	Reset input always enabled	Inverter output shut off when PU disconnected.	Decelerates to a stop when  is input in any of the PU, external and communication operation modes.
3, 103	Reset input enabled only when protective function activated		
14 (Initial value), 114	Reset input always enabled	Operation continues even when PU is disconnected.	Decelerates to a stop when  is input in any of the PU, external and communication operation modes.
15, 115	Reset input enabled only when protective function activated		
16, 116	Reset input always enabled	Inverter output shut off when PU disconnected.	Decelerates to a stop when  is input in any of the PU, external and communication operation modes.
17, 117	Reset input enabled only when protective function activated		

- Reset selection (**P.E100**)  
When **P.E100** = "1" or **Pr.75** = "1, 3, 15, 17, 100, 101, 103, 115, or 117" is set, reset (reset command via RES signal or communication) input is enabled only when the protective function is activated.
- Disconnected PU detection (**P.E101**)  
If the PU (FR-DU08/FR-PU07) is detected to be disconnected from the inverter for 1 s or longer while **P.E101** = "1" or **Pr.75** = "2, 3, 16, 17, 102, 103, 116, or 117", PU disconnection (E.PUE) is displayed and the inverter output is shut off.
- PU stop selection (**P.E102**)

Stop can be performed by inputting from the PU in any of the operation modes of PU operation, External operation and network operation.

- Reset limit function (**P.E107**)  
When **Pr.75** = any of "100 to 103 and 114 to 117", if an electronic thermal O/L relay or an overcurrent protective function (E.THM, E.THT, E.OC[]) is activated while one of them has been already activated within 3 minutes, the inverter will not accept any reset command (RES signal, etc.) for about 3 minutes from the second activation.

The reset limit function is available with the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher.

## Fault code output function

Pr.	GROUP	Name
76	M510	Fault code output selection

When a fault occurs, the corresponding data can be output as a 4-bit digital signal using via an open collector output terminal.

The fault code can be read using a programmable controller, etc., and countermeasures can be displayed on the HMI (Human Machine Interface), etc.

Pr.76 setting	Description
0 (initial value)	Without fault code output
1	With fault code output (Refer to the table below.)
2	Fault code is output only when a fault occurs. (Refer to the table below.)

- The fault codes that can be output are shown in the table below. (0: Output transistor OFF, 1: Output transistor ON)

Operation panel indication (FR-DU08)	Output terminal operation				Fault code
	SU	IPF	OL	FU	
Normal *1	0	0	0	0	0
E.OC1	0	0	0	1	1
E.OC2	0	0	1	0	2
E.OC3	0	0	1	1	3
E.OV1 to E.OV3	0	1	0	0	4
E.THM	0	1	0	1	5
E.THT	0	1	1	0	6
E.IPF	0	1	1	1	7
E.UVT	1	0	0	0	8
E.FIN	1	0	0	1	9
E.BE	1	0	1	0	A
E.GF	1	0	1	1	B
E.OHT	1	1	0	0	C
E.OLT	1	1	0	1	D
E.OPT E.OP1	1	1	1	0	E
Other than the above	1	1	1	1	F

\*1 When Pr.76 = "2", the terminal outputs the signal assigned by Pr.191 to Pr.194 in normal operation.

## Parameter write selection

Pr.	GROUP	Name
77	E400	Parameter write selection

Whether to enable the writing to various parameters or not can be selected. Use this function to prevent parameter values from being rewritten by misoperation.

Pr.77 setting	Description
0 (initial value)	Writing is enabled only during stop.
1	Parameter writing is disabled.
2	Parameter writing is enabled in any operation mode regardless of the operation status. (Writing is disabled for some parameters.)

## Reverse rotation prevention selection

Pr.	GROUP	Name
78	D020	Reverse rotation prevention selection

This function can prevent reverse rotation fault resulting from the incorrect input of the start signal.

































Pr.78 setting	Description
0 (initial value)	Both forward and reverse rotations allowed
1	Reverse rotation disabled
2	Forward rotation disabled

## Operation mode selection

Pr.	GROUP	Name	Pr.	GROUP	Name
79	D000	Operation mode selection	340	D001	Communication startup mode selection

Select the operation mode of the inverter.

The mode can be changed among operations using external signals (External operation), operation by operation panel (FR-DU08) or parameter unit (FR-PU07) (PU operation), combined operation of PU operation and External operation (External/PU combined operation), and Network operation (when RS-485 terminals or communication option is used).

Pr.79 setting	Description			LED display : OFF : ON
0 (initial value)	Use the External/PU switchover mode (  ) to switch between the PU and External operation mode. At power ON, the inverter is in the External operation mode.			PU operation mode    External operation mode    NET operation mode   
1	Operation mode	Frequency command	Start command	PU operation mode   
	PU operation mode fixed	Operation panel (FR-DU08) and PU(FR-PU07)	 or  on PU (FR-DU08/FR-PU07)	
2	External operation mode fixed. The operation can be performed by switching between the External and NET operation modes.	External signal input (terminal 2 and 4, JOG, multi-speed selection, etc.)	External signal input (terminal STF, STR)	External operation mode    NET operation mode   
	External/PU combined operation mode 1	PU (FR-DU08/FR-PU07) or external signal input (multi-speed setting, terminal 4)	External signal input (terminal STF, STR)	
4	External/PU combined operation mode 2	External signal input (terminal 2 and 4, JOG, multi-speed selection, etc.)	 or  on PU (FR-DU08/FR-PU07)	  
	Switchover mode Switching of PU, External, and NET operation modes can be performed during operation.			
7	External operation mode (PU operation interlock) X12 signal ON: Switchover to PU operation mode enabled (during External operation, output shutoff) X12 signal OFF: Switchover to PU operation mode disabled			External operation mode    NET operation mode   

### • Selecting the operation mode for power-ON (Pr.340)

When power is switched ON or when power comes back ON after an instantaneous power failure, the inverter can be started up in the Network operation mode.

After the inverter starts up in Network operation mode, parameter writing and operation can be commanded from programs.

Set this mode when performing communication operation using the RS-485 terminals or a communication option.


Use **Pr.79** and **Pr.340** to set the operation mode at power-ON (reset).

Pr.340 setting	Pr.79 setting	Operation mode at power-ON, at power restoration, or after a reset.	Operation mode switching
0 (initial value)	Follows the <b>Pr.79</b> setting.		
1, 2 *1	0	NET operation mode	Switching among the External, PU, and NET operation modes is enabled*2
	1	PU operation mode	PU operation mode fixed
	2	NET operation mode	Switching between the External and NET operation modes is enabled. Switching to PU operation mode is disabled
	3, 4	External/PU combined operation mode	Operation mode switching is disabled
	6	NET operation mode	Switching among the External, PU, and NET operation mode is enabled while running.
	7	X12 (MRS) signal ON NET operation mode	Switching among the External, PU, and NET operation modes is enabled*2
		X12 (MRS) signal OFF External operation mode	External operation mode fixed (Forcibly switched to External operation mode)
10, 12 *1	0	NET operation mode	Switching between the PU and NET operation mode is enabled*3
	1	PU operation mode	PU operation mode fixed
	2	NET operation mode	NET operation mode fixed
	3, 4	External/PU combined operation mode	Operation mode switching is disabled
	6	NET operation mode	Switching between the PU and NET operation mode is enabled while running*3
	7	NET operation mode	Switching between the PU and NET operation mode is enabled while running*3
		External operation mode	External operation mode fixed (Forcibly switched to External operation mode)

\*1 Use **Pr.340** = "2 or 12" setting to perform communication with the RS-485 terminals.

Even if an instantaneous power failure occurs while **Pr.57 Restart coasting time** ≠ "9999" (with automatic restart after instantaneous power failure), the inverter continues operation at the condition before the instantaneous failure.

\*2 The operation mode cannot be directly changed between the PU operation mode and Network operation mode.

\*3 Switching between the PU and NET operation modes is available with the  key on the operation panel (FR-DU08) and the X65 signal.





## Changing the control method

Pr.	GROUP	Name	Pr.	GROUP	Name
71	C100	Applied motor	80	C101	Motor capacity
81	C102	Number of motor poles	83	C104	Rated motor voltage
84	C105	Rated motor frequency	89	G932	Speed control gain (Advanced magnetic flux vector)
450	C200	Second applied motor	451	G300	Second motor control method selection
453	C201	Second motor capacity	454	C202	Number of second motor poles
569	G942	Second motor speed control gain	800	G200	Control method selection
862	C242	Encoder option selection			

Select the inverter control method.

Pr.80 (Pr.453), Pr.81 (Pr.454)	Pr.71 (Pr.450)	Pr.800 setting *1	Pr.451 setting *1	Control method	Control mode
Other than 9999	Induction motor	0, 100		Vector control-2	Speed control
		1, 101			Torque control
		2, 102			Speed control/torque control switchover
		3, 103			Position control
		4, 104			Speed control/position control switchover
		5, 105			Position control/torque control switchover
		6, 106		Torque control (variable-current limiter control)	
		9, 109	-	Vector control test operation	
		10, 110-3		Real sensorless vector control	Speed control
		11, 111			Torque control
		12, 112			Speed control/torque control switchover
		20 (initial value)	20	Advanced magnetic flux vector control	Speed control
	-	9999 (initial value)	Advanced magnetic flux vector control for the second motor		
	IPM motor (MM-CF)	9, 109	-	PM sensorless vector control test operation	
		13, 113		PM sensorless vector control	Position control-9
		14, 114			Speed control/position control switchover-9
		20 (initial value), 110-4	20, 110-5		Speed control
	IPM/SPM motor (other than MM-CF)	9, 109	-	PM sensorless vector control test operation	
		20 (initial value), 110-6	20, 110-7	PM sensorless vector control	Speed control
		0 to 6, 100 to 106		Vector control (Refer to the instruction manual of the FR-A8APR.)	
IPM/SPM motor	-	9999 (initial value)	The setting value of Pr.800 is used for the second motor. (PM sensorless vector control (speed control) when Pr.800="9 or 109")		
9999-s (initial value)	-	-	V/F control		

- \*1 The setting values of 100 and above are used when the fast-response operation is selected.
- \*2 A vector control compatible option is required.
- \*3 The operation for the setting of "10 or 110" is performed when "13, 14, 113, or 114" is set.
- \*4 The operation for the setting of "20 or 110" is performed when a value other than "9, 13, 14, 109, 113, or 114" is set.
- \*5 The operation for the setting of "20 or 110" is performed when a value other than "13, 14, 113, 114, or 9999" is set.
- \*6 The operation for the setting of "20 or 110" is performed when a value other than "9 or 109" is set.
- \*7 The operation for the setting of "20 or 110" is performed when a value other than "9999" is set.
- \*8 V/F control when Pr.80 or Pr.81 is "9999", regardless of the Pr.800 setting. When Pr.71 is set to the IPM motor MM-CF, PM sensorless vector control is enabled even if Pr.80 ≠ "9999" or Pr.81 = "9999".
- \*9 Setting Pr.788 (Pr.747) Low speed range torque characteristic selection = "0" (Low-speed range high-torque characteristic disabled) selects speed control.

- Set Pr.89 (Pr.569) to make adjustments to keep the motor speed constant during variable load operation under Advanced magnetic flux vector control.
- The second motor control method can also be selected by the RT signal.
- The Pr.22 function changes according to the Pr.800 setting (stall prevention operation level/torque limit level).
- Setting Pr.800 (Pr.451) = "any of 100 to 105 or 109 to 114" selects the fast-response operation. The fast-response operation is available during vector control, Real sensorless vector control, and PM sensorless vector control. (During fast-response operation, the carrier frequency is always 4 kHz. During fast-response operation, continuous operation with 100% inverter rated current is not possible. (E.THT is likely to occur.))
- Using the FR-A8TP together with the FR-A8AP enables vector control by switching between two encoder-equipped motors.

Features	Application Example
FR Configurator2	PLC Function
Connection Examples	Terminal Connection Diagrams
Standard Specs	Operation Panel
Dimensions	Parameter List
Terminal Specs	Explanations of Parameters
Operation Panel	Protective Functions
Parameter List	Options
Explanations of Parameters	LVS/Cables
Protective Functions	Precautions
Options	Motors
LVS/Cables	Compatibility
Precautions	Warranty Inquiry
Motors	
Compatibility	
Warranty Inquiry	

## Offline auto tuning

Pr.	GROUP	Name	Pr.	GROUP	Name
82	C125	Motor excitation current	83	C104	Rated motor voltage
84	C105	Rated motor frequency	90	C120	Motor constant (R1)
91	C121	Motor constant (R2)	92	C122	Motor constant (L1)/ d-axis inductance (Ld)
93	C123	Motor constant (L2)/ q-axis inductance (Lq)	94	C124	Motor constant (X)
96	C110	Auto tuning setting/status	455	C225	Second motor excitation current
456	C204	Rated second motor voltage	457	C205	Rated second motor frequency
458	C220	Second motor constant (R1)	459	C221	Second motor constant (R2)
460	C222	Second motor constant (L1) / d-axis inductance (Ld)	461	C223	Second motor constant (L2) / q-axis inductance (Lq)
462	C224	Second motor constant (X)	463	C210	Second motor auto tuning setting/status
859	C126	Torque current/Rated PM motor current	860	C226	Second motor torque current/Rated PM motor current
9	C103	Electronic thermal O/L relay	51	C203	Second electronic thermal O/L relay
71	C100	Applied motor	80	C101	Motor capacity
81	C102	Number of motor poles	298	A711	Frequency search gain
450	C200	Second applied motor	453	C201	Second motor capacity
454	C202	Number of second motor poles	560	A712	Second frequency search gain
684	C000	Tuning data unit switchover	702	C106	Maximum motor frequency
706	C130	Induced voltage constant (phi f)	707	C107	Motor inertia (integer)
711	C131	Motor Ld decay ratio	712	C132	Motor Lq decay ratio
717	C182	Starting resistance tuning compensation	721	C185	Starting magnetic pole position detection pulse width
724	C108	Motor inertia (exponent)	725	C133	Motor protection current level
738	C230	Second motor induced voltage constant (phi f)	739	C231	Second motor Ld decay ratio
740	C232	Second motor Lq decay ratio	741	C282	Second starting resistance tuning compensation
742	C285	Second motor magnetic pole detection pulse width	743	C206	Second motor maximum frequency
744	C207	Second motor inertia (integer)	745	C208	Second motor inertia (exponent)
746	C233	Second motor protection current level	1002	C150	Lq tuning target current adjustment coefficient

Offline auto tuning operation can be executed to automatically calculate the motor constant under Advanced magnetic flux vector control, Real sensorless vector control, vector control, or PM sensorless vector control.

Offline tuning is necessary under Real sensorless vector control. Also, when the automatic restart after instantaneous power failure or flying start function is used under V/F control or with an IPM motor MM-CF, offline auto tuning improves the precision of the frequency search for motor speed detection.

Pr. 96 setting	Description
0 (initial value)	No offline auto tuning
1 *1	Performs offline auto tuning without rotating the motor
101 *1	Performs offline auto tuning by rotating the motor
11 *2	Performs offline auto tuning without rotating the motor (V/F control, PM sensorless vector control (IPM motor MM-CF)).

\*1 For Advanced magnetic flux vector control, Real sensorless vector control and vector control

\*2 For V/F control and PM sensorless vector control

- The offline tuning data (motor constants) can be copied to another inverter with the operation panel (FR-DU08).
- Even if a motor other than Mitsubishi standard motors (SF-JR 0.4 kW or higher), high-efficiency motors (SF-HR 0.4 kW or higher), Mitsubishi constant-torque motors (SF-JRCA 4P, SF-HRCA 0.4 kW to 55 kW), Mitsubishi high-performance energy-saving motor SF-PR, or Mitsubishi vector-dedicated motors (SF-V5RU (1500 r/min series)), such as other manufacturers' induction motors, SF-JRC, SF-TH, etc., is used, or when the wiring length is long (approx. 30 m or longer), an inductive motor can run with the optimum operation characteristics by using the offline auto tuning function.
- The offline auto tuning enables the operation with SPM motors and IPM motors other than MM-CF when using the PM motor. When using a PM motor other than the IPM motor MM-CF series, offline auto tuning must be performed.
- When using an induction motor, the motor rotation can be locked (**Pr.96** = "1, 11") or unlocked (**Pr.96** = "101"). The tuning is more accurate when the motor can rotate (unlocked).
- Requirements for offline auto tuning
  - A motor is connected.
  - For the motor capacity, the rated motor current should be equal to or less than the inverter rated current. (It must be 0.4 kW or higher.)  
Using a motor with the rated current substantially lower than the inverter rated current will cause torque ripples, etc. and degrade the speed and torque accuracies. As a reference, select the motor with the rated motor current that is about 40% or higher of the inverter rated current.
  - The highest frequency is 400 Hz.
  - The target motor is other than a high-slip motor, a high-speed motor, or a special motor.
- When using an induction motor, check the following points if **Pr.96 (Pr.463)** = "101" (Perform offline auto tuning by rotating the motor) is selected.
  - Torque is not sufficient during tuning.
  - The motor can be rotated up to the frequency close to the motor rated frequency (**Pr.84** setting value).
  - The brake is released.
- The motor may rotate slightly even if **Pr.96 (Pr.463)** = "1, 11" (performs tuning without rotating the motor) is selected. Fix the motor securely with a mechanical brake, or before tuning, make sure that it is safe even if the motor rotates. Make sure to perform the above especially in vertical lift applications. Note that if the motor runs slightly, tuning performance is unaffected.

**Pr.89** ➤ Refer to the page on Pr.80.

## Online auto tuning

Magnetic flux Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
95	C111	Online auto tuning selection	574	C211	Second motor online auto tuning

If online auto tuning is selected, favorable torque accuracy is retained by adjusting temperature even when the resistance value varies due to increase in the motor temperature.

When vector control is used, select the magnetic flux observer.

Pr.95	Pr.574	Description
0 (initial value)		Do not perform online auto tuning
1		Perform online auto tuning at startup
2		Magnetic flux observer (tuning always)

- Perform offline auto tuning before performing online auto tuning at startup.
- When performing the online auto tuning at start for a lift, consider utilization of a brake sequence function for the brake opening timing at a start or tuning using the external terminal. The tuning is completed in approximately 500 ms at the maximum after the start. Not enough torque may be provided during that period. Caution is required to prevent the object from dropping.
- Offline auto tuning is not necessary if selecting magnetic flux observer for the SF-V5RU, SF-JR (with encoder), SF-HR (with encoder), SF-JRCA (with encoder) or SF-HRCA (with encoder). (However, when the wiring length is long (30 m or longer as a reference), perform offline auto tuning so that the resistance for the wiring length can be reflected to the control.)

**Pr.96** ➔ Refer to the page on Pr.82.

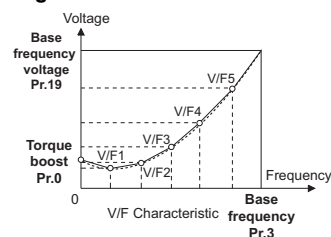
## Adjustable 5 points V/F Magnetic flux

Pr.	GROUP	Name	Pr.	GROUP	Name
71	C100	Applied motor	100	G040	V/F1 (first frequency)
101	G041	V/F1 (first frequency voltage)	102	G042	V/F2 (second frequency)
103	G043	V/F2 (second frequency voltage)	104	G044	V/F3 (third frequency)
105	G045	V/F3 (third frequency voltage)	106	G046	V/F4 (fourth frequency)
107	G047	V/F4 (fourth frequency voltage)	108	G048	V/F5 (fifth frequency)
109	G049	V/F5 (fifth frequency voltage)			

By setting a desired V/F characteristic from the start up to the base frequency or base voltage with the V/F control (frequency voltage/frequency), a dedicated V/F pattern can be generated.

Optimal V/F patterns that match the torque characteristics of the facility can be set.

- Set **Pr.71** = "2" and set a voltage and frequency in **Pr.100 to Pr.109**.
- Read only error ( $E_{r-1}$ ) is generated when the frequency value for each point is the same. Also, set the frequency and voltage within the range of **Pr.3 Base frequency** and **Pr.19 Base frequency voltage**.



- At the time of **Pr.19 Base frequency voltage** = "8888, 9999", setting of **Pr.71** = "2" cannot be made. When setting **Pr.71** = "2", set the rated voltage value in **Pr.19**.

**Pr.110, 111** ➔ Refer to the page on Pr.7.

**Pr.112** ➔ Refer to the page on Pr.0.

**Pr.113** ➔ Refer to the page on Pr.3.

**Pr.114, 115** ➔ Refer to the page on Pr.22.

**Pr.116** ➔ Refer to the page on Pr.41.



## Initial settings for communication

Pr.	GROUP	Name	Pr.	GROUP	Name
117	N020	PU communication station number	118	N021	PU communication speed
119	N022	PU communication data length	119	N023	PU communication stop bit length
119	-	PU communication stop bit length / data length	120	N024	PU communication parity check
121	N025	Number of PU communication retries	122	N026	PU communication check time interval
123	N027	PU communication waiting time setting	124	N028	PU communication CR/LF selection
331	N030	RS-485 communication station number	332	N031	RS-485 communication speed
333	N032	RS-485 communication data length	333	N033	RS-485 communication stop bit length
333	-	RS-485 communication stop bit length / data length	334	N034	RS-485 communication parity check selection
335	N035	RS-485 communication retry count	336	N036	RS-485 communication check time interval
337	N037	RS-485 communication waiting time setting	341	N038	RS-485 communication CR/LF selection
342	N001	Communication EEPROM write selection	343	N080	Communication error count
502	N013	Stop mode selection at communication error	539	N002	MODBUS RTU communication check time interval
549	N000	Protocol selection	779	N014	Operation frequency during communication error

### Initial settings and specifications of RS-485 communication (Pr.117 to Pr.124, Pr.331 to Pr.337, Pr.341)

Use the following parameters to perform required settings for the RS-485 communication between the inverter and a personal computer.

- There are two types of communication, communication using the inverter's PU connector and communication using the RS-485 terminals.
- Parameter setting, monitoring, etc. can be performed using the Mitsubishi inverter protocol or MODBUS RTU communication protocol.
- To establish communication between the computer and inverter, setting of the communication specifications must be made to the inverter in advance.
- Data communication cannot be established if the initial settings are not made or if there is any setting error.

Pr.	Setting range	Description	
117 331	0 to 31 (0 to 247) <sup>-1</sup>	Specify the inverter station number. Set the inverter station numbers when two or more inverters are connected to one personal computer.	
118 332	48, 96, 192, 384, 576, 768, 1152 (3, 6, 12, 24) <sup>-2</sup>	Set the communication speed. The setting value × 100 equals the communication speed. For example, if 192 is set, the communication speed is 19200 bps.	
E022 N032	0 (initial value) 1	Data length 8 bits Data length 7 bits	
E023 N033	0 1 (initial value)	Stop bit length 1 bit Stop bit length 2 bit	
119 333	0 1 (initial value)	Stop bit length	
		Data length	
	10	1 bit	8 bits
	11	2 bits	
120 334	0	Without parity check	
	1	With odd parity check	
	2 (initial value)	With even parity check	

Pr.	Setting range	Description
121 335	0 to 10	Set the permissible number of retries for unsuccessful data reception. If the number of consecutive errors exceeds the permissible value, the inverter will trip.
	9999	If a communication error occurs, the inverter will not trip.
122 336	0	No PU connector communication (Pr.122) Communication is available using the RS-485 terminals, but the inverter trips in the NET operation mode. (Pr.336)
	0.1 to 999.8 s	Set the interval of the communication check (signal loss detection) time. If a no-communication state persists for longer than the permissible time, the inverter will trip.
	9999 (initial value)	No communication check (signal loss detection)
123 337	0 to 150 ms	Set the waiting time between data transmission to the inverter and the response.
	9999 (initial value)	Set with communication data.
124 341	0	Without CR/LF
	1 (initial value)	With CR
	2	With CR/LF

- \*1 When communication is made from the RS-485 terminal using the MODBUS RTU protocol, the setting range in parentheses is applied to Pr.331.
- \*2 Values in parentheses are added to the Pr.332 setting range.

### Communication EEPROM write selection (Pr.342)

When parameter write is performed via the inverter PU connector, RS-485 terminal, or a communication option, the parameters storage device can be changed from EEPROM + RAM to RAM only. If parameter settings are changed frequently, set "1" in Pr.342.

### Operation selection at a communication error (Pr.502, Pr.779)

For communication using RS-485 terminals or a communication option, operation at a communication error can be selected. The operation is active under the Network operation mode.

Pr.	Setting range	At fault occurrence	At fault removal
502	0 (initial value)	Coasts to stop E.SER display *1 ALM signal output	Stays stopped (E.SER display *1)
	1	Deceleration stop E.SER display after stop *1 ALM signal output after stop	Stays stopped (E.SER display *1)
	2	Deceleration stop E.SER display after stop *1	Automatic restart
	3	Operation continued at the set frequency of Pr.779	Normal operation
779	0 to 590 Hz	Set the frequency to be run at a communication error occurrence.	
	9999 (initial value)	The motor runs at the frequency used before the communication error.	

- \*1 If in communication by the communication option, E.OP1 is displayed.

### MODBUS RTU communication specification (Pr.343, Pr.539, Pr.549)

The MODBUS RTU protocol is valid only in communication from the RS-485 terminals.

Pr.	Setting range	Description
343	-	Displays the communication error count during MODBUS RTU communication. Read-only.
539	0	MODBUS RTU communication, but the inverter trips in the NET operation mode.
	0.1 to 999.8 s	Set the interval of the communication check (signal loss detection) time. (the same specifications as Pr.122)
	9999 (initial value)	No communication check (signal loss detection)
549	0 (initial value)	Mitsubishi inverter protocol (computer link)
	1	MODBUS RTU protocol



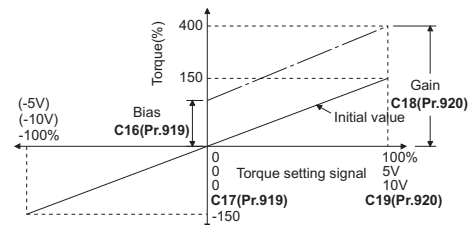
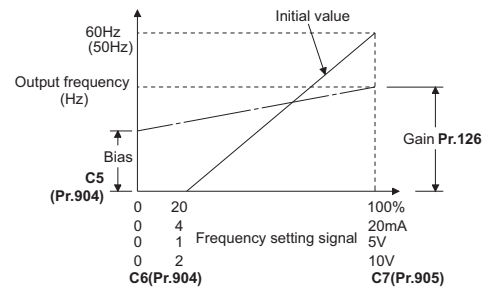
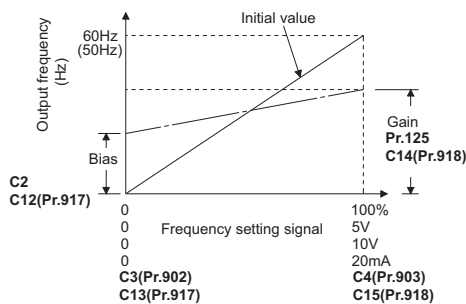
## Changing and adjusting (calibrating) the frequency (speed) and torque/magnetic flux using analog input

Pr.	GROUP	Name	Pr.	GROUP	Name
125 (903)	T202 T022	Terminal 2 frequency setting gain frequency	126 (905)	T402 T042	Terminal 4 frequency setting gain frequency
C2 (902)	T200	Terminal 2 frequency setting bias frequency	C3 (902)	T201	Terminal 2 frequency setting bias
C4 (903)	T203	Terminal 2 frequency setting gain	C5 (904)	T400	Terminal 4 frequency setting bias frequency
C6 (904)	T401	Terminal 4 frequency setting bias	C7 (905)	T403	Terminal 4 frequency setting gain
C12 (917)	T100	Terminal 1 bias frequency (speed)	C13 (917)	T101	Terminal 1 bias (speed)
C14 (918)	T102	Terminal 1 gain frequency (speed)	C15 (918)	T103	Terminal 1 gain (speed)
C16 (919)	T110	Terminal 1 bias command (torque)	C17 (919)	T111	Terminal 1 bias (torque)
C18 (920)	T112	Terminal 1 gain command (torque)	C19 (920)	T113	Terminal 1 gain (torque)
C38 (932)	T410	Terminal 4 bias command (torque)	C39 (932)	T411	Terminal 4 bias (torque)
C40 (933)	T412	Terminal 4 gain command (torque)	C41 (933)	T413	Terminal 4 gain (torque)
241	M043	Analog input display unit switchover			

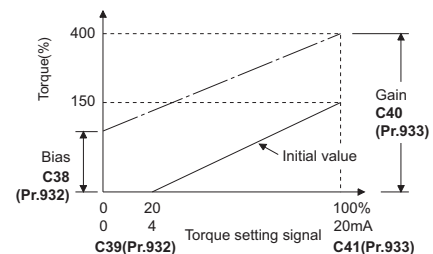
The degree (slope) of the output frequency (speed, torque/magnetic flux) to the frequency/torque setting signal (0 to 5 V DC, 0 to 10 V DC or 4 to 20 mA) is selectable to a desired amount.

- To change the frequency (speed) for the maximum analog input (**Pr.125, Pr.126, C14 (Pr.918)**)  
To change only the frequency setting (gain) for the maximum analog input voltage (current), set **Pr.125 (Pr.126, C14 (Pr.918))**. (Other calibration parameter settings do not need to be changed.)
- To change the torque/magnetic flux for the maximum analog input (**C18 (Pr.920), C40 (Pr.933)**)  
To change only the torque/magnetic flux command of the maximum analog input voltage (current), set to **C18 (Pr.920), C40 (Pr.933)**. (Other calibration parameter settings do not need to be changed.)
- Calibration of analog input bias and gain (**C2 (Pr.902) to C7 (Pr.905), C16 (Pr.919) to C19 (Pr.920), C38 (Pr.932) to C41 (Pr.933)**)

The "bias" and "gain" functions are used to adjust the relationship between the output frequency (torque/magnetic flux) and the setting input signal, such as 0 to 5 V DC/0 to 10 V DC or 4 to 20 mA DC, entered from outside to set the output frequency (torque/magnetic flux).



Calibration example of terminal 1



Calibration example of terminal 4

- Analog input display unit changing (**Pr.241**)  
The analog input display unit (%/V/mA) for analog input bias and gain calibration can be changed.





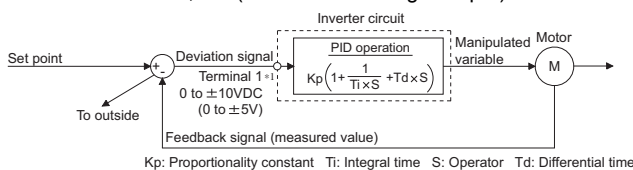
## PID control, Dancer control

Pr.	GROUP	Name	Pr.	GROUP	Name
127	A612	PID control automatic switchover frequency	128	A610	PID action selection
129	A613	PID proportional band	130	A614	PID integral time
131	A601	PID upper limit	132	A602	PID lower limit
133	A611	PID action set point	134	A615	PID differential time
553	A603	PID deviation limit	554	A604	PID signal operation selection
575	A621	Output interruption detection time	576	A622	Output interruption detection level
577	A623	Output interruption cancel level	609	A624	PID set point/deviation input selection
610	A625	PID measured value input selection	753	A650	Second PID action selection
754	A652	Second PID control automatic switchover frequency	755	A651	Second PID action set point
756	A653	Second PID proportional band	757	A654	Second PID integral time
758	A655	Second PID differential time	C42 (934)	A630	PID display bias coefficient
C43 (934)	A631	PID display bias analog value	C44 (935)	A632	PID display gain coefficient
C45 (935)	A633	PID display gain analog value	1015	A607	Integral stop selection at limited frequency
1140	A664	Second PID set point/deviation input selection	1141	A665	Second PID measured value input selection
1142	A640	Second PID unit selection	1143	A641	Second PID upper limit
1144	A642	Second PID lower limit	1145	A643	Second PID deviation limit
1146	A644	Second PID signal operation selection	1147	A661	Second output interruption detection time
1148	A662	Second output interruption detection level	1149	A663	Second output interruption cancel level
759	A600	PID unit selection	1134	A605	PID upper limit manipulated value
1135	A606	PID lower limit manipulated value	1136	A670	Second PID display bias coefficient
1137	A671	Second PID display bias analog value	1138	A672	Second PID display gain coefficient
1139	A673	Second PID display gain analog value	44	F020	Second acceleration/deceleration time
45	F021	Second deceleration time			

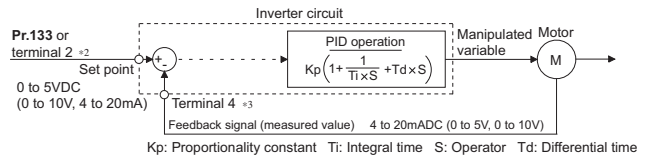
### ◆ PID control

Process control such as control of the flow rate, air volume or pressure, is possible via the inverter. When the parameter unit (FR-PU07) is used, the display unit of parameters and monitored items related to PID control can be changed to various units. A feedback system can be configured and PID control can be performed using the terminal 2 input signal or parameter setting value as the set point, and the terminal 4 input signal as the feedback value.

- Pr.128 = "10, 11" (deviation value signal input)



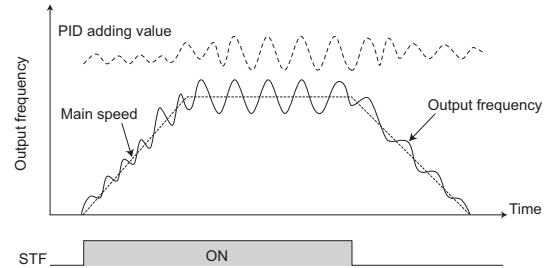
- Pr.128 = "20, 21" (measured value input)



When the second PID function is set, two sets of PID functions can be switched for use. The second PID function is enabled by turning ON the RT signal.

### ◆ Dancer control

Dancer control is performed by setting "40 to 43" in **Pr.128 PID action selection**. The main speed command is the speed command for each operation mode (External, PU and communication). PID control is performed by the dancer roll position detection signal, and the control result is added to the main speed command. For the main speed acceleration/deceleration time, set the acceleration time to **Pr.44 Second acceleration/deceleration time** and the deceleration time to **Pr.45 Second deceleration time**.



## Commercial power supply-inverter switchover function

V/F Magnetic flux Sensorless Vector

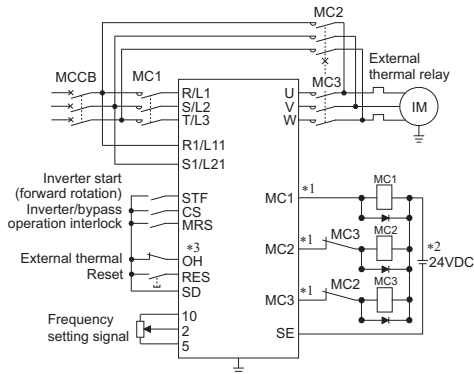
Pr.	GROUP	Name	Pr.	GROUP	Name
135	A000	Electronic bypass sequence selection	136	A001	MC switchover interlock time
137	A002	Start waiting time	138	A003	Bypass selection at a fault
139	A004	Automatic switchover frequency from inverter to bypass operation	159	A005	Automatic switchover frequency range from bypass to inverter operation
57	A702	Restart coasting time	58	A703	Restart cushion time

The inverter contains complicated sequence circuits for switching between the commercial power supply operation and inverter operation. Therefore, interlock operation of the magnetic contactor for switching can be easily performed by simply inputting start, stop, and automatic switching selection signals.

The commercial power supply operation is not available with Mitsubishi vector control dedicated motors (SF-V5RU).

Pr.135 setting	Description
0 (initial value)	Without electronic bypass sequence
1	With electronic bypass sequence

Sink logic, Pr.185 = "7", Pr.192 = "17", Pr.193 = "18", Pr.194 = "19"



Electronic bypass sequence connection diagram (standard model)

- \*1 Be careful of the capacity of the sequence output terminals.
- \*2 When connecting a DC power supply, insert a protective diode.
- \*3 The applied terminals differ by the settings of Pr.180 to Pr.189 (input terminal function selection).

Pr. 140 to 143 Refer to the page on Pr.29.

Pr. 144 Refer to the page on Pr.37.

## PU display language selection

Pr.	GROUP	Name
145	E103	PU display language selection

The display language of the parameter unit (FR-PU07) can be selected.

Pr.145 setting	Description
0	Japanese
1	English
2	German
3	French
4	Spanish
5	Italian
6	Swedish
7	Finnish

Pr. 147 Refer to the page on Pr.7.

Pr. 148, 149 Refer to the page on Pr.22.

## Output current detection (Y12 signal) and zero current detection (Y13 signal)

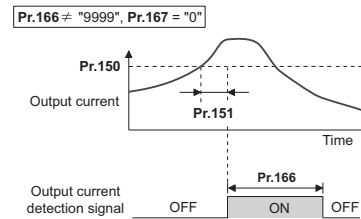
Pr.	GROUP	Name	Pr.	GROUP	Name
150	M460	Output current detection level	151	M461	Output current detection signal delay time
152	M462	Zero current detection level	153	M463	Zero current detection time
166	M433	Output current detection signal retention time	167	M464	Output current detection operation selection

The output current during inverter running can be detected and output to the output terminal.

- Output current detection

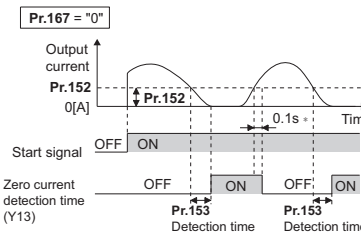
(Y12 signal, Pr.150, Pr.151, Pr.166, Pr.167)

- The output current detection function can be used for purposes such as overtorque detection.
- If the output during inverter running is the Pr.150 setting or higher for the time set in Pr.151 or longer, the output current detection signal (Y12) is output from the inverter's open collector or relay output terminal.



- Zero current detection (Y13 signal, Pr.152, Pr.153, Pr.167)

If the output during inverter running is the Pr.152 setting or lower for the time set in Pr.153 or longer, the zero current detection signal (Y13) is output from the inverter's open collector or relay output terminal.



\* When the output is restored to the Pr.152 level, the Y13 signal is turned OFF after 0.1 s.

- Output current detection operation selection (Pr.167)

Pr.167 setting	Y12 signal-ON	Y13 signal-ON
0 (initial value)	Continuous operation	Continuous operation
1	E.CDO	Continuous operation
10	Continuous operation	E.CDO
11	E.CDO	E.CDO

Pr. 154 Refer to the page on Pr.22.



## Selecting operating conditions of the second function signal (RT) and the third function signal (X9)

Pr.	GROUP	Name
155	T730	RT signal function validity condition selection

The second (third) function can be selected by the RT (X9) signal. Operating conditions (validity conditions) for the second (third) function can also be set.

Pr.155 setting	Description
0 (initial value)	The second (third) function is immediately enabled with ON of the RT (X9) signal.
10	The second (third) function will be enabled while the RT signal is ON and while running at a constant speed. (Disabled while accelerating or decelerating)

- Items that can be set as the second function and third function (When the RT (X9) signal is ON, the following second (third) functions are selected at the same time.)

Function	First function Parameter number	Second function Parameter number	Third function Parameter number
Torque boost	Pr.0	Pr.46	Pr.112
Base frequency	Pr.3	Pr.47	Pr.113
Acceleration time	Pr.7	Pr.44	Pr.110
Deceleration time	Pr.8	Pr.44, Pr.45	Pr.110, Pr.111
Electronic thermal O/L relay	Pr.9	Pr.51	*2
Free thermal	Pr.600 to Pr.604	Pr.692 to Pr.696	*2
Stall prevention	Pr.22	Pr.48, Pr.49	Pr.114, Pr.115
Applied motor *1	Pr.71	Pr.450	*2
Motor constant *1	Pr.80 to Pr.84, Pr.89 to Pr.94, Pr.298, Pr.702, Pr.706, Pr.707, Pr.711, Pr.712, Pr.717, Pr.721, Pr.724, Pr.725, Pr.859	Pr.453 to Pr.457, Pr.560, Pr.569, Pr.458 to Pr.462, Pr.738 to Pr.747, Pr.860	*2
Offline auto tuning *1	Pr.96	Pr.463	*2
Online auto tuning *1	Pr.95	Pr.574	*2
PID control	Pr.127 to Pr.134	Pr.753 to Pr.758	*2
PID pre-charge function	Pr.760 to Pr.764	Pr.765 to Pr.769	*2
Brake sequence *1	Pr.278 to Pr.285, Pr.639, Pr.640	Pr.641 to Pr.648, Pr.650, Pr.651	*2
Droop	Pr.286 to Pr.288, Pr.994, Pr.995	Pr.679 to Pr.683	*2
Low-speed range torque characteristic selection *1	Pr.788	Pr.747	*2
Motor control method *1	Pr.800	Pr.451	*2
Speed control gain	Pr.820, Pr.821	Pr.830, Pr.831	*2
Analog input filter	Pr.822, Pr.826	Pr.832, Pr.836	*2
Speed detection filter	Pr.823	Pr.833	*2
Torque control gain	Pr.824, Pr.825	Pr.834, Pr.835	*2
Torque detection filter	Pr.827	Pr.837	*2

- \*1 The function can be changed by switching the RT signal ON/OFF while the inverter is stopped. If a signal is switched during operation, the operation method changes after the inverter stops.
- \*2 When the RT signal is OFF, the first function is selected and when it is ON, the second function is selected.

Pr.156, 157 ➤ Refer to the page on Pr.22.

Pr.158 ➤ Refer to the page on Pr.52.

Pr.159 ➤ Refer to the page on Pr.135.

## User group function

Pr.	GROUP	Name	Pr.	GROUP	Name
160	E440	User group read selection	172	E441	User group registered display/batch clear
173	E442	User group registration	174	E443	User group clear

This function restricts the parameters that are read by the operation panel and parameter unit.

The initial setting displays all parameters.

Pr.160 setting	Description
0 (initial value)	Displays all parameters.
1	Displays parameters registered in the user group.
9999	Displays only the simple mode parameters.

- User group function (Pr.160, Pr.172 to Pr.174)  
The user group function is a function for displaying only the parameters required for a setting. A maximum of 16 parameters from any of the parameters can be registered in a user group. When Pr.160 = "1", reading/writing is enabled only for the parameters registered in user groups. (Parameters not registered in user groups can no longer be read.) To register a parameter in a user group, set the parameter number in Pr.173. To clear a parameter from a user group, set the parameter number in Pr.174. To batch clear all the registered parameters, set Pr.172 = "9999".

## Operation panel operation selection

Pr.	GROUP	Name	Pr.	GROUP	Name
161	E200	Frequency setting/key lock operation selection	295	E201	Frequency change increment amount setting

### ◆ Setting dial potentiometer mode/key lock operation selection (Pr.161)

The setting dial of the operation panel (FR-DU08) can be used for setting like a potentiometer.

The key operation of the operation panel can be disabled.

Pr.161 setting	Description
0 (initial value)	Setting dial frequency setting mode Key lock mode disabled
1	Setting dial potentiometer mode Key lock mode disabled
10	Setting dial frequency setting mode Key lock mode enabled
11	Setting dial potentiometer mode Key lock mode enabled

### ◆ Frequency change increment amount setting (Pr.295)

When setting a frequency using the setting dial on the operation panel (FR-DU08), the frequency change increment is determined by how quickly the setting dial is rotated.

Pr.162 to 165 ➤ Refer to the page on Pr.57.

Pr.166, 167 ➤ Refer to the page on Pr.150.

Pr.168, 169 ➤ Parameter for manufacturer setting. Do not set.

Pr.170, 171 ➤ Refer to the page on Pr.52.

Pr.172 to 174 ➤ Refer to the page on Pr.160.

## Input terminal function assignment

Pr.	GROUP	Name	Pr.	GROUP	Name
178	T700	STF terminal function selection	179	T701	STR terminal function selection
180	T702	RL terminal function selection	181	T703	RM terminal function selection
182	T704	RH terminal function selection	183	T705	RT terminal function selection
184	T706	AU terminal function selection	185	T707	JOG terminal function selection
186	T708	CS terminal function selection	187	T709	MRS terminal function selection
188	T710	STOP terminal function selection	189	T711	RES terminal function selection
699	T740	Input terminal filter			

Use the following parameters to select or change the input terminal functions.

(When **Pr.419 Position command source selection** = "2" (simple pulse train position command), the terminal JOG is used as a simple position pulse train input terminal, independently of the **Pr.185** setting.)

Setting	Signal name	Function	
0	RL	Pr.59 = 0 (initial value)	Low-speed operation command
		Pr.59 ≠ 0 *1	Remote setting (setting clear)
		Pr.270 = 1, 3, 11, 13 *2	Stop-on-contact selection 0
1	RM	Pr.59 = 0 (initial value)	Middle-speed operation command
		Pr.59 ≠ 0 *1	Remote setting (deceleration)
2	RH	Pr.59 = 0 (initial value)	High-speed operation command
		Pr.59 ≠ 0 *1	Remote setting (acceleration)
3	RT	Second function selection	
		Pr.270 = 1, 3, 11, 13 *2	Stop-on-contact selection 1
4	AU	Terminal 4 input selection	
5	JOG	Jog operation selection	
6	CS	Selection of automatic restart after instantaneous power failure, flying start	
		Electronic bypass function	
7	OH	External thermal relay input *3	
8	REX	15-speed selection (Combination with multi-speeds of RL, RM, and RH)	
9	X9	Third function selection	
10	X10	Inverter run enable signal (FR-HC2/FR-CV/FR-CC2 connection)	
11	X11	FR-HC2/FR-CC2 connection, instantaneous power failure detection	
12	X12	PU operation external interlock	
13	X13	External DC injection brake operation start	
14	X14	PID control valid terminal	
15	BRI	Brake opening completion signal	
16	X16	PU/External operation switchover (External operation with X16-ON)	
17	X17	Load pattern selection forward/reverse rotation boost (for constant-torque load with X17-ON)	
18	X18	V/F switchover (V/F control with X18-ON)	
19	X19	Load torque high-speed frequency	
20	X20	S-pattern acceleration/deceleration C switchover	
22	X22	Orientation command (for FR-A8AP/FR-A8APR/FR-A8TP) *4*6	
23	LX	Pre-excitation/servo ON *5	
24	MRS	Output stop	
		Electronic bypass function	
25	STOP	Start self-holding selection	

Setting	Signal name	Function
26	MC	Control mode switchover
27	TL	Torque limit selection
28	X28	Start-time tuning start external input
37	X37	Traverse function selection
42	X42	Torque bias selection 1
43	X43	Torque bias selection 2
44	X44	P/PI control switchover(P control with X44-ON)
45	BRI2	Second brake sequence open completion
46	TRG	Trace trigger input
47	TRC	Trace sampling start/end
48	X48	Power failure stop external
50	SQ	Sequence start
51	X51	Fault clear signal
52	X52	Cumulative pulse monitor clear (for FR-A8AP/FR-A8APR)
53	X53	Cumulative pulse monitor clear (control terminal option) (for FR-A8TP)
60	STF	Forward rotation command (Assignable to the STF terminal ( <b>Pr.178</b> ) only)
61	STR	Reverse rotation command (Assignable to the STR terminal ( <b>Pr.179</b> ) only)
62	RES	Inverter reset
64	X64	During retry
65	X65	PU/NET operation switchover (PU operation with X65-ON)
66	X66	External/NET operation switchover (NET operation with X66-ON)
67	X67	Command source switchover (Command by <b>Pr.338</b> , <b>Pr.339</b> enabled with X67-ON)
68	NP	Simple position pulse train sign
69	CLR	Simple position droop pulse clear
70	X70	DC feeding operation permission *7
71	X71	DC feeding cancel *7
72	X72	PID P control switchover
73	X73	Second PID P control switchover
74	X74	Magnetic flux decay output shutoff signal
76	X76	Proximity dog
77	X77	Pre-charge end command
78	X78	Second pre-charge end command
79	X79	Second PID forward/reverse action switchover
80	X80	Second PID control valid terminal
87	X87	Sudden stop
92	X92	Emergency stop
93	X93	Torque limit selection
94	X94	Control signal input for main circuit power supply MC
95	X95	Converter unit fault input
96	X96	Converter unit fault (E.OHT, E.CPU) input
9999	—	No function

- \*1 When **Pr.59 Remote function selection** ≠ "0", functions of the RL, RM, and RH signals will be changed as in the table.
- \*2 When **Pr.270 Stop-on contact/load torque high-speed frequency control selection** = "1, 3, 11, or 13", functions of the RL and RT signals will be changed as in the table.
- \*3 The OH signal will operate with the relay contact "open".
- \*4 When the stop position is to be input externally for orientation control, the FR-A8AX (16-bit digital input) is required.
- \*5 Servo ON is enabled during the position control.
- \*6 Available when the option is connected.
- \*7 The setting is available only for standard models and IP55 compatible models.

- Adjusting the response of input terminal (**Pr.699**)

Pr.699 setting	Description
5 to 50 ms	Set the time to delay the input terminal response.
9999 (initial value)	No input terminal filter



## Output terminal function assignment

Pr.	GROUP	Name	Pr.	GROUP	Name
190	M400	RUN terminal function selection	191	M401	SU terminal function selection
192	M402	IPF terminal function selection	193	M403	OL terminal function selection
194	M404	FU terminal function selection	195	M405	ABC1 terminal function selection
196	M406	ABC2 terminal function selection	289	M431	Inverter output terminal filter

Use the following parameters to change the functions of the open collector output terminals and relay output terminals.

Setting		Signal name	Function
Positive logic	Negative logic		
0	100	RUN	Inverter running
1	101	SU	Up to frequency <sup>*1</sup>
2	102	IPF	Instantaneous power failure/undervoltage <sup>*5</sup>
3	103	OL	Overload warning
4	104	FU	Output frequency detection
5	105	FU2	Second output frequency detection
6	106	FU3	Third output frequency detection
7	107	RBP	Regenerative brake pre-alarm <sup>*4</sup>
8	108	THP	Electronic thermal O/L relay pre-alarm
10	110	PU	PU operation mode
11	111	RY	Inverter operation ready
12	112	Y12	Output current detection
13	113	Y13	Zero current detection
14	114	FDN	PID lower limit
15	115	FUP	PID upper limit
16	116	RL	PID forward/reverse rotation output
17	—	MC1	Electronic bypass MC1
18	—	MC2	Electronic bypass MC2
19	—	MC3	Electronic bypass MC3
20	120	BOF	Brake opening request
22	122	BOF2	Second brake opening request
25	125	FAN	Fan fault output
26	126	FIN	Heatsink overheat pre-alarm
27	127	ORA	Orientation complete (for FR-A8AP/FR-A8APR/FR-A8TP) <sup>*3</sup>
28	128	ORM	Orientation fault (for FR-A8AP/FR-A8APR/FR-A8TP) <sup>*3</sup>
30	130	Y30	Forward rotation output (for FR-A8AP/FR-A8APR/FR-A8TP) <sup>*3</sup>
31	131	Y31	Reverse rotation output (for FR-A8AP/FR-A8APR/FR-A8TP) <sup>*3</sup>
32	132	Y32	Regenerative status output (for FR-A8AP/FR-A8APR/FR-A8TP) <sup>*3</sup>
33	133	RY2	Operation ready 2
34	134	LS	Low speed detection
35	135	TU	Torque detection
36	136	Y36	In-position
38	138	MEND	Travel completed
39	139	Y39	Start time tuning completion
40	140	Y40	Trace status
41	141	FB	Speed detection
42	142	FB2	Second speed detection
43	143	FB3	Third speed detection
44	144	RUN2	Inverter running 2
45	145	RUN3	Inverter running and start command is ON
46	146	Y46	During deceleration at occurrence of power failure <sup>*5</sup>
47	147	PID	During PID control activated
48	148	Y48	PID deviation limit
49	149	Y49	During pre-charge operation
50	150	Y50	During second pre-charge operation
51	151	Y51	Pre-charge time over
52	152	Y52	Second pre-charge time over
53	153	Y53	Pre-charge level over
54	154	Y54	Second pre-charge level over

Setting		Signal name	Function
Positive logic	Negative logic		
55	155	Y55	Motor temperature detection (for FR-A8AZ) <sup>*3</sup>
56	156	ZA	Home position return failure
57	157	IPM	During PM motor control
60	160	FP	Position detection level
61	161	PBSY	During position command operation
63	163	ZPEND	Home position return completed
64	164	Y64	During retry
67	167	Y67	Power failed signal
68	168	EV	24 V external power supply operation
70	170	SLEEP	PID output interruption
79	179	Y79	Pulse train output of output power
84	184	RDY	Position control preparation ready
85	185	Y85	DC current feeding <sup>*5</sup>
86	186	Y86	Control circuit capacitor life (for FR-A8AY, FR-A8AR) <sup>*3</sup>
87	187	Y87	Main circuit capacitor life (for FR-A8AY, FR-A8AR) <sup>*3+5</sup>
88	188	Y88	Cooling fan life (for FR-A8AY, FR-A8AR) <sup>*3</sup>
89	189	Y89	Inrush current limit circuit life (for FR-A8AY, FR-A8AR) <sup>*3+5</sup>
90	190	Y90	Life alarm
91	191	Y91	Fault output 3 (power-OFF signal)
92	192	Y92	Energy saving average value updated timing
93	193	Y93	Current average monitor signal
94	194	ALM2	Fault output 2
95	195	Y95	Maintenance timer signal
96	196	REM	Remote output
97	197	ER	Alarm output 2
98	198	LF	Alarm
99	199	ALM	Fault
200	300	FDN2	Second PID lower limit
201	301	FUP2	Second PID upper limit
202	302	RL2	Second PID forward/reverse rotation output
203	303	PID2	Second During PID control activated
204	304	SLEEP 2	During second PID output shutoff
205	305	Y205	Second PID deviation limit
206	306	Y206	Cooling fan operation command signal
207	307	Y207	Control circuit temperature signal
208	308	PS	PU stopped signal
9999	—	—	No function

- \*1 Be careful when changing the frequency setting with an analog signal or the setting dial of the operation panel (FR-DU08) because this change speed and the timing of the change speed determined by the acceleration/deceleration time setting may cause the output of the SU (up to frequency) signal to switch repeatedly between ON and OFF. (This repeating does not occur when the acceleration/deceleration time setting is "0 s".)
- \*2 When the power is reset, the fault output 2 signal (ALM2) turns OFF at the same time as the power turns OFF.
- \*3 Available when the option is connected.
- \*4 The setting is available only for standard models.
- \*5 The setting is available only for standard models and IP55 compatible models.

- Adjusting the output terminal response level (Pr.289)

Pr. 289 setting	Description
5 to 50 ms	Set the time delay for the output terminal response.
9999 (initial value)	No output terminal filter.

Pr. 232 to 239 ➤ Refer to the page on Pr.4.

Pr. 240 ➤ Refer to the page on Pr.72.

Pr. 241 ➤ Refer to the page on Pr.125.

Pr. 242, 243 ➤ Refer to the page on Pr.73.



## Cooling fan operation selection

Pr.	GROUP	Name
244	H100	Cooling fan operation selection

A cooling fan is built into the inverter and its operation can be controlled.

Pr.244 setting	Description
0	A cooling fan operates at power ON. Cooling fan ON/OFF control is invalid. (The cooling fan is always ON at power ON)
1 (initial value)	Cooling fan ON/OFF control is valid. The fan is always ON while the inverter is running. During a stop, the inverter status is monitored and the fan switches ON/OFF according to the temperature.
101 to 105	Cooling fan ON/OFF control is valid. Set the cooling fan stop waiting time within 1 to 5 s. The waiting time is the Pr.244 setting minus 100.

## Slip compensation

Pr.	GROUP	Name	Pr.	GROUP	Name
245	G203	Rated slip	246	G204	Slip compensation time constant
247	G205	Constant-power range slip compensation selection			

Motor slip is estimated from the inverter output current and the rotation of the motor is maintained as a constant.

## Self power management



Pr.	GROUP	Name	Pr.	GROUP	Name
248	A006	Self power management selection	254	A007	Main circuit power OFF waiting time
137	A002	Start waiting time	30	E300	Regenerative function selection

By turning ON the magnetic contactor (MC) on the input side before the motor is started and turning OFF the MC after the motor is stopped, supplying power to the main circuit is stopped, reducing the standby power.

Pr.	Setting range	Description
248	0 (initial value)	Self power management function disabled
	1	Self power management function enabled (main circuit OFF at protective function activation)
	2	Self power management function enabled (main circuit OFF at protective function activation due to a circuit failure)
137	0 to 100 s	Set a time period that is a little longer than the time period from the ON signal input to the actual pick-up operation of MC1 (0.3 to 0.5 s).
254	0 to 3600 s	Set the waiting time until the main circuit power supply is turned OFF after the motor is stopped.
	9999	The main circuit power supply is turned OFF only when the protective function selected by Pr.248 is activated.
30	100, 101	Power supply to the inverter: AC (terminals R, S, and T) When power is supplied only to the control circuit, and then switched to be supplied to both the control and main circuits, inverter reset is not performed.
	0 to 2, 10, 11, 20, 21, 102, 110, 111, 120, 121	For other settings, refer to page 96.

When setting parameters, refer to the Instruction Manual (Detailed) and understand instructions.

## Earth (ground) fault detection at start



Pr.	GROUP	Name
249	H101	Earth (ground) fault detection at start

Select whether to enable/disable earth (ground) fault detection at start. When enabled, earth (ground) fault detection is performed immediately after a start signal is input to the inverter.

Pr.249 setting	Description
0 (initial value)	Without the earth (ground) fault detection at start
1	With the earth (ground) fault detection at start

- If a ground fault is detected at start while Pr.249 = "1", the output side earth (ground) fault overcurrent (E.GF) is displayed and the outputs are shut off.

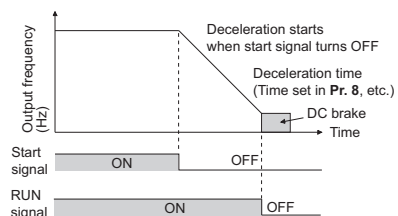
## Motor stop method/start signal selection

Pr.	GROUP	Name
250	G106	Stop selection

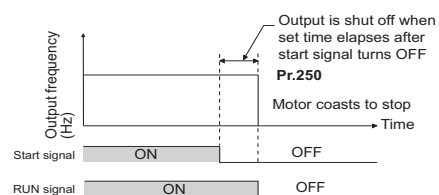
Select the stopping method (deceleration stop or casting) at turn-OFF of the start signal. Use this function to stop a motor with a mechanical brake at turn-OFF of the start signal. The start signal (STF/STR) operation can also be selected.

Pr.250 Setting	Description	
	Start signal (STF/STR)	Stop operation
0 to 100 s	STF signal: Forward rotation start STR signal: Reverse rotation start	It will coast to stop after set time when the start signal is turned OFF.
1000 s to 1100 s	STF signal: Start signal STR signal: Forward/reverse rotation signal	It will coast to stop after (Pr.250 - 1000) s when the start signal is turned OFF.
9999	STF signal: Forward rotation start STR signal: Reverse rotation start	It will perform deceleration stop when the start signal is turned OFF.
8888	STF signal: Start signal STR signal: Forward/reverse rotation signal	It will perform deceleration stop when the start signal is turned OFF.

When Pr.250 is "9999 (initial value) or 8888"



When Pr.250 is other than "9999 (initial value) or 8888"



Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## I/O phase loss protection selection

Pr.	GROUP	Name	Pr.	GROUP	Name
251	H200	Output phase loss protection selection	872	H201	Input phase loss protection selection

The output phase loss protective function, which stops the inverter output if one of the three phases (U, V, W) on the inverter's output side (load side) is lost, can be disabled.

The input phase loss protective function on the inverter's input side (R, S, T) can be enabled.

Pr.	Setting range	Description
251	0	Without output phase loss protection
	1 (initial value)	With output phase loss protection
872	0 (initial value)	Without input phase loss protection
	1	With input phase loss protection

**Pr. 252, 253** ➔ Refer to the page on Pr.73.

## Displaying the life of the inverter parts

Pr.	GROUP	Name	Pr.	GROUP	Name
255	E700	Life alarm status display	256	E701	Inrush current limit circuit life display
257	E702	Control circuit capacitor life display	258	E703	Main circuit capacitor life display
259	E704	Main circuit capacitor life measuring			

The degree of deterioration of the main circuit capacitor, control circuit capacitor, inrush current limit circuit, cooling fan, and internal fan alarm\*1 can be diagnosed on the monitor.

When a part approaches the end of its life, an alarm can be output by self diagnosis to prevent a fault.

(Note that the life diagnosis of this function should be used as a guideline only, because with the exception of the main circuit capacitor, the life values are theoretical calculations.)

Pr.	Setting range	Description
255	(0 to 31)	Displays whether or not the parts of the control circuit capacitor, main circuit capacitor, cooling fan, Internal fan alarm*1, and inrush current limit circuit have reached the life alarm output level. Read-only.
256*2	(0 to 100%)	Displays the deterioration degree of the inrush current limit circuit. Read-only.
257	(0 to 100%)	Displays the deterioration degree of the control circuit capacitor. Read-only.
258*2	(0 to 100%)	Displays the deterioration degree of the main circuit capacitor. Read-only. The value measured by Pr.259 is displayed.
259*2	0, 1 (2, 3, 8, 9)	Setting "1" and turning the power supply OFF starts the measurement of the main circuit capacitor life. If the setting value of Pr.259 becomes "3" after turning the power supply ON again, it means that the measurement is completed. The deterioration degree is read to Pr.258.

\*1 The internal fan is only available for the IP55 compatible model.  
\*2 Not compatible with the separated converter type.

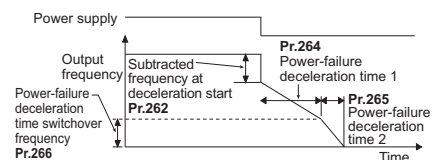
**Pr. 260** ➔ Refer to the page on Pr.72.

## Power failure time deceleration stop function

Pr.	GROUP	Name	Pr.	GROUP	Name
261	A730	Power failure stop selection	262	A731	Subtracted frequency at deceleration start
263	A732	Subtraction starting frequency	264	A733	Power-failure deceleration time 1
265	A734	Power-failure deceleration time 2	266	A735	Power failure deceleration time switchover frequency
294	A785	UV avoidance voltage gain	606	T722	Power failure stop external signal input selection
668	T786	Power failure stop frequency gain			

At instantaneous power failure or undervoltage, the motor can be decelerated to a stop or decelerated once and re-accelerated to the set frequency.

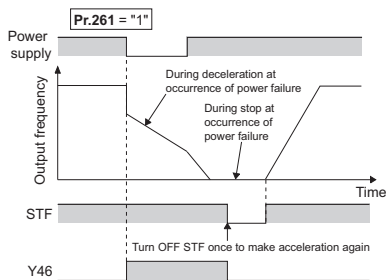
Pr.	Setting range	Description
261	0 (initial value)	Power failure time deceleration stop function disabled
	1, 2, 11, 12, 21, 22	Power failure time deceleration stop function enabled Select action at an undervoltage or when a power failure occurs.
262	0 to 20Hz	Normally, the motor runs at the initial value as it is. However, adjust to suit the size of the load specification (moment of inertia, torque).
263	0 to 590 Hz	When output frequency $\geq$ Pr.263 Deceleration from (output frequency - Pr.262) When output frequency $<$ Pr.263 Deceleration from output frequency
	9999	Deceleration from (output frequency - Pr.262)
264	0 to 3600 s	Set the slope applicable from the deceleration start to the Pr.266 set frequency.
265	0 to 3600 s	Set the slope applicable for the frequency range starting at Pr.266 and downward.
	9999 (initial value)	Same as Pr.264.
266	0 to 590 Hz	Set the frequency at which the slope during deceleration switches from the Pr.264 setting to the Pr.265 setting.
294	0 to 200%	Adjust the response level at UV avoidance operation. Setting a large value improves the response to changes in the bus voltage. If the inertia is high, the amount of regeneration is too large. Set a smaller value.
606	0	Normally open input (NO contact input specification)
	1 (initial value)	Normally closed input (NC contact input specification)
668	0 to 200%	Adjust the response level for the operation where the deceleration time is automatically adjusted.



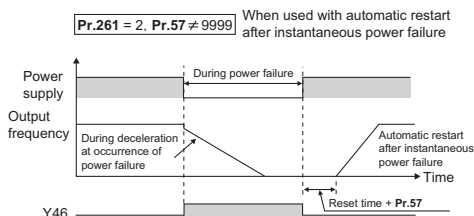
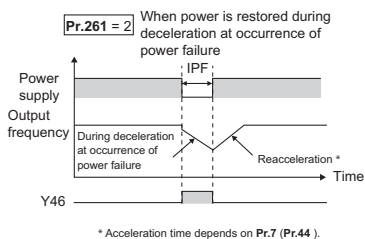
- Set Pr.261 to select the action at an undervoltage and power failure.

Pr.261 setting	Action at undervoltage and power failure	Power restoration during deceleration at occurrence of power failure	Deceleration stop time	Undervoltage avoidance function
0	Coasts to stop	Coasts to stop	-	-
1	Deceleration stop	Deceleration stop	According to Pr.266 setting	Not used
2		Re-acceleration		Not used
11		Deceleration stop	With	
12		Re-acceleration	With	
21	Deceleration stop	Automatic adjustment of deceleration time	Automatic adjustment of deceleration time	Not used
22	Re-acceleration	Automatic adjustment of deceleration time	Automatic adjustment of deceleration time	Not used

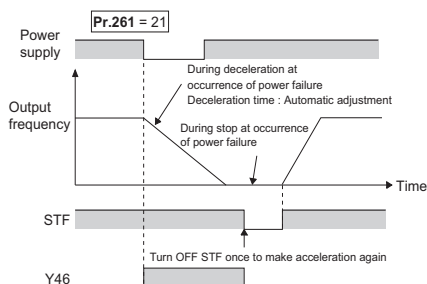
- Power failure stop function (**Pr.261 = "1, 11, 21"**)  
Even if power is restored during deceleration triggered by a power failure, deceleration stop is continued after which the inverter stays stopped. To restart operation, turn the start signal OFF then ON again.



- Continuous operation function at instantaneous power failure (**Pr.261 = "2, 12, 22"**)  
The motor re-accelerates to the set frequency if the power restores during deceleration at occurrence of power failure. Combining with the automatic restart after instantaneous power failure function enables a power failure time deceleration stop and re-acceleration at a power restoration. If the power is restored after stoppage by a power failure, a restart operation is performed when automatic restart after instantaneous power failure (**Pr.57 ≠ "9999"**) is selected.



- Automatic adjustment of deceleration time (**Pr.261 = "21, 22"** **Pr.294, Pr.668**)  
When "21, 22" is set in **Pr.261**, the deceleration time is automatically adjusted to keep (DC bus) voltage constant in the converter when the motor decelerates to a stop at a power failure. Setting of **Pr.262** to **Pr.266** is not required. Use **Pr.668 Power failure stop frequency gain** to adjust the response level during deceleration time auto adjustment. Increasing the setting improves the response level to the bus voltage fluctuations, but the output frequency may be unstable. If setting **Pr.294 UV avoidance voltage gain** lower also does not suppress the vibration, set **Pr.668** lower.



- Pr.267** Refer to the page on Pr.73.
- Pr.268** Refer to the page on Pr.52.
- Pr.269** Parameter for manufacturer setting. Do not set.

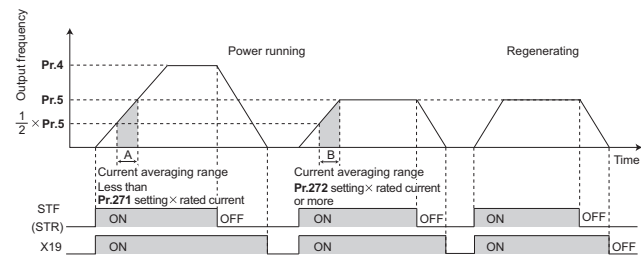
## Load torque high-speed frequency control

Pr.	GROUP	Name	Pr.	GROUP	Name
270	A200	Stop-on contact/load torque high-speed frequency control selection	271	A201	High-speed setting maximum current
272	A202	Middle-speed setting minimum current	273	A203	Current averaging range
274	A204	Current averaging filter time constant	4	D301	Multi-speed setting (high speed)
5	D302	Multi-speed setting (middle speed)			

This function is designed to increase speed automatically under light load, for example to minimize the incoming/outgoing time in a multi-story parking lot. The load size during power driving is estimated by detecting average currents at set timings after a start. When the load is light, the frequency is increased from the originally-set frequency. (During regeneration load operation, the frequency is not increased.)

Pr.270 setting	Description	
0 (initial value)	Normal operation	
1	Stop-on-contact control	
2	Load torque high-speed frequency control	
3	Stop-on-contact + load torque high-speed frequency control	
11	Stop-on-contact control	E.OLT detection invalid under stop-on contact control
13	Stop-on-contact + load torque high-speed frequency control	

- Set such items as the current and averaging range for load torque high-speed frequency control selected by setting **Pr.270 = "2** or **3"**.
- When the load torque high-speed frequency selection (X19) signal is ON, the inverter automatically adjusts the maximum frequency in the range between the **Pr.4 Multi-speed setting (high speed)** and **Pr.5 Multi-speed setting (middle speed)** setting in accordance with the average current while the motor is accelerating from a frequency that is half of the **Pr.5** setting to the **Pr.5** setting as shown in the figure below.



Pr.	Setting range	Description
4	0 to 590 Hz	Set the higher-speed frequency.
5	0 to 590 Hz	Set the lower-speed frequency.
271	0 to 400%	Set the upper and lower limits of the current at high and middle speeds.
272	0 to 400%	
273	0 to 590 Hz	Set the average current during acceleration from ( <b>Pr.273</b> × 1/2) Hz to ( <b>Pr.273</b> ) Hz.
	9999 (Initialization)	Set the average current during acceleration from ( <b>Pr.5</b> × 1/2) Hz to ( <b>Pr.5</b> ) Hz.
274	1 to 4000	Set the time constant of the primary delay filter relative to the output current. (The time constant [ms] is 0.5 × <b>Pr.274</b> , and the initial value is 8 ms.) A larger setting results in a stable operation with poorer response.

## Stop-on-contact control Magnetic flux Sensorless

Pr.	GROUP	Name	Pr.	GROUP	Name
270	A200	Stop-on contact/load torque high-speed frequency control selection	275	A205	Stop-on contact excitation current low-speed multiplying factor
276	A206	PWM carrier frequency at stop-on contact	22	H500	Stall prevention operation level
6	D303	Multi-speed setting (low speed)	48	H600	Second stall prevention operation level

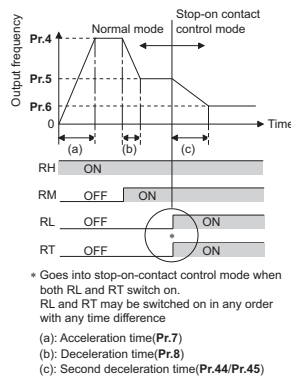
To ensure accurate positioning at the upper limit, etc. of a lift, stop-on-contact control causes the mechanical brake to close while the motor creates a holding torque to keep the load in contact with a mechanical stopper, etc.

This function suppresses vibration that is likely to occur when the load is stopped upon contact in lift applications, thereby ensuring reliable and highly accurate positioning stop.

Pr.270 setting	Description
0 (initial value)	Normal operation
1	Stop-on-contact control
2	Load torque high-speed frequency control
3	Stop-on-contact + load torque high-speed frequency control
11	Stop-on-contact control
13	Stop-on-contact + load torque high-speed frequency control

E.OLT invalid under stop-on-contact control

- Select either Real sensorless vector control (speed control) or Advanced magnetic flux vector control. When both the RT and RL signals are switched ON, the inverter enters the stop-on-contact control, and operation is performed at the frequency set in **Pr.6 Multi-speed setting (low speed)** independently of the preceding speed.



Pr.	Setting range	Description
6	0 to 590 Hz	Set the output frequency for stop-on-contact control. Set the frequency as low as possible (about 2 Hz). If a frequency higher than 30 Hz is set, it operates with 30 Hz. When performing stop-on-contact control during encoder feedback control, encoder feedback control is invalid due to a transition to the stop-on-contact control mode.
22	0 to 400%	Set the stall prevention operation level for stop-on-contact control used under Advanced magnetic flux vector control.
48	0 to 400%	The smaller value set in either <b>Pr.22</b> or <b>Pr.48</b> has priority. The torque limit level uses the <b>Pr.22</b> setting for Real sensorless vector control.
275	50 to 300%	Normally set this parameter within the range of 130% to 180%. Set the force (holding torque) for stop-on-contact control.
	9999 (initial value)	No compensation.

Pr.	Setting range	Description
276	0 to 9 *1	Set a PWM carrier frequency for stop-on-contact control.
	0 to 4 *2	For Real sensorless vector control, the carrier frequency is always 2 kHz when the setting value is 0 to 5 and always 6 kHz when the setting value is 6 to 9. (Valid at the output frequency of 3 Hz or less.)
	9999 (initial value)	As set in <b>Pr.72 PWM frequency selection</b> .

- \*1 The setting range of FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower
- \*2 The setting range of FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher

## Brake sequence function

Pr.	GROUP	Name	Pr.	GROUP	Name
278	A100	Brake opening frequency	279	A101	Brake opening current
280	A102	Brake opening current detection time	281	A103	Brake operation time at start
282	A104	Brake operation frequency	283	A105	Brake operation time at stop
284	A106	Deceleration detection function selection	285	A107	Overspeed detection frequency
292	F500	Automatic acceleration/ deceleration	639	A108	Brake opening current selection
640	A109	Brake operation frequency selection	641	A130	Second brake sequence operation selection
642	A120	Second brake opening frequency	643	A121	Second brake opening current
644	A122	Second brake opening current detection time	645	A123	Second brake operation time at start
646	A124	Second brake operation frequency	647	A125	Second brake operation time at stop
648	A128	Second deceleration detection function selection	650	A128	Second brake opening current selection
651	A129	Second brake operation frequency selection			





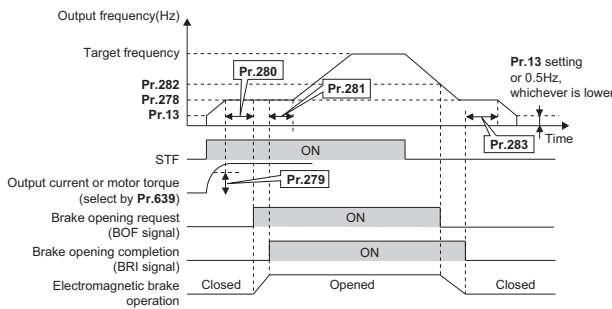
This function outputs operation timing signals of the mechanical brake from the inverter, such as for lift applications. This function is useful in preventing load slippage at a start due to poor mechanical brake timing and overcurrent alarm in stop status and enable secure operation.

<Operation example>

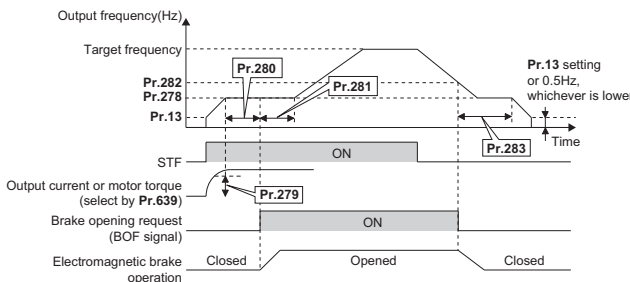
- At start  
When the start signal is input to the inverter, the inverter starts running, and when the output frequency reaches the frequency set in **Pr.278** and the output current or the motor torque is equal to or greater than the **Pr.279** setting, the brake opening request signal (BOF) is output after the time set in **Pr.280**. The brake opening completion signal (BRI) is input, and the output frequency is increased to the set speed after the set time in **Pr.281**.
- Deceleration time  
When the inverter decelerates to the frequency set in **Pr.282**, the inverter turns OFF the BOF signal and decelerates further to the frequency set in **Pr.278**. After electromagnetic brake operation completes and the inverter recognizes the turn OFF of the BRI signal, the inverter holds the frequency set in **Pr.283** for the time set in **Pr.283**. And after the time set in **Pr.283** passes, the inverter decelerates again. \*1 The inverter outputs is shut off when the frequency reaches **Pr.13 Starting frequency** setting or 0.5 Hz, whichever is lower.

\*1 When **Pr.292 = "8"** (without mechanical brake opening completion signal input), the time starts when the brake opening completion signal is output.

When **Pr.292 = "7"** (with brake opening completion signal input)



When **Pr.292 = "8"** (without brake opening completion signal input)



- Turning ON the RT signal enables the second brake sequence function.

Pr.	Setting range	Description
<b>278</b>	0 to 30Hz	Set the rated slip frequency of the motor + approx. 1.0 Hz. This can be set only when <b>Pr.278 ≤ Pr.282</b> .
<b>279</b>	0 to 400%	If the setting is too low, dropping of the load is more likely to occur at a start, and generally, it is set between 50 and 90%. The inverter rated current is regarded as 100%.
<b>280</b>	0 to 2 s	Generally set between 0.1 and 0.3 s.
<b>281</b>	0 to 5 s	<b>Pr.292 = 7:</b> Set the mechanical delay time until braking eases. <b>Pr.292 = 8:</b> Set the mechanical delay time until braking eases + approx. 0.1 to 0.2 s.
<b>282</b>	0 to 30Hz	Frequency that turns OFF the brake opening request signal (BOF) and operates the electromagnetic brake. Generally, set the setting value of <b>Pr.278 + 3</b> to 4 Hz. This can be set only when <b>Pr.282 ≥ Pr.278</b> .
<b>283</b>	0 to 5 s	<b>Pr.292 = 7:</b> Set the mechanical delay time until the brake closes + 0.1 s. <b>Pr.292 = 8:</b> Set the mechanical delay time until the brake closes + approx. 0.2 to 0.3 s.
<b>284</b>	0 (initial value)	The deceleration detection function disabled.
	1	The protective function activates when the deceleration speed of the deceleration operation is not normal.
<b>285 *2</b>	0 to 30Hz	The brake sequence fault (E.MB1) activates when the difference between the detection frequency and output frequency is equal to or greater than the setting value under encoder feedback control.
	9999 (initial value)	Overspeed detection disabled.
<b>292</b>	0, 1, 3, 5 to 8, 11	Setting this parameter to "7, 8" enables the brake sequence function.
<b>639</b>	0 (initial value)	Brake opening by output current
	1	Brake opening by motor torque
<b>640</b>	0 (initial value)	Brake closing operation by frequency command
	1	Brake closing operation by the actual motor rotation speed (estimated value)
<b>641</b>	0 (initial value)	Normal operation when the RT signal is ON
	7	Second brake sequence 1 when the RT signal is ON
	8	Second brake sequence 2 when the RT signal is ON
	9999	First brake sequence 1 is valid when the RT signal is ON

\*2 The speed deviation excess detection frequency is used when vector control is performed.

- Features
- Application Example
- PLC Function
- FR Configurator2
- Connection Examples
- Standard Specs
- Outline Dimensions
- Terminal Diagrams
- Terminal Specs
- Operation Panel
- Parameter List
- Explanations of Parameters
- Protective Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty Inquiry

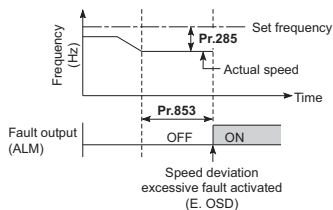




## Avoiding motor overrunning Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
285	H416	Speed deviation excess detection frequency	853	H417	Speed deviation time
873	H415	Speed limit			

• Speed deviation excess detection (**Pr.285, Pr.853**)  
 When the difference (absolute value) between the speed command value and actual rotation speed in speed control under vector control is equal to or higher than the setting value in **Pr.285 Speed deviation excess detection frequency** for a continuous time equal to or longer than the setting value in **Pr.853 Speed deviation time**, Speed deviation excess detection (E.OSD) activates to shut off the inverter output.



• Speed limit (**Pr.873**)  
 This function prevents overrunning even when the setting value for the number of encoder pulses and the value of the actual number of pulses are different. When the setting value for the number of encoder pulses is lower than the actual number of pulses, because the motor may increase speed, the output frequency is limited with the frequency of (set frequency + **Pr.873**).

## Droop control

Magnetic flux Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
286	G400	Droop gain	287	G401	Droop filter time constant
288	G402	Droop function activation selection	679	G420	Second droop gain
680	G421	Second droop filter time constant	681	G422	Second droop function activation selection
682	G423	Second droop break point gain	683	G424	Second droop break point torque
994	G403	Droop break point gain	995	G404	Droop break point torque

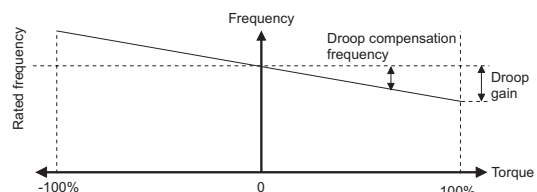
This is a function to give droop characteristics to the speed by balancing the load in proportion with the load torque. This is effective when balancing the load when using multiple inverters.

Pr.	Setting range	Description
286	0 (initial value)	Droop control disabled
	0.1 to 100%	Set the droop amount at the rated torque as % value of the rated motor frequency.
287	0 to 1 s	Set the filter time constant to apply to the current for torque.

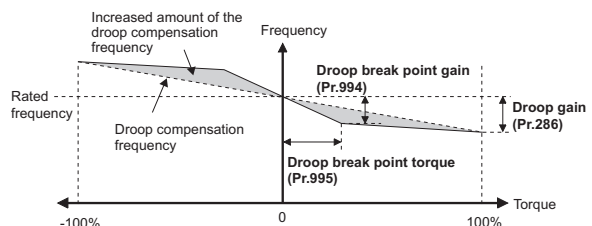
Pr.	Setting range	Description	
288	0 (initial value)	Without droop control during acceleration/ deceleration (With 0 limit)	
	1 *1	Constantly droop control during operation (With 0 limit)	Rated motor frequency is the droop compensation reference.
	2 *1	Constantly droop control during operation (Without 0 limit)	
	10 *1	Without droop control during acceleration/ deceleration (With 0 limit)	Motor speed is the droop compensation reference.
	11 *1	Constantly droop control during operation (With 0 limit)	
994	0.1 to 100%	Set the droop amount to be changed as % value of the rated motor frequency.	
	9999 (initial value)	No function	
995	0.1 to 100%	Set the torque when the droop amount is to be changed.	

\*1 Under Advanced magnetic flux vector control, the operation is the same with setting the parameter to "0".

- Droop control  
 Droop control is enabled for Advanced magnetic flux vector control, Real sensorless vector control, vector control, and PM sensorless vector control when **Pr.286** is not "0". The upper limit of the droop compensation frequency is 120 Hz.
- Turning ON the RT signal enables the second droop control.



- Break point setting for droop control (**Pr.994, Pr.995**)  
 Set **Pr.994** and **Pr.995** to have a break point on a droop compensation frequency line. Setting a break point allows the inverter to raise the droop compensation frequency for light-load operation without raising it for heavy-load operation.



- Pr.289** ➤ Refer to the page on Pr.190.
- Pr.290** ➤ Refer to the page on Pr.52.



## Pulse train input/output

Pr.	GROUP	Name	Pr.	GROUP	Name
291	D100	Pulse train I/O selection	384	D101	Input pulse division scaling factor
385	D110	Frequency for zero input pulse	386	D111	Frequency for maximum input pulse

A pulse train input to the terminal JOG can be used to set the inverter's speed command.

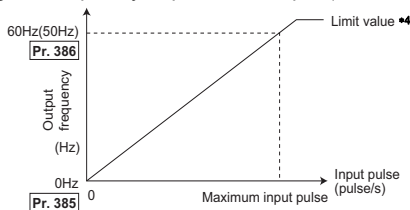
The pulse train can be output from the terminal FM by the open collector output system.

Speed synchronized operation of an inverter can be performed by using the pulse train input/output together with the terminal JOG.

Pr.291 setting	Input (Terminal JOG)	Output (Terminal FM)
0 (initial value)	JOG signal *2	FM output *3
1	Pulse train input	FM output *3
10 *3	JOG signal *2	Pulse train output (50% duty)
11 *3	Pulse train input	
20 *3	JOG signal *2	Pulse train output (ON width fixed)
21 *3	Pulse train input	Pulse train output (ON width fixed) *1
100 *3		

- \*1 Regardless of the Pr.54 setting, the signal input as a pulse train is output as it is.
- \*2 The function is assigned in Pr.185 JOG terminal function selection.
- \*3 Only the FM type inverters support the pulse train output.

• Changing the frequency at pulse train input (Pr.385, Pr.386)



\*4 Limit value = (Pr.386 - Pr.385) 1.1 + Pr.385

- How to calculate the input pulse division scaling factor (Pr.384)  
Maximum number of pulses (pulse/s) = Pr.384 × 400  
(Allowable maximum number of pulses = 100k pulses/s)
- If Pr.419 Position command source selection = "2" (simple pulse train position command) is set, the terminal JOG is used for the simple position pulse train input regardless of the Pr.291 Pulse train I/O selection setting.

Pr.292, 293 ➤ Refer to the page on Pr.61.

Pr.294 ➤ Refer to the page on Pr.261.

Pr.295 ➤ Refer to the page on Pr.161.

## Password function

Pr.	GROUP	Name	Pr.	GROUP	Name
296	E410	Password lock level	297	E411	Password lock/unlock

Registering a 4-digit password can restrict parameter reading/writing.

- Level of reading/writing restriction by PU/NET mode operation command can be selected by Pr.296.

Pr.296 setting	PU mode operation command		NET mode operation command			
	Read	Write	RS-485 terminals		Communication option	
			Read	Write	Read	Write
9999 (initial value)	○	○	○	○	○	○
0, 100	×	×	×	×	×	×
1, 101	○	×	○	×	○	×
2, 102	○	×	○	○	○	○
3, 103	○	○	○	×	○	×
4, 104	×	×	×	×	○	×
5, 105	×	×	○	○	○	○
6, 106	○	○	×	×	○	×
99, 199	Only the parameters registered in the user group can be read/written. (For the parameters not registered in the user group, the same restriction level as "4, 104" applies.)					

○: Enabled, ×: Disabled

Pr. 297 setting	Description
1000 to 9998	Register a 4-digit password.*1
(0 to 5)*2	Displays password unlock error count. (Reading only) (Valid when Pr.296 = "100 to 106")
9999 (initial value)	No password lock

- \*1 If the password is forgotten, it can be unlocked with all parameter clear, but doing so will also clear the other parameters.
- \*2 When Pr.297 = "0, 9999", writing is always enabled, but setting is disabled. (The display cannot be changed.)

Pr. 298 ➤ Refer to the page on Pr.81.

Pr. 299 ➤ Refer to the page on Pr.57.

Pr. 331 to 337 ➤ Refer to the page on Pr.117.

Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## Start command source and frequency command source during communication operation

Pr.	GROUP	Name	Pr.	GROUP	Name
338	D010	Communication operation command source	339	D011	Communication speed command source
550	D012	NET mode operation command source selection	551	D013	PU mode operation command source selection

The operation and speed commands from an external device can be made valid when using the RS-485 terminals or the communication option. The operation command source in the PU operation mode can also be selected.

Pr.	Setting range	Description
338	0 (initial value)	Start command source is communication.
	1	Start command source is external.
339	0 (initial value)	Frequency command source is communication.
	1	Frequency command source is external.
	2	Frequency command source is external. (When there is no external input, the frequency command via communication is valid, and the frequency command from terminal 2 is invalid.)
550	0	The communication option is the command source when in the NET operation mode.
	1	The RS-485 terminals are the command source when in the NET operation mode.
	9999 (initial value)	Communication option is recognized automatically. Normally, the RS-485 terminals are the command source. When the communication option is mounted, the communication option is the command source.
551	1	The RS-485 terminals are the command source when in the PU operation mode.
	2	The PU connector is the command source when in the PU operation mode.
	3	The USB connector is the command source when in the PU operation mode.
	9999 (initial value)	USB automatic recognition. Normally, the PU connector is the command source. When the USB is connected, the USB connector is the command source.

**Pr. 340** ➔ Refer to the page on Pr.79.

**Pr. 341 to 343** ➔ Refer to the page on Pr.117.

## Orientation control

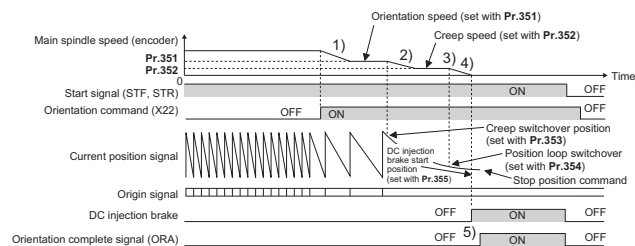
V/F Magnetic flux Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
350	A510	Stop position command selection	351	A526	Orientation speed
352	A527	Creep speed	353	A528	Creep switchover position
354	A529	Position loop switchover position	355	A530	DC injection brake start position
356	A531	Internal stop position command	357	A532	Orientation in-position zone
358	A533	Servo torque selection	359	C141	Encoder rotation direction
360	A511	16-bit data selection	361	A512	Position shift
362	A520	Orientation position loop gain	363	A521	Completion signal output delay time
364	A522	Encoder stop check time	365	A523	Orientation limit
366	A524	Recheck time	369	C140	Number of encoder pulses
393	A525	Orientation selection	394	A540	Number of machine side gear teeth
395	A541	Number of motor side gear teeth	396	A542	Orientation speed gain (P term)
397	A543	Orientation speed integral time	398	A544	Orientation speed gain (D term)
399	A545	Orientation deceleration ratio	851	C240	Control terminal option-Number of encoder pulses
852	C241	Control terminal option-Encoder rotation direction	862	C242	Encoder option selection

The inverter can adjust the stop position (Orientation control) using a position detector (encoder) attached to a place such as the main shaft of the machine.

An orientation control compatible option is required.

- Internal stop position command  
When "0" is set in **Pr.350 Stop position command selection**, the internal position command mode is activated. In the internal position command mode, the setting value of **Pr.356 Internal stop position command** is used as the stop position.
- Internal stop position command  
When **Pr.350 Stop position command selection** is set to "1" and the FR-A8AX is used, 16-bit data (binary input) is used to give the stop position.
- Operation timing chart



- Using the FR-A8TP (motor end) together with the plug-in option FR-A8AP (machine end) enables machine end orientation control. Setting **Pr.862** = "1" enables machine end orientation.

## Encoder feedback control

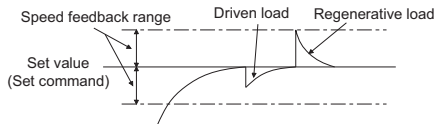
V/F Magnetic flux

Pr.	GROUP	Name	Pr.	GROUP	Name
359	C141	Encoder rotation direction	367	G240	Speed feedback range
368	G241	Feedback gain	369	C140	Number of encoder pulses
144	M002	Speed setting switchover	285	A107	Overspeed detection frequency
851	C240	Control terminal option-Number of encoder pulses	852	C241	Control terminal option-Encoder rotation direction

By detecting the rotation speed of the motor with the speed detector (encoder) and feeding it back to the inverter, output frequency of the inverter is controlled to keep the speed of the motor constant even for the load change.

A vector control compatible option is required.

- Using **Pr.359 Encoder rotation direction** and **Pr.369 Number of encoder pulses**, set the rotation direction and the number of pulses for the encoder.
- When a value other than "9999" is set in **Pr.367 Speed feedback range**, encoder feedback control is valid. Using the set point (frequency at which stable speed operation is performed) as reference, set the higher and lower setting range. Normally, set the frequency converted from the slip amount ( $r$ /min) of the rated motor speed (rated load). If the setting is too large, response becomes slow.



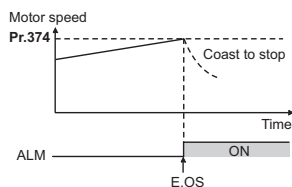
- Set **Pr.368 Feedback gain** when the rotation is unstable or response is slow.

Pr.368 setting	Description
Pr.368 > 1	Response will become faster but it may cause overcurrent or become unstable.
1 > Pr.368	Response will become slower but it will become more stable.

## Motor overspeeding detection

Pr.	GROUP	Name
374	H800	Overspeed detection level

If the motor rotation speed exceeds the speed set in **Pr.374** during encoder feedback control, Real sensorless vector control, vector control or PM sensorless vector control, Overspeed occurrence (E.OS) occurs, the inverter output is shut off.



## Signal loss detection of encoder signals

V/F Magnetic flux Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
376	C148	Encoder signal loss detection enable/disable selection	855	C248	Control terminal option-Signal loss detection enable/disable selection

If encoder signals are disconnected during encoder feedback control, orientation control or vector control, Signal loss detection (E.ECT) is turned ON to shut off the inverter output.

- Pr.380 to 383** Refer to the page on Pr.29.
- Pr.384 to 386** Refer to the page on Pr.291.
- Pr.393 to 399** Refer to the page on Pr.350.

## PLC function

Pr.	GROUP	Name	Pr.	GROUP	Name
414	A800	PLC function operation selection	415	A801	Inverter operation lock mode setting
416	A802	Pre-scale function selection	417	A803	Pre-scale setting value
498	A804	PLC function flash memory clear	1150 to 1199	A810 to A859	User parameters 1 to User parameters 50

The inverter can be run in accordance with a sequence program. In accordance with the machine specifications, a user can set various operation patterns: inverter movements at signal inputs, signal outputs at particular inverter statuses, and monitor outputs, etc.

Pr.	Setting range	Description
414	0 (initial value)	PLC function disabled
	1	PLC function enabled The SQ signal is enabled by input from a command source (external input terminal / communication). The SQ signal is enabled by input from an external input terminal.
	2	
415	0 (initial value)	The inverter start command is enabled regardless of the operating status of the sequence program.
	1	The inverter start command is enabled only while the sequence program is running.
416	0 to 5	Unit scale factor 0: No function 1: x 1 2: x 0.1 3: x 0.01 4: x 0.001 5: x 0.0001
		When the pulse train is input from terminal JOG, the number of sampled pulses can be converted. The result of conversion is stored to SD1236. "Number of sampled pulses" = "input pulse value per count cycle" x "pre-scale setting value (Pr.417)" x "unit scale factor (Pr.416)"
417	0 to 3267	Pre-scale setting value
		0: Clears the flash memory fault display (no operation after writing while the flash memory is in normal operation). 9696: Clears the flash memory (no operation Write after writing during flash memory fault). Other than 0 and 9696: Outside of the setting range
498	0 to 9999	0: Normal display
		1: The flash memory has not been cleared because the PLC function is enabled.
		9696: During flash memory clearing operation or flash memory fault
		Write
1150 to 1199	0 to 65535	Desired values can be set. Because devices D206 to D255 used by the PLC function can be mutually accessed, the values set to Pr.1150 to Pr.1199 can be used by the sequence program. The result of performing calculation by a sequence program can also be monitored by Pr.1150 to Pr.1199.
		Read



- Switch the execution key (RUN/STOP) of the sequence program by turning the SQ signal ON/OFF. The sequence program can be executed by turning the SQ signal ON. To input the SQ signal, set "50" in any of **Pr.178 to Pr.189 (input terminal function selection)** to assign the function to a terminal.
- To write to the sequence program, use FR Configurator2 on a personal computer that is connected to the inverter via RS-485 communication.
- This function copies the PLC function project data to a USB memory device.  
The PLC function project data copied in the USB memory device can be copied to other inverters. This function is useful in backing up the parameter setting and for allowing multiple inverters to operate by the same sequence programs.

## Simple positioning function by parameters **Vector** **PM**

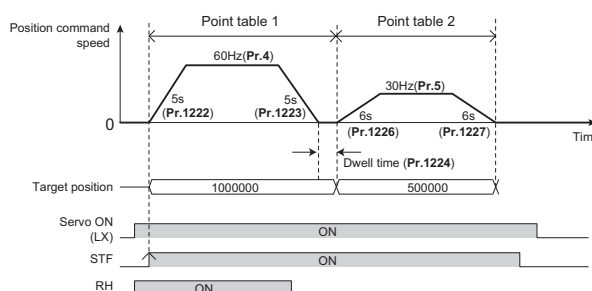
Pr.	GROUP	Name	Pr.	GROUP	Name
419	B000	Position command source selection	464	B020	Digital position control sudden stop deceleration time
465	B021	First target position lower 4 digits	466	B022	First target position upper 4 digits
467	B023	Second target position lower 4 digits	468	B024	Second target position upper 4 digits
469	B025	Third target position lower 4 digits	470	B026	Third target position upper 4 digits
471	B027	Fourth target position lower 4 digits	472	B028	Fourth target position upper 4 digits
473	B029	Fifth target position lower 4 digits	474	B030	Fifth target position upper 4 digits
475	B031	Sixth target position lower 4 digits	476	B032	Sixth target position upper 4 digits
477	B033	Seventh target position lower 4 digits	478	B034	Seventh target position upper 4 digits
479	B035	Eighth target position lower 4 digits	480	B036	Eighth target position upper 4 digits
481	B037	Ninth target position lower 4 digits	482	B038	Ninth target position upper 4 digits
483	B039	Tenth target position lower 4 digits	484	B040	Tenth target position upper 4 digits
485	B041	Eleventh target position lower 4 digits	486	B042	Eleventh target position upper 4 digits
487	B043	Twelfth target position lower 4 digits	488	B044	Twelfth target position upper 4 digits
489	B045	Thirteenth target position lower 4 digits	490	B046	Thirteenth target position upper 4 digits
491	B047	Fourteenth target position lower 4 digits	492	B048	Fourteenth target position upper 4 digits
493	B049	Fifteenth target position lower 4 digits	494	B050	Fifteenth target position upper 4 digits
1221	B101	Start command edge detection selection	1222	B120	First positioning acceleration time
1223	B121	First positioning deceleration time	1224	B122	First positioning dwell time
1225	B123	First positioning sub-function	1226	B124	Second positioning acceleration time
1227	B125	Second positioning deceleration time	1228	B126	Second positioning dwell time
1229	B127	Second positioning sub-function	1230	B128	Third positioning acceleration time
1231	B129	Third positioning deceleration time	1232	B130	Third positioning dwell time
1233	B131	Third positioning sub-function	1234	B132	Fourth positioning acceleration time
1235	B133	Fourth positioning deceleration time	1236	B134	Fourth positioning dwell time
1237	B135	Fourth positioning sub-function	1238	B136	Fifth positioning acceleration time
1239	B137	Fifth positioning deceleration time	1240	B138	Fifth positioning dwell time
1241	B139	Fifth positioning sub-function	1242	B140	Sixth positioning acceleration time
1243	B141	Sixth positioning deceleration time	1244	B142	Sixth positioning dwell time
1245	B143	Sixth positioning sub-function	1246	B144	Seventh positioning acceleration time
1247	B145	Seventh positioning deceleration time	1248	B146	Seventh positioning dwell time

Pr.	GROUP	Name	Pr.	GROUP	Name
1249	B147	Seventh positioning sub-function	1250	B148	Eighth positioning acceleration time
1251	B149	Eighth positioning deceleration time	1252	B150	Eighth positioning dwell time
1253	B151	Eighth positioning sub-function	1254	B152	Ninth positioning acceleration time
1255	B153	Ninth positioning deceleration time	1256	B154	Ninth positioning dwell time
1257	B155	Ninth positioning sub-function	1258	B156	Tenth positioning acceleration time
1259	B157	Tenth positioning deceleration time	1260	B158	Tenth positioning dwell time
1261	B159	Tenth positioning sub-function	1262	B160	Eleventh positioning acceleration time
1263	B161	Eleventh positioning deceleration time	1264	B162	Eleventh positioning dwell time
1265	B163	Eleventh positioning sub-function	1266	B164	Twelfth positioning acceleration time
1267	B165	Twelfth positioning deceleration time	1268	B166	Twelfth positioning dwell time
1269	B167	Twelfth positioning sub-function	1270	B168	Thirteenth positioning acceleration time
1271	B169	Thirteenth positioning deceleration time	1272	B170	Thirteenth positioning dwell time
1273	B171	Thirteenth positioning sub-function	1274	B172	Fourteenth positioning acceleration time
1275	B173	Fourteenth positioning deceleration time	1276	B174	Fourteenth positioning dwell time
1277	B175	Fourteenth positioning sub-function	1278	B176	Fifteenth positioning acceleration time
1279	B177	Fifteenth positioning deceleration time	1280	B178	Fifteenth positioning dwell time
1281	B179	Fifteenth positioning sub-function	1282	B180	Home position return method selection
1283	B181	Home position return speed	1284	B182	Home position return creep speed
1285	B183	Home position shift amount lower 4 digits	1286	B184	Home position shift amount upper 4 digits
1287	B185	Travel distance after proximity dog ON lower 4 digits	1288	B186	Travel distance after proximity dog ON upper 4 digits
1289	B187	Home position return stopper torque	1290	B188	Home position return stopper waiting time
1292	B190	Position control terminal input selection	1293	B191	Roll feeding mode selection

Set positioning parameters such as the number of pulses (position) and acceleration/deceleration time in advance to create a point table (point table method). Positioning operation is performed by selecting the point table.

- Positioning operation by point tables, example 1 (automatic continuous positioning operation)  
The figure below shows an operation example when the following settings are made for point tables.

Point table	Target position		Maximum speed (Hz)	Acceleration time (s)	Deceleration time (s)	Dwell time (ms)	Auxiliary function
	Upper	Lower					
1	100	0	60	5	5	1000	1 (absolute position, continuous)
2	50	0	30	6	6	0	10 (incremental position, individual)





- Selecting the home position return method (Pr.1282 to Pr.1288)

Pr.1282 Setting	Home position return method	Description
0	Dog type *1 <b>Vector</b>	Deceleration starts when the proximity dog signal is turned ON. For the home position after turn OFF of the proximity dog signal, the position specified by the first Z-phase signal or the position of the first Z-phase signal shifted by the home position shift amount (Pr.1285, Pr.1286) is used.
1	Count type *1 <b>Vector</b>	Deceleration starts when the proximity dog signal is turned ON. After the proximity dog, the motor travels the specified travel distance (Pr.1287, Pr.1288). Then, it uses the position specified by the the first Z-phase signal or position of the Z-phase signal shifted by the home position shift amount (Pr.1285, Pr.1286).
2	Data set type <b>Vector</b> <b>PM</b>	The position at which the start signal is input is used as the home position.
3	Stopper type <b>Vector</b> <b>PM</b>	A workpiece is pressed to a mechanical stopper, and the position where it is stopped is set as the home position. Pressing is confirmed when the estimated speed value has fallen below Pr.865 Low speed detection for 0.5 s during activation of the torque limit operation. (While the stopper-type home position is performed, Pr.1289 Home position return stopper torque is applied.) After Pr.1290 Home position return stopper waiting time has passed after pressing is confirmed, the home position is shifted by the home position shift amount (Pr.1285 and Pr.1286). After a position command is created and the absolute value of the droop pulse (after electronic gear) falls below the in-position width, the home position return is completed.
4 (initial value)	Ignoring the home position (Servo ON position as the home position) <b>Vector</b> <b>PM</b>	The servo ON position is used as the home position.
5	Dog type back end reference <b>Vector</b> <b>PM</b>	Deceleration starts at the front end of the proximity dog. After the back end is passed, the position is shifted by the post-dog travel distance and home position shift amount. The position after the shifts is set as the home position. Set pulses required for deceleration from the creep speed or more as the total of the postdog travel distance and home position shift amount.
6	Count type front end reference <b>Vector</b> <b>PM</b>	Deceleration starts at the front end of the proximity dog, and the position is shifted by the postdog travel distance and home position shift distance. The position after the shifts is set as the home position. Set pulses required for changing the speed from the home position speed to the creep speed or more as the total of the post-dog travel distance and home position shift amount.

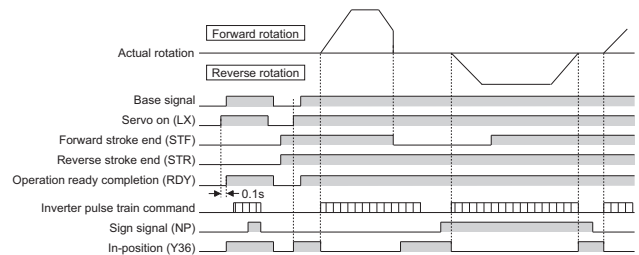
\*1 If it is set under PM sensorless vector control, Home position return parameter setting error (HP3) occurs.

## Position control by inverter pulse train input **Vector** **PM**

Pr.	GROUP	Name	Pr.	GROUP	Name
419	B000	Position command source selection	428	B009	Command pulse selection
429	B010	Clear signal selection	430	B011	Pulse monitor selection
635	M610	Cumulative pulse clear signal selection	636	M611	Cumulative pulse division scaling factor
637	M612	Control terminal option-Cumulative pulse division scaling factor	638	M613	Cumulative pulse storage

The simple position pulse train command can be input by pulse train input and sign signal (NP) from the JOG terminal.

- Setting "2" in Pr.419 selects the simple pulse train position command.
- Select the command pulse train with Pr.428.
- If the Pre-excitation/servo ON (LX) signal is turned ON, output shutoff is canceled and the Position control preparation ready (RDY) signal is turned ON after 0.1 s. Turning ON STF (forward rotation stroke end signal) or STR (reverse rotation stroke end signal) rotates the motor according to the command pulse. If the forward (reverse) rotation stroke end signal is turned OFF, the motor does not rotate in the corresponding direction.



## Electronic gear setting under position control **Vector** **PM**

Pr.	GROUP	Name	Pr.	GROUP	Name
420	B001	Command pulse scaling factor numerator (electronic gear numerator)	421	B002	Command pulse multiplication denominator (electronic gear denominator)
424	B005	Position command acceleration/ deceleration time constant			

Set the gear ratio between the machine gear and motor gear.

Pr.	Setting range	Description
420	0 to 32767	Set the electronic gear. Pr.420 is the numerator and Pr.421 is the denominator.
421		
424	0 to 50 s	Use it when the rotation is not smooth because the electronic gear ratio is large (10 times or larger) and the rotation speed is slow.

Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel  
Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## Position control gain adjustment

Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
422	B003	Position control gain	423	B004	Position feed forward gain
425	B006	Position feed forward command filter	446	B012	Model position control gain
1298	B013	Second position control gain			

- Adjust **Pr.422** when any of such phenomena as unusual vibration, noise and overcurrent of the motor/machine occurs. Increasing the setting improves traceability for the position command and also improves servo rigidity at a stop, but oppositely makes an overshoot and vibration more liable to occur.
- The function of **Pr.423** is to cancel a delay caused by the droop pulses in the deviation counter.
- The first delay filter for the feed forward command can be input in **Pr.425**.
- Use **Pr.446** to set the gain for the model position controller.
- Turning ON the RT signal enables the second position loop gain.

## Position adjustment parameter

Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
426	B007	In-position width	427	B008	Excessive level error
1294	B192	Position detection lower 4 digits	1295	B193	Position detection upper 4 digits
1296	B194	Position detection selection	1297	B195	Position detection hysteresis width

- If the number of droop pulses is equal to or smaller than the **Pr.426** setting value, the In-position (Y36) signal turns ON.
- If the number of droop pulses exceeds the **Pr.427** setting, a position error is detected, Excessive position fault (E.OD) is activated and the inverter output is shut off.
- If the current position (before the electronic gear) exceeds the detected position (**Pr.1294** + **Pr.1295**), the Position detected signal (FP) turns ON.
- Use **Pr.1296 Position detection selection** to determine whether to detect a position in the positive position range or in the negative position range.

**Pr.** 428, 429 ➤ Refer to the page on Pr.419.

**Pr.** 446 ➤ Refer to the page on Pr.422.

**Pr.** 450 ➤ Refer to the page on Pr.71.

**Pr.** 451 ➤ Refer to the page on Pr.80.

**Pr.** 453, 454 ➤ Refer to the page on Pr.80.

**Pr.** 455 to 463 ➤ Refer to the page on Pr.82.

## Remote output function

Pr.	GROUP	Name	Pr.	GROUP	Name
495	M500	Remote output selection	496	M501	Remote output data 1
497	M502	Remote output data 2			

The inverter output signals can be turned ON/OFF instead of the remote output terminals of a programmable controller.

Pr.	Setting range	Description
495	0 (initial value)	Remote output data is cleared when the power supply is turned OFF.
	1	Remote output data is retained when the power supply is turned OFF.
	10	Remote output data is cleared when the power supply is turned OFF.
	11	Remote output data is retained when the power supply is turned OFF.
496	0 to 4095	Refer to the diagram below. (Even if <b>Pr.77 Parameter write selection</b> is set to "0 (initial value)", the setting value can be changed regardless whether the inverter is running or not or of the operation mode.)
497	0 to 4095	

<Remote output data>

### Pr.496

b11										b0	
*1	*1	*1	*1	*1	ABC2	ABC1	FU	OL	IPF	SU	RUN

### Pr.497

b11										b0	
*1	*1	RA3 *3	RA2 *3	RA1 *3	Y6 *2	Y5 *2	Y4 *2	Y3 *2	Y2 *2	Y1 *2	Y0 *2

\*1 Any value.

\*2 Y0 to Y6 are available when the extension output option (FR-A8AY) is installed.

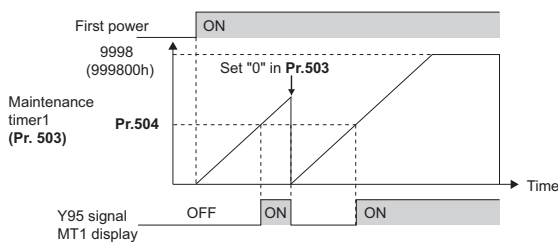
\*3 RA1 to RA3 are available when the relay output option (FR-A8AR) is installed.

## Maintenance timer warning

Pr.	GROUP	Name	Pr.	GROUP	Name
503	E710	Maintenance timer 1	504	E711	Maintenance timer 1 warning output set time
686	E712	Maintenance timer 2	687	E713	Maintenance timer 2 warning output set time
688	E714	Maintenance timer 3	689	E715	Maintenance timer 3 warning output set time

The maintenance timer output signal (Y95) is output when the inverter's cumulative energization time reaches the time period set with the parameter. MT1, MT2 or MT3 is displayed on the operation panel (FR-DU08).

This can be used as a guideline for the maintenance time of peripheral devices.



Operation example of the maintenance timer 1 (Pr.503, Pr.504) (with both MT2 and MT3 OFF)

- The cumulative energization time of the inverter is stored in the EEPROM every hour and displayed in **Pr.503 (Pr.686, Pr.688)** in 100 h increments. **Pr.503 (Pr.686, Pr.688)** is clamped at 9998 (999800 h).

**Pr. 516 to 519** ➤ Refer to the page on Pr.29.

## Output stop function

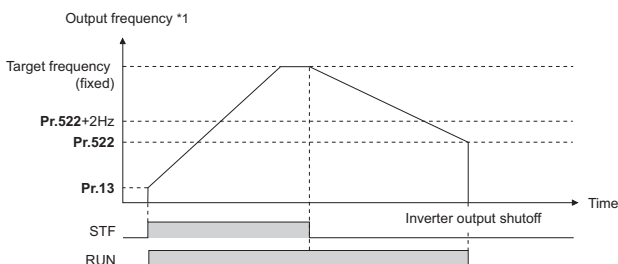
Pr.	GROUP	Name
522	G105	Output stop frequency

The motor coasts to a stop (inverter output shutoff) when inverter output frequency falls to **Pr. 522** setting or lower.

Pr.522 setting	Description
0 to 590 Hz	Set the frequency to start coasting to a stop (output shutoff).
9999 (initial value)	No function

- When both of the frequency setting signal and output frequency falls to the frequency set in **Pr.522** or lower, the inverter stops the output and the motor coasts to a stop.

Example of when target frequency > Pr.522 + 2Hz, and start signal is ON/OFF



\*1 The output frequency before the slip compensation is compared with the **Pr.522** setting.

- At a stop condition, the motor starts running when the frequency setting signal exceeds **Pr.522 + 2Hz**. The motor is accelerated at the **Pr.13 Starting frequency** (0.01Hz under IPM motor control) at the start.

## USB device communication

Pr.	GROUP	Name	Pr.	GROUP	Name
547	N040	USB communication station number	548	N041	USB communication check time interval

Setup of the inverter can be easily performed with FR Configurator2 through the USB communication.

Pr.	Setting range	Description
547	0 to 31	Inverter station number specification
548	0	USB communication is possible, however the inverter will trip (E.USB) when the mode changes to the PU operation mode.
	0.1 to 999.8	Set the communication check time interval. If a no-communication state persists for longer than the permissible time, the inverter will trip (E.USB).
	9999 (initial value)	No communication check

**Pr. 549** ➤ Refer to the page on Pr.117.

**Pr. 550, 551** ➤ Refer to the page on Pr.338.

**Pr. 552** ➤ Refer to the page on Pr.31.

**Pr. 553, 554** ➤ Refer to the page on Pr.127.

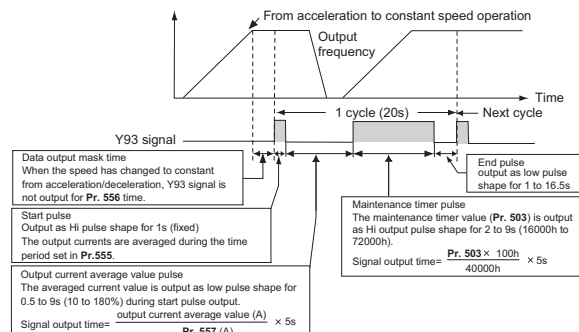
## Current average value monitor signal

Pr.	GROUP	Name	Pr.	GROUP	Name
555	E720	Current average time	556	E721	Data output mask time
557	E722	Current average value monitor signal output reference current			

The output current average value during constant-speed operation and the maintenance timer value are output to the current average value monitor signal (Y93) as a pulse.

The output pulse width can be used in a device such as the I/O module of a programmable controller as a guideline for the maintenance time for mechanical wear, belt stretching, or deterioration of devices with age.

The pulse is repeatedly output during constant-speed operation in cycles of 20 s to the Current average monitor signal (Y93).



**Pr. 560** ➤ Refer to the page on Pr.9.

**Pr. 561** ➤ Refer to the page on Pr.82.

**Pr. 563, 564** ➤ Refer to the page on Pr.52.

**Pr. 569** ➤ Refer to the page on Pr.80.



## Multiple rating setting

Pr.	GROUP	Name
570	E301	Multiple rating setting

Four rating types of different rated current and permissible load can be selected. The optimal inverter rating can be chosen in accordance with the application, enabling equipment size to be reduced.

Pr.570 setting	Description
0 *1	SLD rating 110% 60 s, 120% 3 s (inverse-time characteristics) Surrounding air temperature 40°C
1	LD rating 120% 60 s, 150% 3 s (inverse-time characteristics) Surrounding air temperature 50°C
2 (initial value)	ND rating 150% 60 s, 200% 3 s (inverse-time characteristics) Surrounding air temperature 50°C
3 *1	HD rating 200% 60 s, 250% 3 s (inverse-time characteristics) Surrounding air temperature 50°C

\*1 Not compatible with the IP55 compatible model.

**Pr. 571** ➤ Refer to the page on Pr.13.

## Checking of current input on analog input terminal

Pr.	GROUP	Name	Pr.	GROUP	Name
573	A680 T052	4 mA input check selection	777	A681 T053	4 mA input check operation frequency
778	A682 T054	4 mA input check filter			

When current is input to the analog input terminal 2 and terminal 4, operation when the current input has gone below the specified level (loss of analog current input) can be selected. It is possible to continue the operation even when the analog current input is lost.

Pr.	Setting range	Description
547	1	Continues the operation with output frequency before the current input loss.
	2	When the current input loss is detected, 4 mA input fault (E.LCI) is activated.
	3	Decelerates to stop when the current input loss is detected. After it is stopped, 4 mA input fault (E.LCI) is activated.
	4	Continues operation with the Pr.777 setting.
	9999 (initial value)	No current input check
548	0 to 590 Hz	Set the running frequency for current input loss. (Valid when Pr.573 = "4")
	9999 (initial value)	No current input check when Pr.573 = "4"
778	0 to 10 s	Set the current input loss detection time.

**Pr. 574** ➤ Refer to the page on Pr.95.

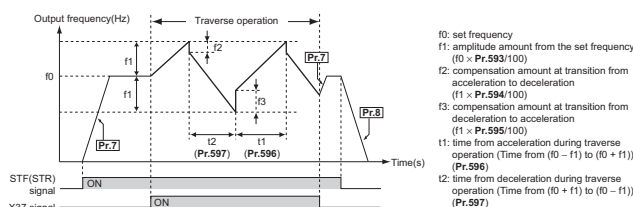
**Pr. 575 to 577** ➤ Refer to the page on Pr.127.

## Traverse function

Pr.	GROUP	Name	Pr.	GROUP	Name
592	A300	Traverse function selection	593	A301	Maximum amplitude amount
594	A302	Amplitude compensation amount during deceleration	595	A303	Amplitude compensation amount during acceleration
596	A304	Amplitude acceleration time	597	A305	Amplitude deceleration time

The traverse operation, which oscillates the frequency at a constant cycle, is available.

Pr.	Setting range	Description
592	0	Traverse function invalid
	1	Traverse function valid only in External operation mode
	2	Traverse function valid regardless of the operation mode
593	0 to 25%	Level of amplitude during traverse operation
594	0 to 50%	Compensation amount during amplitude inversion (from acceleration to deceleration)
595	0 to 50%	Compensation amount during amplitude inversion (from deceleration to acceleration)
596	0.1 to 3600 s	Time period of acceleration during traverse operation
597	0.1 to 3600 s	Time period of deceleration during traverse operation



## Varying the activation level of the undervoltage protective function

Pr.	GROUP	Name
598	H102	Undervoltage level

If the undervoltage protection (E.UVT) is activated due to unstable voltage in the power supply, the undervoltage level (DC bus voltage value) can be changed. (only available for 400 V class)

Pr. 598 setting	Description
350 to 430 VDC	Set the DC voltage value at which E.UVT occurs.
9999 (initial value)	E.UVT occurs at 430 VDC.

**Pr. 599** ➤ Refer to the page on Pr.30.

**Pr. 600 to 604** ➤ Refer to the page on Pr.9.

**Pr. 609, 610** ➤ Refer to the page on Pr.127.

**Pr. 611** ➤ Refer to the page on Pr.57.

**Pr. 639 to 648, 650, 651** ➤ Refer to the page on Pr.278.

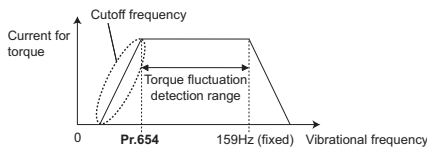


## Speed smoothing control V/F

Pr.	GROUP	Name	Pr.	GROUP	Name
653	G410	Speed smoothing control	654	G411	Speed smoothing cutoff frequency

The vibration (resonance) of the machine during motor operation can be suppressed.

- Set **Pr.653** to 100%, and check if the vibration is suppressed. If the vibration is not suppressed, raise the setting value of **Pr.653** gradually to minimize the vibration.
- When the vibrational frequency due to the mechanical resonance (fluctuation of torque, speed, and converter output voltage) is known using a tester and such, set 1/2 to 1 times of the vibrational frequency to **Pr.654**. (Setting vibrational frequency range can suppress the vibration better.)



## Analog remote output function

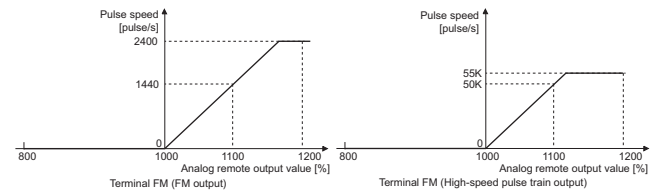
Pr.	GROUP	Name	Pr.	GROUP	Name
655	M530	Analog remote output selection	656	M531	Analog remote output 1
657	M532	Analog remote output 2	658	M533	Analog remote output 3
659	M534	Analog remote output 4			

An analog value can be output from the analog output terminal.

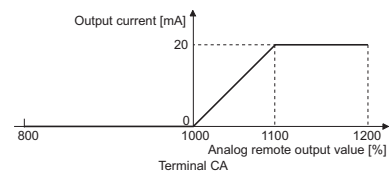
Pr. 655 setting	Description
0 (initial value)	Remote output data is cleared when the power supply is turned OFF. Remote output data is cleared during an inverter reset.
1	Remote output data is retained when the power supply is turned OFF. Remote output data is retained during an inverter reset.
10	Remote output data is cleared when the power supply is turned OFF. Remote output data is retained during an inverter reset.
11	Remote output data is retained when the power supply is turned OFF. Remote output data is retained during an inverter reset.

The terminals FM/CA, AM and the analog output terminal of the option FR-A8AY can output the values set in **Pr.656 to Pr.659** (Analog remote output).

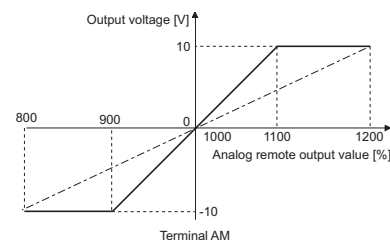
When **Pr.54 FM/CA terminal function selection** = "87, 88, 89, or 90" (remote output), the FM type inverter can output a pulse train from the terminal FM.



When **Pr.54 FM/CA terminal function selection** = "87, 88, 89, or 90" (remote output), the CA type inverter can output any analog current from the terminal CA.



When **Pr.158 AM terminal function selection** = "87, 88, 89, or 90", an analog voltage can be output from the terminal AM.







## Increased magnetic excitation deceleration

V/F Magnetic flux Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
660	G130	Increased magnetic excitation deceleration operation selection	661	G131	Magnetic excitation increase rate
662	G132	Increased magnetic excitation current level			

Increase the loss in the motor by increasing the magnetic flux at the time of deceleration. Deceleration time can be reduced by suppressing the stall prevention (overvoltage) (oL). It will make possible to reduce the deceleration time without a brake resistor. (Usage can be reduced if a brake resistor is used.)

Pr.	Setting range	Description
660	0 (initial value)	Without increased magnetic excitation deceleration
	1	With increased magnetic excitation deceleration
661	0 to 40%	Set the increase of magnetic excitation.
	9999 (initial value)	Magnetic excitation increase rate 10% under V/F control and Advanced magnetic flux vector control Magnetic excitation increase rate 0% under Real sensorless vector control and vector control
662	0 to 300%	The increased magnetic excitation rate is automatically lowered when the output current exceeds the setting value at the time of increased magnetic excitation deceleration.

- Setting of increased magnetic excitation rate (Pr.660, Pr.661)  
When the DC bus voltage exceeds the increased magnetic excitation deceleration operation level during the deceleration, excitation is increased in accordance with the setting value in Pr.661.

Inverter	Increased magnetic excitation deceleration operation level
200 V class	340 V
400 V class	680 V
With 500 V input	740 V

## Surrounding air temperature change monitoring

Pr.	GROUP	Name
663	M060	Control circuit temperature signal output level

Turn ON/OFF the control circuit temperature signal (Y207) according to the result of comparison between the Pr.663 setting and the monitored value of the control circuit temperature.

- Pr. 665 Refer to the page on Pr.882.
- Pr. 668 Refer to the page on Pr.261.

## SF-PR slip amount adjustment mode

V/F

Pr.	GROUP	Name	Pr.	GROUP	Name
673	G060	SF-PR slip amount adjustment operation selection	674	G061	SF-PR slip amount adjustment gain

As compared to our conventional SF-JR motor, the slip amount is small for the high-performance energy-saving SF-PR motor. When replacing the SF-JR to the SF-PR, the slip amount is reduced and the rotations per minute increases. Therefore, when the SF-PR is used with the same frequency setting as that of the SF-JR, power consumption may increase as compared to the SF-JR.

By setting the slip amount adjustment mode, the frequency command can be adjusted to keep the rotations per minute of the SF-PR equivalent to those of the SF-JR for power consumption reduction.

Pr.	Setting range	Description
673	2, 4, 6	Set the number of SF-PR motor poles.
	9999 (initial value)	Slip amount adjustment mode invalid
674	0 to 500%	Setting is available for fine adjustment of the slip amount. To reduce the rotations per minute, set a larger value. To increase the rotations per minute, set a smaller value.

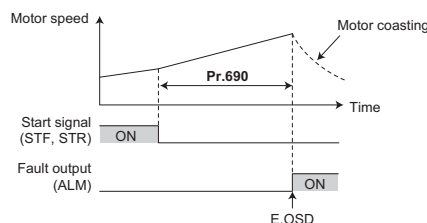
- Pr. 679 to 683 Refer to the page on Pr.286.
- Pr. 684 Refer to the page on Pr.82.
- Pr. 686 to 689 Refer to the page on Pr.503.

## Deceleration check Vector

Pr.	GROUP	Name
690	H881	Deceleration check time

When performing a deceleration stop on the motor, accidental acceleration can cause the inverter to trip. This can prevent a malfunction due to an incorrect encoder pulse setting, when the motor has stopped.

Pr. 690 setting	Description
0 to 3600 s	Set the time required to shut off output due to deceleration check after the start signal is OFF.
9999	No deceleration check



- Pr. 692 to 696 Refer to the page on Pr.9.
- Pr. 699 Refer to the page on Pr.178.
- Pr. 702, 706, 707, 711, 712, 717, 721, 724, , 725, 738 to 746 Refer to the page on Pr.82.
- Pr. 747 Refer to the page on Pr.788.
- Pr. 753 to 759 Refer to the page on Pr.127.

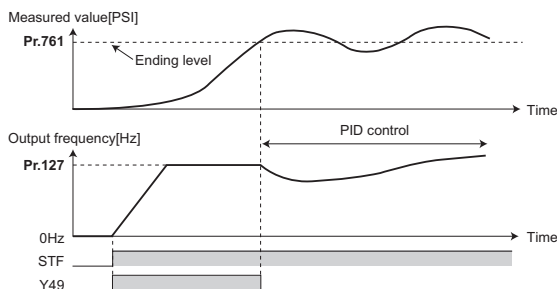
## PID pre-charge function

Pr.	GROUP	Name	Pr.	GROUP	Name
760	A616	Pre-charge fault selection	761	A617	Pre-charge ending level
762	A618	Pre-charge ending time	763	A619	Pre-charge upper detection level
764	A620	Pre-charge time limit	765	A656	Second pre-charge fault selection
766	A657	Second pre-charge ending level	767	A658	Second pre-charge ending time
768	A659	Second pre-charge upper detection level	769	A660	Second pre-charge time limit

This function is to drive the motor at a certain speed before starting PID control. This function is useful for a pump with a long hose. Without this function, PID control would start before the pump is filled with water, and proper control would not be performed.

Pr.	Setting range	Description
760	0 (initial value)	Fault indication with output shutoff immediately after a pre-charge fault occurs.
	1	Fault indication with deceleration stop after a pre-charge fault occurs.
761	0 to 100%	Set the measurement level to end the pre-charge operation.
	9999 (initial value)	Without pre-charge ending level
762	0 to 3600 s	Set the time to end the pre-charge operation.
	9999 (initial value)	Without pre-charge ending time
763	0 to 100%	Set the upper limit for the pre-charged amount. A pre-charge fault occurs when the measured value exceeds the setting during pre-charging.
	9999 (initial value)	Without pre-charge upper limit level
764	0 to 3600 s	Set the time limit for the pre-charge operation. A pre-charge fault occurs when the pre-charge time exceeds the setting.
	9999 (initial value)	Without pre-charge time limit

- Example of pre-charge operation  
When the measured amount reaches the pre-charge ending level (Pr.761 Pre-charge ending level ≠ "9999")The pre-charge operation ends when the measured value reaches the Pr.761 setting or higher, then the PID control is performed.



- Turning ON the RT signal enables the second pre-charge function.

Pr. 774 to 776 ➤ Refer to the page on Pr.52.

Pr. 779 ➤ Refer to the page on Pr.117.

## Low-speed range torque characteristics selection **PM**

Pr.	GROUP	Name	Pr.	GROUP	Name
788	G250	Low speed range torque characteristic selection	747	G350	Second motor low-speed range torque characteristic selection

The torque characteristics in a low-speed range under PM sensorless vector control can be changed.

Pr.	Setting range	Description
788	0	Disables the low-speed range torque characteristic (current synchronization operation).
	9999 (initial value) *1	Enables the low-speed range torque characteristic (high frequency superposition control)
747	0	Disables the low-speed range torque characteristic (current synchronization operation) while the RT signal is ON.
	9999 (initial value) *1	Enables the low-speed range torque characteristic (high frequency superposition control) while the RT signal is ON.

\*1 The low-speed range high-torque characteristic (current synchronization operation) is disabled for PM motors other than MM-CF, even if "9999" is set.

- Use Pr.747 to switch the torque characteristic according to the application or to switch among motors connected to one inverter.

Pr. 791, 792 ➤ Refer to the page on Pr.7.

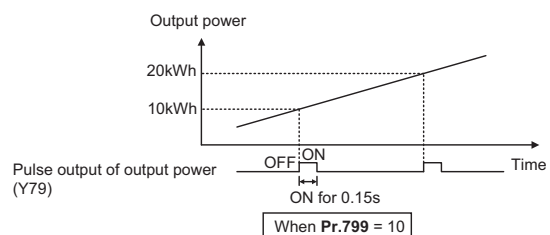
## Pulse train output of output power (Y79 signal)

Pr.	GROUP	Name
799	M520	Pulse increment setting for output power

After power ON or inverter reset, output signal (Y79 signal) is output in pulses every time accumulated output power, which is counted after the Pr.799 Pulse increment setting for output power is set, reaches the specified value (or its integral multiples).

Pr. 799 setting	Description
0.1kWh, 1kWh (initial value), 10kWh, 100kWh, 1000kWh	Pulse train output of output power (Y79) is output in pulses at every output power (kWh) that is specified.

- The inverter continues to count the output power at retry function or when automatic restart after instantaneous power failure function works without power OFF of output power (power failure that is too short to cause an inverter reset), and it does not reset the count.
- If power failure occurs, output power is counted from 0 kWh again.
- Assign pulse output of output power (Y79: setting value 79 (positive logic), 179 (negative logic)) to any of Pr.190 to Pr.196 (Output terminal function selection).



Pr. 800 ➤ Refer to the page on Pr.80.

Pr. 802 ➤ Refer to the page on Pr.10.

## Torque command source selection

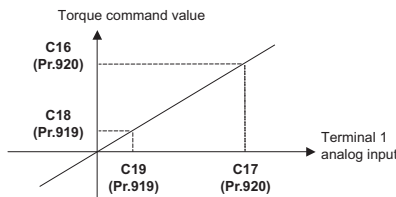
Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
803	G210	Constant output range torque characteristic selection	804	D400	Torque command source selection
805	D401	Torque command value (RAM)	806	D402	Torque command value (RAM, EEPROM)
1114	D403	Torque command reverse selection			

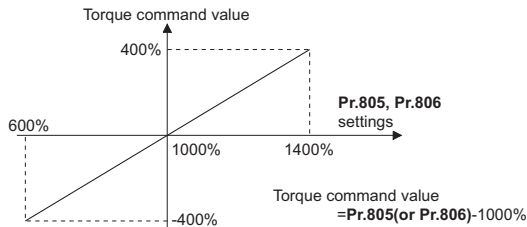
For torque control, the torque command source can be selected.

Pr.	Setting range	Description	
803	0 (initial value), 10	Constant motor output command	In the torque command setting, select torque command for the constant output area.
	1, 11	Constant torque command	
804	0 (initial value)	Torque command based on the analog input to the terminal 1	
	1	Torque command by the parameters Setting value of Pr.805 or Pr.806 (-400% to 400%)	
	3	Torque command via CC-Link communication (FR-A8NC/FR-A8NCE) For details, refer to the Instruction Manual of the FR-A8NC/FR-A8NCE (option).	
	4	Digital input from the option (FR-A8AX) For details, refer to the Instruction Manual of the FR-A8AX (option).	
	5, 6	Torque command via CC-Link communication (FR-A8NC/FR-A8NCE) For details, refer to the Instruction Manual of the FR-A8NC/FR-A8NCE (option).	
805	600 to 1400%	Torque command values can be set by setting Pr.805 (RAM) and Pr.806 (RAM, EEPROM). (Communication options can also be used for the setting.)	
806	600 to 1400%	In this case, set an appropriate value for the speed limit value to prevent overspeed.	

- Torque command based on the analog input to the terminal 1  
The following figure shows the torque command based on the analog input to the terminal 1 according to C16, C17 (Pr.919), C18, and C19 (Pr.920).



- Torque command by the parameters  
The following diagram shows relation between the Pr.805 or Pr.806 setting and the actual torque command value. The torque command is shown by offset from 1000% that is regarded as 0%.



- The Pr.1114 setting determines whether or not the torque command polarity is reversed when the reverse rotation command (STR) is turned ON.

Pr.1114 setting	Torque command polarity (sign) when the STR signal is ON
0	Not reversed
1 (initial value)	Reversed

## Speed limit under torque control

Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
807	H410	Speed limit selection	808	H411	Forward rotation speed limit/speed limit
809	H412	Reverse rotation speed limit/reverse-side speed limit	1113	H414	Speed limit method selection

When the inverter is operating under torque control, motor overspeeding may occur if the load torque drops to a value less than the torque command value. Set the speed limit value to prevent such overspeeding.

- The speed limit control method can be selected using Pr.1113.

Pr.807 setting	Speed limit control system	Speed limit
9999	Mode 1 (speed control by analog input)	Forward rotation speed limit Pr.807 = "0": Speed command under speed control Pr.807 = "1": Pr.808 setting value Pr.807 = "2": Analog input at 0 to 10 V input (to the terminal 1). Pr.1 setting value at -10 to 0 V input (to the terminal 1).  Reverse rotation speed limit Pr.807 = "0": Speed command under speed control Pr.807 = "1": Pr.809 setting value. If Pr.809 = "9999", the Pr.808 setting value applies. Pr.807 = "2": Analog input at 0 to 10 V input (to the terminal 1). Analog input at -10 to 0 V input (to the terminal 1).
0 (initial value)	Mode 2 (normal setting)	Speed limit Pr.807 = "0, 2": Speed command under speed control Pr.807 = "1": Pr.808 setting value  Inverted side speed limit Pr.809 setting value
1	Mode 3 (winding/unwinding by a positive torque command)	
2	Mode 4 (winding/unwinding by a negative torque command)	
10	Switchover by external terminals	X93 signal OFF: Speed limit by the speed limit mode 3 X93 signal ON: Speed limit by the speed limit mode 4

Pr.810 to 817 Refer to the page on Pr.22.

Pr.811 Refer to the page on Pr.37.

## Easy gain tuning selection

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
818	C112	Easy gain tuning response level setting	819	C113	Easy gain tuning selection

The load inertia ratio (load moment of inertia) for the motor is calculated in real time from the torque command and rotation speed during motor driving by the vector control. Gains for each control (**Pr.422**, **Pr.820**, **Pr.821**, and **Pr.828**) are set automatically from this load inertia ratio and the setting value for the response level (**Pr.818**). Under Real sensorless vector control or PM sensorless vector control, enter the load inertia ratio manually.

The work required for gain adjustment is reduced.

- Set the response level in **Pr.818** to calculate each gain from the load inertia ratio.
- The **Pr.819** setting enables/disables the easy gain tuning.

Pr.	Setting range	Description
818	1 to 15	1: Slow response ↓ 15: Fast response
819	0 (initial value)	No easy gain tuning
	1	Gain is calculated with load calculation. (This function is valid under vector control.)
	2	Gain is calculated with load ( <b>Pr.880</b> ) manual input.

## Proportional gain setting for speed loop

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
820	G211	Speed control P gain 1	830	G311	Speed control P gain 2
1116	G206	Constant output range speed control P gain compensation	1117	G261	Speed control P gain 1 (per-unit system)
1118	G361	Speed control P gain 2 (per-unit system)	1121	G260	Per-unit speed control reference frequency

Set the proportional gain for speed loop. (Setting this parameter higher improves the speed response and reduces the speed fluctuation caused by external disturbance. However, too large setting causes vibration or noise.)

- The setting range of **Pr.820 Speed control P gain 1** and **Pr.830 Speed control P gain 2** is 0 to 1000%. The initial value of **Pr.820** is 60%.
- A speed loop proportional gain can be set in the per-unit system using **Pr.1117**, **Pr.1118**, and **Pr.1121**.
- As the speed control response level is decreased in the constant output range (at the rated speed or more) due to the weak field magnet, the speed control P gain is compensated in **Pr.1116**.

## Integral time setting for speed control

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
821	G212	Speed control integral time 1	831	G312	Speed control integral time 2
1115	G218	Speed control integral term clear time			

Set the integral compensation time for speed loop.

Setting this parameter lower shortens the return time to the original speed when the speed fluctuates due to external disturbance.

However, too small setting causes overshoot.

Setting this parameter higher improves the level of safety. However, large setting prolongs the return time (response time) and may cause undershoot. Turning the X44 signal ON stops the speed loop integral calculation and clears the integral term in accordance with the **Pr.1115** setting.

**Pr.822** ➤ Refer to the page on Pr.74.

## Speed detection filter function

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
823	G215	Speed detection filter 1	833	G315	Speed detection filter 2

Set the time constant of primary delay filter for speed feedback signal.

Speed loop response is reduced. Under ordinary circumstances, therefore, use the initial value as it is.

If there is speed ripple due to high frequency disturbance, set a time constant.

Speed is oppositely destabilized if the setting value is too large.

## Proportional gain setting for current loop

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
824	G213	Torque control P gain 1 (current loop proportional gain)	834	G313	Torque control P gain 2

Set the proportional gain under torque control.

If the setting value is large, changes in the current command can be followed well and current fluctuation relative to external disturbance is smaller. If the setting value is however too large, it becomes unstable and high frequency torque pulse is produced.

The setting range of **Pr.824 Torque control P gain 1 (current loop proportional gain)** and **Pr.834 Torque control P gain 2** is 0 to 500%. The initial value of **Pr.824** is 100%.

For ordinary adjustment, try to set within the range of 50 to 200%.

## Current control integral time setting

Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
825	G214	Torque control integral time 1 (current loop integral time)	835	G314	Torque control integral time 2

Set the current loop integral compensation time under torque control.

Setting this parameter smaller increases torque response. However, too small setting may destabilize current.

If the setting value is small, it produces current fluctuation toward disturbance, decreasing time until it returns to the original current value.

**Pr.826** ➤ Refer to the page on Pr.74.

## Torque detection filter function

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
827	G216	Torque detection filter 1	837	G316	Torque detection filter 2

Set the time constant of primary delay filter for torque feedback signal.

Current loop response is reduced. Under ordinary circumstances, therefore, use the initial value as it is.





## Speed feed forward control and model adaptive speed control

Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
828	G224	Model speed control gain	877	G220	Speed feed forward control/model adaptive speed control selection
878	G221	Speed feed forward filter	879	G222	Speed feed forward torque limit
880	C114	Load inertia ratio	881	G223	Speed feed forward gain
1119	G262	Model speed control gain (per-unit system)	1121	G260	Per-unit speed control reference frequency

Speed feed forward control or model adaptive speed control can be selected using parameter settings.

Under speed feed forward control, the motor trackability for speed command changes can be improved.

Under model adaptive speed control, the speed trackability and the response level to motor external disturbance torque can be adjusted individually.

Pr. 877 setting	Description
0 (initial value)	Perform normal speed control.
1	Perform speed feed forward control.
2	Model adaptive speed control becomes valid.

- **Speed feed forward control**  
When the load inertia ratio is set in **Pr.880**, the required torque for the set inertia is calculated according to the acceleration and deceleration commands, and the torque is generated quickly. When the inertia ratio is to be estimated by easy gain tuning, the estimated inertia ratio is stored as the setting value of **Pr.880**. The speed feed forward is calculated based on this setting value. When the speed feed forward gain is 100%, the calculation result for speed feed forward is applied as is. If the speed command changes suddenly, the torque is increased by the speed feed forward calculation. The maximum limit for the speed feed forward torque is set in **Pr.879**. The speed feed forward result can also be lessened with a primary delay filter in **Pr.878**.
- **Model adaptive speed control**  
The model speed of the motor is calculated, and the feedback is applied to the speed controller on the model side. Also, this model speed is set as the command of the actual speed controller. The inertia ratio of **Pr.880** is used when the speed controller on the model side calculates the torque current command value. When the inertia ratio is to be estimated by easy gain tuning, the setting value of **Pr.880** is overwritten by the estimated inertia ratio. The torque current command value is calculated based on this setting value. The torque current command of the speed controller on the model side is added to the output of the actual speed controller, and set as the input of the iq current control. **Pr.828** is used for the speed control on the model side (P control), and first gain **Pr.820** is used for the actual speed controller. The model adaptive speed control is enabled for the first motor. Even if the driven motor is switched to the second motor while **Pr.877** = "2", the second motor is operated as **Pr.877** = "0".
- The model adaptive speed control gain can be set in the per-unit system using **Pr.1119** and **Pr.1121**.

- Pr.** 830 ➤ Refer to the page on Pr.820.
- Pr.** 831 ➤ Refer to the page on Pr.821.
- Pr.** 832 ➤ Refer to the page on Pr.74.
- Pr.** 833 ➤ Refer to the page on Pr.823.
- Pr.** 834 ➤ Refer to the page on Pr.824.
- Pr.** 835 ➤ Refer to the page on Pr.825.
- Pr.** 836 ➤ Refer to the page on Pr.74.
- Pr.** 837 ➤ Refer to the page on Pr.827.

## Torque bias Sensorless Vector

Pr.	GROUP	Name	Pr.	GROUP	Name
840	G230	Torque bias selection	841	G231	Torque bias 1
842	G232	Torque bias 2	843	G233	Torque bias 3
844	G234	Torque bias filter	845	G235	Torque bias operation time
846	G236	Torque bias balance compensation	847	G237	Fall-time torque bias terminal 1 bias
848	G238	Fall-time torque bias terminal 1 gain			

The torque bias function can be used to make the starting torque start-up faster. At this time, the motor starting torque can be adjusted with a contact signal or analog signal.

Pr. 840 setting	Description
0	Set the torque bias amount using contact signals (X42, X43) in <b>Pr.841</b> to <b>Pr.843</b> .
1	Set the torque bias amount using terminal 1 in any of <b>C16</b> to <b>C19</b> . (When the squirrel cage rises during forward motor rotation.)
2	Set the torque bias amount using terminal 1 in any of <b>C16</b> to <b>C19</b> . (When the squirrel cage rises during reverse motor rotation.)
3	The torque bias amount using terminal 1 can be set automatically in <b>C16</b> to <b>C19</b> and <b>Pr.846</b> according to the load.
24	For details of the torque bias command via PROFIBUS communication (FR-A8NP), refer to the Instruction Manual of the FR-A8NP (option).
25	
9999 (initial value)	No torque bias, rated torque 100%

- **Pr.841 Torque bias 1, Pr.842 Torque bias 2, and Pr.843 Torque bias 3**  
The rated torque of 100% equals to the torque bias setting value of 1000%, which is the central value of the torque. When the setting value is 1000%, the bias value is "0".
- **Pr.844 Torque bias filter**  
The torque start-up can be made slower. The torque start-up operation at this time is the time constant of the primary delay filter.
- **Pr.845 Torque bias operation time**  
Set the time for continuing the output torque simply by using the command value for the torque bias.
- **Pr.846 Torque bias balance compensation**  
Set the voltage of the torque bias analog input value that is input to terminal 1 to compensate the balance of the torque bias amount.
- **Pr.847 Fall-time torque bias terminal 1 bias, Pr.848 Fall-time torque bias terminal 1 gain**  
Set the torque bias amount of when the cage is descended.

- Pr.** 849 ➤ Refer to the page on Pr.74.
- Pr.** 850 ➤ Refer to the page on Pr.10.
- Pr.** 851, 852 ➤ Refer to the page on Pr.359.
- Pr.** 853 ➤ Refer to the page on Pr.285.



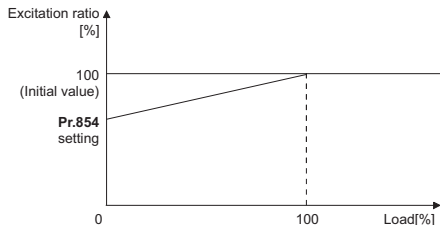


## Excitation ratio Sensorless Vector

Pr.	GROUP	Name
854	G217	Excitation ratio

The excitation ratio can be lowered to enhance efficiency for light loads. (Motor magnetic noise can be reduced.)

When excitation ratio is reduced, output torque startup is less responsive.



**Pr. 855** ➔ Refer to the page on Pr.376.

## Analog input terminal (terminal 1, 4) function assignment

Pr.	GROUP	Name	Pr.	GROUP	Name
858	T040	Terminal 4 function assignment	868	T010	Terminal 1 function assignment

The analog input terminal 1 and terminal 4 functions are set and changeable with parameters.

Pr.	Setting range	V/F control, Advanced magnetic flux vector control	Real sensorless vector control, PM sensorless vector control, vector control		
			Speed control	Torque control	Position control
868	0 (initial value)	Frequency setting auxiliary	Speed setting auxiliary	Speed limit assistance	-
	1	-	Magnetic flux command +1	Magnetic flux command +1	Magnetic flux command +1
	2	-	Regenerative driving torque limit (Pr.810 = 1)	-	Regenerative driving torque limit (Pr.810 = 1)
	3	-	-	Torque command (Pr.804 = 0)	-
	4	Stall prevention operation level input	Torque limit (Pr.810 = 1)	Torque command (Pr.804 = 0)	Torque limit (Pr.810 = 1)
	5	-	-	Forward/reverse rotation speed limit (Pr.807 = 2)	-
	6	-	Torque bias input (Pr.840 = 1, 2, 3)	-	-
9999	-	-	-	-	
858	0 (initial value)	Frequency command (AU signal-ON)	Speed command (AU signal-ON)	Speed limit (AU signal-ON)	-
	1	-	Magnetic flux command +1	Magnetic flux command +1	Magnetic flux command +1
	4	Stall prevention operation level input	Torque limit (Pr.810 = 1)	-	Torque limit (Pr.810 = 1)
	9999	-	-	-	-

\*1 This function is valid under vector control.

-: No function

**Pr. 859, 860** ➔ Refer to the page on Pr.82.

**Pr. 862** ➔ Refer to the page on Pr.80.

## Encoder pulse dividing output Vector

Pr.	GROUP	Name
863	M600	Control terminal option-Encoder pulse division ratio

With the FR-A8TP, the encoder pulse signal at the motor end can be divided in division ratio set in **Pr.863** and output.

Use this parameter to make the response of the machine to be input slower, etc.

## Output torque detection

Magnetic flux Sensorless Vector PM

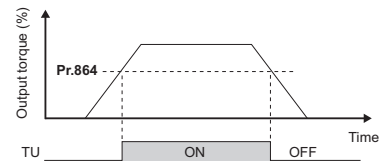
Pr.	GROUP	Name
864	M470	Torque detection

A signal is output when the motor torque is higher than the setting of **Pr.864**.

This function can be used for electromagnetic brake operation, open signal, etc.

The Torque detection (TU) signal turns ON when the output torque reaches the detection torque value set in **Pr.864** or higher.

The Torque detection (TU) signal turns OFF when the output torque drops lower than the detection torque value.



**Pr. 865** ➔ Refer to the page on Pr.41.

**Pr. 866** ➔ Refer to the page on Pr.55.

**Pr. 867** ➔ Refer to the page on Pr.C0(900).

**Pr. 868** ➔ Refer to the page on Pr.858.

**Pr. 869** ➔ Refer to the page on Pr.C0(900).

**Pr. 870** ➔ Refer to the page on Pr.41.

**Pr. 872** ➔ Refer to the page on Pr.251.

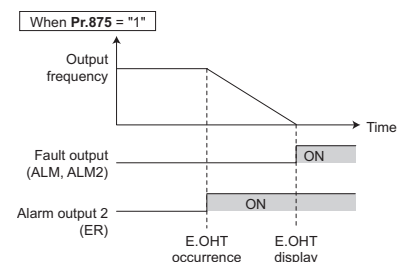
**Pr. 873** ➔ Refer to the page on Pr.285.

**Pr. 874** ➔ Refer to the page on Pr.22.

## Fault definition

Pr.	GROUP	Name
875	H030	Fault definition

Fault output can be done after deceleration stop when motor thermal protection is activated.



Pr.875 setting	Operation	Description
0 (initial value)	Normal operation	The output of the inverter is shut off immediately if any fault occurs. At this time, the alarm output 2 signal (ER) and a fault signal are output.
1	Fault definition	At activation of the external thermal relay (E.OHT), motor load (electronic thermal O/L relay) (E.THM) and PTC thermistor (PTC) protective functions, the alarm output 2 (ER) signal is displayed, and the motor decelerates to stop. After it stops, a fault signal is output. During fault occurrence aside from the E.OHT, E.THM and E.PTC, the output is immediately shut off, and the fault is outputted. Under position control, the operation of the setting value "0" is applied.

**Pr.876** ➤ Refer to the page on Pr.9.

**Pr.877 to 881** ➤ Refer to the page on Pr.828.

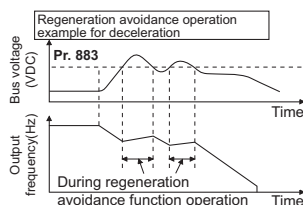
## Regeneration avoidance function

Pr.	GROUP	Name	Pr.	GROUP	Name
882	G120	Regeneration avoidance operation selection	883	G121	Regeneration avoidance operation level
884	G122	Regeneration avoidance at deceleration detection sensitivity	885	G123	Regeneration avoidance compensation frequency limit value
886	G124	Regeneration avoidance voltage gain	665	G125	Regeneration avoidance frequency gain

The regenerative status can be avoided by detecting the regenerative status and raising the frequency.

- Continuous operation is possible by increasing the frequency automatically so it will not go into regenerative operation even when the fan is turned forcefully by other fans in the same duct.

Pr.	Setting range	Description
882	0 (initial value)	Disables regeneration avoidance function
	1	Constantly enables regeneration avoidance function
	2	Enables regeneration avoidance function only during constant-speed operation
883	300 to 800 V	Set the bus voltage level to operate the regeneration avoidance operation. When the bus voltage level is set low, it will be harder to generate overvoltage error, but actual deceleration time will be longer. Set the setting value higher than power supply voltage $\times \sqrt{2}$ .
884	0 (initial value)	Disables regeneration avoidance due to bus voltage change rate
	1 to 5	Set the sensitivity to detect the bus voltage change rate. Setting value 1 $\rightarrow$ 5 Detection sensitivity Low $\rightarrow$ High
885	0 to 590 Hz	Set the limit value for frequency to rise when the regeneration avoidance function operates.
	9999	Disables frequency limit
886	0 to 200%	Adjust the response at the time of regeneration avoidance operation. When the setting value is set larger, response against the bus voltage change will improve, but the output frequency may become unstable. If the load inertia of the motor is large, set the setting value of Pr.886 smaller.
665	0 to 200%	When the vibration cannot be stabilized even if the setting value of Pr.886 is made smaller, set the setting value of Pr.665 smaller.



## Free parameter

Pr.	GROUP	Name	Pr.	GROUP	Name
888	E420	Free parameter 1	889	E421	Free parameter 2

These parameters can be used for any purpose.

Any number within the setting range of 0 to 9999 can be input.

For example, these numbers can be used:

- As a unit number when multiple units are used.
- As a pattern number for each operation application when multiple units are used.
- As the year and month of introduction or inspection.

## Energy saving monitor

Pr.	GROUP	Name	Pr.	GROUP	Name
891	M023	Cumulative power monitor digit shifted times	892	M200	Load factor
893	M201	Energy saving monitor reference (motor capacity)	894	M202	Control selection during commercial power-supply operation
895	M203	Power saving rate reference value	896	M204	Power unit cost
897	M205	Power saving monitor average time	898	M206	Power saving cumulative monitor clear
899	M207	Operation time rate (estimated value)	52	M100	Operation panel main monitor selection
54	M300	FM/CA terminal function selection	158	M301	AM terminal function selection
774	M101	Operation panel monitor selection 1	775	M102	Operation panel monitor selection 2
776	M103	Operation panel monitor selection 3	992	M104	Operation panel setting dial push monitor selection

From the power consumption estimated value during commercial power supply operation, the energy saving effect by use of the inverter can be monitored and output.

- The items that can be monitored on the power saving monitor (Pr.52, Pr.54, Pr.158, Pr.774 to Pr.776, Pr.992 = "50") are indicated below.

(Only Power saving and Average power saving can be set to Pr.54 (terminal FM, terminal CA) and Pr.158 (terminal AM).)

Energy saving monitored item	Description and formula	Increment
Power saving	The difference between the estimated value of the required power during commercial power supply operation and the input power calculated with the inverter. Power supply during commercial power supply operation - input power monitor	0.01 kW /0.1 kW *1
Power saving rate	The power saving ratio with the commercial power supply operation as 100%. $\frac{\text{Power saving}}{\text{Power during commercial power supply operation}} \times 100$ The power saving ratio with Pr.893 as 100%. $\frac{\text{Power saving}}{\text{Pr.893}} \times 100$	0.1%
Average power saving	The average power saving per hour during a predetermined time (Pr.897). $\frac{\Sigma (\text{Power saving} \times \Delta t)}{\text{Pr.897}}$	0.01 kWh /0.1 kWh *1
Average power saving rate	The average power saving ratio with the commercial power supply operation as 100%. $\frac{\Sigma (\text{Power saving rate} \times \Delta t)}{\text{Pr.897}} \times 100$ The average power saving ratio with Pr.893 as 100%. $\frac{\text{Average power saving}}{\text{Pr.893}} \times 100$	0.1%
Average power cost savings	The average power saving in terms of cost. Average power saving $\times$ Pr.896	0.01/0.1 *1

- The items that can be monitored on the cumulative energy saving monitor (Pr.52, Pr.774 to Pr.776, Pr.992 = "51") are indicated below. (The monitor value of the cumulative monitor can be shifted to the right with Pr.891 Cumulative power monitor digit shifted times.)

Energy saving monitored item	Description and formula	Increment
<b>Power saving amount</b>	The cumulative power saving is added up per hour. $\Sigma (\text{Power saving rate} \times \Delta t)$	0.01 kWh *1 0.1 kWh *2
<b>Power cost saving</b>	The power saving amount in terms of cost. Power saving $\times$ Pr.896	0.01 *1 0.1 *2
<b>Annual power saving amount</b>	Estimated value of annual power saving amount. $\frac{\text{Power saving amount}}{\text{Operation time during power saving accumulation}} \times 24 \times 365 \times \frac{\text{Pr.899}}{100}$	0.01 kWh *1 0.1 kWh *2
<b>Annual power cost savings</b>	Annual power saving amount in terms of cost. Annual power saving amount $\times$ Pr.896	0.01 *1 0.1 *2

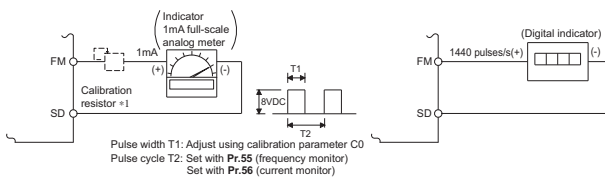
- \*1 Increment for the FR-A820-03160(55K) or lower and the FR-A840-01800(55K) or lower
- \*2 Increment for the FR-A820-03800(75K) or higher and the FR-A840-02160(75K) or higher

## Adjusting terminal FM/CA and terminal AM (calibration)

Pr.	GROUP	Name	Pr.	GROUP	Name
C0 (900)	M310	FM terminal calibration	C1 (901)	M320	AM terminal calibration
C8 (930)	M330	Current output bias signal	C9 (930)	M331	Current output bias current
C10 (931)	M332	Current output gain signal	C11 (931)	M333	Current output gain current
867	M321	AM output filter	869	M334	Current output filter

By using the operation panel or parameter unit, terminals FM, CA and AM can be calibrated to the full scale.

- Terminal FM calibration (C0 (Pr.900))  
The terminal FM is preset to output pulses. By setting the calibration parameter C0 (Pr.900), the meter connected to the inverter can be calibrated by parameter setting without use of a calibration resistor.  
Using the pulse train output of the terminal FM, a digital display can be provided to connect a digital counter. The monitor value is 1440 pulses/s output at the full-scale value of Pr.54 FM/CA terminal function selection.



- \*1 Not needed when the operation panel (FR-DU08) or parameter unit (FR-PU07) is used for calibration. Use a calibration resistor when the indicator (frequency meter) needs to be calibrated by a neighboring device because the indicator is located far from the inverter. However, the frequency meter needle may not deflect to full-scale if the calibration resistor is connected. In this case, calibrate additionally with the operation panel or parameter unit.

Calibration with Pr.900 cannot be done when the terminal FM is set to open collector output with Pr.291 Pulse train I/O selection.

- Calibration of terminal AM (C1 (Pr.901))  
Terminal AM is initially set to provide a 10 VDC output in the full-scale state of the corresponding monitor item. Calibration parameter C1 (Pr.901) allows the output voltage ratio (gains) to be adjusted according to the meter scale. Note that the maximum output voltage is 10 VDC.
- Using Pr.867, the output voltage response of the terminal AM can be adjusted in the range of 0 to 5 s.
- Terminal CA calibration (C0 (Pr.900), C8 (Pr.930) to C11 (Pr.931))  
Terminal CA is initially set to provide a 20 mADC output in the full-scale state of the corresponding monitor item. Calibration parameter C0 (Pr.900) allows the output current ratio (gains) to be adjusted according to the meter scale. Note that the maximum output current is 20 mA DC.

- Set a value at the minimum current output in the calibration parameters C8 (Pr.930) and C9 (Pr.930). Calibration parameter C10 (Pr.931) and C11 (Pr.931) are used to set a value at the maximum current output.
- Using Pr.869, the output current response of the terminal CA can be adjusted in the range of 0 to 5 s.

Pr. C2 (902) to C7 (905), C12 (917) to C19 (920), C38 (932) to C41 (933)

Refer to the page on Pr.125.

Pr. C8 (930) to C11 (931) Refer to the page on Pr.C0 (900).

Pr. C42 (934) to C45 (935) Refer to the page on Pr.127.

## Using the power supply exceeding 480 V

Pr.	GROUP	Name
977	E302	Input voltage mode selection

To input a voltage between 480 V and 500 V to the 400 V class inverter, change the voltage protection level.

Pr. 977 setting	Description
0 (initial value)	400 V class voltage protection level
1	500 V class voltage protection level

## Parameter clear, parameter copy, and initial value change list

Pr.	GROUP	Name	Pr.	GROUP	Name
989	E490	Parameter copy alarm release	Pr.CLR		Parameter clear
ALL.CL		All parameter clear	Err.CL		Fault history clear
Pr.CPY		Parameter copy	Pr.CHG		Initial value change list

- Set Pr.CLR Parameter clear = "1" to initialize all parameters. (Calibration parameters are not cleared.)\*1
- Set ALL.CL All parameter clear = "1" to initialize all parameters.\*1
- Set Err.CL Fault history clear = "1" to clear the faults history.
- Use Pr.CPY to copy the parameter setting to multiple inverters.

Pr. CPY setting	Description
0.---	Cancel
1.RD	Copy the source parameters to the operation panel.
2.WR	Write the parameters copied to the operation panel to the destination inverter.
3.VFY	Verify parameters in the inverter and operation panel.

If the parameter setting is copied from the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower to the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher, or from the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher to the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower, the warning appears on the operation panel. After setting the parameters that have the different setting range, set Pr.989 as follows.

Pr. 989 setting	Operation
10	Cancel the warning of FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower.
100	Cancel the warning of FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher.

To display only the numbers of the parameters that have been changed from their initial values, use Pr.CHG Initial value change list.

- \*1 If Pr.77 Parameter write selection = "1", the parameter setting is not cleared.

## Buzzer control of the operation panel

Pr.	GROUP	Name
990	E104	PU buzzer control

The buzzer can be set to "beep" when the keys of the operation panel (FR-DU08) and parameter unit (FR-PU07) are operated.

Pr.990 setting	Description
0	Without buzzer
1 (initial value)	With buzzer

## PU contrast adjustment

Pr.	GROUP	Name
991	E105	PU contrast adjustment

Contrast adjustment of the LCD of the LCD operation panel (FR-LU08) and the parameter unit (FR-PU07) can be performed. Decreasing the setting value makes the contrast lighter.

Pr. 991 setting	Description
0 to 63	0: Light ↓ 63: Dark

**Pr.992** ➤ Refer to the page on Pr.52.

**Pr.997, 998** ➤ Refer to the page on Pr.286.

## Fault initiation function

Pr.	GROUP	Name
997	H103	Fault initiation

A fault (protective function) is initiated by setting the parameter. This function can be used to check how the system operates at activation of a protective function. The read value is always "9999". Even if "9999" is set, the protective function is not activated.

- Faults that can be written with **Pr.997 Fault initiation**

Pr.997 setting	Fault	Pr.997 setting	Fault	Pr.997 setting	Fault
16	E.OC1	165	E.17	214	E.MB2
17	E.OC2	165	E.18	215	E.MB3
18	E.OC3	165	E.19	216	E.MB4
32	E.OV1	165	E.20	217	E.MB5
33	E.OV2	176	E.PE	218	E.MB6
34	E.OV3	177	E.PUE	219	E.MB7
48	E.THT	178	E.RET	220	E.EP
49	E.THM	179	E.PE2	222	E.MP
64	E.FIN	192	E.CPU	225	E.IAH-1
80	E.IPF	193	E.CTE	228	E.LCI
81	E.UVT	194	E.P24	229	E.PCH
82	E.ILF	196	E.CDO	230	E.PID
96	E.OLT	197	E.IOH	241	E.1
97	E.SOT	198	E.SER	242	E.2
112	E.BE	199	E.AIE	243	E.3
128	E.GF	200	E.USB	245	E.5
129	E.LF	201	E.SAF	246	E.6
144	E.OHT	208	E.OS	247	E.7
145	E.PTC	209	E.OSD	251	E.11
160	E.OPT	210	E.ECT	253	E.13
161	E.OP1	211	E.OD		
164	E.16	213	E.MB1		

\*1 IP55 compatible models only.

**Pr.998 and IPM** ➤ Refer to the page 196.

## Automatic parameter setting

Pr.	GROUP	Name	Pr.	GROUP	Name
999	E431	Automatic parameter setting	AUTO		Automatic parameter setting

Parameter settings are changed as a batch. Those include communication parameter settings for the Mitsubishi's human machine interface (GOT) connection and the parameter setting for the rated frequency settings of 50 Hz/60 Hz.

Multiple parameters are changed automatically. Users do not have to consider each parameter number. (Automatic parameter setting mode)

Pr.999 setting	Description	Operation in the automatic parameter setting mode (AUTO)
9999 (initial value)	No action	-
1	Sets the standard monitor indicator setting of PID control.	"AUTO" → "PID" → Write "1"
2	Automatically sets the monitor indicator for PID control.	"AUTO" → "PID" → Write "2"
10	Automatically sets the communication parameters for the GOT connection with a PU connector ("Controller Type" in GOT: FREQROL 500/700/800, SENSORLESS SERVO)	"AUTO" → "GOT" → Write "1"
11	Automatically sets the communication parameters for the GOT connection with RS-485 terminals ("Controller Type" in GOT: FREQROL 500/700/800, SENSORLESS SERVO)	-
12	Automatically sets the communication parameters for the GOT connection with a PU connector ("Controller Type" in GOT: FREQROL 800(Automatic Negotiation))	"AUTO" → "GOT" → Write "2"
13	Automatically sets the communication parameters for the GOT connection with RS-485 terminals ("Controller Type" in GOT: FREQROL 800(Automatic Negotiation))	-
20	50 Hz rated frequency	Sets the related parameters of the rated frequency according to the power supply frequency "AUTO" → "F50" → Write "1"
21	60 Hz rated frequency	-

**Pr.1002** ➤ Refer to the page on Pr.82.

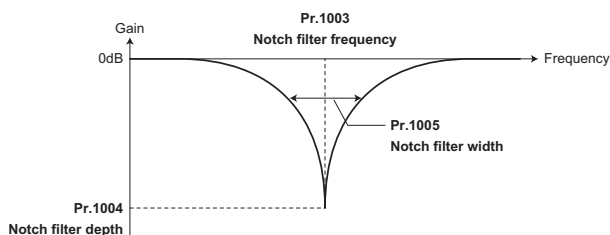


## Notch filter Sensorless Vector PM

Pr.	GROUP	Name	Pr.	GROUP	Name
1003	G601	Notch filter frequency	1004	G602	Notch filter depth
1005	G603	Notch filter width			

The response level of speed control in the resonance frequency band of mechanical systems can be lowered to avoid mechanical resonance.

Pr.	Setting range	Description
1003	0 (initial value)	No notch filter
	8 to 1250 Hz	Set the frequency for the center of gain attenuation.
1004	0 to 3	0 (Deep) → 3 (Shallow)
1005	0 to 3	0 (Narrow) → 3 (Wide)



## Simple clock function

Pr.	GROUP	Name	Pr.	GROUP	Name
1006	E020	Clock (year)	1007	E021	Clock (month, day)
1008	E022	Clock (hour, minute)			

The time can be set. The time can only be updated while the inverter power is ON.

Pr.	Description
1006	Set the year (A.D.). Initial value: 2000
1007	Set the month and day. 1000 and 100 digits: January to December 10 and 1 digits: 1 to end of month (28, 29, 30 or 31) For December 31, set "1231". Initial value: 101 (January 1)
1008	Set the hour and minute using the 24-hour clock. 1000 and 100 digits: 0 to 23 hours 10 and 1 digits: 0 to 59 minutes For 23:59, set "2359". Initial value: 0 (00:00)

- When the year, month, day, time and minute are set in the parameters, the inverter counts the date and time. The date and time can be checked by reading the parameters.
- Because the date and time are cleared after turning OFF the control circuit power supply, the clock function must be reset after turning ON the power supply. Use a separate power supply, such as an external 24 V power supply, for the control circuit of the simple clock function, and supply power continuously to this control circuit.
- By using the real-time clock function with the FR-LU08, it is not necessary to set the time again even when the power supply is turned OFF.
- The set clock is also used for functions such as faults history.

**Pr. 1018** Refer to the page on Pr.52.

## Trace function

Pr.	GROUP	Name	Pr.	GROUP	Name
1020	A900	Trace operation selection	1021	A901	Trace mode selection
1022	A902	Sampling cycle	1023	A903	Number of analog channels
1024	A904	Sampling auto start	1025	A905	Trigger mode selection
1026	A906	Number of sampling before trigger	1027	A910	Analog source selection (1ch)
1028	A911	Analog source selection (2ch)	1029	A912	Analog source selection (3ch)
1030	A913	Analog source selection (4ch)	1031	A914	Analog source selection (5ch)
1032	A915	Analog source selection (6ch)	1033	A916	Analog source selection (7ch)
1034	A917	Analog source selection (8ch)	1035	A918	Analog trigger channel
1036	A919	Analog trigger operation selection	1037	A920	Analog trigger level
1038	A930	Digital source selection (1ch)	1039	A931	Digital source selection (2ch)
1040	A932	Digital source selection (3ch)	1041	A933	Digital source selection (4ch)
1042	A934	Digital source selection (5ch)	1043	A935	Digital source selection (6ch)
1044	A936	Digital source selection (7ch)	1045	A937	Digital source selection (8ch)
1046	A938	Digital trigger channel	1047	A939	Digital trigger operation selection

The operating status of the inverter can be traced and saved on a USB memory device.

Saved data can be monitored by FR Configurator2, and the status of the inverter can be analyzed.

- This function samples the status (analog monitor and digital monitor) of the inverter, traces the sampling data when a trigger (trace start condition) is generated, and saves the resulting trace data.
- Start of sampling and copying of data (**Pr.1020**, **Pr.1024**)  
Set the trace operation. The trace operation is set by one of two ways, by setting **Pr.1020 Trace operation selection** and by setting in the trace mode on the operation panel.  
To automatically start sampling when the power supply is turned ON or at a recovery after an inverter reset, set "1" to **Pr.1024 Sampling auto start**.

Pr. 1020 setting	Setting by trace mode	Operation
0 (initial value)	0----	Sampling standby
1	IRUN	Sampling start
2	2TRG	Forced trigger (sampling stop)
3	3END	Sampling stop
4	4CPY	Data transmission

## Turning OFF the operation panel display

Pr.	GROUP	Name
1048	E106	Display-off waiting time

Monitor indicators can be turned OFF while the operation panel (FR-DU08) is not used.

Pr. 1048 setting	Description
0 (initial value)	The display is always ON.
1 to 60 min	Set the waiting time to turn off the monitor display after the operation panel becomes idle.



## Resetting USB host errors

Pr.	GROUP	Name
1049	E110	USB host reset

When a USB device is connected to the USB connector (connector A), the USB host error can be canceled without performing an inverter reset.

Pr. 1049 setting	Description
0 (initial value)	Read only
1	Resets the USB host.

## Anti-sway control

Pr.	GROUP	Name	Pr.	GROUP	Name
1072	A310	DC brake judgment time for anti-sway control operation	1073	A311	Anti-sway control operation selection
1074	A312	Anti-sway control frequency	1075	A313	Anti-sway control depth
1076	A314	Anti-sway control width	1077	A315	Rope length
1078	A316	Trolley weight	1079	A317	Load weight

Swinging of crane-lifted load is suppressed on the crane running axis.

Pr.	Setting range	Description
1072	0 to 10 s	Set the waiting time to start the DC injection brake (zero speed control, servo lock) after the output frequency reaches the Pr.10 DC injection brake operation frequency or lower.
1073	0 (initial value)	Anti-sway control disabled
	10 to 1250 Hz	Anti-sway control enabled
1074	0.05 to 2 Hz	Sets the vibration frequency of the load.
	9999	A vibration frequency is estimated based on the Pr.1077 to Pr.1079 settings, and anti-sway control is performed.
1075	0 to 3	0 (Deep) → 3 (Shallow)
1076	0 to 3	0 (Narrow) → 3 (Wide)
1077	0.1 to 50 m	Set the rope length of the crane.
1078	1 to 50000 kg	Set the weight of the trolley.
1079	1 to 50000 kg	Set the weight of the load.

## Emergency stop function

Pr.	GROUP	Name
1103	F040	Deceleration time at emergency stop

At a failure in the host controller, the motor can be decelerated to a stop using an input via an external terminal.

At turn-ON of the emergency stop signal (X92), the motor is decelerated in the deceleration time of Pr.1103 in accordance with the torque limit set in Pr.815.

- Pr. 1134 to 1149 ➤ Refer to the page on Pr.127.
- Pr. 1150 to 1199 ➤ Refer to the page on Pr.414.
- Pr. 1221 to 1288 ➤ Refer to the page on Pr.419.
- Pr. 1298 ➤ Refer to the page on Pr.422.
- Pr. 1299 ➤ Refer to the page on Pr.10.

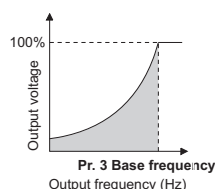
## ● To perform energy-saving operation for an application such as a fan or pump

To perform energy-saving operation for an application such as a fan or pump, set the parameters as follows.

### • Load pattern selection (Pr.14)

Optimal output characteristics (V/F characteristics) can be selected for application or load characteristics.

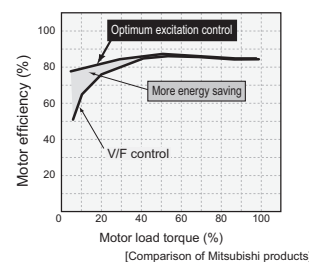
- Set "1" (for variable-torque load) in Pr.14 Load pattern selection.
- The output voltage will change in square curve against the output frequency at the base frequency or lower.
- Set this parameter when driving a load with load torque change proportionally against the square of the rotation speed, such as a fan or pump.



### • Energy saving control (Pr.60)


Inverter will perform energy saving control automatically even when the detailed parameter settings are made. It is appropriate for an application such as a fan or pump.

- Set Pr.60 Energy saving control selection = "9" (Optimum excitation control mode).
- The Optimum excitation control is a control method to decide the output voltage by controlling the excitation current so the efficiency of the motor is maximized.
- The energy saving effect cannot be expected when the motor capacity is extremely smaller than the inverter capacity, or when multiple motors are connected to one inverter.



## ● The list of inverter protective functions

When the inverter detects a fault, depending on the nature of the fault, the operation panel displays an error message or warning, or a protective function is activated to trip the inverter.

	Name	Description	Operation panel indication
Error message *2	Faults history	The operation panel stores the fault indications which appears when a protective function is activated to display the fault record for the past eight faults.	E-----
	Operation panel lock	Appears when operation was tried during operation panel lock.	HOLD
	Password locked	Appears when a password restricted parameter is read/written.	LOCd
	Parameter write error	Appears when an error occurred during parameter writing.	Er 1 to Er 4 Er 8
	Copy operation error	Appears when an error occurred during parameter copying.	rE 1 to rE 4 rE 6 to rE 8
	Error	Appears when the RES signal is on or the PU and inverter can not make normal communication.	Err.
Warning *3	Stall prevention (overcurrent)	Appears during overcurrent stall prevention.	OL
	Stall prevention (overvoltage)	Appears during overvoltage stall prevention. Appears while the regeneration avoidance function is activated.	oL
	Regenerative brake pre-alarm *8	Appears if the regenerative brake duty reaches or exceeds 85% of the <b>Pr.70 Special regenerative brake duty</b> value. If the regenerative brake duty reaches 100%, a regenerative overvoltage (E. OV[] ) occurs. (Standard models only)	Rb
	Electronic thermal relay function pre-alarm	Appears when the electronic thermal O/L relay has reached 85% of the specified value.	TH
	PU stop	Appears if  is pressed in an operation mode other than the PU operation mode.	PS
	Speed limit indication (output during speed limit)	Appears if the speed limit level is exceeded during torque control.	SL
	Parameter copy	Appears when parameter copy is performed between inverters FR-A820-03160(55K) or lower, FR-A840-01800(55K) or lower, FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher	CP
	Safety stop	Appears when safety stop function is activated (during output shutoff).	SA
	Maintenance signal output 1 to 3 *8	Appears when the inverter's cumulative energization time reaches or exceeds the parameter set value.	MF 1 to MF 3
	USB host error	Appears when an excessive current flows into the USB A connector.	UF
	Home position return error	Appears when an error occurs during the home position return operation under position control.	HP 1 to HP 3
	24 V external power supply operation	Flickers when the main circuit power supply is off and the 24 V external power supply is being input.	EV
	Alarm *4	Fan alarm	Appears when the cooling fan remains stopped when operation is required or when the speed has decreased.
Internal fan alarm		Appears when the internal fan fails, or at a reference replacement time. (IP55 compatible models only)	FN2
Fault *5	Overcurrent trip during acceleration	Appears when an overcurrent occurred during acceleration.	E. OC 1
	Overcurrent trip during constant speed	Appears when an overcurrent occurred during constant speed operation.	E. OC 2
	Overcurrent trip during deceleration or stop	Appears when an overcurrent occurred during deceleration and at a stop.	E. OC 3
	Regenerative overvoltage trip during acceleration	Appears when an overvoltage occurred during acceleration.	E. OV 1
	Regenerative overvoltage trip during constant speed	Appears when an overvoltage occurred during constant speed operation.	E. OV 2
	Regenerative overvoltage trip during deceleration or stop	Appears when an overvoltage occurred during deceleration and at a stop.	E. OV 3
	Inverter overload trip (electronic thermal relay function) *1	Appears when the electronic thermal relay function for inverter element protection was activated.	E. THF
	Motor overload trip (electronic thermal relay function) *1	Appears when the electronic thermal relay function for motor protection was activated.	E. THM
	Heatsink overheat	Appears when the heatsink overheated.	E. FIN
	Instantaneous power failure	Appears when an instantaneous power failure occurred at an input power supply. (Standard models and IP55 compatible models only)	E. 1PF
	Undervoltage	Appears when the main circuit DC voltage became low. (Standard models and IP55 compatible models only)	E. UVF
	Input phase loss *8	Appears if one of the three phases on the inverter input side opened. (Standard models and IP55 compatible models only)	E. 1LF
	Stall prevention stop	Appears 3 s after the output frequency is reduced to the reference value by the stall prevention (torque limit) operation.	E. OLF
	Loss of synchronism detection	The inverter trips when the motor operation is not synchronized. (This function is only available under PM sensorless vector control.)	E. SDF
	Brake transistor alarm detection	The inverter trips if an alarm occurs in the brake circuit, e.g. damaged brake transistors. In this case, the inverter must be powered off immediately. (Appears when an internal circuit fault occurred for separated converter types and IP55 compatible models.)	E. bE
	Output side earth (ground) fault overcurrent	Appears when an earth (ground) fault occurred on the Inverter's output side.	E. GF
	Output phase loss	Appears if one of the three phases on the inverter output side opened.	E. LF
	External thermal relay operation *6	Appears when the external thermal relay connected to the terminal OH is activated.	E. OHF

Features

Application Example  
PLC Function  
FR Configurator 2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal SpecsOperation Panel  
Parameter List

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



Name	Description	Operation panel indication
PTC thermistor operation	The inverter trips if resistance of the PTC thermistor connected between the terminal 2 and terminal 10 has reached the <b>Pr.561 PTC thermistor protection level</b> setting or higher.	E. PTC
Option fault	Appears when torque command by the plug-in option is selected using <b>Pr. 804</b> when no plug-in option is mounted or an AC power supply is connected to the R/L1, S/L2, T/L3 when the high power factor converter and power regeneration common converter connection setting ( <b>Pr.30 =2</b> ) is selected.	E. OPF
Communication option fault	Appears when a communication line error occurs in the communication option.	E. OP1
Parameter storage device fault	Appears when operation of the element where parameters stored became abnormal. (control board)	E. PE
PU disconnection	Appears when a communication error between the PU and inverter occurred, the communication interval exceeded the permissible time during the RS-485 communication with the PU connector, or communication errors exceeded the number of retries during the RS-485 communication.	E. PUE
Retry count excess *8	Appears when the operation was not restarted within the set number of retries.	E. REF
Parameter storage device fault	Appears when operation of the element where parameters stored became abnormal. (main circuit board)	E. PE2
CPU fault	Appears during the CPU and peripheral circuit errors occurred.	E. CPU E. 5 to E. 7
Operation panel power supply short circuit/RS-485 terminals power supply short circuit	Appears when the RS-485 terminal power supply or operation panel power supply was shorted.	E. CFE
24 VDC power fault	When the 24 VDC power output via the terminal PC is shorted, or when the external 24 VDC power supplied to the terminal +24 is not enough, this function shuts off the power output.	E. P24
Abnormal output current detection *8	Appears when the output current is out of the output current detection range set by parameters.	E. Cdo
Inrush current limit circuit fault	Appears when the resistor of the inrush current limit circuit overheated. (Standard models and IP55 compatible models only)	E. IOH
Communication fault (inverter)	Appears when a communication error occurred during the RS-485 communication with the RS-485 terminals.	E. SER
Analog input fault	Appears when 30 mA or more is input or a voltage (7.5 V or more) is input with the terminal 2/4 set to current input.	E. AIE
USB communication fault	Appears when USB communication error occurred.	E. USB
Safety circuit fault	The inverter trips when a safety circuit fault occurs.	E. SAF
Overspeed occurrence *8	Indicates that the motor speed has exceeded the overspeed setting level ( <b>Pr.374</b> ).	E. OS
Speed deviation excess detection *7 *8	Stops the inverter output if the motor speed is increased or decreased under the influence of the load etc. during vector control and cannot be controlled in accordance with the speed command value.	E. OSd
Signal loss detection *7 *8	Stops the inverter output if the encoder signal is shut off.	E. ECF
Excessive position fault *8	Indicates that the difference between the position command and position feedback exceeded the reference.	E. Od
Brake sequence fault *8	The inverter output is stopped when a sequence error occurs during use of the brake sequence function ( <b>Pr.278 to Pr.285</b> ).	E. Mb 1 to E. Mb 7
Encoder phase fault *7 *8	When the rotation command of the inverter differs from the actual motor rotation direction detected from the encoder, the inverter output is stopped. (detected only during tuning is performed in the "rotation mode" of offline auto tuning)	E. EP
Magnetic pole position unknown *7	When the offset value between the motor home magnetic pole position and the resolver home position is unknown, the protective circuit is activated to stop the inverter output. (Only when the FR-A8APR is used.)	E. MP
Abnormal internal temperature	The inverter output is stopped when the internal temperature of the inverter rises abnormally. (IP55 compatible models only)	E. IAH
4 mA input fault *8	The inverter trips when the analog input current is 2 mA or less for the time set in <b>Pr.778 4 mA input check filter</b> .	E. LCI
Pre-charge fault *8	The inverter trips when the pre-charge time exceeds <b>Pr.764 Pre-charge time limit</b> . The inverter trips when the measured value exceeds <b>Pr.763 Pre-charge upper detection level</b> during pre-charging.	E. PCH
PID signal fault *8	The inverter trips if the measured value exceeds the PID upper limit or PID lower limit parameter setting, or the absolute deviation value exceeds the PID deviation parameter setting during PID control.	E. PID
Option fault	The inverter trips when a contact fault is found between the inverter and the plug-in option, or when the communication option is not connected to the connector 1.	E. 1 to E. 3
Internal circuit fault *8	The speed may not decelerate during low speed operation if the rotation direction of the speed command and the estimated speed differ when the rotation is changing from forward to reverse or from reverse to forward under real sensorless vector control. At this time, the inverter output is stopped if the rotation direction will not change, causing overload.	E. 11
Internal circuit fault	Appears when an internal circuit error occurred.	E. Pbf E. 13
User definition error by the PLC function	Appears when the values 16 to 20 are set in the device SD1214 with the program operation of the PLC function.	E. 16 to E. 20

\*1 Resetting the inverter initializes the internal cumulative heat value of the electronic thermal O/L relay function.

\*2 The error message shows an operational error. The inverter output is not shut off.

\*3 Warnings are messages given before faults occur. The inverter output is not shut off.

\*4 Alarm warn the operator of failures with output signals. The inverter output is not shut off.

\*5 When faults occur, the protective functions are activated to shut off the inverter output and output the alarms.

\*6 The external thermal operates only when the OH signal is set in **Pr.178 to Pr.189 (input terminal function selection)**.

\*7 Appears when a vector control compatible option is installed.

\*8 This protective function is not available in the initial status.

## ● The list of converter unit protective functions

When the converter unit detects a fault, depending on the nature of the fault, the operation panel displays an error message or warning, or a protective function is activated to trip the inverter.

Name		Description	Operation panel indication
Error message *2	Faults history	The operation panel stores the fault indications which appears when a protective function is activated to display the fault record for the past eight faults.	E-----
	Operation panel lock	Appears when operation was tried during operation panel lock.	HOLD
	Password locked	Appears when a password restricted parameter is read/written.	LOCd
	Parameter write error	Appears when an error occurred during parameter writing.	Er 1
	Copy operation error	Appears when an error occurred during parameter copying.	rE 1 to rE 4
	Error	Appears when the RES signal is on or the PU and converter unit can not make normal communication.	Err.
Warning *3	Electronic thermal relay function pre-alarm	Appears when the electronic thermal O/L relay has reached 85% of the specified value.	TH
	Maintenance signal output 1 to 3 *7	Appears when the converter unit's cumulative energization time reaches or exceeds the parameter set value.	MF 1 to MF 3
	24 V external power supply operation	Flickers when the main circuit power supply is off and the 24 V external power supply is being input.	EV
Alarm *4	Fan alarm	Appears when the cooling fan remains stopped when operation is required or when the speed has decreased.	FN
Fault *5	Oversvoltage trip	Appears when the converter unit's internal main circuit DC voltage exceeds the specified value.	E. OVF
	Converter overload trip (electronic thermal relay function) *1	Appears when the electronic thermal O/L relay of the converter unit diode module is activated.	E. FHC
	Heatsink overheat	Appears when the heatsink overheated.	E. FIN
	Instantaneous power failure	Appears when an instantaneous power failure occurred at an input power supply.	E. I PF
	Undervoltage	Appears when power supply voltage of the converter unit is set at a low level.	E. UVF
	Input phase loss *7	Appears if one of the three phases on the converter unit input side opened.	E. I LF
	External thermal relay operation *6	Appears when the external thermal relay connected to the terminal OH is activated.	E. OHF
	Parameter storage device fault	Appears when operation of the element where parameters stored became abnormal. (control board)	E. PE
	PU disconnection	Appears when a communication error between the PU and inverter occurred, the communication interval exceeded the permissible time during the RS-485 communication with the PU connector, or communication errors exceeded the number of retries during the RS-485 communication.	E. PUE
	Retry count excess *7	Appears when the operation was not restarted within the set number of retries.	E. REF
	Parameter storage device fault	Appears when operation of the element where parameters stored became abnormal. (main circuit board)	E. PE2
	CPU fault	Appears during the CPU and peripheral circuit errors occurred.	E. CPU E. 5 to E. 7
	Operation panel power supply short circuit/RS-485 terminals power supply short circuit	Appears when the RS-485 terminal power supply or operation panel power supply was shorted.	E. CFE
	24 VDC power fault	When the 24 VDC power output via the terminal PC is shorted, or when the external 24 VDC power supplied to the terminal +24 is not enough, this function shuts off the power output.	E. P24
	Inrush current limit circuit fault	Appears when the resistor of the inrush current limit circuit overheated.	E. IOH
	Communication fault (inverter)	Appears when a communication error occurred during the RS-485 communication with the RS-485 terminals.	E. SER
	Internal circuit fault	Appears when an internal circuit error occurred.	E. P6F
			E. 13
	Option fault	The inverter trips if a plug-in option is disconnected while the converter unit power is ON.	E. 1

\*1 Resetting the converter unit initializes the internal cumulative heat value of the electronic thermal O/L relay function.

\*2 The error message shows an operational error. The inverter output is not shut off.

\*3 Warnings are messages given before faults occur. The inverter output is not shut off.

\*4 Alarm warn the operator of failures with output signals. The inverter output is not shut off.

\*5 When faults occur, the protective functions are activated to shut off the inverter output and output the alarms.

\*6 The external thermal operates only when the OH signal is set in Pr.178, Pr.180, Pr.187 or Pr.189 (input terminal function selection).

\*7 This protective function is not available in the initial status.

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry




# Option and Peripheral Devices

## Option List

By fitting the following options to the inverter, the inverter is provided with more functions.

Three plug-in options can be fitted at a time. (more than two same options and communication options can not be fitted)

Name		Type	Applications, Specifications, etc.	Applicable Inverter	
Plug-in Type	Vector control	FR-A8AP	Vector control can be performed for encoder-equipped motors (induction motors).	Shared among all models	
		FR-A8APR	Vector control can be performed for resolver-equipped motors (induction/PM motors).		
	Orientation control Encoder feedback control	FR-A8AP	The main spindle can be stopped at a specified position (orientation) in combination with an encoder (resolver). The motor speed is sent back and the speed is maintained constant.		
		FR-A8APR			
	16-bit digital input	FR-A8AX	This input interface sets the high frequency accuracy of the inverter using an external BCD or binary digital signal. • BCD code 3 digits / 4 digits • Binary 12 bits / 16 bits		
	Digital output Extension analog output	FR-A8AY	Output signals provided with the inverter as standard are selected to output from the open collector.		
			This option adds 2 different signals that can be monitored such as the output frequency and output voltage. 20mADC or 10VDC meter can be connected.		
	Relay output	FR-A8AR	Output any three output signals available with the inverter as standard from the relay contact terminals.		
	Bipolar analog output High resolution analog input Motor thermistor interface	FR-A8AZ	This option adds different signals that can be monitored such as the motor torque and torque command by the $\pm 10$ V output. Highly accurate operation is achieved by using high-resolution analog input (16 bits). Thermistor-equipped motors can detect the motor temperature, and the temperature feedback is used to reduce the fluctuation of output torque.		
	Communication	CC-Link communication	FR-A8NC		This option allows the inverter to be operated or monitored or the parameter setting to be changed from a computer or programmable controller.
CC-Link IE Field Network communication		FR-A8NCE			
DeviceNet communication		FR-A8ND			
PROFIBUS-DP communication		FR-A8NP			
Control terminal	Screw terminal block	FR-A8TR	The screw type control circuit terminal block enables wiring using round crimping terminals.	Shared among all models	
	Vector control terminal block	FR-A8TP	The control circuit terminal block equipped with the encoder power supply (24 VDC output) enables orientation control, encoder feedback control, vector control, encoder pulse division output with encoder-equipped motors (induction motors). (The 24 VDC power supply can be used for the encoder of the SF-V5RU.)		
Stand-alone Shared	Liquid crystal display operation panel	FR-LU08	Graphical operation panel with liquid crystal display *3	Shared among all models	
	Parameter unit	FR-PU07	Interactive parameter unit with LCD display		
	Parameter unit with battery pack	FR-PU07BB(-L) *4	Enables parameter setting without supplying power to the inverter.		
	Parameter unit connection cable	FR-CB20□	Cable for connection of operation panel or parameter unit □ indicates a cable length. (1m, 3m, 5m)		
	USB cable	MR-J3USBCBL3M Cable length: 3 m	Amplifier connector Mini B connector (5-pin) Personal computer connector A connector 		
	Operation panel connection connector	FR-ADP	Connector to connect the operation panel (FR-DU08) and connection cable		
	Encoder cable Mitsubishi vector control dedicated motor (SF-V5RU)	FR-V7CBL□	Connection cable for the inverter and encoder for Mitsubishi vector control dedicated motor (SF-V5RU). □ indicates a cable length. (5m, 15m, 30m)		
	Control circuit terminal block intercompatibility attachment	FR-A8TAT	An attachment for installing the control circuit terminal block of the FR-A700/A500 series to that of the FR-A800 series		
	Heatsink protrusion attachment	FR-A8CN	The heatsink of the inverter can be protruded outside the enclosure. For the enclosure cut dimensions, refer to <b>page 36</b> .		FR-A820-00105(1.5K) to FR-A820-04750(90K) FR-A840-00023(0.4K) to FR-A840-03610(132K) According to capacities
	Intercompatibility attachment	FR-AAT	Attachment for replacing with the A800 series using the installation holes of the FR-A700/A500/A200E series.		According to capacities
		FR-A5AT			
	AC reactor	FR-HAL	For harmonic current reduction and inverter input power factor improvement		Shared among all models
DC reactor	FR-HEL				
Line noise filter	FR-BSF01	For line noise reduction	Shared among all models		
	FR-BLF				
High-duty brake resistor	FR-ABR	The regenerative braking capability can be improved (permissible duty 10%/6%ED).	FR-A820-01250(22K) or lower, FR-A840-00620(22K) or lower *1		




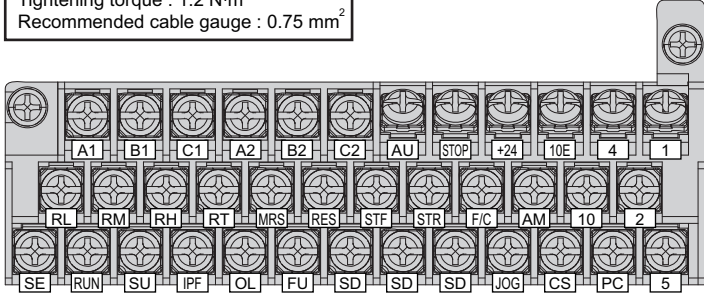
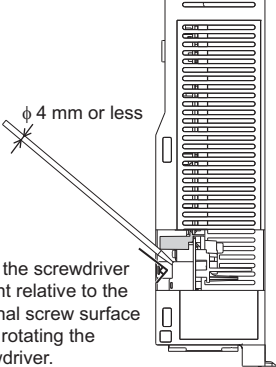
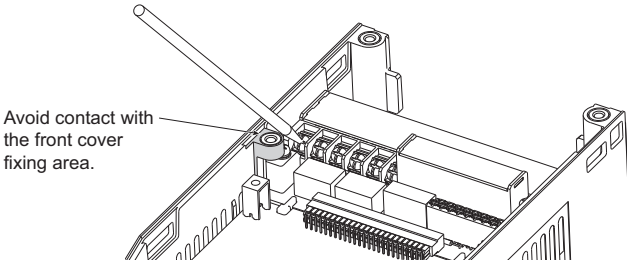


Name		Type	Applications, Specifications, etc.	Applicable Inverter	
Stand-alone Shared	Brake unit	FR-BU2	For increasing the braking capability of the inverter (for high-inertia load or negative load) Brake unit and resistor unit are used in combination	According to capacities	
	Resistor unit	FR-BR		FR-A820-03160(55K) or lower, FR-A840-01800(55K) or lower *1	
		MT-BR5		FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher *1	
	Power regeneration common converter Stand-alone reactor dedicated for the FR-CV	FR-CV/ FR-CVL	Unit which can return motor-generated braking energy back to the power supply in common converter system	FR-A820-03160(55K) or lower, FR-A840-01800(55K) or lower *1	
	Power regeneration converter	MT- RC	Energy saving type high performance brake unit which can regenerate the braking energy generated by the motor to the power supply.	FR-A840-02160(75K) or higher *1	
	High power factor converter	FR-HC2	The high power factor converter switches the converter section on/off to reshape an input current waveform into a sine wave, greatly suppressing harmonics. (Used in combination with the standard accessory.)	According to capacities	
	Surge voltage suppression filter	FR-ASF	Filter for suppressing surge voltage on motor	FR-A840-01800(55K) or lower *1	
		FR-BMF		FR-A840-00170(5.5K) to FR-A840-00930(37K) *2 According to capacities	
	Sine wave filter	Reactor	MT- BSL (-HC)	Reduce the motor noise during inverter driving Use in combination with a reactor and a capacitor	FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher *1
		Capacitor	MT- BSC		According to capacities
FR Series Manual Controller/Speed Controller	Manual controller	FR-AX	For independent operation. With frequency meter, frequency potentiometer and start switch.	Shared among all models	
	DC tach. follower	FR-AL	For synchronous operation (1VA) by external signal (0 to 5V, 0 to 10V DC) *2		
	Three speed selector	FR-AT	For three speed switching, among high, middle and low speed operation (1.5VA) *2		
	Motorized speed setter	FR-FK	For remote operation. Allows operation to be controlled from several places (5VA) *2		
	Ratio setter	FR-FH	For ratio operation. Allows ratios to be set to five inverters. (3VA) *2		
	Speed detector	FR-FP	For tracking operation by a pilot generator (PG) signal (2VA) *2		
	Master controller	FR-FG	Master controller (5VA) for parallel operation of multiple (maximum 35) inverters. *2		
	Soft starter	FR-FC	For soft start and stop. Enables acceleration/deceleration in parallel operation (3VA) *2		
	Deviation detector	FR-FD	For continuous speed control operation. Used in combination with a deviation sensor or synchro (5VA) *2		
	Preamplifier	FR-FA	Used as an A/V converter or arithmetic amplifier (3VA) *2		
Others	Pilot generator	QVAH-10	For tracking operation. 70V/35VAC 500Hz (at 2500r/min)		
	Deviation sensor	YVGC-500W-NS	For continuous speed control operation (mechanical deviation detection) Output 90VAC/90°		
	Frequency setting potentiometer	WA2W 1kΩ	For frequency setting. Wire-wound 2W 1kΩ type B characteristic		
	Analog frequency meter (64mm x 60mm)	YM206NRI 1mA	Dedicated frequency meter (graduated to 130Hz). Moving-coil type DC ammeter		
	Calibration resistor	RV24YN 10kΩ	For frequency meter calibration. Carbon film type B characteristic		
	FR Configurator2 (Inverter setup software)	SW1DND-FRC2-E	Supports an inverter startup to maintenance.		

\*1 Applicable inverters for the ND rating. For the SLD, LD, and HD ratings, different inverters are used depending on the applicable motor capacity.  
 \*2 Rated power consumption. The power supply specifications of the FR series manual controllers and speed controllers are 200VAC 50Hz, 200V/220VAC 60Hz, and 115VAC 60Hz.  
 \*3 The battery (CR1216: a diameter of 12 mm, a height of 16 mm) is not bundled.  
 \*4 To use a parameter unit with battery pack (FR-PU07BB) outside Japan, order a "FR-PU07BB-L" (parameter unit type indicated on the package has L at the end). Since batteries may conflict with laws in countries to be used (new EU Directive on batteries and accumulators, etc.), batteries are not enclosed with an FR-PU07BB.

- Features
- Application Example  
PLC Function  
FR Configurator2
- Connection  
Examples
- Standard  
Specs
- Outline  
Dimensions
- Terminal Connection  
Diagrams  
Terminal Specs
- Operation Panel
- Parameter List
- Explanations  
of  
Parameters
- Protective  
Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty  
Inquiry

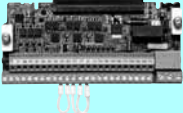
## ● Control terminal option

Name (model)	Specification and structure
<p data-bbox="132 712 323 757"><b>Screw terminal block FR-A8TR</b></p> 	<p data-bbox="352 300 900 322">Replace the standard control circuit terminal block with this option.</p> <ul data-bbox="352 322 491 344" style="list-style-type: none"> <li>Terminal layout</li> </ul> <div data-bbox="544 353 892 434" style="border: 1px solid black; padding: 5px; margin: 10px 0;"> <p>Terminal screw size : M3.5 Tightening torque : 1.2 N·m Recommended cable gauge : 0.75 mm<sup>2</sup></p> </div>  <ul data-bbox="352 698 1439 896" style="list-style-type: none"> <li>Restrictions for the FR-A8TR As compared with the standard control circuit terminal block, the FR-A8TR has the following restrictions.           <ol style="list-style-type: none"> <li>When the plug-in option FR-A8NC or FR-A8NCE is used, terminals +24, 10E, 4, and STOP of the FR-A8TR cannot be used.</li> <li>Because the height is restricted, two wires cannot be wired to upper-row terminals (except for terminals A1, B1, C1, A2, B2, and C2) and middle-row terminals on the terminal block.</li> <li>The safety stop function is not available.</li> <li>For the connection to the terminal 1, use a screwdriver with a diameter of 4 mm or less. To avoid contact with the front cover fixing area, put the screwdriver upright relative to the terminal screw surface.</li> </ol> </li> </ul> <div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div data-bbox="422 907 699 1272" style="text-align: center;">  <p data-bbox="438 1012 566 1034">φ 4 mm or less</p> <p data-bbox="371 1167 563 1272">Keep the screwdriver upright relative to the terminal screw surface while rotating the screwdriver.</p> </div> <div data-bbox="766 1019 1396 1281" style="text-align: center;">  <p data-bbox="766 1126 922 1193">Avoid contact with the front cover fixing area.</p> </div> </div>



**Name (model)**

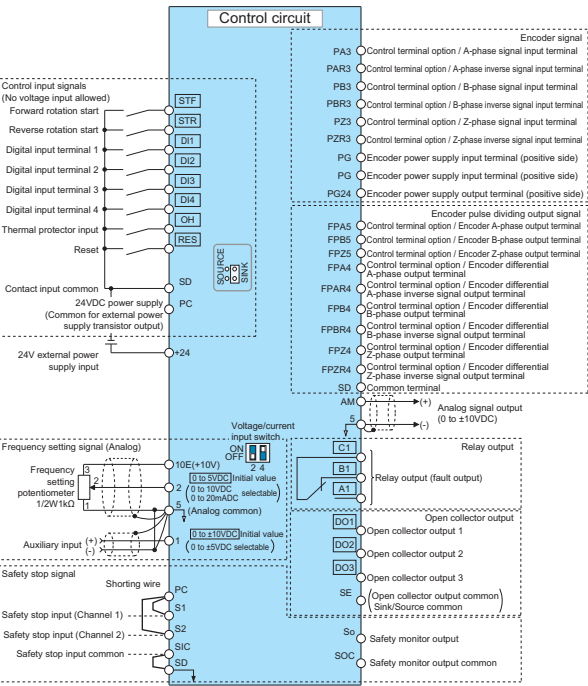
**Vector control terminal block FR-A8TP**



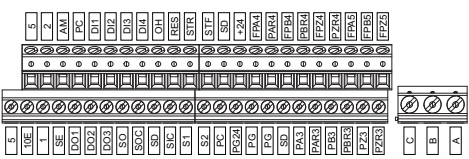
**Specification and structure**

Replace the standard control circuit terminal block with this option. The 24 VDC power supply can be used for the encoder of the SF-V5RU.

- Terminal connection diagrams



**Control terminal layout**



Tightening torque: 0.5 N·m to 0.6 N·m (terminals A, B, and C) 0.22 N·m to 0.25 N·m (terminals other than described above)  
Small flat-blade screwdriver (Tip thickness: 0.4 mm / tip width: 2.5 mm)

**Control terminal specification**

[Input signal]

Function	Terminal symbol	Terminal name	Terminal function description
Contact input	DI1 to DI4	Digital input terminal 1 to 4	Functions can be assigned to terminals by the input terminal function selection ( <b>Pr.180 to Pr.182, Pr.185</b> ).
	OH	Thermal protector input	Temperature detector input terminal for overheat protection of a motor. When the OH signal turns OFF, the external thermal relay (E.OHT) protective function is activated Use <b>Pr.876</b> to switch valid/invalid status of terminal function. Switches the control logic (sink logic or source logic) independently by the external thermal relay switch (SW5A).
Encoder signal	PA3	Control terminal option / A-phase signal input terminal	A-, B- and Z-phase signals are input from the encoder.
	PAR3	Control terminal option / A-phase inverse signal input terminal	
	PB3	Control terminal option / B-phase signal input terminal	
	PBR3	Control terminal option / B-phase inverse signal input terminal	
	PZ3	Control terminal option / Z-phase signal input terminal	
	PZR3	Control terminal option / Z-phase inverse signal input terminal	
	PG	Encoder power supply terminal (positive side)	Input power for the encoder power supply. Connect the external power supply (5 V, 12 V, 15 V) and the encoder power cable. When the encoder output is the differential line driver type, only 5 V can be input. Make sure the voltage of the external power supply the same as the encoder output voltage. (Check the encoder specification.) If using the 24 V power supply of the FR-A8TP, 24 V power can be supplied from terminal PG24.

Features

Application Example  
PLC Function  
FR Configurator 2

Connection Examples

Standard Specs

Outline Dimensions

Terminal Connection Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations of Parameters

Protective Functions

**Options**

LVS/Cables

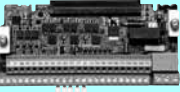
Precautions

Motors

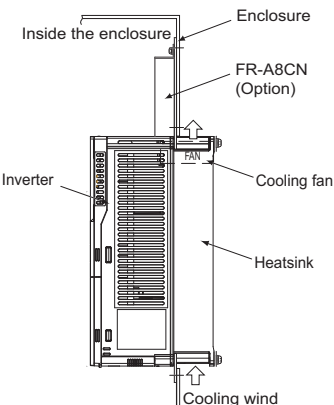
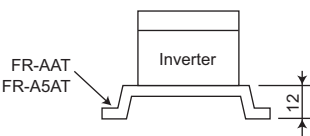
Compatibility

Warranty Inquiry



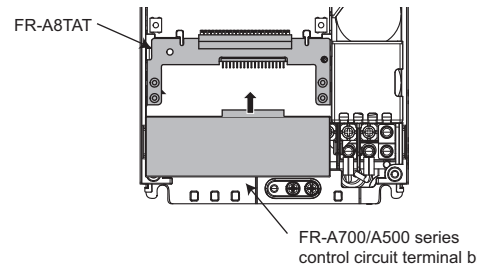
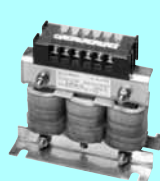
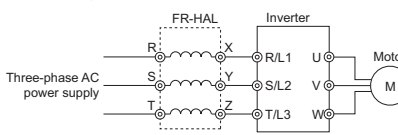
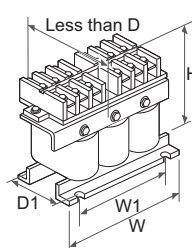
Name (model)	Specification and structure			
<p data-bbox="124 663 331 719">Vector control terminal block FR-A8TP</p> 	[Output signal]			
	Function	Terminal symbol	Terminal name	Terminal function description
	Open collector	DO1 to DO3	Digital output terminal 1 to 3	The function can be assigned to an output terminal by the output terminal function selection ( <b>Pr.190 to Pr.192</b> ).
		SE	Open collector output common	Common terminal for terminals DO1, DO2, DO3. Isolated from terminals SD and 5.
	Encoder pulse dividing output	FPA5	Control terminal option / Encoder A-phase output terminal	Outputs A-, B- and Z-phase (home position and mark pulse) signals from the encoder. The A- and B-phase signals can be divided by the ratio (1/n) and output. n=1 to 32767 (an integer) Use <b>Pr.863 Control terminal option-Encoder pulse division ratio</b> for division. Common terminal is terminal SD.
		FPB5	Control terminal option / Encoder B-phase output terminal	
		FPZ5	Control terminal option / Encoder Z-phase output terminal	
		FPA4	Control terminal option / Encoder differential A-phase output terminal	
		FPAR4	Control terminal option / Encoder differential A-phase inverse signal output terminal	
		FPB4	Control terminal option / Encoder differential B-phase output terminal	
		FPBR4	Control terminal option / Encoder differential B-phase inverse signal output terminal	
		FPZ4	Control terminal option / Encoder differential Z-phase output terminal	
	Power supply output for encoder	PG24	Encoder power supply terminal (positive side)	Used for the 24 VDC power supply for an encoder. If used, connect this terminal to terminal PG, and this will supply power from the terminal PG to the encoder.
		Specifications are the same as those of the standard control circuit terminals for the input signals (STF, STR, RES, SD, PC, 10E, 2, 1, 5, and +24) and the output signals (A, B, C, AM, S1, S2, SIC, SO, and SOC).		

● Stand-alone option


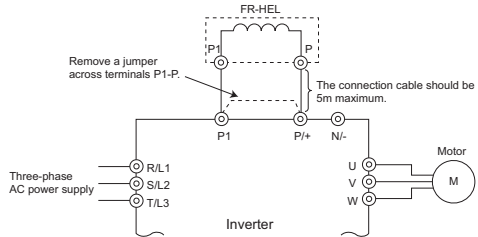
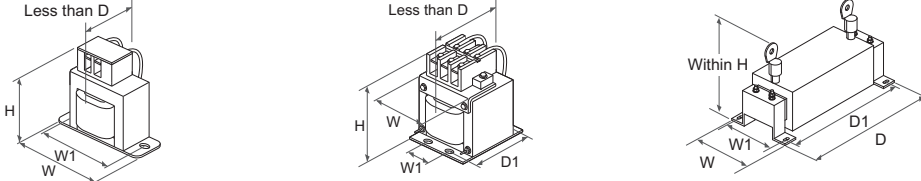
Name (model)	Specification and structure																																																																																																																																																																																																																																																																																																																							
<p><b>Heatsink protrusion attachment FR-A8CN[]</b></p>	<p>With this attachment the heatsink which is the exothermic section of the inverter can be placed on the rear of the enclosure. Since the heat generated in the inverter can be radiated to the rear of the enclosure, the enclosure can be downsized. The use of this attachment requires more installation area. For installation, refer to the drawing after attachment installation (page 36).</p> <p>For a panel cutting drawing, refer to page 36.</p> <ul style="list-style-type: none"> <li>• Applicable models</li> </ul> <table border="1" data-bbox="387 443 1066 846"> <thead> <tr> <th rowspan="2">Model</th> <th colspan="2">Applicable inverter</th> </tr> <tr> <th>FR-A820</th> <th>FR-A840</th> </tr> </thead> <tbody> <tr> <td>FR-A8CN01</td> <td>00105(1.5K), 00167(2.2K), 00250(3.7K)</td> <td>00023(0.4K), 00038(0.75K), 00052(1.5K), 00083(2.2K), 00126(3.7K)</td> </tr> <tr> <td>FR-A8CN02</td> <td>00340(5.5K), 00490(7.5K)</td> <td>00170(5.5K), 00250(7.5K)</td> </tr> <tr> <td>FR-A8CN03</td> <td>00630(11K)</td> <td>00310(11K), 00380(15K)</td> </tr> <tr> <td>FR-A8CN04</td> <td>00770(15K), 00930(18.5K), 01250(22K)</td> <td>00470(18.5K), 00620(22K)</td> </tr> <tr> <td>FR-A8CN05</td> <td>01540(30K)</td> <td>00770(30K)</td> </tr> <tr> <td>FR-A8CN06</td> <td>01870(37K), 02330(45K)</td> <td>00930(37K), 01160(45K), 01800(55K)</td> </tr> <tr> <td>FR-A8CN07</td> <td>03160(55K)</td> <td>—</td> </tr> <tr> <td>FR-A8CN08</td> <td>03800(75K), 04750(90K)</td> <td>03250(110K), 03610(132K)</td> </tr> <tr> <td>FR-A8CN09</td> <td>—</td> <td>02160(75K), 02600(90K)</td> </tr> </tbody> </table> 	Model	Applicable inverter		FR-A820	FR-A840	FR-A8CN01	00105(1.5K), 00167(2.2K), 00250(3.7K)	00023(0.4K), 00038(0.75K), 00052(1.5K), 00083(2.2K), 00126(3.7K)	FR-A8CN02	00340(5.5K), 00490(7.5K)	00170(5.5K), 00250(7.5K)	FR-A8CN03	00630(11K)	00310(11K), 00380(15K)	FR-A8CN04	00770(15K), 00930(18.5K), 01250(22K)	00470(18.5K), 00620(22K)	FR-A8CN05	01540(30K)	00770(30K)	FR-A8CN06	01870(37K), 02330(45K)	00930(37K), 01160(45K), 01800(55K)	FR-A8CN07	03160(55K)	—	FR-A8CN08	03800(75K), 04750(90K)	03250(110K), 03610(132K)	FR-A8CN09	—	02160(75K), 02600(90K)																																																																																																																																																																																																																																																																																							
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FR-A8CN02	00340(5.5K), 00490(7.5K)	00170(5.5K), 00250(7.5K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN03	00630(11K)	00310(11K), 00380(15K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN04	00770(15K), 00930(18.5K), 01250(22K)	00470(18.5K), 00620(22K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN05	01540(30K)	00770(30K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN06	01870(37K), 02330(45K)	00930(37K), 01160(45K), 01800(55K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN07	03160(55K)	—																																																																																																																																																																																																																																																																																																																						
FR-A8CN08	03800(75K), 04750(90K)	03250(110K), 03610(132K)																																																																																																																																																																																																																																																																																																																						
FR-A8CN09	—	02160(75K), 02600(90K)																																																																																																																																																																																																																																																																																																																						
<p><b>Intercompatibility attachment FR-AAT[] FR-A5AT[]</b></p>	<p>Enables the FR-A800 inverter to be installed using the mounting holes made for the conventional FR-A700/A500/A200E series inverter. This attachment is useful for replacing a conventional inverter with the FR-A800 series inverter. The inverter with this attachment requires greater installation depth.</p> <ul style="list-style-type: none"> <li>• Models replaceable with FR-A820</li> </ul> <table border="1" data-bbox="387 1052 1468 1512"> <thead> <tr> <th colspan="2" rowspan="2"></th> <th colspan="8">FR-A820</th> </tr> <tr> <th>0.4K/0.75K</th> <th>1.5K to 3.7K</th> <th>5.5K/7.5K</th> <th>11K</th> <th>15K to 22K</th> <th>30K</th> <th>37K/45K</th> <th>55K</th> </tr> </thead> <tbody> <tr> <td rowspan="10">Conventional model and capacity</td> <td rowspan="6">FR-A220E</td> <td>0.4K/0.75K</td> <td>FR-A5AT01</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>1.5K to 3.7K</td> <td>FR-A5AT02</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>5.5K to 11K</td> <td>—</td> <td>FR-A5AT03</td> <td>FR-A5AT03</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>15K</td> <td>—</td> <td>—</td> <td>FR-AAT02</td> <td>FR-AAT24</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>18.5K/22K</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-A5AT04</td> <td>FR-A5AT04</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>30K</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-AAT27</td> <td>○</td> <td>—</td> <td>—</td> </tr> <tr> <td rowspan="4">FR-A520/A720</td> <td>37K/45K</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-AAT23</td> <td>○</td> <td>—</td> </tr> <tr> <td>55K</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-A5AT05</td> <td>○</td> </tr> <tr> <td>0.4K/0.75K</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>1.5K to 3.7K</td> <td>FR-AAT21</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td rowspan="6">FR-A540</td> <td>5.5K/7.5K</td> <td>—</td> <td>FR-AAT22</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> 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rowspan="6">Conventional model and capacity</td> <td rowspan="6">FR-A240E</td> <td>0.4K to 3.7K</td> <td>FR-A5AT02</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>5.5K/7.5K</td> <td>FR-A5AT03</td> <td>FR-A5AT03</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>11K/15K</td> <td>—</td> <td>FR-AAT02</td> <td>FR-AAT24</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>18.5K/22K</td> <td>—</td> <td>—</td> <td>FR-A5AT04</td> <td>FR-A5AT04</td> <td>—</td> <td>—</td> </tr> <tr> <td>30K</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-AAT27</td> <td>○</td> <td>—</td> </tr> <tr> <td>37K/45K</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-AAT23</td> <td>○</td> </tr> <tr> <td rowspan="4">FR-A540</td> <td>55K</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>FR-A5AT05</td> <td>○</td> </tr> <tr> <td>0.4K to 3.7K</td> <td>○</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> <td>—</td> </tr> <tr> <td>5.5K/7.5K</td> <td>FR-AAT22</td> <td>○</td> <td>—</td> 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3.7K	FR-A5AT02	—	—	—	—	—	5.5K/7.5K	FR-A5AT03	FR-A5AT03	—	—	—	—	11K/15K	—	FR-AAT02	FR-AAT24	—	—	—	18.5K/22K	—	—	FR-A5AT04	FR-A5AT04	—	—	30K	—	—	—	FR-AAT27	○	—	37K/45K	—	—	—	—	FR-AAT23	○	FR-A540	55K	—	—	—	—	FR-A5AT05	○	0.4K to 3.7K	○	—	—	—	—	—	5.5K/7.5K	FR-AAT22	○	—	—	—	—	11K to 22K	—	FR-AAT02	FR-AAT24	○	—	—	FR-A740	30K	—	—	—	FR-AAT27	○	—	37K to 55K	—	—	—	—	FR-AAT23	○	0.4K to 3.7K	○	—	—	—	—	—	5.5K/7.5K	FR-AAT22	○	—	—	—	—	FR-A740	11K/15K	—	FR-A5AT03	○	—	—	—	18.5K/22K	—	—	FR-AAT24	○	—	—	30K	—	—	—	FR-AAT27	○	—	37K to 55K	—	—	—	—	FR-AAT23	○
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Features  
Application Example  
PLC Function  
FR Configurator2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry


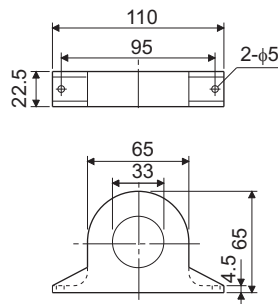
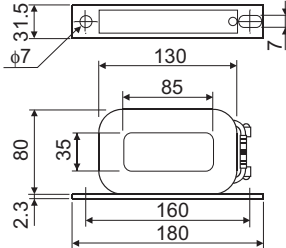
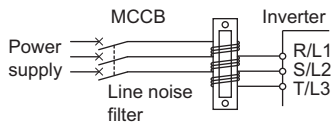

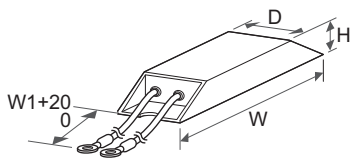


Name (model)	Specification and structure																																																																																																																																																																																																																																																																																																																																
<p><b>Control circuit terminal block intercompatibility attachment FR-A8TAT</b></p>	<p>This attachment allows the conventional FR-A700/A500 series control circuit terminal blocks to be installed without removing any cables. This attachment is useful for replacing a conventional inverter with the FR-A800 series inverter.</p>  <p>(a) For using the control circuit terminal block of the FR-A500 series, open or remove the cover of the control circuit terminal block. Otherwise, the front cover of the inverter may not close properly.</p> <p>(b) Since the specifications of the control circuit terminals of the FR-A700/A500 series are different from those of the FR-A800 series, certain functions of the inverter are restricted (refer to the table below).</p> <table border="1" data-bbox="462 638 1197 750"> <thead> <tr> <th></th> <th>Relay output 2 terminals</th> <th>24 V external power supply input terminal</th> <th>Safety stop signal terminals</th> </tr> </thead> <tbody> <tr> <td>FR-A500 series</td> <td>x</td> <td>x</td> <td>x</td> </tr> <tr> <td>FR-A700 series</td> <td>O</td> <td>x</td> <td>x</td> </tr> </tbody> </table> <p style="text-align: center;">O ... Available, x... Not available</p> <p>(c) The FR-A8NC or FR-A8NCE plug-in option cannot be used.</p> <p>(d) When using a plug-in option, connect the plug-in option using a cable that can be routed through the space between the the front cover and the control circuit terminal block (FR-A700 series: 7 mm, FR-A500 series: 0.8 mm).</p>		Relay output 2 terminals	24 V external power supply input terminal	Safety stop signal terminals	FR-A500 series	x	x	x	FR-A700 series	O	x	x																																																																																																																																																																																																																																																																																																																				
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(Select the AC reactor according to the motor capacity even if the capacity is smaller than the inverter capacity.)</li> <li>• Connection diagram</li> </ul>  <ul style="list-style-type: none"> <li>• Outline dimension (Unit: mm)</li> </ul> <table border="1" data-bbox="359 1153 885 1702"> <thead> <tr> <th>Model</th> <th>W</th> <th>W1</th> <th>H</th> <th>D</th> <th>D1</th> <th>d</th> <th>Mass (kg)</th> </tr> </thead> <tbody> <tr><td>0.4K</td><td>104</td><td>84</td><td>99</td><td>72</td><td>40</td><td>M5</td><td>0.6</td></tr> <tr><td>0.75K</td><td>104</td><td>84</td><td>99</td><td>74</td><td>44</td><td>M5</td><td>0.8</td></tr> <tr><td>1.5K</td><td>104</td><td>84</td><td>99</td><td>77</td><td>50</td><td>M5</td><td>1.1</td></tr> <tr><td>2.2K</td><td>115</td><td>40</td><td>115</td><td>77</td><td>57</td><td>M6</td><td>1.5</td></tr> <tr><td>3.7K</td><td>115</td><td>40</td><td>115</td><td>83</td><td>67</td><td>M6</td><td>2.2</td></tr> <tr><td>5.5K</td><td>115</td><td>40</td><td>115</td><td>83</td><td>67</td><td>M6</td><td>2.3</td></tr> <tr><td>7.5K</td><td>130</td><td>50</td><td>135</td><td>100</td><td>86</td><td>M6</td><td>4.2</td></tr> <tr><td>11K</td><td>160</td><td>75</td><td>164</td><td>111</td><td>92</td><td>M6</td><td>5.2</td></tr> <tr><td>15K</td><td>160</td><td>75</td><td>167</td><td>126</td><td>107</td><td>M6</td><td>7.0</td></tr> <tr><td>18.5K</td><td>160</td><td>75</td><td>128</td><td>175</td><td>107</td><td>M6</td><td>7.1</td></tr> <tr><td>22K</td><td>185</td><td>75</td><td>150</td><td>158</td><td>87</td><td>M6</td><td>9.0</td></tr> <tr><td>30K</td><td>185</td><td>75</td><td>150</td><td>168</td><td>87</td><td>M6</td><td>9.7</td></tr> <tr><td>37K</td><td>210</td><td>75</td><td>175</td><td>174</td><td>82</td><td>M6</td><td>12.9</td></tr> <tr><td>45K</td><td>210</td><td>75</td><td>175</td><td>191</td><td>97</td><td>M6</td><td>16.4</td></tr> <tr><td>55K</td><td>210</td><td>75</td><td>175</td><td>201</td><td>97</td><td>M6</td><td>17.4</td></tr> <tr><td>75K</td><td>240</td><td>150</td><td>210</td><td>215.5</td><td>109</td><td>M8</td><td>23</td></tr> <tr><td>110K</td><td>330</td><td>170</td><td>325</td><td>259</td><td>127</td><td>M10</td><td>40</td></tr> </tbody> </table> <table border="1" data-bbox="901 1142 1428 1803"> <thead> <tr> <th>Model</th> <th>W</th> <th>W1</th> <th>H</th> <th>D</th> <th>D1</th> <th>d</th> <th>Mass (kg)</th> </tr> </thead> <tbody> <tr><td>H0.4K</td><td>135</td><td>120</td><td>115</td><td>64</td><td>45</td><td>M4</td><td>1.5</td></tr> <tr><td>H0.75K</td><td>135</td><td>120</td><td>115</td><td>64</td><td>45</td><td>M4</td><td>1.5</td></tr> <tr><td>H1.5K</td><td>135</td><td>120</td><td>115</td><td>64</td><td>45</td><td>M4</td><td>1.5</td></tr> <tr><td>H2.2K</td><td>135</td><td>120</td><td>115</td><td>64</td><td>45</td><td>M4</td><td>1.5</td></tr> 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<tr><td>H45K</td><td>280</td><td>255</td><td>245</td><td>165</td><td>80</td><td>M6</td><td>15</td></tr> <tr><td>H55K</td><td>280</td><td>255</td><td>245</td><td>170</td><td>90</td><td>M6</td><td>18</td></tr> <tr><td>H75K</td><td>210</td><td>75</td><td>170</td><td>210.5</td><td>105</td><td>M6</td><td>20</td></tr> <tr><td>H110K</td><td>240</td><td>150</td><td>225</td><td>220</td><td>99</td><td>M8</td><td>28</td></tr> <tr><td>H185K</td><td>330</td><td>170</td><td>325</td><td>271</td><td>142</td><td>M10</td><td>55</td></tr> <tr><td>H280K</td><td>330</td><td>170</td><td>325</td><td>321</td><td>192</td><td>M10</td><td>80</td></tr> <tr><td>H355K</td><td>330</td><td>170</td><td>325</td><td>346</td><td>192</td><td>M10</td><td>90</td></tr> <tr><td>H560K</td><td>450</td><td>300</td><td>540</td><td>635</td><td>345</td><td>M12</td><td>190</td></tr> </tbody> </table> <p>(a) Approximately 88% of the power factor improving effect can be obtained (92.3% when calculated with 1 power factor for the fundamental wave according to the Architectural Standard Specifications (Electrical Installation) (2013 revision) supervised by the Ministry of Land, Infrastructure, Transport and Tourism of Japan).</p> <p>(b) This is a sample outline dimension drawing. The shape differs by the model. W1 and D1 indicate distances between installation holes. The installation hole size is indicated by d.</p> <p>(c) When installing an AC reactor (FR-HAL), install in the orientation shown below.          •(H)55K or lower: Horizontal installation or vertical installation          •(H)75K or higher: Horizontal installation</p> <p>(d) Keep enough clearance around the reactor because it heats up. (Keep a clearance of minimum 10cm each on top and bottom and minimum 5cm each on right and left regardless of the installation orientation.)</p> 	Model	W	W1	H	D	D1	d	Mass (kg)	0.4K	104	84	99	72	40	M5	0.6	0.75K	104	84	99	74	44	M5	0.8	1.5K	104	84	99	77	50	M5	1.1	2.2K	115	40	115	77	57	M6	1.5	3.7K	115	40	115	83	67	M6	2.2	5.5K	115	40	115	83	67	M6	2.3	7.5K	130	50	135	100	86	M6	4.2	11K	160	75	164	111	92	M6	5.2	15K	160	75	167	126	107	M6	7.0	18.5K	160	75	128	175	107	M6	7.1	22K	185	75	150	158	87	M6	9.0	30K	185	75	150	168	87	M6	9.7	37K	210	75	175	174	82	M6	12.9	45K	210	75	175	191	97	M6	16.4	55K	210	75	175	201	97	M6	17.4	75K	240	150	210	215.5	109	M8	23	110K	330	170	325	259	127	M10	40	Model	W	W1	H	D	D1	d	Mass (kg)	H0.4K	135	120	115	64	45	M4	1.5	H0.75K	135	120	115	64	45	M4	1.5	H1.5K	135	120	115	64	45	M4	1.5	H2.2K	135	120	115	64	45	M4	1.5	H3.7K	135	120	115	74	57	M4	2.5	H5.5K	160	145	142	76	55	M4	3.5	H7.5K	160	145	142	96	75	M4	5.0	H11K	160	145	146	96	75	M4	6.0	H15K	220	200	195	105	70	M5	9.0	H18.5K	220	200	215	170	70	M5	9.0	H22K	220	200	215	170	70	M5	9.5	H30K	220	200	215	170	75	M5	11	H37K	220	200	214	170	100	M5	12.5	H45K	280	255	245	165	80	M6	15	H55K	280	255	245	170	90	M6	18	H75K	210	75	170	210.5	105	M6	20	H110K	240	150	225	220	99	M8	28	H185K	330	170	325	271	142	M10	55	H280K	330	170	325	321	192	M10	80	H355K	330	170	325	346	192	M10	90	H560K	450	300	540	635	345	M12	190
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<p style="text-align: center;"><b>DC reactor (for power supply coordination) FR-HEL-(H)□K</b></p> 	<p>Improves the power factor and reduces the harmonic current at the input side. Make sure to install this option for the FR-A820-03800(75K) or higher and the FR-A840-02160(75K) or higher. Also install this option when using a motor of 75 kW or higher capacity. (The IP55 compatible model has a built-in DC reactor.)</p> <ul style="list-style-type: none"> <li>• Selection method Select a DC reactor to the inverter terminals according to the applied motor capacity. (Select it according to the motor capacity even if the capacity is smaller than the inverter capacity.) (Refer to <b>page 179</b>.)</li> <li>• Connection diagram Connect a DC reactor to the inverter terminals P1 and P. For the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower, the jumper across terminals P1 and P must be removed. (If the jumper is left attached, no power factor improvement can be obtained.) The connection cable between the reactor and the inverter should be as short as possible (5m or less).</li> </ul> 																																																																																																																																																																																																																																																																																																																																						
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<tr><td>15K</td><td>105</td><td>64</td><td>133</td><td>115</td><td>84</td><td>M6 4.1</td></tr> <tr><td>18.5K</td><td>105</td><td>64</td><td>93</td><td>165</td><td>94</td><td>M6 4.7</td></tr> <tr><td>22K</td><td>105</td><td>64</td><td>93</td><td>175</td><td>104</td><td>M6 5.6</td></tr> <tr><td>30K</td><td>114</td><td>72</td><td>100</td><td>200</td><td>101</td><td>M6 7.8</td></tr> <tr><td>37K</td><td>133</td><td>86</td><td>117</td><td>195</td><td>98</td><td>M6 10</td></tr> <tr><td>45K</td><td>133</td><td>86</td><td>117</td><td>205</td><td>108</td><td>M6 11</td></tr> <tr><td>55K</td><td>153</td><td>126</td><td>132</td><td>209</td><td>122</td><td>M6 12.6</td></tr> <tr><td>75K</td><td>150</td><td>130</td><td>190</td><td>340</td><td>310</td><td>M6 17</td></tr> <tr><td>90K</td><td>150</td><td>130</td><td>200</td><td>340</td><td>310</td><td>M6 19</td></tr> <tr><td>110K</td><td>175</td><td>150</td><td>200</td><td>400</td><td>365</td><td>M8 20</td></tr> </tbody> </table>	Model	W	W1	W1	D	D1	d	Mass (kg)	200 V	0.4K	70	60	71	61	-	M4 0.4	0.75K	85	74	81	61	-	M4 0.5	1.5K	85	74	81	70	-	M4 0.8	2.2K	85	74	81	70	-	M4 0.9	3.7K	77	55	92	82	57	M4 1.5	5.5K	77	55	92	92	67	M4 1.9	7.5K	86	60	113	98	72	M4 2.5	11K	105	64	133	112	79	M6 3.3	15K	105	64	133	115	84	M6 4.1	18.5K	105	64	93	165	94	M6 4.7	22K	105	64	93	175	104	M6 5.6	30K	114	72	100	200	101	M6 7.8	37K	133	86	117	195	98	M6 10	45K	133	86	117	205	108	M6 11	55K	153	126	132	209	122	M6 12.6	75K	150	130	190	340	310	M6 17	90K	150	130	200	340	310	M6 19	110K	175	150	200	400	365	M8 20	<table border="1"> <thead> <tr> <th>Model</th> <th>W</th> <th>W1</th> <th>W1</th> <th>D</th> <th>D1</th> <th>d</th> <th>Mass (kg)</th> </tr> </thead> <tbody> <tr><td rowspan="19">400 V</td><td>H0.4K</td><td>90</td><td>75</td><td>78</td><td>60</td><td>-</td><td>M5 0.6</td></tr> <tr><td>H0.75K</td><td>66</td><td>50</td><td>100</td><td>70</td><td>48</td><td>M4 0.8</td></tr> <tr><td>H1.5K</td><td>66</td><td>50</td><td>100</td><td>80</td><td>54</td><td>M4 1</td></tr> <tr><td>H2.2K</td><td>76</td><td>50</td><td>110</td><td>80</td><td>54</td><td>M4 1.3</td></tr> <tr><td>H3.7K</td><td>86</td><td>55</td><td>120</td><td>95</td><td>69</td><td>M4 2.3</td></tr> <tr><td>H5.5K</td><td>96</td><td>60</td><td>128</td><td>100</td><td>75</td><td>M5 3</td></tr> <tr><td>H7.5K</td><td>96</td><td>60</td><td>128</td><td>105</td><td>80</td><td>M5 3.5</td></tr> <tr><td>H11K</td><td>105</td><td>75</td><td>137</td><td>110</td><td>85</td><td>M5 4.5</td></tr> <tr><td>H15K</td><td>105</td><td>75</td><td>152</td><td>125</td><td>95</td><td>M5 5</td></tr> <tr><td>H18.5K</td><td>114</td><td>75</td><td>162</td><td>120</td><td>80</td><td>M5 5</td></tr> <tr><td>H22K</td><td>133</td><td>90</td><td>178</td><td>120</td><td>75</td><td>M5 6</td></tr> <tr><td>H30K</td><td>133</td><td>90</td><td>178</td><td>120</td><td>80</td><td>M5 6.5</td></tr> <tr><td>H37K</td><td>133</td><td>90</td><td>187</td><td>155</td><td>100</td><td>M5 8.5</td></tr> <tr><td>H45K</td><td>133</td><td>90</td><td>187</td><td>170</td><td>110</td><td>M5 10</td></tr> <tr><td>H55K</td><td>152</td><td>105</td><td>206</td><td>170</td><td>106</td><td>M6 11.5</td></tr> <tr><td>H75K</td><td>140</td><td>120</td><td>185</td><td>320</td><td>295</td><td>M6 16</td></tr> <tr><td>H90K</td><td>150</td><td>130</td><td>190</td><td>340</td><td>310</td><td>M6 20</td></tr> <tr><td>H110K</td><td>150</td><td>130</td><td>195</td><td>340</td><td>310</td><td>M6 22</td></tr> <tr><td>H132K</td><td>175</td><td>150</td><td>200</td><td>405</td><td>370</td><td>M8 26</td></tr> <tr><td>H160K</td><td>175</td><td>150</td><td>205</td><td>405</td><td>370</td><td>M8 28</td></tr> <tr><td>H185K</td><td>175</td><td>150</td><td>240</td><td>405</td><td>370</td><td>M8 29</td></tr> <tr><td>H220K</td><td>175</td><td>150</td><td>240</td><td>405</td><td>370</td><td>M8 30</td></tr> <tr><td>H250K</td><td>190</td><td>165</td><td>250</td><td>440</td><td>400</td><td>M8 35</td></tr> <tr><td>H280K</td><td>190</td><td>165</td><td>255</td><td>440</td><td>400</td><td>M8 38</td></tr> <tr><td>H315K</td><td>210</td><td>185</td><td>250</td><td>495</td><td>450</td><td>M10 42</td></tr> <tr><td>H355K</td><td>210</td><td>185</td><td>250</td><td>495</td><td>450</td><td>M10 46</td></tr> </tbody> </table>	Model	W	W1	W1	D	D1	d	Mass (kg)	400 V	H0.4K	90	75	78	60	-	M5 0.6	H0.75K	66	50	100	70	48	M4 0.8	H1.5K	66	50	100	80	54	M4 1	H2.2K	76	50	110	80	54	M4 1.3	H3.7K	86	55	120	95	69	M4 2.3	H5.5K	96	60	128	100	75	M5 3	H7.5K	96	60	128	105	80	M5 3.5	H11K	105	75	137	110	85	M5 4.5	H15K	105	75	152	125	95	M5 5	H18.5K	114	75	162	120	80	M5 5	H22K	133	90	178	120	75	M5 6	H30K	133	90	178	120	80	M5 6.5	H37K	133	90	187	155	100	M5 8.5	H45K	133	90	187	170	110	M5 10	H55K	152	105	206	170	106	M6 11.5	H75K	140	120	185	320	295	M6 16	H90K	150	130	190	340	310	M6 20	H110K	150	130	195	340	310	M6 22	H132K	175	150	200	405	370	M8 26	H160K	175	150	205	405	370	M8 28	H185K	175	150	240	405	370	M8 29	H220K	175	150	240	405	370	M8 30	H250K	190	165	250	440	400	M8 35	H280K	190	165	255	440	400	M8 38	H315K	210	185	250	495	450	M10 42	H355K	210	185	250	495	450	M10 46
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55K	153	126	132	209	122	M6 12.6																																																																																																																																																																																																																																																																																																																																	
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	H18.5K	114	75	162	120	80	M5 5																																																																																																																																																																																																																																																																																																																																
	H22K	133	90	178	120	75	M5 6																																																																																																																																																																																																																																																																																																																																
	H30K	133	90	178	120	80	M5 6.5																																																																																																																																																																																																																																																																																																																																
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	H45K	133	90	187	170	110	M5 10																																																																																																																																																																																																																																																																																																																																
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	H75K	140	120	185	320	295	M6 16																																																																																																																																																																																																																																																																																																																																
	H90K	150	130	190	340	310	M6 20																																																																																																																																																																																																																																																																																																																																
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H185K	175	150	240	405	370	M8 29																																																																																																																																																																																																																																																																																																																																	
H220K	175	150	240	405	370	M8 30																																																																																																																																																																																																																																																																																																																																	
H250K	190	165	250	440	400	M8 35																																																																																																																																																																																																																																																																																																																																	
H280K	190	165	255	440	400	M8 38																																																																																																																																																																																																																																																																																																																																	
H315K	210	185	250	495	450	M10 42																																																																																																																																																																																																																																																																																																																																	
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<ul style="list-style-type: none"> <li>(a) The size of the cables used should be equal to or larger than that of the power supply cables (R/L1, S/L2, T/L3). (Refer to <b>page 171</b>)</li> <li>(b) Approximately 93% of the power factor improving effect can be obtained (94.4% when calculated with 1 power factor for the fundamental wave according to the Architectural Standard Specifications (Electrical Installation) (2010 revision) supervised by the Ministry of Land, Infrastructure, Transport and Tourism of Japan).</li> <li>(c) This is a sample outline dimension drawing. The shape differs by the model. W1 and D1 indicate distances between installation holes. The installation hole size is indicated by d.</li> <li>(d) When installing a DC reactor (FR-HEL), install in the orientation shown below. •(H)55K or lower: Horizontal installation or vertical installation •(H)75K or higher: Horizontal installation</li> <li>(e) Keep enough clearance around the reactor because it heats up. (Keep a clearance of minimum 10cm each on top and bottom and minimum 5cm each on right and left regardless of the installation orientation.)</li> </ul>																																																																																																																																																																																																																																																																																																																																							

- Features
- Application Example  
PLC Function  
FR Configurator2
- Connection  
Examples
- Standard  
Specs
- Outline  
Dimensions
- Terminal Connection  
Diagrams  
Terminal Specs
- Operation Panel
- Parameter List
- Explanations  
of  
Parameters
- Protective  
Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty  
Inquiry

Name (model)	Specification and structure																																																																																																																																																																						
<p><b>Line noise filter</b> FR-BSF01 (for small capacities) / FR-BLF</p> 	<p>Install an EMC filter (ferrite core) to reduce the electromagnetic noise generated from the inverter. Effective in the range from about 0.5 MHz to 5 MHz. range from about 0.5 MHz to 5 MHz. The FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower are equipped with built-in common mode chokes.</p> <ul style="list-style-type: none"> <li>• Outline dimension</li> </ul> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>FR-BSF01</p>  </div> <div style="text-align: center;"> <p>FR-BLF</p>  </div> </div> <p style="text-align: center;">(Unit: mm)</p> <ol style="list-style-type: none"> <li>Wind each phase for three times (4T) in the same direction. (The greater the number of turns, the more effective result is obtained.) When using several line noise filters to make 4T or more, wind the phases (cables) together. Do not use a different line noise filter for different phases.</li> <li>When the cables are too thick to be wound, run each cable (phase) through four or more filters installed in series in one direction.</li> <li>The filter can be used in the same way as the output side. When using filters at the output side, do not wind the cable more than 3 times (4T) for each filter because the filter may overheat.</li> <li>A thick cable of 38 mm<sup>2</sup> or more is not applicable to the FR-BSF01. Use FR-BLF for a larger diameter cable.</li> <li>Do not wind the earthing (grounding) cable.</li> </ol> <div style="text-align: right;">  </div>																																																																																																																																																																						
<p><b>High-duty brake resistor</b> FR-ABR-(H)[]K</p> 	<p>Improves the braking capability of the inverter built-in brake.</p> <ul style="list-style-type: none"> <li>• Selection method</li> <li>Select the model according to the applied inverter capacity.</li> <li>• Outline dimension</li> </ul> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th rowspan="2">Model : FR-ABR-[]</th> <th rowspan="2">Permissible brake duty</th> <th colspan="4">Outline dimension (mm)</th> <th rowspan="2">Resistance value (Ω)</th> <th rowspan="2">Approx mass (kg)</th> </tr> <tr> <th>W</th> <th>W1</th> <th>D</th> <th>H</th> </tr> </thead> <tbody> <tr> <td rowspan="9" style="writing-mode: vertical-rl; transform: rotate(180deg);">200 V</td> <td>0.4K</td> <td>10%</td> <td>140</td> <td>500</td> <td>40</td> <td>21</td> <td>200</td> <td>0.2</td> </tr> <tr> <td>0.75K</td> <td>10%</td> <td>215</td> <td>500</td> <td>40</td> <td>21</td> <td>100</td> <td>0.4</td> </tr> <tr> <td>2.2K*1</td> <td>10%</td> <td>240</td> <td>500</td> <td>50</td> <td>26</td> <td>60</td> <td>0.5</td> </tr> <tr> <td>3.7K</td> <td>10%</td> <td>215</td> <td>500</td> <td>61</td> <td>33</td> <td>40</td> <td>0.8</td> </tr> <tr> <td>5.5K</td> <td>10%</td> <td>335</td> <td>500</td> <td>61</td> <td>33</td> <td>25</td> <td>1.3</td> </tr> <tr> <td>7.5K</td> <td>10%</td> <td>400</td> <td>500</td> <td>80</td> <td>40</td> <td>20</td> <td>2.2</td> </tr> <tr> <td>11K</td> <td>6%</td> <td>400</td> <td>700</td> <td>100</td> <td>50</td> <td>13</td> <td>3.5</td> </tr> <tr> <td>15K*2</td> <td>6%</td> <td>300</td> <td>700</td> <td>100</td> <td>50</td> <td>18 (×1/2)</td> <td>2.4 (×2)</td> </tr> <tr> <td>22K*3</td> <td>6%</td> <td>400</td> <td>700</td> <td>100</td> <td>50</td> <td>13 (×1/2)</td> <td>3.3 (×2)</td> </tr> <tr> <td rowspan="9" style="writing-mode: vertical-rl; transform: rotate(180deg);">400 V</td> <td>H0.4K</td> <td>10%</td> <td>115</td> <td>500</td> <td>40</td> <td>21</td> <td>1200</td> <td>0.2</td> </tr> <tr> <td>H0.75K</td> <td>10%</td> <td>140</td> <td>500</td> <td>40</td> <td>21</td> <td>700</td> <td>0.2</td> </tr> <tr> <td>H1.5K</td> <td>10%</td> <td>215</td> <td>500</td> <td>40</td> <td>21</td> <td>350</td> <td>0.4</td> </tr> <tr> <td>H2.2K</td> <td>10%</td> <td>240</td> <td>500</td> <td>50</td> <td>26</td> <td>250</td> <td>0.5</td> </tr> <tr> <td>H3.7K</td> <td>10%</td> <td>215</td> <td>500</td> <td>61</td> <td>33</td> <td>150</td> <td>0.8</td> </tr> <tr> <td>H5.5K</td> <td>10%</td> <td>335</td> <td>500</td> <td>61</td> <td>33</td> <td>110</td> <td>1.3</td> </tr> <tr> <td>H7.5K</td> <td>10%</td> <td>400</td> <td>500</td> <td>80</td> <td>40</td> <td>75</td> <td>2.2</td> </tr> <tr> <td>H11K</td> <td>6%</td> <td>400</td> <td>700</td> <td>100</td> <td>50</td> <td>52</td> <td>3.2</td> </tr> <tr> <td>H15K*4</td> <td>6%</td> <td>300</td> <td>700</td> <td>100</td> <td>50</td> <td>18 (×2)</td> <td>2.4 (×2)</td> </tr> <tr> <td>H22K*5</td> <td>6%</td> <td>450</td> <td>700</td> <td>100</td> <td>50</td> <td>52 (×1/2)</td> <td>3.3 (×2)</td> </tr> </tbody> </table> <ol style="list-style-type: none"> <li>For the 1.5K and 2.2K inverter.</li> <li>For the 15K brake resistor, configure so that two 18 Ω resistors are connected in parallel.</li> <li>For the 18.5K and 22K inverter. For the 22K brake resistor, configure so that two 13 Ω resistors are connected in parallel.</li> <li>For the H15K brake resistor, configure so that two 18 Ω resistors are connected in series. FR-ABR-15K is indicated on the resistor. (same resistor as the 200 V class 15K)</li> <li>For the H18.5K and H22K inverter. For the H22K brake resistor, configure so that two 52 Ω resistors are connected in parallel.</li> </ol> <div style="text-align: right;">  </div> <ol style="list-style-type: none"> <li>When using the FR-ABR type brake resistor, remove the jumper across terminal PR-PX. Failure to remove will cause the brake resistor to overheat.</li> <li>The regenerative brake duty setting should be less than permissible brake duty in the table above.</li> <li>The temperature of the brake resistor becomes 300°C or more depending on the operation frequency, care must be taken for installation and heat dissipation.</li> <li>MYS type resistor can be also used. Note the permissible brake duty.</li> <li>Do not remove a jumper across terminal P/+ and P1 except when connecting a DC reactor.</li> <li>Install a thermal relay to prevent an overheat and burnout of the brake resistor.</li> </ol>	Model : FR-ABR-[]	Permissible brake duty	Outline dimension (mm)				Resistance value (Ω)	Approx mass (kg)	W	W1	D	H	200 V	0.4K	10%	140	500	40	21	200	0.2	0.75K	10%	215	500	40	21	100	0.4	2.2K*1	10%	240	500	50	26	60	0.5	3.7K	10%	215	500	61	33	40	0.8	5.5K	10%	335	500	61	33	25	1.3	7.5K	10%	400	500	80	40	20	2.2	11K	6%	400	700	100	50	13	3.5	15K*2	6%	300	700	100	50	18 (×1/2)	2.4 (×2)	22K*3	6%	400	700	100	50	13 (×1/2)	3.3 (×2)	400 V	H0.4K	10%	115	500	40	21	1200	0.2	H0.75K	10%	140	500	40	21	700	0.2	H1.5K	10%	215	500	40	21	350	0.4	H2.2K	10%	240	500	50	26	250	0.5	H3.7K	10%	215	500	61	33	150	0.8	H5.5K	10%	335	500	61	33	110	1.3	H7.5K	10%	400	500	80	40	75	2.2	H11K	6%	400	700	100	50	52	3.2	H15K*4	6%	300	700	100	50	18 (×2)	2.4 (×2)	H22K*5	6%	450	700	100	50	52 (×1/2)	3.3 (×2)
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<p>Provides a braking capability greater than that is provided by an external brake resistor. This option can also be connected to the inverters without built-in brake transistors. Three types of discharging resistors are available. Make a selection according to the required braking torque.</p> <p>• Specification [Brake unit]</p> <p>Model: FR-BU2-□</p> <table border="1"> <thead> <tr> <th rowspan="2">Model: FR-BU2-□</th> <th colspan="6">200 V</th> <th colspan="6">400 V</th> </tr> <tr> <th>1.5K</th><th>3.7K</th><th>7.5K</th><th>15K</th><th>30K</th><th>55K</th> <th>H7.5K</th><th>H15K</th><th>H30K</th><th>H55K</th><th>H75K</th><th>H220K</th><th>H280K</th> </tr> </thead> <tbody> <tr> <td>Applicable motor capacity</td> <td colspan="13">The applicable capacity differs by the braking torque and the operation rate (%ED).</td> </tr> <tr> <td>Connected brake resistor</td> <td colspan="10">GRZG type, FR-BR, MT-BR5 (For the combination, refer to the table below.)</td> <td colspan="2">MT-BR5*1</td> </tr> <tr> <td>Multiple (parallel) driving</td> <td colspan="13">Max. 10 units (However, the torque is limited by the permissible current of the connected inverter.)</td> </tr> <tr> <td>Approximate mass (kg)</td> <td>0.9</td><td>0.9</td><td>0.9</td><td>0.9</td><td>1.4</td><td>2.0</td> <td>0.9</td><td>0.9</td><td>1.4</td><td>2.0</td><td>2.0</td><td>13</td><td>13</td> </tr> </tbody> </table> <p>*1 Please contact your sales representative to use a brake resistor other than MT-BR5. [Resistor unit]</p> <p>Model: GRZG type *2</p> <table border="1"> <thead> <tr> <th rowspan="2">Model: GRZG type *2</th> <th colspan="4">200 V</th> <th colspan="3">400 V</th> </tr> <tr> <th>GZG300W-50Ω (1 unit)</th> <th>GRZG200-10Ω (3 units)</th> <th>GRZG300-5Ω (4 units)</th> <th>GRZG400-2Ω (6 units)</th> <th>GRZG200-10Ω (3 units)</th> <th>GRZG300-5Ω (4 units)</th> <th>GRZG400-2Ω (6 units)</th> </tr> </thead> <tbody> <tr> <td>Number of connectable units</td> <td>1 unit</td> <td>3 in series (1 set)</td> <td>4 in series (1 set)</td> <td>6 in series (1 set)</td> <td>6 in series (2 sets)</td> <td>8 in series (2 sets)</td> <td>12 in series (2 sets)</td> </tr> <tr> <td>Discharging resistor combined resistance (Ω)</td> <td>50</td> <td>30</td> <td>20</td> <td>12</td> <td>60</td> <td>40</td> <td>24</td> </tr> <tr> <td>Continuous operation permissible power (W)</td> <td>100</td> <td>300</td> <td>600</td> <td>1200</td> <td>600</td> <td>1200</td> <td>2400</td> </tr> </tbody> </table> <p>*2 The 1 set contains the number of units in the parentheses. 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For the 400 V class, 2 sets are required. *4 The number next to the model name indicates the number of connectable units in parallel.</p> <p>• Selection method [GRZG type]</p> <ul style="list-style-type: none"> <li>The maximum temperature rise of the discharging resistors is about 100°C. Use heat-resistant wires to perform wiring, and make sure that they will not come in contact with resistors.</li> <li>Do not touch the discharging resistor while the power is ON or for about 10 minutes after the power supply turns OFF. Otherwise you may get an electric shock.</li> </ul> <table border="1"> <thead> <tr> <th rowspan="2">Power supply voltage</th> <th rowspan="2">Braking torque</th> <th colspan="8">Motor capacity</th> </tr> <tr> <th>0.4</th><th>0.75</th><th>1.5</th><th>2.2</th><th>3.7</th><th>5.5</th><th>7.5</th><th>11</th><th>15</th> </tr> </thead> <tbody> <tr> <td rowspan="2">200 V</td> <td>50% 30s</td> <td colspan="3">FR-BU2-1.5K</td> <td colspan="2">FR-BU2-3.7K</td> <td colspan="2">FR-BU2-7.5K</td> <td colspan="2">FR-BU2-15K</td> </tr> <tr> <td>100% 30s</td> <td>FR-BU2-1.5K</td> <td colspan="2">FR-BU2-3.7K</td> <td colspan="2">FR-BU2-7.5K</td> <td colspan="2">FR-BU2-15K</td> <td colspan="2">2×FR-BU2-15K *5</td> </tr> <tr> <td rowspan="2">400 V</td> <td>50% 30s</td> <td colspan="3">--*6</td> <td colspan="3">FR-BU2-H7.5K</td> <td colspan="3">FR-BU2-H15K</td> </tr> <tr> <td>100% 30s</td> <td colspan="3">--*6</td> <td colspan="2">FR-BU2-H7.5K</td> <td colspan="2">FR-BU2-H15K</td> <td colspan="2">FR-BU2-H30K</td> </tr> </tbody> </table> <table border="1"> <thead> <tr> <th rowspan="2">Power supply voltage</th> <th rowspan="2">Braking torque</th> <th colspan="5">Motor capacity</th> </tr> <tr> <th>18.5</th><th>22</th><th>30</th><th>37</th><th>45</th><th>55</th> </tr> </thead> <tbody> <tr> <td rowspan="2">200 V</td> <td>50% 30s</td> <td colspan="3">2×FR-BU2-15K*5</td> <td colspan="2">3×FR-BU2-15K*5</td> <td colspan="1">4×FR-BU2-15K*5</td> </tr> <tr> <td>100% 30s</td> <td>3×FR-BU2-15K*5</td> <td colspan="2">4×FR-BU2-15K*5</td> <td colspan="2">5×FR-BU2-15K*5</td> <td colspan="1">6×FR-BU2-15K*5</td> </tr> <tr> <td rowspan="2">400 V</td> <td>50% 30s</td> <td colspan="3">FR-BU2-H30K</td> <td colspan="2">2×FR-BU2-H30K *5</td> <td colspan="1">4×FR-BU2-H30K*5</td> </tr> <tr> <td>100% 30s</td> <td colspan="3">2×FR-BU2-H30K*5</td> <td colspan="2">3×FR-BU2-H30K *5</td> <td colspan="1">4×FR-BU2-H30K*5</td> </tr> </tbody> </table> <p>*5 The number next to the model name indicates the number of connectable units in parallel. *6 FR-A840-00052(1.5K) or lower capacity inverters cannot be used with brake units. When using brake units with inverters, use the FR-A840-00083(2.2K) or higher capacity inverters.</p>	Model: FR-BU2-□	200 V						400 V						1.5K	3.7K	7.5K	15K	30K	55K	H7.5K	H15K	H30K	H55K	H75K	H220K	H280K	Applicable motor capacity	The applicable capacity differs by the braking torque and the operation rate (%ED).													Connected brake resistor	GRZG type, FR-BR, MT-BR5 (For the combination, refer to the table below.)										MT-BR5*1		Multiple (parallel) driving	Max. 10 units (However, the torque is limited by the permissible current of the connected inverter.)													Approximate mass (kg)	0.9	0.9	0.9	0.9	1.4	2.0	0.9	0.9	1.4	2.0	2.0	13	13	Model: GRZG type *2	200 V				400 V			GZG300W-50Ω (1 unit)	GRZG200-10Ω (3 units)	GRZG300-5Ω (4 units)	GRZG400-2Ω (6 units)	GRZG200-10Ω (3 units)	GRZG300-5Ω (4 units)	GRZG400-2Ω (6 units)	Number of connectable units	1 unit	3 in series (1 set)	4 in series (1 set)	6 in series (1 set)	6 in series (2 sets)	8 in series (2 sets)	12 in series (2 sets)	Discharging resistor combined resistance (Ω)	50	30	20	12	60	40	24	Continuous operation permissible power (W)	100	300	600	1200	600	1200	2400	Model: FR-BR-□	200 V			400 V			Model: MT-BR5-□		15K	30K	55K	H15K	H30K	H55K	200 V 55K	400 V H75K	Discharging resistor combined resistance (Ω)	8	4	2	32	16	8	Discharging resistor combined resistance (Ω)	2	6.5	Continuous operation permissible power (W)	990	1990	3910	990	1990	3910	Continuous operation permissible power (W)	5500	7500	Approximate mass (kg)	15	30	70	15	30	70	Approximate mass (kg)	70	65	Brake unit model	Discharging resistor model or resistor unit model				GRZG type		FR-BR	MT-BR5	Model *3	Number of connectable units	200 V	FR-BU2-1.5K	GZG 300W-50Ω (1 unit)	1 unit	-	-	FR-BU2-3.7K	GRZG 200-10Ω (3 units)	3 in series (1 set)	-	-	FR-BU2-7.5K	GRZG 300-5Ω (4 units)	4 in series (1 set)	-	-	FR-BU2-15K	GRZG 400-2Ω (6 units)	6 in series (1 set)	FR-BR-15K	-	FR-BU2-30K	-	-	FR-BR-30K	-	400 V	FR-BU2-55K	-	-	FR-BR-55K	MT-BR5-55K	FR-BU2-H7.5K	GRZG 200-10Ω (3 units)	6 in series (2 sets)	-	-	FR-BU2-H15K	GRZG 300-5Ω (4 units)	8 in series (2 sets)	FR-BR-H15K	-	FR-BU2-H30K	GRZG 400-2Ω (6 units)	12 in series (2 sets)	FR-BR-H30K	-	FR-BU2-H55K	-	-	FR-BR-H55K	-	FR-BU2-H75K	-	-	-	MT-BR5-H75K	FR-BU2-H220K	-	-	-	3×MT-BR5-H75K *4	FR-BU2-H280K	-	-	-	4×MT-BR5-H75K *4	Power supply voltage	Braking torque	Motor capacity								0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	200 V	50% 30s	FR-BU2-1.5K			FR-BU2-3.7K		FR-BU2-7.5K		FR-BU2-15K		100% 30s	FR-BU2-1.5K	FR-BU2-3.7K		FR-BU2-7.5K		FR-BU2-15K		2×FR-BU2-15K *5		400 V	50% 30s	--*6			FR-BU2-H7.5K			FR-BU2-H15K			100% 30s	--*6			FR-BU2-H7.5K		FR-BU2-H15K		FR-BU2-H30K		Power supply voltage	Braking torque	Motor capacity					18.5	22	30	37	45	55	200 V	50% 30s	2×FR-BU2-15K*5			3×FR-BU2-15K*5		4×FR-BU2-15K*5	100% 30s	3×FR-BU2-15K*5	4×FR-BU2-15K*5		5×FR-BU2-15K*5		6×FR-BU2-15K*5	400 V	50% 30s	FR-BU2-H30K			2×FR-BU2-H30K *5		4×FR-BU2-H30K*5	100% 30s	2×FR-BU2-H30K*5			3×FR-BU2-H30K *5		4×FR-BU2-H30K*5
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	FR-BU2-3.7K	GRZG 200-10Ω (3 units)	3 in series (1 set)	-	-																																																																																																																																																																																																																																																																																																																																																								
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	FR-BU2-H220K	-	-	-	3×MT-BR5-H75K *4																																																																																																																																																																																																																																																																																																																																																								
	FR-BU2-H280K	-	-	-	4×MT-BR5-H75K *4																																																																																																																																																																																																																																																																																																																																																								
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Brake unit  
FR-BU2-(H)□K  
Discharging resistor  
GRZG type  
Resistor unit  
FR-BR-(H)□K  
MT-BR5-(H)□K




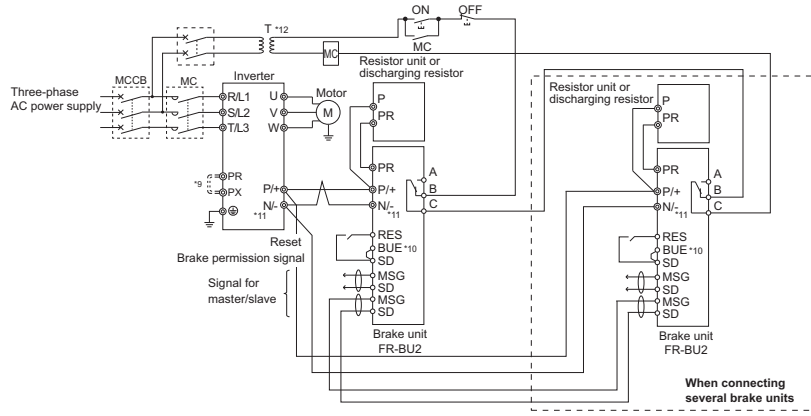
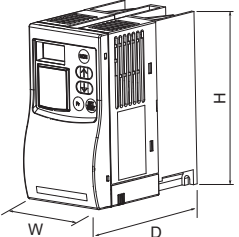
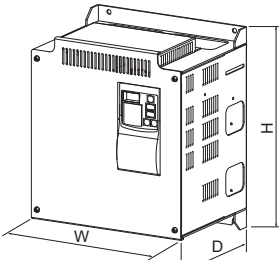
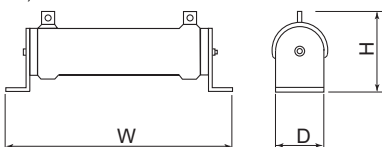
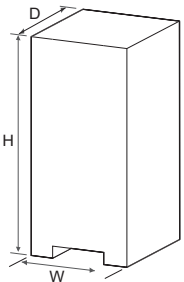
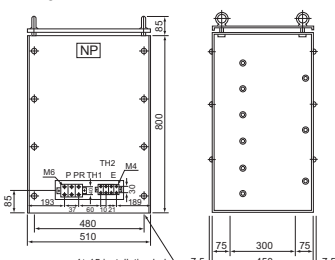
Features  
Application Example  
FR Configurator 2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LV/S/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry



Name (model)	Specification and structure																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																		
<p><b>Brake unit</b> FR-BU2-(H)□□K</p> <p><b>Discharging resistor</b> GZG type GRZG type</p> <p><b>Resistor unit</b> FR-BR-(H)□□K MT-BR5-(H)□□K</p> 	<p>[FR-BR] The maximum temperature rise of the resistor unit is about 100°C. Therefore, use heat-resistant wires (such as glass wires).</p> <p>%ED at short-time rating when braking torque is 100%</p> <table border="1" style="width: 100%; text-align: center;"> <thead> <tr> <th colspan="2" rowspan="2">Model</th> <th colspan="10">Motor capacity</th> </tr> <tr> <th>5.5kW</th><th>7.5kW</th><th>11kW</th><th>15kW</th><th>18.5kW</th><th>22kW</th><th>30kW</th><th>37kW</th><th>45kW</th><th>55kW</th> </tr> </thead> <tbody> <tr> <td rowspan="3">200 V</td> <td>FR-BU2-15K</td> <td rowspan="3">%ED</td> <td>80</td><td>40</td><td>15</td><td>10</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-30K</td> <td>-</td><td>-</td><td>65</td><td>30</td><td>25</td><td>15</td><td>10</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-55K</td> <td>-</td><td>-</td><td>-</td><td>-</td><td>90</td><td>60</td><td>30</td><td>20</td><td>15</td><td>10</td> </tr> <tr> <td rowspan="3">400 V</td> <td>FR-BU2-H15K</td> <td rowspan="3">%ED</td> <td>80</td><td>40</td><td>15</td><td>10</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-H30K</td> <td>-</td><td>-</td><td>65</td><td>30</td><td>25</td><td>15</td><td>10</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-H55K</td> <td>-</td><td>-</td><td>-</td><td>-</td><td>90</td><td>60</td><td>30</td><td>20</td><td>15</td><td>10</td> </tr> </tbody> </table> <p>Braking torque (%) at 10%ED in short-time rating of 15 s</p> <table border="1" style="width: 100%; text-align: center;"> <thead> <tr> <th colspan="2" rowspan="2">Model</th> <th colspan="10">Motor capacity</th> </tr> <tr> <th>5.5kW</th><th>7.5kW</th><th>11kW</th><th>15kW</th><th>18.5kW</th><th>22kW</th><th>30kW</th><th>37kW</th><th>45kW</th><th>55kW</th> </tr> </thead> <tbody> <tr> <td rowspan="3">200 V</td> <td>FR-BU2-15K</td> <td rowspan="3">Braking torque (%)</td> <td>280</td><td>200</td><td>120</td><td>100</td><td>80</td><td>70</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-30K</td> <td>-</td><td>-</td><td>260</td><td>180</td><td>160</td><td>130</td><td>100</td><td>80</td><td>70</td><td>-</td> </tr> <tr> <td>FR-BU2-55K</td> <td>-</td><td>-</td><td>-</td><td>-</td><td>300</td><td>250</td><td>180</td><td>150</td><td>120</td><td>100</td> </tr> <tr> <td rowspan="3">400 V</td> <td>FR-BU2-H15K</td> <td rowspan="3">Braking torque (%)</td> <td>280</td><td>200</td><td>120</td><td>100</td><td>80</td><td>70</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>FR-BU2-H30K</td> <td>-</td><td>-</td><td>260</td><td>180</td><td>160</td><td>130</td><td>100</td><td>80</td><td>70</td><td>-</td> </tr> <tr> <td>FR-BU2-H55K</td> <td>-</td><td>-</td><td>-</td><td>-</td><td>300</td><td>250</td><td>180</td><td>150</td><td>120</td><td>100</td> </tr> </tbody> </table> <p style="text-align: center;">Regeneration duty factor (operation frequency)%ED = <math>\frac{t_b}{t_c} \times 100</math>    <math>t_b &lt; 15s</math> (continuous operation time)</p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>Example 1 Travel operation</p> </div> <div style="text-align: center;"> <p>Example 2 Lift operation</p> <p><math>t_b = t_1 + t_2 + t_3 + t_4</math></p> </div> </div> <p>[MT-BR5]</p> <ul style="list-style-type: none"> <li>• Be sure to select a well-ventilated place for the installation of the resistor unit. Ventilation is necessary when installing the resistor in a place such as an enclosure, where heat is not well diffused.</li> <li>• The maximum temperature rise of the resistor unit is about 300deg. When wiring, be careful not to touch the resistor. Also, keep any heat-sensitive component away from the resistor (minimum 40 to 50 cm).</li> <li>• The temperature of the resistor unit abnormally increases if the brake unit is operated exceeding the specified duty. Since the resistor unit may result in overheat if the temperature of the brake unit is left unchanged, switch off the inverter.</li> <li>• A resistor unit is equipped with thermostat (NO contact) for overheat protection. If this protective thermostat activates in normal operation, the deceleration time may be too short. Set the inverter's deceleration time longer.</li> </ul> <p>%ED at short-time rating when braking torque is 100%</p> <table border="1" style="width: 100%; text-align: center;"> <thead> <tr> <th rowspan="2">Number of connectable units*7</th> <th colspan="16">Motor capacity</th> </tr> <tr> <th>75 kW</th><th>90 kW</th><th>110 kW</th><th>132 kW</th><th>160 kW</th><th>185 kW</th><th>220 kW</th><th>250 kW</th><th>280 kW</th><th>315 kW</th><th>355 kW</th><th>375 kW</th><th>400 kW</th><th>450 kW</th><th>500 kW</th><th>560 kW</th> </tr> </thead> <tbody> <tr> <td rowspan="2">200 V FR-BU2-55K</td> <td>1</td><td>5</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>20</td><td>15</td><td>10</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H75K</td> <td>1</td><td>10</td><td>5</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>40</td><td>25</td><td>20</td><td>10</td><td>5</td><td>5</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H220K</td> <td>1</td><td>80</td><td>60</td><td>40</td><td>25</td><td>15</td><td>10</td><td>10</td><td>5</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>20</td><td>20</td><td>15</td><td>15</td><td>10</td><td>10</td><td>10</td><td>5</td><td>-</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H280K</td> <td>1</td><td>-</td><td>80</td><td>65</td><td>40</td><td>30</td><td>20</td><td>15</td><td>10</td><td>10</td><td>5</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>20</td><td>20</td><td>15</td><td>15</td><td>15</td><td>10</td><td>10</td> </tr> </tbody> </table> <p>Braking torque (%) in short-time rating of 15 s</p> <table border="1" style="width: 100%; text-align: center;"> <thead> <tr> <th rowspan="2">Number of connectable units*7</th> <th colspan="16">Motor capacity</th> </tr> <tr> <th>75 kW</th><th>90 kW</th><th>110 kW</th><th>132 kW</th><th>160 kW</th><th>185 kW</th><th>220 kW</th><th>250 kW</th><th>280 kW</th><th>315 kW</th><th>355 kW</th><th>375 kW</th><th>400 kW</th><th>450 kW</th><th>500 kW</th><th>560 kW</th> </tr> </thead> <tbody> <tr> <td rowspan="2">200 V FR-BU2-55K</td> <td>1</td><td>70</td><td>60</td><td>50</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>150</td><td>120</td><td>100</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H75K</td> <td>1</td><td>100</td><td>80</td><td>70</td><td>55</td><td>45</td><td>40</td><td>35</td><td>-</td><td>25</td><td>-</td><td>-</td><td>20</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>150</td><td>150</td><td>135</td><td>110</td><td>90</td><td>80</td><td>70</td><td>60</td><td>50</td><td>45</td><td>40</td><td>40</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H220K</td> <td>1</td><td>-</td><td>-</td><td>150</td><td>150</td><td>135</td><td>115</td><td>100</td><td>80</td><td>55</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>150</td><td>150</td><td>140</td><td>120</td><td>110</td><td>100</td><td>90</td> </tr> <tr> <td rowspan="2">400 V FR-BU2-H280K</td> <td>1</td><td>-</td><td>-</td><td>-</td><td>-</td><td>150</td><td>150</td><td>150</td><td>125</td><td>100</td><td>70</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td> </tr> <tr> <td>2</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>150</td><td>150</td><td>130</td><td>115</td> </tr> </tbody> </table> <p>*7 The number next to the model name indicates the number of connectable units in parallel. *8 To obtain a large braking torque, the motor has to have a torque characteristic that meets the braking torque. Check the torque characteristic of the motor.</p>	Model		Motor capacity										5.5kW	7.5kW	11kW	15kW	18.5kW	22kW	30kW	37kW	45kW	55kW	200 V	FR-BU2-15K	%ED	80	40	15	10	-	-	-	-	-	-	FR-BU2-30K	-	-	65	30	25	15	10	-	-	-	FR-BU2-55K	-	-	-	-	90	60	30	20	15	10	400 V	FR-BU2-H15K	%ED	80	40	15	10	-	-	-	-	-	-	FR-BU2-H30K	-	-	65	30	25	15	10	-	-	-	FR-BU2-H55K	-	-	-	-	90	60	30	20	15	10	Model		Motor capacity										5.5kW	7.5kW	11kW	15kW	18.5kW	22kW	30kW	37kW	45kW	55kW	200 V	FR-BU2-15K	Braking torque (%)	280	200	120	100	80	70	-	-	-	-	FR-BU2-30K	-	-	260	180	160	130	100	80	70	-	FR-BU2-55K	-	-	-	-	300	250	180	150	120	100	400 V	FR-BU2-H15K	Braking torque (%)	280	200	120	100	80	70	-	-	-	-	FR-BU2-H30K	-	-	260	180	160	130	100	80	70	-	FR-BU2-H55K	-	-	-	-	300	250	180	150	120	100	Number of connectable units*7	Motor capacity																75 kW	90 kW	110 kW	132 kW	160 kW	185 kW	220 kW	250 kW	280 kW	315 kW	355 kW	375 kW	400 kW	450 kW	500 kW	560 kW	200 V FR-BU2-55K	1	5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	2	20	15	10	-	-	-	-	-	-	-	-	-	-	-	-	400 V FR-BU2-H75K	1	10	5	-	-	-	-	-	-	-	-	-	-	-	-	-	2	40	25	20	10	5	5	-	-	-	-	-	-	-	-	-	400 V FR-BU2-H220K	1	80	60	40	25	15	10	10	5	-	-	-	-	-	-	-	2	-	-	-	-	-	-	20	20	15	15	10	10	10	5	-	400 V FR-BU2-H280K	1	-	80	65	40	30	20	15	10	10	5	-	-	-	-	-	2	-	-	-	-	-	-	-	-	20	20	15	15	15	10	10	Number of connectable units*7	Motor capacity																75 kW	90 kW	110 kW	132 kW	160 kW	185 kW	220 kW	250 kW	280 kW	315 kW	355 kW	375 kW	400 kW	450 kW	500 kW	560 kW	200 V FR-BU2-55K	1	70	60	50	-	-	-	-	-	-	-	-	-	-	-	-	2	150	120	100	-	-	-	-	-	-	-	-	-	-	-	-	400 V FR-BU2-H75K	1	100	80	70	55	45	40	35	-	25	-	-	20	-	-	-	2	150	150	135	110	90	80	70	60	50	45	40	40	-	-	-	400 V FR-BU2-H220K	1	-	-	150	150	135	115	100	80	55	-	-	-	-	-	-	2	-	-	-	-	-	-	-	-	150	150	140	120	110	100	90	400 V FR-BU2-H280K	1	-	-	-	-	150	150	150	125	100	70	-	-	-	-	-	2	-	-	-	-	-	-	-	-	-	-	-	150	150	130	115
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200 V FR-BU2-55K	1	70	60	50	-	-	-	-	-	-	-	-	-	-	-	-																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																			
	2	150	120	100	-	-	-	-	-	-	-	-	-	-	-	-																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																			
400 V FR-BU2-H75K	1	100	80	70	55	45	40	35	-	25	-	-	20	-	-	-																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																			
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400 V FR-BU2-H220K	1	-	-	150	150	135	115	100	80	55	-	-	-	-	-	-																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																			
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400 V FR-BU2-H280K	1	-	-	-	-	150	150	150	125	100	70	-	-	-	-	-																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																			
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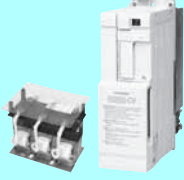
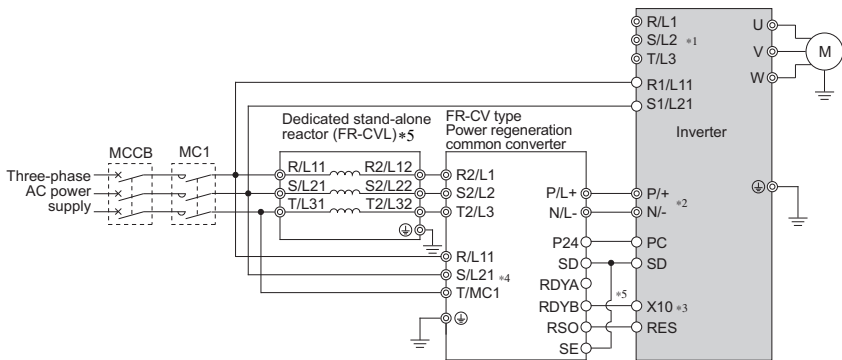
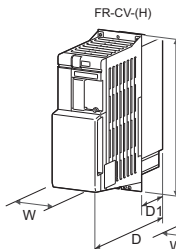
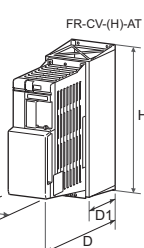
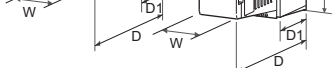
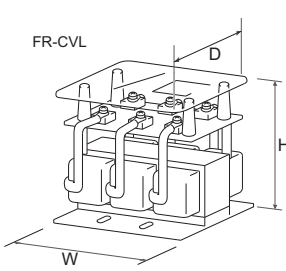




Name (model)	Specification and structure																																																																																
<p><b>Brake unit</b> FR-BU2-(H)□K</p> <p><b>Discharging resistor</b> GZG type GRZG type</p> <p><b>Resistor unit</b> FR-BR-(H)□K MT-BR5-(H)□K</p> 	<p>• Connection diagram</p>  <p>*9 When using the FR-BU2 with the FR-A820-00490(7.5K) or lower and the FR-A840-00250(7.5K) or lower inverters, be sure to remove the jumper across terminals PR and PX.</p> <p>*10 A jumper is connected across BUE and SD in the initial status.</p> <p>*11 When wiring, make sure to match the terminal symbol (P/+, N/-) at the inverter side and at the brake unit (FR-BU2) side. Incorrect connection will damage the inverter. (For the FR-A820-00770(15K) to 02150(22K), and the FR-A840-00470(18.5K) to 01800(55K), use terminals P3 and N/-.) Do not remove the jumper across terminal P/+ and P1 except for connecting the DC reactor.</p> <p>*12 When the power supply is 400 V class, install a step-down transformer.</p> <p>• Outline dimensions &lt;FR-BU2&gt;</p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;">  <p>FR-BU2-1.5K to 55K FR-BU2-H7.5K to H75K</p> </div> <div style="text-align: center;">  <p>FR-BU2-H220K, H280K</p> </div> </div> <table border="1" data-bbox="973 940 1460 1176"> <thead> <tr> <th>Model</th> <th>W</th> <th>H</th> <th>D</th> </tr> </thead> <tbody> <tr> <td>FR-BU2-1.5K to 15K</td> <td>68</td> <td>128</td> <td>132.5</td> </tr> <tr> <td>FR-BU2-30K</td> <td>108</td> <td>128</td> <td>129.5</td> </tr> <tr> <td>FR-BU2-55K</td> <td>170</td> <td>128</td> <td>142.5</td> </tr> <tr> <td>FR-BU2-H7.5K, H15K</td> <td>68</td> <td>128</td> <td>132.5</td> </tr> <tr> <td>FR-BU2-H30K</td> <td>108</td> <td>128</td> <td>129.5</td> </tr> <tr> <td>FR-BU2-H55K, H75K</td> <td>170</td> <td>128</td> <td>142.5</td> </tr> <tr> <td>FR-BU2-H220K, H280K</td> <td>250</td> <td>300</td> <td>200</td> </tr> </tbody> </table> <p style="text-align: right;">(Unit: mm)</p> <p>&lt;GZG, GRZG&gt;</p> <div style="display: flex; justify-content: space-around;">  <table border="1" data-bbox="981 1254 1332 1400"> <thead> <tr> <th>Model</th> <th>W</th> <th>H</th> <th>D</th> </tr> </thead> <tbody> <tr> <td>GZG300W</td> <td>335</td> <td>78</td> <td>40</td> </tr> <tr> <td>GRZG200</td> <td>306</td> <td>55</td> <td>26</td> </tr> <tr> <td>GRZG300</td> <td>334</td> <td>79</td> <td>40</td> </tr> <tr> <td>GRZG400</td> <td>411</td> <td>79</td> <td>40</td> </tr> </tbody> </table> </div> <p style="text-align: right;">(Unit: mm)</p> <p>&lt;FR-BR&gt;</p> <div style="text-align: center;">  <table border="1" data-bbox="981 1478 1364 1680"> <thead> <tr> <th>Model</th> <th>W</th> <th>H</th> <th>D</th> </tr> </thead> <tbody> <tr> <td>FR-BR-15K</td> <td>170</td> <td>450</td> <td>220</td> </tr> <tr> <td>FR-BR-30K</td> <td>340</td> <td>600</td> <td>220</td> </tr> <tr> <td>FR-BR-55K</td> <td>480</td> <td>700</td> <td>450</td> </tr> <tr> <td>FR-BR-H15K</td> <td>170</td> <td>450</td> <td>220</td> </tr> <tr> <td>FR-BR-H30K</td> <td>340</td> <td>600</td> <td>220</td> </tr> <tr> <td>FR-BR-H55K</td> <td>480</td> <td>700</td> <td>450</td> </tr> </tbody> </table> <p style="text-align: right;">(Unit: mm)</p> </div> <p>&lt;MT-BR5&gt;</p> <div style="text-align: center;">  </div>	Model	W	H	D	FR-BU2-1.5K to 15K	68	128	132.5	FR-BU2-30K	108	128	129.5	FR-BU2-55K	170	128	142.5	FR-BU2-H7.5K, H15K	68	128	132.5	FR-BU2-H30K	108	128	129.5	FR-BU2-H55K, H75K	170	128	142.5	FR-BU2-H220K, H280K	250	300	200	Model	W	H	D	GZG300W	335	78	40	GRZG200	306	55	26	GRZG300	334	79	40	GRZG400	411	79	40	Model	W	H	D	FR-BR-15K	170	450	220	FR-BR-30K	340	600	220	FR-BR-55K	480	700	450	FR-BR-H15K	170	450	220	FR-BR-H30K	340	600	220	FR-BR-H55K	480	700	450
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Features	Application Example PLC Function FR Configurator2
Connection Examples	Standard Specs
Standard Specs	Outline Dimensions
Terminal Connection Diagrams	Terminal Specs
Operation Panel	Parameter List
Explanations of Parameters	Protective Functions
Options	LVS/Cables
Precautions	Motors
Compatibility	Warranty Inquiry




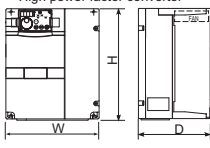
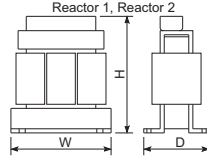
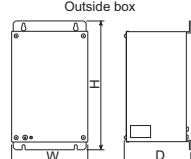
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<p><b>Power regeneration common converter FR-CV-(H)□K</b></p> 	<p>Enables continuous regenerative operation at 100% torque. This option can support continuous regenerative operations including line operation.</p> <p>This converter eliminates the need of preparing brake units per inverter. This converter can cut down the total space and the cost. The regenerated energy is used by another inverter, and if there is still an excess, it is returned to the power supply, saving on the energy consumption.</p> <ul style="list-style-type: none"> <li>• Selection method Select the model according to capacity of the inverter or the applicable motor, whichever larger.</li> <li>• Connection diagram</li> </ul>																																																																	
																																																																		
	<ul style="list-style-type: none"> <li>*1 Remove the jumpers across R/L1 and R/L11 and across S/L2 and S1/L21, and connect the power supply for the control circuit to the terminals R1/L11 and S1/L21. Do not connect anything to the power supply input terminals R/L1, S/L2, and T/L3. Incorrect connection will damage the inverter. Connecting the opposite polarity of terminals N/- and P/+ will damage the inverter.</li> <li>*2 Do not install an MCCB for the terminals P/+ and N/- (between terminals P/+ and P/+ or between N/- and N/-). Always match the terminal symbols (P/+, N/-) at the inverter side and at the power regeneration common converter side. Incorrect connection will damage the inverter.</li> <li>*3 Assign the X10 signal to a terminal using any of <b>Pr.178 to Pr.189 (input terminal function selection)</b>.</li> <li>*4 Be sure to connect the power supply and terminals R/L11, S/L21, and T/MC1. Operating the inverter without connecting them will damage the power regeneration common converter.</li> <li>*5 Install the dedicated stand-alone reactor (FR-CVL) on a horizontal surface.</li> <li>*6 Always connect terminal RDYB of the FR-CV to the inverter terminal where the X10 signal or the MRS signal is assigned to. Always connect terminal SE of the FR-CV to the inverter terminal SD. Not connecting these terminals may damage the FR-CV.</li> </ul>																																																																	
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<p style="text-align: center;"><b>Power regeneration converter MT-RC-H[K]</b></p>	<p>A power regeneration converter allows energy generated at braking operation of the inverter to be regenerated to the power supply. Since a converter does not require a discharging resistor necessary like a brake unit, it is effective in space and energy saving and it provides a large peak braking torque.</p> <ul style="list-style-type: none"> <li>• Selection method</li> <li>• Select the model according to the applied motor capacity.</li> <li>• Connection diagram</li> </ul>																																																						
	<p>• Outline dimension (Unit: mm)</p> <div style="display: flex; justify-content: space-around;"> <div data-bbox="414 828 638 1265"> <p><b>MT-RC-H75K</b></p> </div> <div data-bbox="654 828 925 1265"> <p><b>MT-RC-H160K to H280K</b></p> </div> </div>																																																						
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Features  
Application Example  
PLC Function  
FR Configurator 2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LV/SCables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry



Name (model)	Specification and structure																
<p><b>High power factor converter FR-HC2- (H)□K</b></p> 	<p>Substantially suppresses power harmonics to obtain the equivalent capacity conversion coefficient <math>K5 = 0</math> specified in "the Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage" in Japan.                      The power regeneration function comes standard.                      The common converter driving with several inverters is possible.</p> <ul style="list-style-type: none"> <li>• Selection method                              Select the model according to capacity of the inverter or the applicable motor, whichever larger.</li> <li>• Specifications</li> </ul>																
	<b>Model: FR-HC2-□ *2</b>	<b>200 V</b>					<b>400 V</b>										
	<b>Applicable inverter capacity (ND rating)*1</b>	3.7K to 7.5K	7.5K to 15K	15K to 30K	30K to 55K	37K to 75K	3.7K to 7.5K	7.5K to 15K	15K to 30K	30K to 55K	37K to 75K	55K to 110K	90K to 160K	110K to 220K	160K to 280K	200K to 400K	280K to 560K
	<b>Rated input voltage/frequency</b>	Three-phase 200 V to 220 V 50 Hz 200 V to 230 V 60 Hz					Three-phase 380 V to 460 V 50/60 Hz										
	<b>Rated input current (A)</b>	33	61	115	215	278	17	31	57	110	139	203	290	397	506	716	993
	<p>*1 The total capacity of the connected inverters.                      *2 If a high power factor converter (FR-HC2) is purchased, it comes with reactor 1 (FR-HCL21), reactor 2 (FR-HCL22), and an outside box (FR-HCB2). Do not connect the DC reactor to the inverter when using a high power factor converter.                      (If an H280K or higher is purchased, it comes with FR-HCL21, FR-HCL22, FR-HCC2, FR-HCR2, and FR-HCM2.)</p>																
	<p>• Outline dimension (Unit: mm)</p>																
	<b>Voltage</b>	<b>Capacity</b>	<b>High power factor converter FR-HC2</b>			<b>Reactor 1 FR-HCL21*3</b>			<b>Reactor 2 FR-HCL22*3</b>			<b>Outside box FR-HCB2*4</b>					
			<b>W</b>	<b>H</b>	<b>D</b>	<b>W</b>	<b>H</b>	<b>D</b>	<b>W</b>	<b>H</b>	<b>D</b>	<b>W</b>	<b>H</b>	<b>D</b>			
	<b>200 V</b>	<b>7.5K</b>	220	260	170	132	150	100	237.5	230	140	190	320	165			
<b>15K</b>		250	400	190	162	172	126	257.5	260	165							
<b>30K</b>		325	550	195	195	210	150	342.5	305	180	270	450	203				
<b>55K</b>		370	620	250	210	180	200.5	432.5	380	280							
<b>75K</b>		465	620	300	240	215	215.5	474	460	280				400	450	250	
<b>400 V</b>	<b>H7.5K</b>	220	300	190	132	140	100	237.5	220	140	190	320	165				
	<b>H15K</b>	220	300	190	162	170	126	257.5	260	165							
	<b>H30K</b>	325	550	195	182	195	101	342.5	300	180							
	<b>H55K</b>	370	670	250	282.5	245	165	392.5	365	200	270	450	203				
	<b>H75K</b>	325	620	250	210	175	210.5	430	395	280	300	350	250				
	<b>H110K</b>	465	620	300	240	230	220	500	440	370	350	450	380				
	<b>H160K</b>	498	1010	380	280	295	274.5	560	520	430	400	450	440				
	<b>H220K</b>	498	1010	380	330	335	289.5	620	620	480							
	<b>H280K</b>	680	1010	380	330	335	321	690	700	560	-	-	-				
	<b>H400K</b>	790	1330	440	402	460	550	632	675	705	-	-	-				
<b>H560K</b>	790	1330	440	452	545	645	632	720	745	-	-	-					
<div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div style="text-align: center;"> <p>High power factor converter</p>  </div> <div style="text-align: center;"> <p>Reactor 1, Reactor 2</p>  </div> <div style="text-align: center;"> <p>Outside box</p>  </div> </div> <p>*3 Install reactors (FR-HCL21 and 22) on a horizontal surface.                      *4 The H280K or higher are not equipped with FR-HCB2. A filter capacitor and inrush current limit resistors are provided instead.</p>																	



Name (model)	Specification and structure																																																																																																																					
<b>Surge voltage suppression filter FR-ASF-HJK</b>	A surge voltage suppression filter limits surge voltage applied to motor terminals when driving the 400 V class motor by the inverter. <ul style="list-style-type: none"> <li>• Selection method</li> <li>• Select the model according to the applied motor capacity.</li> <li>• Specifications</li> </ul>																																																																																																																					
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Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry





Name (model)	Specification and structure								
<p><b>Surge voltage suppression filter FR-BMF-HJK</b></p>	Limits surge voltage applied to motor terminals when driving a 400 V class motor with an inverter. This filter is compatible with the 5.5 to 37 kW motors.								
	• Selection method Select the model according to the applied motor capacity.								
	• Specifications								
	<b>Model: FR-BMF-HJK</b>	<b>7.5</b>		<b>15</b>		<b>22</b>		<b>37</b>	
	<b>Applicable motor capacity (kW) *1</b>	5.5	7.5	11	15	18.5	22	30	37
	<b>Rated current (A)</b>	17		31		43		71	
	<b>Overload current rating*2</b>	150% 60 s, 200% 0.5 s (inverse-time characteristics)							
	<b>Rated AC input voltage*2</b>	Three-phase 380 to 480 V							
	<b>Permissible AC voltage fluctuation*2</b>	323 to 528 V							
	<b>Maximum frequency*2</b>	120 Hz							
	<b>PWM carrier frequency</b>	2 kHz or lower*3							
	<b>Protective structure (JEM 1030)</b>	Open type (IP00)							
	<b>Cooling system</b>	Self-cooling							
	<b>Maximum wiring length</b>	100m or lower							
	<b>Approx. mass (kg)</b>	5.5		9.5		11.5		19	
<b>Environment</b>	<b>Surrounding air temperature</b>	-10°C to +50°C (non-freezing)							
	<b>Surrounding air humidity</b>	90% RH or less (non-condensing)							
	<b>Atmosphere</b>	Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt, etc.)							
	<b>Altitude/vibration</b>	Maximum 1000 m above sea level, 5.9 m/s <sup>2</sup> or less*4 at 10 to 55 Hz (directions of X, Y, Z axes)							
*1 Indicates the maximum capacity applicable with the Mitsubishi 4-pole standard motor. (PM motors are not applicable.)									
*2 Determined by the specification of the connected inverter (400 V class).									
*3 Set the <b>Pr.72 PWM frequency selection</b> to 2 kHz or less.									
*4 When an inverter has a filter mounted on its back, do not use such an inverter on a moving object or in a place that vibrates (exceeding 1.96 m/s <sup>2</sup> ).									
• Connection diagram									
<p style="text-align: center;">* Install a step-down transformer.</p>									
• Outline dimension									
<b>FR-BMF-H7.5K</b>		<b>FR-BMF-H15K, H22K</b>			<b>FR-BMF-H37K</b>				
<p style="text-align: right;">(Unit: mm)</p>		<p style="text-align: right;">(Unit: mm)</p>			<p style="text-align: right;">(Unit: mm)</p>				



Name (model)	Specification and structure																																																																																																																																											
<p><b>Sine wave filter</b> MT-BSL-(H)□K MT-BSC-(H)□K</p>	<p>• Sine wave filter application A sine wave filter can be installed to adjust the motor voltage and current waveforms to be sine waves. Install a sine wave filter to the output side of the inverter. This filter is compatible with the FR-A820-03800(75K) or higher and the FR-A840-02160(75K) or higher. (This product is available only with general-purpose motors.) A sine wave filter will bring operation characteristic equivalent to the operation with a sine wave power supply and also will provide the following benefits. A sine wave filter will bring operation characteristic equivalent to the operation with a sine wave power supply and also will provide the following benefits.</p> <p>(a) Low noise (b) No surge current (c) Small motor losses (for a standard motor)</p> <p>• Operating condition The following settings and conditions are required to use a sine wave filter.</p> <p>(a) Set "25" in Pr.72. (The initial value is "2".) This setting changes the carrier frequency to 2.5 kHz. (A sine wave filter is designed on the assumption of 2.5 kHz carrier frequency. Always change this setting.) The operation with Pr.72 = "25" setting may damage inverter and the sine wave filter.</p> <p>(b) A sine wave filter can be used for the operation with an inverter output frequency of 60 Hz or lower. It cannot be used for the operation with higher frequency. (Using it with the higher frequency will increase the filter loss.)</p> <p>(c) It is applicable only under V/F control. (When Pr.72 = "25", V/F control is automatically set.)</p> <p>(d) When using the sine wave filter and the FR-HC2 together, use the MT-BSL-HC.</p> <p>• Circuit configuration and connection</p> <p>* Install the filter near the inverter. For a capacitor cable, use a cable with size larger than indicated in the table below "recommended cable size".</p>																																																																																																																																											
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Application Example  
PLC Function  
FR Configurator2  
Connection  
Examples  
Standard  
Specs  
Outline  
Dimensions  
Terminal Connection  
Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations  
of  
Parameters  
Protective  
Functions  
Options  
LV/SCables  
Precautions  
Motors  
Compatibility  
Warranty  
Inquiry

● Dedicated cable option

Name (model)	Specification and structure																										
Encoder cable FR-V7CBL□	<p>• For dedicated motors</p> <p>• A shield earthing (grounding) P-clip is included.</p>																										
	<p>Positioning guide (key groove)</p> <p>D/MS3106B20-29S (As viewed from wiring side)</p> <table border="1"> <thead> <tr> <th>Model</th> <th>Length L (m)</th> </tr> </thead> <tbody> <tr> <td>FR-V7CBL5</td> <td>5</td> </tr> <tr> <td>FR-V7CBL15</td> <td>15</td> </tr> <tr> <td>FR-V7CBL30</td> <td>30</td> </tr> </tbody> </table> <p>• For cables of 30 m or longer, contact your sales representative.</p>	Model	Length L (m)	FR-V7CBL5	5	FR-V7CBL15	15	FR-V7CBL30	30																		
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<p>• Cable fabrication specifications</p> <p>When option connection cables are not available, fabricate cables according to the following table. Use parallel connection or a large-gauge cable for wiring between the terminals "PG" and "SD" and the motor end encoder. (For cables for other terminals, use cables 0.2 mm<sup>2</sup>.)</p>																											
<table border="1"> <thead> <tr> <th rowspan="2">Wiring distance</th> <th rowspan="2">Options dedicated encoder cable</th> <th colspan="2">Cable gauge for terminals PG and SD</th> </tr> <tr> <th>For wiring using cables 0.2 mm<sup>2</sup></th> <th>For wiring using a cable with larger gauge</th> </tr> </thead> <tbody> <tr> <td>5 m or lower</td> <td>FR-V7CBL5</td> <td>2 or more cables in parallel</td> <td rowspan="2">0.4 mm<sup>2</sup> or more</td> </tr> <tr> <td>10 m or lower</td> <td rowspan="2">FR-V7CBL15</td> <td>2 or more cables in parallel</td> </tr> <tr> <td>15 m or lower</td> <td>4 or more cables in parallel</td> <td rowspan="2">0.75 mm<sup>2</sup> or more</td> </tr> <tr> <td>20 m or lower</td> <td rowspan="2">FR-V7CBL30</td> <td>4 or more cables in parallel</td> </tr> <tr> <td>30 m or lower</td> <td>6 or more cables in parallel</td> </tr> <tr> <td>50 m or lower</td> <td>* Cables on order</td> <td rowspan="2">6 or more cables in parallel</td> <td rowspan="2">1.25 mm<sup>2</sup> or more</td> </tr> <tr> <td>100 m or lower</td> <td>Consult us separately.</td> </tr> </tbody> </table>	Wiring distance	Options dedicated encoder cable	Cable gauge for terminals PG and SD		For wiring using cables 0.2 mm <sup>2</sup>	For wiring using a cable with larger gauge	5 m or lower	FR-V7CBL5	2 or more cables in parallel	0.4 mm <sup>2</sup> or more	10 m or lower	FR-V7CBL15	2 or more cables in parallel	15 m or lower	4 or more cables in parallel	0.75 mm <sup>2</sup> or more	20 m or lower	FR-V7CBL30	4 or more cables in parallel	30 m or lower	6 or more cables in parallel	50 m or lower	* Cables on order	6 or more cables in parallel	1.25 mm <sup>2</sup> or more	100 m or lower	Consult us separately.
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Encoder connector (DDK Ltd.) (reference) (unit: mm)

Straight plug D/MS3106B20-29S	Angle plug D/MS3108B20-29S
	<p>• This angle type connector is not an option item. Prepare the connector at the customer's side.</p>

Cable clamp D/MS3057-12A

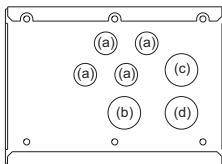


### ● Cable glands and nuts (IP55 compatible model)

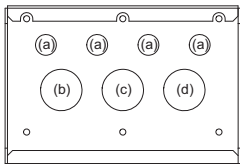
For wiring of the IP55 compatible model, fix the cables using a cable gland and a nut, according to the diameter of the holes of the wiring cover.

For the details such as wiring cover hole diameters and recommended cable glands, refer to the following table.

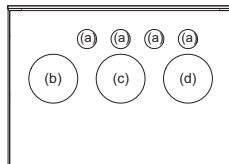
FR-A846-00023(0.4K) to 00170(5.5K)



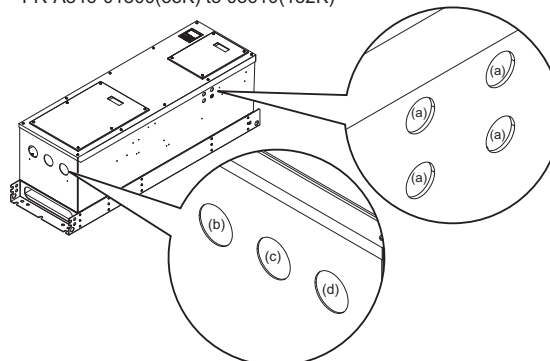
FR-A846-00250(7.5K) to 00470(18.5K)



FR-A846-00620(22K) to 01160(45K)



FR-A846-01800(55K) to 03610(132K)



Inverter capacity	Symbol	Recommended layout example	Hole diameter (mm)	Recommended cable gland	Recommended nut
				SKINTOP MS-SC-M (Manufactured by LAPP KABEL)	SKINDICHT SM-M (Manufactured by LAPP KABEL)
FR-A846-00023(0.4K) to 00170(5.5K)	(a)	Control circuit wiring	20.3	53112630	52103020
	(b)	AC power input wiring	32.3	53112677	52103040
	(c)	Brake unit connection wiring			
	(d)	Inverter output wiring			
FR-A846-00250(7.5K) to 00470(18.5K)	(a)	Control circuit wiring	20.3	53112630	52103020
	(b)	AC power input wiring	40.4	53112660	52103050
	(c)	Brake unit connection wiring			
	(d)	Inverter output wiring			
FR-A846-00620(22K) to 01160(45K)	(a)	Control circuit wiring	20.2	53112630	52103020
	(b)	AC power input wiring	63	53112680	52103070
	(c)	Brake unit connection wiring			
	(d)	Inverter output wiring			
FR-A846-01800(55K) to 03610(132K)	(a)	Control circuit wiring	20.2	53112020	52103020
	(b)	AC power input wiring	63	53112681	52103070
	(c)	Brake unit connection wiring			
	(d)	Inverter output wiring			

Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

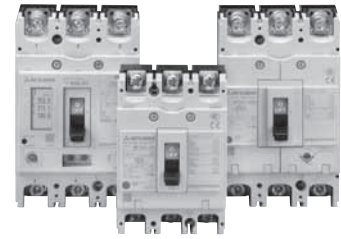
Compatibility

Warranty  
Inquiry

# Low-Voltage Switchgear/Cables

## Mitsubishi Molded Case Circuit Breakers and Earth Leakage Circuit Breakers WS-V Series

"WS-V Series" is the new circuit breakers that have a lot of superior aspects such as higher breaking capacity, design for easy use, standardization of accessory parts, and compliance to the global standards.



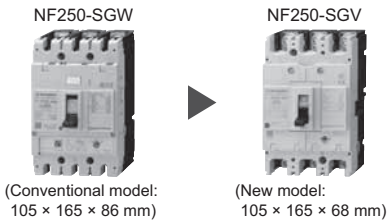
### ◆ Features

#### ◆ Technologies based on long years of experience are brought together to achieve improved performance

The new circuit breaking technology "Expanded ISTAC" has improved the current-limiting performance and upgraded the overall breaking capacity. Expansion of the conductor under the stator shortens the contact parting time of the mover as compared to the conventional ISTAC structure. The current-limiting performance has been improved remarkably. (The maximum peak current value has been reduced by approx. 10%.)

#### ◆ Compact design for ease of use

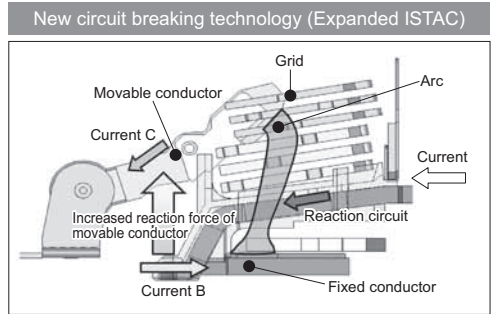
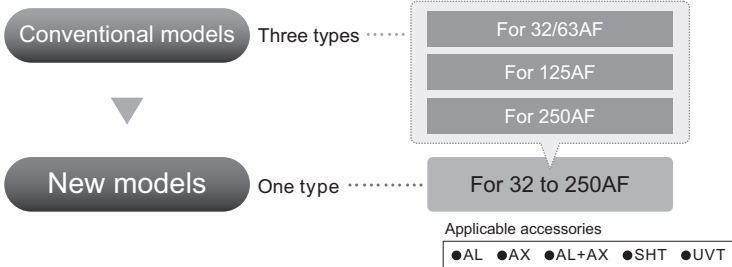
The thermal adjustable circuit breakers and electronic circuit breakers are smaller.



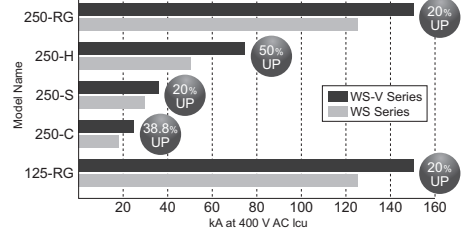
**Volume ratio 79%**  
(Compared with our conventional models)

#### ◆ Types of internal accessories are reduced from 3 types to 1 type

Standardization of internal accessories contributes to a reduction of stock and delivery time.

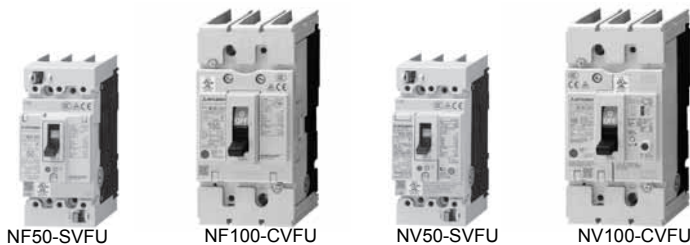


■ Breaking capacity comparison with a conventional model



#### ◆ Lineup of UL 489 listed circuit breakers with 54 mm width "Small Fit" **F** Style

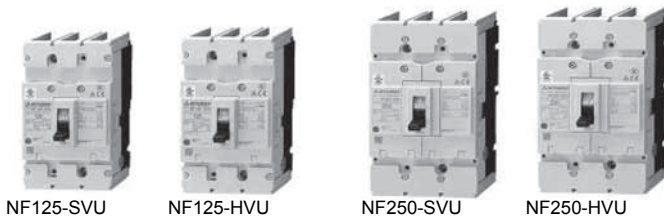
The compact breakers contribute to a size reduction of machines, and IEC 35 mm rail mounting is standard.



For security and standard compliance of machines, F-type and V-type operating handles are available for breakers with 54 mm width.

#### ◆ Lineup of UL 489 listed circuit breakers for 480 V AC "High Performance"

The breaking capacity has been improved to satisfy the request for SCCR upgrading.



Breaking capacity of UL 489 listed circuit breakers for 480 V AC (UL 489)

NF125-SVU/NV125-SVU	30 kA
NF125-HVU/NV125-HVU	50 kA
NF250-SVU/NV250-SVU	35 kA
NF250-HVU/NV250-HVU	50 kA



## Mitsubishi Magnetic Motor Starters and Magnetic Contactors MS-T Series

MS-T series is newly released.

The MS-T series is smaller than ever, enabling more compact control panel. The MS-T series is suitable for other Mitsubishi FA equipment. In addition, the MS-T conforms to a variety of global standards, supporting the global use. DC operated SD-T magnetic contactors (13 A frame to 32 A frame) are now available.

### ◆ Features

#### ◆ Compact

The width of the 10 A-frame model is as small as 36 mm.

General-purpose magnetic contactor with smallest width\*1 in the industry.

The width of MS-T series is reduced by 32% as compared to the prior MS-N series, enabling a more compact panel.

\*1 Based on Mitsubishi Electric research as of October 2013 in the general-purpose magnetic contactor industry for 10 A-frame class.



S-T10

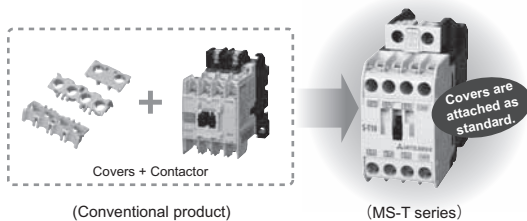
[Unit: mm]

Frame size		11 A	13 A		20 A	25 A
MS-N series	Front view					
		S-N10	S-N11 (Auxiliary 1-pole)	S-N12 (Auxiliary 2-pole)	S-N20	S-N25
New MS-T series	Front view					
		S-T10	S-T12 (Auxiliary 2-pole)	S-T20	S-T25	

Frame size	13 A		18 A	20 A	32 A
SD-N			None		None
	SD-N11	SD-N12		SD-N21	
SD-T (New model)					
	SD-T12	SD-T20	SD-T21	SD-T32	

### ◆ Standardization

- Covers provided as standard equipment  
Safety improvement is achieved by the standard terminal cover. It is not necessary for the new MS-T series to order a dedicated terminal cover (S-N[CX]) or a retrofit cover (UN-CW, etc.), which is required for the former MS-N series. (Prevention of failure to order)  
The number of items in stock can be reduced.
- The standard integrated terminal cover eliminates the need for additional ordering.



(Conventional product)

(MS-T series)

- Widened range of operation coil ratings (AC operated model)  
The widened range reduces the number of operation coil rating types from 14 (MS-N series) to 7.  
The reduced number of the operation coil types enables more simplified customers' ordering process and the faster delivery.
- Customers can select the operation coil more easily.

(Conventional product)

Coil designation	Rated voltage [V]	
	50 Hz	60 Hz
12 VAC	12	12
24 VAC	24	24
48 VAC	48 to 50	48 to 50
100 VAC	100	100 to 110
120 VAC	110 to 120	115 to 120
127 VAC	125 to 127	127
200 VAC	200	200 to 220
220 VAC	208 to 220	220
230 VAC	220 to 240	230 to 240
260 VAC	240 to 260	260 to 280
380 VAC	346 to 380	380
400 VAC	380 to 415	400 to 440
440 VAC	415-440	460 to 480
500 VAC	500	500 to 550

(MS-T series)

Coil designation	Rated voltage [V]	
	50 Hz/60 Hz	
24 VAC	24	
48 VAC	48 to 50	
100 VAC	100 to 127	
200 VAC	200 to 240	
300 VAC	260 to 300	
400 VAC	380 to 440	
500 VAC	460 to 550	

\*12 VAC type is made on order.

Integrated coil ratings facilitate selection!

### ◆ Global Standard

- Conforms to various global standards  
Not only major global standards such as IEC, JIS, UL, CE, and CCC but also ship standards and other country standards are planned to be certified.
- Conforms to various global standards

Standard	Applicable Standard				Safety Standard
	International	Japan	Europe		China
	IEC*2	JIS	EN	Certification body	GB
			EC Directive		

\*2 The MS-T series also provide safe isolation (mirror contact) specified in the IEC standard.

\*3 The motor starters are certified under each type name of the magnetic contactors and the thermal overload relays on the condition that the magnetic contactors and the thermal overload relays are used in combination.

Features  
Application Example  
PLC Function  
FR Configurator2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry

## Mitsubishi Magnetic Motor Starters and Magnetic Contactors MS-N Series (32 A-Frame Class or Higher)

Environment-friendly Mitsubishi MS-N series ensures safety and conforms to various global standards. Its compact size contributes to space-saving in a machine. The MS-N series is suitable for other Mitsubishi FA equipment and can be used globally.

### ◆ Features

#### ◆ Bifurcated contact adopted to achieve high contact reliability

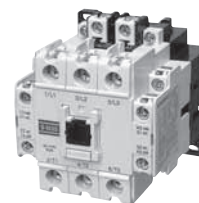
Contact reliability is greatly improved by combining bifurcated moving contact and stationary contact. This series responds to the various needs such as the application to safety circuit. (The MS-T series also has bifurcated contacts.)

#### ◆ Mirror contact (auxiliary contact off at main contact welding)

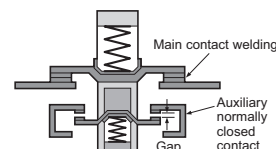
The MS-N series meets requirements of "Control functions in the event of failure" described in EN 60204-1 "Electrical equipment of machines", being suitable as interlock circuit contact. The MS-N series is applicable for category 4 safety circuit. We ensure safety for our customers. (The MS-T series also has mirror contacts.)

#### ◆ Various option units

Various options including surge absorbers and additional auxiliary contact blocks are available.



S-N35CX



## Motor Circuit Breaker MMP-T Series

Motor circuit protection (against overload / phase loss / short-circuit) is achievable the MMP-T series alone.

The wire-saving, space-saving design enables downsizing of the enclosure.

The MMP-T series can be used in combination with the MS-T series (DC operated model).\*1

\*1 The connection conductor unit for the DC operated compact model (SD-T) is to be released soon.

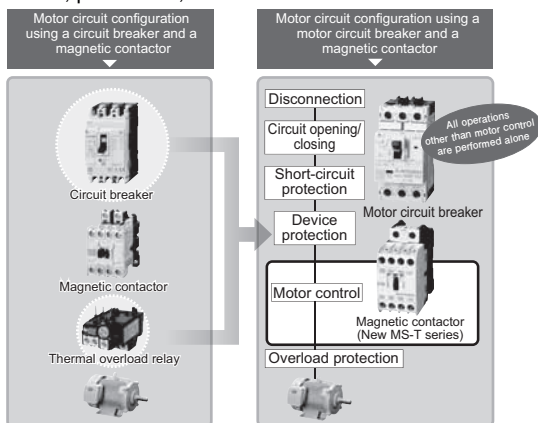


MMP-T32

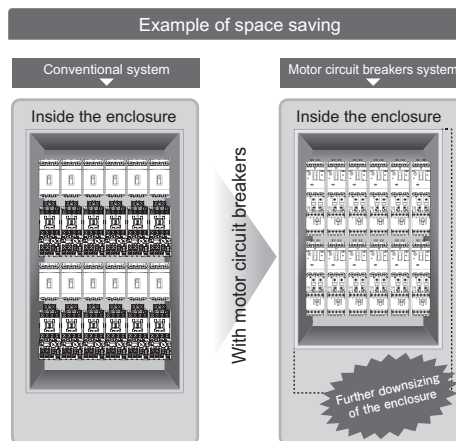
### ◆ Features

#### ◆ What is the motor circuit breaker?

The motor circuit breaker, applicable to the motor circuit, has the functions of a circuit breaker and a thermal overload relay in one unit. The motor circuit breaker provides protection against overload, phase loss, and short circuit.



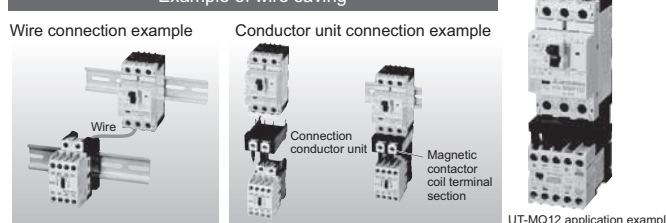
#### ◆ Space-saving design for downsizing of the enclosure



#### ◆ Wire saving

Using a connection conductor unit (option) for connecting a motor circuit breaker and a contactor reduces work hours required for wiring. A connection conductor unit for the high sensitivity contactor (SD-Q) is also available. (Model: UT-MQ12)

#### Example of wire saving



#### ◆ Compliance to major standards support customers' overseas business

##### • Compliance with major global standards

Not only major international standards such as IEC, JIS, UL, CE, and CCC but also other national standards are certified. This will help our customers expand their business in foreign countries.

Standard	Applicable Standard				Safety Standard	
	International	Japan	Europe	China	U.S.A./ Canada	
	IEC	JIS	EN	Certification body	GB	cULus
			EC Directive			
CE			TUV Rheinland	CCC		

• UL60947-4-1A Type E/F is also covered.

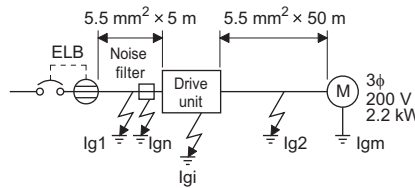
Compliance of the device to UL's Type E/F combination can surely support export to the United States.

## ● Selecting the rated sensitivity current for the earth leakage circuit breaker

When using an earth leakage circuit breaker with the inverter circuit, select its rated sensitivity current as follows, independently of the PWM carrier frequency.

- Breaker designed for harmonic and surge suppression  
Rated sensitivity current  
 $I\Delta n \geq 10 \times (I_{g1} + I_{gn} + I_{gi} + I_{g2} + I_{gm})$
- Standard breaker  
Rated sensitivity current  
 $I\Delta n \geq 10 \times \{I_{g1} + I_{gn} + I_{gi} + 3 \times (I_{g2} + I_{gm})\}$   
I<sub>g1</sub>, I<sub>g2</sub>: Leakage currents in wire path during commercial power supply operation  
I<sub>gn</sub>: Leakage current of inverter input side noise filter  
I<sub>gm</sub>: Leakage current of motor during commercial power supply operation  
I<sub>gi</sub>: Leakage current of inverter unit

<Example>



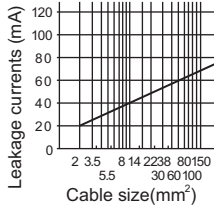
- Install the earth leakage circuit breaker (ELB) on the input side of the inverter.
- In the  $\Delta$  connection earthed-neutral system, the sensitivity current is blunt against a ground fault in the inverter output side. Earthing (Grounding) must conform to the requirements of national and local safety regulations and electrical codes. (NEC section 250, IEC 536 class 1 and other applicable standards)

### ◆ Selection example (in the case of the above figure)

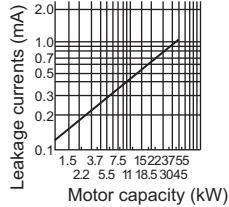
	Breaker designed for harmonic and surge suppression	Standard breaker
Leakage current I <sub>g1</sub> (mA)	$33 \times \frac{5 \text{ m}}{1000 \text{ m}} = 0.17$	
Leakage current I <sub>gn</sub> (mA)	0 (without noise filter)	
Leakage current I <sub>gi</sub> (mA)	1 (without EMC filter) Refer to the following table for the leakage current of the inverter.*1	
Leakage current I <sub>g2</sub> (mA)	$33 \times \frac{50 \text{ m}}{1000 \text{ m}} = 1.65$	
Motor leakage current I <sub>gm</sub> (mA)	0.18	
Total leakage current (mA)	3.00	6.66
Rated sensitivity current (mA) (≥ I <sub>g</sub> × 10)	30	100

\*1 For whether to use the EMC filter or not, refer to the Instruction Manual (Detailed).

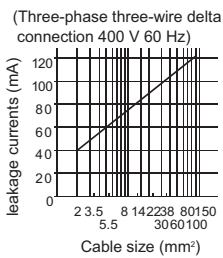
Example of leakage current of cable path per 1 km during the commercial power supply operation when the CV cable is routed in metal conduit (200 V 60 Hz)



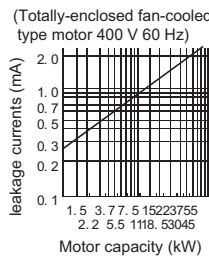
Leakage current example of three-phase induction motor during the commercial power supply operation (200 V 60 Hz)



Example of leakage current per 1 km during the commercial power supply operation when the CV cable is routed in metal conduit



Leakage current example of three-phase induction motor during the commercial power supply operation



For  $\Delta$  connection, the amount of leakage current is approx. 1/3 of the above value.

### ◆ Inverter/converter unit leakage current

200 V class (Input power supply conditions: 220 V/60 Hz, power supply unbalance: within 3%)

Inverter	FR-A800 (Standard model)	
	EMC filter ON	EMC filter OFF
Phase earthing (grounding)	22	1

(mA)

400 V class (Input power supply conditions: 440 V/60 Hz, power supply unbalance: within 3%)

Inverter/converter unit	FR-A800 (Standard model)		FR-A806-C3 (IP55 compatible model)		FR-A806-C2 (IP55 compatible model)	FR-A802 (Separated converter type)	Converter unit FR-CC2			
	EMC filter ON	EMC filter OFF	ON	OFF	ON *1	—	H315K, H355K		H400K to H630K	
Phase earthing (grounding)	35	2	35	2	— *2	2	35	2	70	2
Earthed-neutral system	2	1	2	1	2	1	2	1	2	1

(mA)

\*1 Do not change the initially set ON (enabled) position of the EMC filter ON/OFF connector in the case of the inverter with a built-in C2 filter. The Class C2 compatibility condition is not satisfied with the EMC filter OFF. (The FR-A846-00250(7.5K)-C2 to FR-A846-00470(18.5K)-C2 are not provided with the EMC filter ON/OFF connector. The EMC filter is always ON.)

\*2 The inverter with a built-in C2 filter must be used in the earthed-neutral system.

Features

Application Example  
PLC Function  
FR Configurator2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## ● Molded case circuit breaker, magnetic contactor, cable gauge

### ◆ 280K or lower

Voltage	Motor output (kW) *1	Applicable inverter model (ND rating)	Molded case circuit breaker (MCCB) *2 or earth leakage circuit breaker (ELB) (NF, NV type)		Input side magnetic contactor *3		Recommended cable gauge(mm <sup>2</sup> ) *4	
			Power factor improving (AC or DC) reactor connection		Power factor improving (AC or DC) reactor connection		R/L1, S/L2, T/L3	U, V, W
			Without	With	Without	With		
200 V	0.4	FR-A820-00046(0.4K)	5 A	5 A	S-T10	S-T10	2	2
	0.75	FR-A820-00077(0.75K)	10 A	10 A	S-T10	S-T10	2	2
	1.5	FR-A820-00105(1.5K)	15 A	15 A	S-T10	S-T10	2	2
	2.2	FR-A820-00167(2.2K)	20 A	15 A	S-T10	S-T10	2	2
	3.7	FR-A820-00250(3.7K)	30 A	30 A	S-T21	S-T10	3.5	3.5
	5.5	FR-A820-00340(5.5K)	50 A	40 A	S-N25	S-T21	5.5	5.5
	7.5	FR-A820-00490(7.5K)	60 A	50 A	S-N25	S-N25	14	8
	11	FR-A820-00630(11K)	75 A	75 A	S-N35	S-N35	14	14
	15	FR-A820-00770(15K)	125 A	100 A	S-N50	S-N50	22	22
	18.5	FR-A820-00930(18.5K)	150 A	125 A	S-N65	S-N50	38	38
	22	FR-A820-01250(22K)	175 A	150 A	S-N80	S-N65	38	38
	30	FR-A820-01540(30K)	225 A	175 A	S-N95	S-N80	60	60
	37	FR-A820-01870(37K)	250 A	225 A	S-N150	S-N125	80	80
	45	FR-A820-02330(45K)	300 A	300 A	S-N180	S-N150	100	100
	55	FR-A820-03160(55K)	400 A	350 A	S-N220	S-N180	100	100
75	FR-A820-03800(75K)	-	400 A	-	S-N300	125	125	
90	FR-A820-04750(90K)	-	400 A	-	S-N300	150	150	
400 V	0.4	FR-A840-00023(0.4K)	5 A	5 A	S-T10	S-T10	2	2
	0.75	FR-A840-00038(0.75K)	5 A	5 A	S-T10	S-T10	2	2
	1.5	FR-A840-00052(1.5K)	10 A	10 A	S-T10	S-T10	2	2
	2.2	FR-A840-00083(2.2K)	10 A	10 A	S-T10	S-T10	2	2
	3.7	FR-A840-00126(3.7K)	20 A	15 A	S-T10	S-T10	2	2
	5.5	FR-A840-00170(5.5K)	30 A	20 A	S-T21	S-T12	2	2
	7.5	FR-A840-00250(7.5K)	30 A	30 A	S-T21	S-T21	3.5	3.5
	11	FR-A840-00310(11K)	50 A	40 A	S-T21	S-T21	5.5	5.5
	15	FR-A840-00380(15K)	60 A	50 A	S-N25	S-T21	8	8
	18.5	FR-A840-00470(18.5K)	75 A	60 A	S-N25	S-N25	14	8
	22	FR-A840-00620(22K)	100 A	75 A	S-N35	S-N25	14	14
	30	FR-A840-00770(30K)	125 A	100 A	S-N50	S-N50	22	22
	37	FR-A840-00930(37K)	150 A	125 A	S-N65	S-N50	22	22
	45	FR-A840-01160(45K)	175 A	150 A	S-N80	S-N65	38	38
	55	FR-A840-01800(55K)	200 A	175 A	S-N80	S-N80	60	60
	75	FR-A840-02160(75K)	-	225 A	-	S-N95	60	60
	90	FR-A840-02600(90K)	-	225 A	-	S-N150	60	60
	110	FR-A840-03250(110K)	-	225 A	-	S-N180	80	80
	132	FR-A840-03610(132K)	-	400 A	-	S-N220	100	100
	150	FR-A840-04320(160K)	-	400 A	-	S-N300	125	125
	160	FR-A840-04320(160K)	-	400 A	-	S-N300	125	125
185	FR-A840-04810(185K)	-	400 A	-	S-N300	150	150	
220	FR-A840-05470(220K)	-	500 A	-	S-N400	2×100	2×100	
250	FR-A840-06100(250K)	-	600 A	-	S-N600	2×100	2×100	
280	FR-A840-06830(280K)	-	600 A	-	S-N600	2×125	2×125	

\*1 Assumes the use of a Mitsubishi 4-pole standard motor with the motor capacity of 200 VAC 50 Hz.

\*2 Select an MCCB according to the power supply capacity.  
Install one MCCB per inverter.

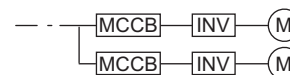
For the use in the United States or Canada, provide the appropriate UL and cUL listed fuse or UL489 molded case circuit breaker (MCCB) that is suitable for branch circuit protection. (Refer to the Instruction Manual (Startup).)

\*3 The magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stops during motor driving, the electrical durability is 25 times. If using an MC for emergency stop during motor driving or using it on the motor side during commercial power supply operation, select an MC with the class AC-3 rated current for the rated motor current.

\*4 Cables

For the FR-A820-03160(55K) or lower and the FR-A840-01800(55K) or lower, it is the gauge of a cable with the continuous maximum permissible temperature of 75°C. (HIV cable (600 V grade heat-resistant PVC insulated wire), etc.) It assumes a surrounding air temperature of 50°C or lower and the wiring distance of 20 m or shorter.

For the FR-A820-03800(75K) or higher and the FR-A840-02160(75K) or higher, it is the gauge of the cable with the continuous maximum permissible temperature of 90°C or higher. (LMFC (heat resistant flexible cross-linked polyethylene insulated cable), etc.) It assumes a surrounding air temperature of 50°C or lower and in-enclosure wiring.



### NOTE

- When the inverter capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the inverter model, and select cables and reactors according to the motor output.
- When the breaker on the inverter's input side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.



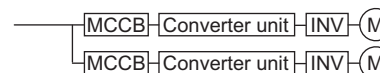
◆ 315K or higher

Voltage	Motor output (kW) *1	Applicable inverter model (ND rating)	Applicable converter model	Molded case circuit breaker (MCCB) *2 or earth leakage circuit breaker (ELB) (NF, NV type)	Input-side magnetic contactor *3	HIV cables, etc. (mm <sup>2</sup> ) *4		
						R/L1, S/L2, T/L3	P/+, N/-	U, V, W
400 V	315	FR-A842-07700(315K)	FR-CC2-H315K	700 A	S-N600	2×150	2×150	2×150
	355	FR-A842-08660(355K)	FR-CC2-H355K	800 A	S-N600	2×200	2×200	2×200
	400	FR-A842-09620(400K)	FR-CC2-H400K	900 A	S-N800	2×200	2×200	2×200
	450	FR-A842-10940(450K)	FR-CC2-H450K	1000 A	1000 A rated product	2×250	2×250	2×250
	500	FR-A842-12120(500K)	FR-CC2-H500K	1200 A	1000 A rated product	3×200	3×200	2×250

\*1 Assumes the use of a Mitsubishi 4-pole standard motor with the motor capacity of 400 VAC 50 Hz.

\*2 Select an MCCB according to the power supply capacity. Install one MCCB per converter.

For the use in the United States or Canada, provide the appropriate UL and cUL listed fuse that is suitable for branch circuit protection. (Refer to the Instruction Manual of the inverter.)



\*3 The magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stops during motor driving, the electrical durability is 25 times. If using an MC for emergency stop during driving the motor, select an MC regarding the converter unit input side current as JEM1038-AC-3 class rated current. When using an MC on the inverter output side for commercial-power supply operation switching using a general-purpose motor, select an MC regarding the rated motor current as JEM1038-AC-3 class rated current.

\*4 The gauge of the cable with the continuous maximum permissible temperature of 90°C or higher. (LMFC (heat resistant flexible cross-linked polyethylene insulated cable), etc.). It assumes a surrounding air temperature of 40°C or lower and in-enclosure wiring.

**NOTE**

- When the converter unit capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the converter unit model, and select cables and reactors according to the motor output.
- When the breaker on the converter unit's input side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter and the converter unit, etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.

Features

Application Example  
PLC Function  
FR Configurator 2

Connection  
Examples

Standard  
Specs

Outline  
Dimensions

Terminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
Parameters

Protective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry



# Precaution on Selection and Operation

## ● Precautions for use

### ◆ Safety instructions

- To use the product safely and correctly, make sure to read the "Instruction Manual" before the use.
- This product has not been designed or manufactured for use with any equipment or system operated under life-threatening conditions.
- Please contact our sales representative when considering using this product in special applications such as passenger mobile, medical, aerospace, nuclear, power or undersea relay equipment or system.
- Although this product was manufactured under conditions of strict quality control, install safety devices to prevent serious accidents when it is used in facilities where breakdowns of the product or other failures are likely to cause a serious accident.
- Do not use the inverter for a load other than the three-phase induction motor and the PM motor.
- Do not connect a PM motor in the induction motor control settings (initial settings). Do not use an induction motor in the PM sensorless vector control settings. It will cause a failure.
- When using an IPM motor (MM-CF), also refer to the precautions for use of the IPM motors (MM-CF).

### ◆ Operation

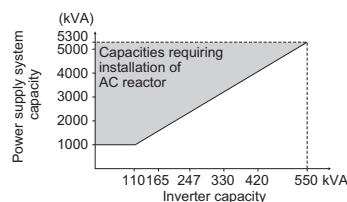
- When a magnetic contactor (MC) is installed on the input side, do not use the MC for frequent starting/stopping. Otherwise the inverter may be damaged.
- When a fault occurs in the inverter, the protective function is activated to stop the inverter output. However, the motor cannot be immediately stopped. For machinery and equipment that require an immediate stop, provide a mechanical stop/holding mechanism.
- Even after turning OFF the inverter/the converter unit, it takes time to discharge the capacitor. Before performing an inspection, wait 10 minutes or longer after the power supply turns OFF, then check the voltage using a tester, etc.

### ◆ Wiring

- Applying the power to the inverter output terminals (U, V, W) causes a damage to the inverter. Before power-on, thoroughly check the wiring and sequence to prevent incorrect wiring, etc.
- Terminals P+, P1, N/-, and P3 are the terminals to connect dedicated options or DC power supply (in the DC feeding mode). Do not connect any device other than the dedicated options or DC power supply (in the DC feeding mode). Do not short-circuit between the frequency setting power supply terminal 10 and the common terminal 5, and between the terminals PC and SD.
- To prevent a malfunction due to noise, keep the signal cables 10cm or more away from the power cables. Also, separate the main circuit cables at the input side from the main circuit cables at the output side.
- After wiring, wire offcuts must not be left in the inverter/the converter unit. Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter/the converter unit clean. When drilling mounting holes in an enclosure etc., take caution not to allow chips and other foreign matter to enter the inverter/the converter unit.
- Set the voltage/current input switch correctly. Incorrect setting may cause a fault, failure or malfunction.

### ◆ Power supply

- When the inverter is connected near a large-capacity power transformer (1000 kVA or more) or when a power factor correction capacitor is to be switched over, an excessive peak current may flow in the power input circuit, damaging the inverter. To prevent this, always install an optional AC reactor (FR-HAL).
- If surge voltage occurs in the power supply system, this surge energy may flow into an inverter, and the inverter may display the overvoltage protection (E. OV[]) and trip. To prevent this, install an optional AC reactor (FR-HAL).



### ◆ Installation

- Install the inverter in a clean place with no floating oil mist, cotton fly, dust and dirt, etc. Alternatively, install the inverter inside the "sealed type" enclosure that prevents entry of suspended substances. For installation in the enclosure, decide the cooling method and the enclosure size to keep the surrounding air temperature of the inverter/the converter unit within the permissible range (for specifications, refer to **page 22**).
- Some parts of the inverter/the converter unit become extremely hot. Do not install the inverter/the converter unit to inflammable materials (wood etc.).
- Attach the inverter vertically.

### ◆ Setting

- Depending on the parameter setting, high-speed operation (up to 590 Hz) is available. Incorrect setting will lead to a dangerous situation. Set the upper limit by using the upper frequency limit setting.
- Setting the DC injection brake operation voltage and operating time larger than their initial values causes motor overheating (electronic thermal O/L relay trip).

### ◆ Real sensorless vector control

- Under Real sensorless vector control, always execute offline auto tuning before starting operations.
- The selectable carrier frequencies under Real sensorless vector control are 2, 6, 10, and 14 kHz.
- Torque control is not available in the low-speed (about 10 Hz or less) regenerative range, or in the low speed with the light load (about 5 Hz or less with about 20% or less of the rated torque). Select the vector control.
- Performing pre-excitation (LX signal and X13 signal) under torque control may start the motor running at a low speed even when the start command (STF or STR) is not input. The motor may run also at a low speed when the speed limit value = 0 with a start command input. Confirm that the motor running will not cause any safety problem before performing pre-excitation.
- Under torque control, do not switch between the forward rotation command (STF) and reverse rotation command (STR). The overcurrent trip (E. OC[]) or opposite rotation deceleration fault (E.11) occurs.
- For FR-A820-00250(3.7K) or lower and FR-A840-00126(3.7K) or lower, if continuous operation is performed under Real sensorless vector control, speed fluctuation may increase at 20 Hz or lower, or insufficient torque may occur in a low-speed range under 1 Hz. In such a case, stop the inverter once and re-accelerate it.
- If the inverter may restart during coasting under Real sensorless vector control, set the automatic restart after instantaneous power failure function to enable frequency search (**Pr.57** ≠ "9999", **Pr.162** = "10").
- Under Real sensorless vector control, sufficient torque may not be obtained in the extremely low-speed range of about 2 Hz or less.
- The approximate speed control range is as described below.  
Power drive: 1:200 (2, 4, 6 poles), 0.3 Hz or more for 60 Hz rating  
1:30 (8, 10 poles), 2 Hz or more for 60 Hz rating  
Regenerative driving: 1:12 (2 to 10 poles), 5 Hz or more for 60 Hz rating

## ◆ Waterproof and dustproof performances (IP55 compatible model)

- The inverter is rated with an IPX5\*1 waterproof rating and an IP5X\*2 dustproof rating when the operation panel (FR-DU08-01), the front cover, the wiring cover, and the cable glands are securely fixed with screws.
- The items enclosed with the inverter such as the Instruction Manual or CD are not rated with the IPX5 waterproof or IP5X dustproof ratings.
- Although the inverter is rated with the IPX5 waterproof and IP5X dustproof ratings, it is not intended for use in water. Also, the ratings do not guarantee protection of the inverter from needless submersion in water or being washed under strong running water such as a shower.
- Do not pour or apply the following liquids over the inverter: water containing soap, detergent, or bath additives; sea water; swimming pool water; warm water; boiling water; etc.
- The inverter is intended for indoor\*4 installation and not for outdoor installation. Avoid places where the inverter is subjected to direct sunlight, rain, sleet, snow, or freezing temperatures.
- If the operation panel (FR-DU08-01) is not installed, if the screws of the operation panel are not tightened, or if the operation panel is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the operation panel, ask for an inspection and repair.
- If the screws of the front cover or the wiring cover are not tightened, if any foreign matter (hair, sand grain, fiber, etc.) is stuck between the inverter and the gasket, if the gasket is damaged, or if the front cover or the wiring cover is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the front cover, wiring cover, or the gasket of the inverter, ask for an inspection and repair.
- Cable glands are important components to maintain the waterproof and dustproof performances. Be sure to use cable glands of the recommended size and shape or equivalent. The standard protective bushes cannot sufficiently maintain the IPX5 waterproof performance and the IP5X dustproof performance.
- If a cable gland is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the cable glands, ask the manufacturer of the cable glands for an inspection and repair.
- To maintain the waterproof and dustproof performances of the inverter, daily and periodic inspections are recommended regardless of the presence or absence of abnormalities.

\*1 IPX5 refers to protection of the inverter functions against water jets from any direction when about 12.5-liter water\*3 is injected from a nozzle with an inside diameter of 6.3 mm from the distance of about 3 m for at least 3 minutes.

\*2 IP5X refers to protection of the inverter functions and maintenance of safety when the inverter is put into a stirring device containing dust of 75 μm or smaller in diameter, stirred for 8 hours, and then removed from the device.

\*3 Water here refers to fresh water at room temperature (5 to 35°C).

\*4 Indoor here refers to the environments that are not affected by climate conditions.

## ● Precautions for use of IPM motor (MM-CF)

For using an IPM motor (MM-CF), also check the following precautions.

### ◆ ⚠ Safety instructions

- Do not use an IPM motor for an application where the motor is driven by the load and runs at a speed higher than the maximum motor speed.

### ◆ Combination of motor and inverter

- The motor capacity is equal to or one rank lower than the inverter capacity. (It must be 0.4 kW or higher.) Using a motor with the rated current substantially lower than the inverter rated current will cause torque ripples, etc. and degrade the speed and torque accuracies. As a reference, select the motor with the rated motor current that is about 40% or higher of the inverter rated current.
- Only one IPM motor can be connected to an inverter.
- An IPM motor cannot be driven by the commercial power supply.

### ◆ Installation

- While power is ON or for some time after power-OFF, do not touch the motor since the motor may be extremely hot. Touching these devices may cause a burn.
- An outline dimension differs between MM-CF and a standard motor.
- Do not apply the load larger than the permissible load to the motor shaft. Doing so may lead to breakage of the shaft.
- Avoid places where the equipment is subjected to oil mist, dust, dirt, etc. for installation. When it is inevitable to install the equipment in such a place, take such measures as to provide a cover to the motor.
- Always use the motor at the specified surrounding air temperature. Increase in the motor temperature may cause the torque to decrease.
- When installing the motor with its shaft facing upward, take countermeasures on the machine side to avoid infiltration of oils from the gear box, etc.
- Select the appropriate cable clamping method to avoid bending stresses or stresses from its own weight at the cable joint section.
- For certain applications in which the motor moves, determine the cable bending radius based on the necessary bending life and the cable type.
- To prevent moving of the power supply cable coming out of the motor, take such measures as to fix the cable to the motor. Otherwise the cable may break.
- Do not modify the connector, terminal, etc. at the end of the cable.

### ◆ Earth (ground)

- To prevent an electric shock and to stabilize the potential of control circuit, always earth (ground) the motor and inverter.
- Earth (ground) the motor and inverter at one point. Connect the both earth (ground) terminals for the ground connection from the inverter side.

### ◆ Wiring

- Applying the commercial power supply to input terminals (U, V, W) of a motor will burn the motor. The motor must be connected with the output terminals (U, V, W) of the inverter.
- Do not install a magnetic contactor at the inverter's output side.
- An IPM motor is a motor with permanent magnets embedded inside. High voltage is generated at the motor terminals while the motor is running. Before wiring or inspection, confirm that the motor is stopped. In an application, such as a fan or blower, where the motor is driven by the load, a low-voltage manual contactor must be connected at the inverter's output side, and wiring and inspection must be performed while the contactor is open. Otherwise an electric shock may be caused. The inverter power must be turned ON before closing the contacts of the contactor at the output side.
- Match the input terminals (U, V, W) of the motor and the output terminals (U, V, W) of the inverter when connecting.
- Keep the wiring length to 100 m or shorter when connecting an IPM motor.

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

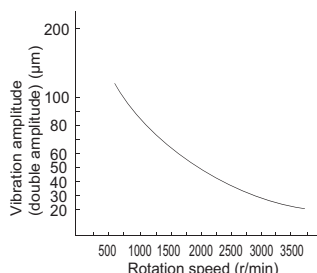
◆ **Operation**

- About 0.1 s (magnetic pole detection time) takes to start a motor after inputting a start signal.
- An IPM motor is a motor with embedded permanent magnets. Regression voltage is generated when the motor coasts at an instantaneous power failure or other incidents. The inverter's DC bus voltage increases if the motor coasts fast in this condition. When using the automatic restart after instantaneous power failure function, it is recommended to also use the regeneration avoidance operation to make startups stable.
- The relationship between speed and frequency setting is:  
Speed = 120 × frequency setting value / number of motor poles

Speed (r/min)	300	600	900	1200	1500	1800	2000	2400	2700	3000
MM-CF (8 poles) frequency setting (Hz)	20	40	60	80	100	120	133.33	160	180	200

◆ **Permissible vibration of the motor**

- Bearing is subjected to fretting while the motor is stopped. Suppress the vibration to about the half of the permissible value. Amplitude at each vibration condition is as shown right.

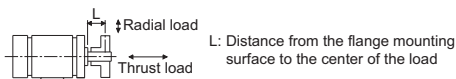


◆ **Permissible load of the shaft**

- Use the flexible coupling to decrease the shaft center gap to keep its radial load value within the permissible radial load of the shaft.
- When selecting a pulley, sprocket or timing belt, keep its radial load value within the permissible radial load value.
- Do not use a rigid coupling because it gives excessive bending force to the shaft and may break the shaft.

Motor	L (mm) <sup>*1</sup>	Permissible radial load (N)	Permissible thrust load (N)
MM-CF52(C)(B) to 152(C)(B)	55	980	490
MM-CF202(C)(B) to 352(C)(B) MM-CF502(C) to 702(C)	79	2058	980

\*1 For "L" in the table, refer to the figure below.



● **Selection precautions**

◆ **Inverter capacity selection**

- When operating a special motor or multiple motors in parallel by one inverter, select the inverter capacity so that 1.05 times of the total of the rated motor current becomes less than the rated output current of the inverter.  
(Multiple PM motors cannot be connected to an inverter.)

◆ **Starting torque of the motor**

- The starting and acceleration characteristics of the motor driven by an inverter are restricted by the overload current rating of the inverter. In general, the torque characteristic has small value compared to when the motor is started by a commercial power supply. When a large starting torque is required, and torque boost adjustment, Advanced magnetic flux vector control, Real sensorless vector control, and vector control cannot generate the sufficient torque, select the HD rating, or increase both the motor and inverter capacities.

◆ **Acceleration/deceleration time**

- The motor acceleration/deceleration time is decided by the torque generated by the motor, load torque, and moment of inertia (J) of load.
- The required time may increase when the torque limit function or stall prevention function operates during acceleration/ deceleration. In such a case, set the acceleration/decelerations time longer.
- To shorten the acceleration/deceleration time, increase the torque boost value (too large setting value may activate the stall prevention function, resulting in longer acceleration time at starting on the contrary). Alternatively, use Advanced magnetic flux vector control, Real sensorless vector control, or vector control, or select the larger inverter and motor capacities. To shorten the deceleration time, use an addition brake unit (FR-BU2) to absorb braking energy, power regeneration common converter (FR-CV), or power supply regeneration unit (MT-RC), etc.

◆ **Power transfer mechanisms (reduction gear, belt, chain, etc.)**

- Caution is required for the low-speed continuous operation of the motor with an oil lubricated gear box, transmission, reduction gear, etc. in the power transfer mechanism. Such an operation may degrade the oil lubrication and cause seizing. On the other hand, the high-speed operation at more than 60 Hz may cause problems with the noise of the power transfer mechanism, life, or insufficient strength due to centrifugal force, etc. Fully take necessary precautions.

◆ **Instructions for overload operation**

- When performing frequent starts/stops by the inverter, rise/fall in the temperature of the transistor element of the inverter will repeat due to a repeated flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing current at locked condition, starting current, etc. Reducing current may extend the service life but may also cause torque shortage, which leads to a start failure. Adding a margin to the current can eliminate such a condition. For an induction motor, use an inverter of a higher capacity (up to two ranks for the ND rating). For an IPM motor, use an inverter and IPM motor of higher capacities.

## ● Precautions on peripheral device selection

### ◆ Selection and installation of molded case circuit breaker

Install a molded case circuit breaker (MCCB) on the power receiving side to protect the wiring at the inverter/the converter unit input side. Select an MCCB according to the inverter power supply side power factor, which depends on the power supply voltage, output frequency and load. Refer to **page 171**. Especially for a completely electromagnetic MCCB, a slightly large capacity must be selected since its operation characteristic varies with harmonic currents. (Check the reference material of the applicable breaker.) As an earth leakage circuit breaker, use the Mitsubishi earth leakage circuit breaker designed for harmonics and surge suppression. (Refer to **page 170**.)

When installing a molded case circuit breaker on the inverter output side, contact the manufacturer of each product for selection.

### ◆ Handling of the input side magnetic contactor (MC)

For the operation using external terminals (using the terminal STF or STR), install the input-side magnetic contactor to prevent accidents due to automatic restart when the power is restored after power failures such as an instantaneous power failure, or for safety during maintenance works. Do not use this magnetic contactor for frequent starting/stopping of the inverter. (The switching life of the converter part is about 1 million times.) In the operation by parameter unit, the automatic restart after power restoration is not performed and the magnetic contactor cannot be used to start the motor. The input-side magnetic contactor can stop the motor. However, the regenerative brake of the inverter does not operate, and the motor coasts to a stop.

### ◆ Handling of the output side magnetic contactor (MC)

- Switch the MC between the inverter and motor only when both the inverter and motor are at a stop. When the magnetic contactor is turned ON while the inverter is operating, overcurrent protection of the inverter and such will activate. When an MC is provided to switch to a commercial power supply, for example, it is recommended to use the commercial power supply-inverter switchover function **Pr.135** to **Pr.139**.
- Do not install a magnetic contactor at the inverter's output side when using a PM motor.

### ◆ Installation of thermal relay

In order to protect the motor from overheating, the inverter has an electronic thermal O/L relay. However, install an external thermal overcurrent relay (OCR) between the inverter and motors to operate several motors or a multi-pole motor with one inverter. In this case, set 0 A to the electronic thermal O/L relay setting of the inverter. For the external thermal overcurrent relay, determine the setting value in consideration of the current indicated on the motor's rating plate and the line-to-line leakage current. (**Refer to page 177**.)

Self cooling ability of a motor reduces in the low-speed operation. Installation of a thermal protector or a use of a motor with built-in thermistor is recommended.

### ◆ Output side measuring instrument

When the inverter-to-motor wiring length is long, especially for the 400 V class, small-capacity models, the meters and CTs may generate heat due to line-to-line leakage current. Therefore, choose the equipment which has enough allowance for the current rating.

When measuring and displaying the output voltage and output current of the inverter, use of the terminals AM and 5 output function of the inverter is recommended.

### ◆ Disuse of power factor improving capacitor (power factor correction capacitor)

The power factor improving capacitor and surge suppressor on the inverter output side may be overheated or damaged by the harmonic components of the inverter output. Also, since an excessive current flows in the inverter to activate overcurrent protection, do not provide a capacitor and surge suppressor. To improve the power factor, use an AC reactor (**on page 153**), a DC reactor (**on page 154**), or a high power factor converter (**on page 161**).

### ◆ Connection between the converter unit and the inverter

- Perform wiring so that the commands sent from the converter unit are transmitted to the inverter without fail. Incorrect connection may damage the converter unit and the inverter.
- For the wiring length, refer to the table below.

Total wiring length	Across the terminals P and P and the terminals N and N	50 m or lower
	Other signal cables	30 m or lower

- For the cable gauge of the cable across the main circuit terminals P/+ and N/- (P and P, N and N), refer to **page 172**.

### ◆ Cable gauge and wiring distance

If the wiring distance is long between the inverter and motor, during the output of a low frequency in particular, use a large cable gauge for the main circuit cable to suppress the voltage drop to 2% or less. (The table on **page 171** indicates a selection example for the wiring length of 20 m.)

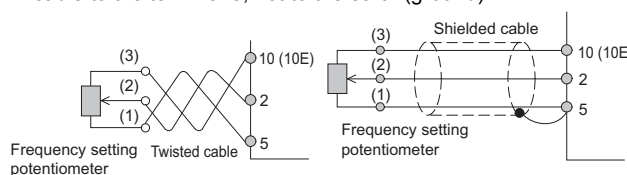
Especially for long-distance wiring or wiring with shielded cables, the inverter may be affected by a charging current caused by stray capacitances of the wiring, leading to an incorrect activation of the overcurrent protective function. Refer to the maximum wiring length shown in the following table. When multiple motors are connected, use the total wiring length shown in the table or shorter (100 m or shorter under vector control and PM sensorless vector control.)

Pr.72 setting (carrier frequency)	FR-A820-00046(0.4K), FR-A840-00023(0.4K)	FR-A820-00077(0.75K), FR-A840-00038(0.75K)	FR-A820-00105(1.5K) or higher, FR-A840-00052(1.5K) or higher
2 (2 kHz) or lower	300 m	500 m	500 m
3 (3 kHz) or higher	200 m	300 m	500 m

When the operation panel is installed away from the inverter and when the parameter unit is connected, use a recommended connection cable.

For the remote operation using analog signals, keep the distance between the remote speed setter and the inverter to 30 m or less. Also, to prevent induction from other devices, keep the wiring away from the power circuits (main circuit and relay sequential circuit).

When the frequency setting is performed using the external potentiometer, not using the parameter unit, use a shielded or twisted cable as shown in the figure below. Connect the shield cable to the terminal 5, not to the earth (ground).



### ◆ Earth (ground)

When the inverter is set for the low acoustic noise operation, the leakage current increases compared to in the normal operation due to the high speed switching operation. Always earth (ground) the inverter, the converter unit, and the motor. Also, always use the earth (ground) terminal of the inverter/the converter unit for earthing (grounding). (Do not use a case or chassis.)

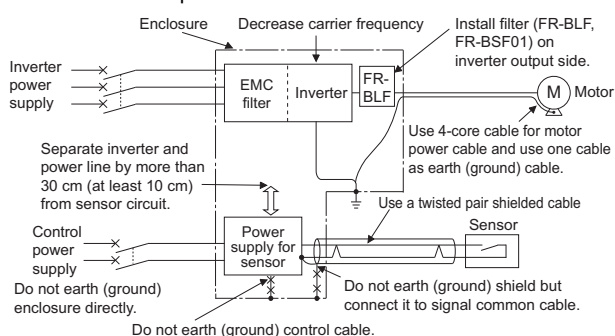


### ◆ Electromagnetic interference (EMI)

For the low acoustic noise operation with high carrier frequency, electromagnetic noise tends to increase. Take countermeasures by referring to the following examples. Depending on an installation condition, noise may affect the inverter also in the normal operation (initial status).

- Decrease the carrier frequency (**Pr.72**) setting to lower the EMI level.
- For countermeasures against the noise in AM radio broadcasting or malfunction of sensors, turn ON the EMC filter. (For the switching method, refer to the Instruction Manual.)
- For effective reduction of induction noise from the power cable of the inverter/the converter unit, secure the distance of 30 cm (at least 10 cm) from the power line and use a shielded twisted pair cable for the signal cable. Do not earth (ground) the shield, and connect the shield to a common terminal by itself.

#### EMI measure example



### ◆ leakage current

Capacitances exist between the inverter/the converter unit I/O cables and other cables or the earth, and within the motor, through which a leakage current flows. Since its value depends on the static capacitances, carrier frequency, etc., low acoustic noise operation at the increased carrier frequency of the inverter will increase the leakage current. Therefore, take the following countermeasures. Select the earth leakage circuit breaker according to its rated sensitivity current, independently of the carrier frequency setting.

#### ◆ To-earth (ground) leakage currents

Type	Influence and countermeasure
Influence and countermeasure	<ul style="list-style-type: none"> <li>• Leakage currents may flow not only into the inverter/the converter unit's own line but also into the other lines through the earthing (grounding) cable, etc. These leakage currents may operate earth leakage circuit breakers and earth leakage relays unnecessarily.</li> <li>Countermeasure</li> <li>• If the carrier frequency setting is high, decrease the <b>Pr.72 PWM frequency selection</b> setting. However, the motor noise increases. Selecting <b>Pr.240 Soft-PWM operation selection</b> makes the sound inoffensive.</li> <li>• By using earth leakage circuit breakers designed for harmonic and surge suppression in the inverter's own line and other line, operation can be performed with the carrier frequency kept high (with low noise).</li> </ul>
Transmission path	<p>The diagram shows the transmission path for leakage current. It starts from the power supply, goes through a leakage breaker (NV1), then through the inverter, and finally through the motor. Another path is shown through a second leakage breaker (NV2) and another motor. Capacitors (C) are shown representing static capacitances between the lines and ground.</p>

### ◆ Line-to-line leakage current

Type	Influence and countermeasure
Influence and countermeasure	<ul style="list-style-type: none"> <li>• Line-to-line leakage current flows through the capacitance between the inverter/the converter unit output lines.</li> <li>• Harmonic component of the leaked current may cause unnecessary operation of an external thermal relay. Long wiring length (50 m or longer) for the 400V class small capacity models (7.5 kW or lower) will increase the rate of leakage current against the rated motor current. In such a case, an unnecessary operation of the external thermal relay may be more liable to occur.</li> <li>Countermeasure</li> <li>• Use <b>Pr.9 Electronic thermal O/L relay</b>.</li> <li>• If the carrier frequency setting is high, decrease the <b>Pr.72 PWM frequency selection</b> setting. However, the motor noise increases. Selecting <b>Pr.240 Soft-PWM operation selection</b> makes the sound inoffensive.</li> <li>To protect motor securely without being subject to the influence of the line-to-line leakage current, direct detection of the motor temperature using a temperature sensor is recommended.</li> </ul>
Transmission path	<p>The diagram shows the transmission path for line-to-line leakage current. It starts from the power supply, goes through an MCCB and MC, then through the inverter/converter, and finally through the motor. Capacitors (C) are shown representing line-to-line static capacitances between the inverter output lines.</p>

### ◆ Harmonic Suppression Guidelines

Inverters have a converter section (rectifier circuit) and generate a harmonic current. Harmonic currents flow from the inverter to a power receiving point via a power transformer. The Harmonic Suppression Guidelines was established to protect other consumers from these outgoing harmonic currents.

The three-phase 200 V input specifications 3.7 kW or lower were previously covered by the "Harmonic Suppression Guidelines for Household Appliances and General-purpose Products" and other models were covered by the "Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage". However, the general-purpose inverter has been excluded from the target products covered by the "Harmonic Suppression Guidelines for Household Appliances and General-purpose Products" in January 2004 and the "Harmonic Suppression Guideline for Household Appliances and General-purpose Products" was repealed on September 6, 2004.

All capacity and all models of general-purpose inverter used by specific consumers are now covered by the "Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage".

- "Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage"
  - This guideline sets the maximum values of outgoing harmonic currents generated from a high-voltage or specially high-voltage receiving consumer who will install, add or renew harmonic generating equipment. If any of the maximum values is exceeded, this guideline requires that consumer to take certain suppression measures.
  - The users who are not subjected to the above guidelines do not need follow the guidelines, but the users are recommended to connect a DC reactor and an AC reactor as usual.



Compliance with the "Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage"

Input power	Target capacity	Countermeasure
Three-phase 200 V	All capacities	Confirm the compliance with the "Harmonic Suppression Guidelines for Consumers Who Receive High Voltage or Special High Voltage" published in September 1994 by the Ministry of International Trade and Industry (the present Japanese Ministry of Economy, Trade and Industry). Take countermeasures if required. Use the following materials as reference to calculate the power supply harmonics. Reference materials • "Harmonic Suppression Measures of the General-purpose Inverter" January 2004, Japan Electrical Manufacturers' Association • "Calculation Method of Harmonic Current of the General-purpose Inverter Used by Specific Consumers" JEM-TR201 (Revised in December 2003), Japan Electrical Manufacturers' Association
Three-phase 400 V		

For compliance to the "Harmonic Suppression Guideline of the General-purpose Inverter (Input Current of 20A or Less) for Consumers Other Than Specific Consumers" published by JEMA

Input power	Target capacity	Measures
Three-phase 200 V	3.7 kW or lower	Connect the AC reactor or DC reactor recommended in the Catalogs and Instruction Manuals. Reference materials • "Harmonic Suppression Guideline of the General-purpose Inverter (Input Current of 20A or Less)" JEM-TR226 (Published in December 2003), Japan Electrical Manufacturers' Association

◆ Calculation of outgoing harmonic current

Outgoing harmonic current = fundamental wave current (value converted from received power voltage) × operation ratio × harmonic content

- Operation ratio: Operation ratio = actual load factor × operation time ratio during 30 minutes
- Harmonic content: Found in the table below.

- Harmonic contents (values when the fundamental wave current is 100%)

Reactor	5th	7th	11th	13th	17th	19th	23rd	25th
Not used	65	41	8.5	7.7	4.3	3.1	2.6	1.8
Used (AC side)	38	14.5	7.4	3.4	3.2	1.9	1.7	1.3
Used (DC side)	30	13	8.4	5.0	4.7	3.2	3.0	2.2
Used (AC, DC sides)	28	9.1	7.2	4.1	3.2	2.4	1.6	1.4

- Rated capacities and outgoing harmonic currents when driven by inverter

Applied motor (kW)	Fundamental wave current (A)		Fundamental wave current converted from 6.6 kV (mA)	Rated capacity (kVA)	Outgoing harmonic current converted from 6.6 kV (mA) (No reactor, 100% operation ratio)									
	200 V	400 V			5th	7th	11th	13th	17th	19th	23rd	25th		
0.4	1.61	0.81	49	0.57	31.85	20.09	4.165	3.773	2.107	1.519	1.274	0.882		
0.75	2.74	1.37	83	0.97	53.95	34.03	7.055	6.391	3.569	2.573	2.158	1.494		
1.5	5.50	2.75	167	1.95	108.6	68.47	14.20	12.86	7.181	5.177	4.342	3.006		
2.2	7.93	3.96	240	2.81	156.0	98.40	20.40	18.48	10.32	7.440	6.240	4.320		
3.7	13.0	6.50	394	4.61	257.1	161.5	33.49	30.34	16.94	12.21	10.24	7.092		
5.5	19.1	9.55	579	6.77	376.1	237.4	49.22	44.58	24.90	17.95	15.05	10.42		
7.5	25.6	12.8	776	9.07	504.4	318.2	65.96	59.75	33.37	24.06	20.18	13.97		
11	36.9	18.5	1121	13.1	728.7	459.6	95.29	86.32	48.20	34.75	29.15	20.18		
15	49.8	24.9	1509	17.6	980.9	618.7	128.3	116.2	64.89	46.78	39.24	27.16		
18.5	61.4	30.7	1860	21.8	1209	762.6	158.1	143.2	79.98	57.66	48.36	33.48		
22	73.1	36.6	2220	25.9	1443	910.2	188.7	170.9	95.46	68.82	57.72	39.96		
30	98.0	49.0	2970	34.7	1931	1218	252.5	228.7	127.7	92.07	77.22	53.46		
37	121	60.4	3660	42.8	2379	1501	311.1	281.8	157.4	113.5	95.16	65.88		
45	147	73.5	4450	52.1	2893	1825	378.3	342.7	191.4	138.0	115.7	80.10		
55	180	89.9	5450	63.7	3543	2235	463.3	419.7	234.4	169.0	141.7	98.10		

Applied motor (kW)	Fundamental wave current (A)		Fundamental wave current converted from 6.6 kV (mA)	Rated capacity (kVA)	Outgoing harmonic current converted from 6.6 kV (mA) (With a DC reactor, 100% operation ratio)									
	200 V	400 V			5th	7th	11th	13th	17th	19th	23rd	25th		
75	245	123	7455	87.2	2237	969	626	373	350	239	224	164		
90	293	147	8909	104	2673	1158	748	445	419	285	267	196		
110	357	179	10848	127	3254	1410	911	542	510	347	325	239		
132	-	216	13091	153	3927	1702	1100	655	615	419	393	288		
160	-	258	15636	183	4691	2033	1313	782	735	500	469	344		
220	-	355	21515	252	6455	2797	1807	1076	1011	688	645	473		
250	-	403	24424	286	7327	3175	2052	1221	1148	782	733	537		
280	-	450	27273	319	8182	3545	2291	1364	1282	873	818	600		
315	-	506	30667	359	9200	3987	2576	1533	1441	981	920	675		
355	-	571	34606	405	10382	4499	2907	1730	1627	1107	1038	761		
400	-	643	38970	456	11691	5066	3274	1949	1832	1247	1169	857		
450	-	723	43818	512	13146	5696	3681	2191	2060	1402	1315	964		
500	-	804	48727	570	14618	6335	4093	2436	2290	1559	1462	1072		
560	-	900	54545	638	16364	7091	4582	2727	2564	1746	1636	1200		
630	-	1013	61394	718	18418	7981	5157	3070	2886	1965	1842	1351		

- Conversion factors

Classification	Circuit type	Conversion coefficient Ki	
3	Three-phase bridge (Capacitor smoothing)	Without reactor	K31 = 3.4
		With reactor (AC side)	K32 = 1.8
		With reactor (DC side)	K33 = 1.8
		With reactors (AC, DC sides)	K34 = 1.4
5	Self-excitation three-phase bridge	When a high power factor converter is used K5 = 0	

- Features
- Application Example
- FR Configurator2
- Connection Examples
- Standard Specs
- Outline Dimensions
- Terminal Connection Diagrams
- Terminal Specs
- Operation Panel
- Parameter List
- Explanations of Parameters
- Protective Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty Inquiry

# Compatible Motors

## List of applicable inverter models by rating (motor capacity → inverter model)

For the combinations within the thick borders, always connect a DC reactor (FR-HEL), which is available as an option.

### ◆ 200 V class (model: FR-A820-[])

Motor capacity (kW) <sup>*1</sup>	DC reactor	SLD (superlight load)			LD (light load)			ND (normal load, initial value)			HD (heavy load)		
	FR-HEL-[]	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)		
0.2	0.4K <sup>*2</sup>	0.4K	00046	4.6	0.4K	00046	4.2	0.4K	00046	3	0.4K	00046	1.5
0.4	0.4K							0.75K	00077	3	0.75K	00077	3
0.75	0.75K							1.5K	00105	5	1.5K	00105	5
1.5	1.5K	0.75K	00077	7.7	0.75K	00077	7	1.5K	00105	8	2.2K	00167	8
2.2	2.2K	1.5K	00105	10.5	1.5K	00105	9.6	2.2K	00167	11	3.7K	00250	11
3.7	3.7K	2.2K	00167	16.7	2.2K	00167	15.2	3.7K	00250	17.5	5.5K	00340	17.5
5.5	5.5K	3.7K	00250	25	3.7K	00250	23	5.5K	00340	24	7.5K	00490	24
7.5	7.5K	5.5K	00340	34	5.5K	00340	31	7.5K	00490	33	11K	00630	33
11	11K	7.5K	00490	49	7.5K	00490	45	11K	00630	46	15K	00770	46
15	15K	11K	00630	63	11K	00630	58	15K	00770	61	18.5K	00930	61
18.5	18.5K	15K	00770	77	15K	00770	70.5	18.5K	00930	76	22K	01250	76
22	22K	18.5K	00930	93	18.5K	00930	85	22K	01250	90	30K	01540	90
30	30K	22K	01250	125	22K	01250	114	30K	01540	115	37K	01870	115
37	37K	30K	01540	154	30K	01540	140	37K	01870	145	45K	02330	145
45	45K	37K	01870	187	37K	01870	170	45K	02330	175	55K	03160	175
55	55K	45K	02330	233	45K	02330	212	55K	03160	215	75K	03800	215
75	75K	55K	03160	316	55K	03160	288	75K	03800	288	90K	04750	288
90	90K	75K	03800	380	75K	03800	346	90K	04750	346	-	-	-
110	110K	90K	04750	475	90K	04750	432	-	-	-	-	-	-
132	110K <sup>*3</sup>	90K	04750	475	-	-	-	-	-	-	-	-	-

### ◆ 400 V class (model: FR-A840-[])

Motor capacity (kW) <sup>*1</sup>	DC reactor	SLD (superlight load)			LD (light load)			ND (normal load, initial value)			HD (heavy load)		
	FR-HEL-[]	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)		
0.2	H0.4K <sup>*2</sup>	0.4K	00023	2.3	0.4K	00023	2.1	0.4K	00023	1.5	0.4K	00023	0.8
0.4	H0.4K							0.75K	00038	2.5	0.75K	00038	1.5
0.75	H0.75K							1.5K	00052	2.5	1.5K	00052	2.5
1.5	H1.5K	0.75K	00038	3.8	0.75K	00038	3.5	1.5K	00052	4	2.2K	00083	4
2.2	H2.2K	1.5K	00052	5.2	1.5K	00052	4.8	2.2K	00083	6	3.7K	00126	6
3.7	H3.7K	2.2K	00083	8.3	2.2K	00083	7.6	3.7K	00126	9	5.5K	00170	9
5.5	H5.5K	3.7K	00126	12.6	3.7K	00126	11.5	5.5K	00170	12	7.5K	00250	12
7.5	H7.5K	5.5K	00170	17	5.5K	00170	16	7.5K	00250	17	11K	00310	17
11	H11K	7.5K	00250	25	7.5K	00250	23	11K	00310	23	15K	00380	23
15	H15K	11K	00310	31	11K	00310	29	15K	00380	31	18.5K	00470	31
18.5	H18.5K	15K	00380	38	15K	00380	35	18.5K	00470	38	22K	00620	38
22	H22K	18.5K	00470	47	18.5K	00470	43	22K	00620	44	30K	00770	44
30	H30K	22K	00620	62	22K	00620	57	30K	00770	57	37K	00930	57
37	H37K	30K	00770	77	30K	00770	70	37K	00930	71	45K	01160	71
45	H45K	37K	00930	93	37K	00930	85	45K	01160	86	55K	01800	86
55	H55K	45K	01160	116	45K	01160	106	55K	01800	110	75K	02160	110
75	H75K	55K	01800	180	55K	01800	144	75K	02160	144	90K	02600	144
90	H90K	75K	02160	216	75K	02160	180	90K	02600	180	110K	03250	180
110	H110K	90K	02600	260	90K	02600	216	110K	03250	216	132K	03610	216
132	H132K	110K	03250	325	110K	03250	260	132K	03610	260	160K	04320	260
160	H160K	132K	03610	361	132K	03610	325	160K	04320	325	185K	04810	325
185	H185K	160K	04320	432	160K	04320	361	185K	04810	361	220K	05470	361
220	H220K	185K	04810	481	185K	04810	432	220K	05470	432	250K	06100	432
250	H250K	220K	05470	547	220K	05470	481	250K	06100	481	280K	06830	481
280	H280K	250K	06100	610	250K	06100	547	280K	06830	547	-	-	-
315	H315K	280K	06830	683	280K	06830	610	-	-	-	-	-	-
355	H355K	280K	06830	683	-	-	-	-	-	-	-	-	-

### ◆ 400 V class (model: FR-A842-[])

Motor capacity (kW) <sup>*1</sup>	Converter unit	SLD (superlight load)			LD (light load)			ND (normal load, initial value)			HD (heavy load)		
	FR-CC2-[]	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)	Model	Rated current (A)		
280	H315K	-	-	-	-	-	-	-	-	-	-	-	
315	H315K	-	-	-	-	-	-	315K	07700	610	355K	08660	610
355	H355K	-	-	-	315K	07700	683	355K	08660	683	400K	09620	683
400	H400K	315K	07700	770	355K	08660	770	400K	09620	770	450K	10940	770
450	H450K	355K	08660	866	400K	09620	866	450K	10940	866	500K	12120	866
500	H500K	400K	09620	962	450K	10940	962	500K	12120	962	-	-	-
560	H560K	450K	10940	1094	500K	12120	1094	-	-	-	-	-	-
630	H630K	500K	12120	1212	-	-	-	-	-	-	-	-	-

\*1 Indicates the maximum capacity applicable with the Mitsubishi 4-pole standard motor.

\*2 The power factor may be slightly lower.

\*3 The FR-HEL-110K supports the 200 V class 132 kW motor.

### ◆ Overload current rating

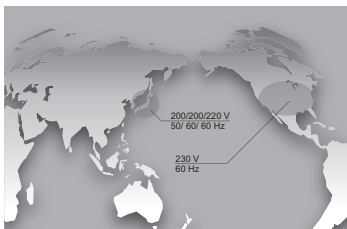
SLD	110% 60 s, 120% 3 s (inverse-time characteristics) at surrounding air temperature 40°C
LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature 50°C
ND	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature 50°C
HD	200% 60 s, 250% 3 s (inverse-time characteristics) at surrounding air temperature 50°C

## High-performance energy-saving motor superline premium series SF-PR



### ◆ One motor conforms to the power supply in Japan and the United States.

- The SF-PR series conform to the Top Runner Standard of the "Act on the Rational Use of Energy (energy saving law)" to be applied on April 1, 2015.
- The 230 V 60 Hz motor also conforms to the Energy Independence and Security Act (EISA).



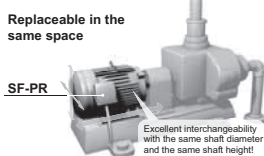
200	200	220	230	V
50	60	60	60	Hz

+ For the 200 V class

In Japan      In the United States

### ◆ Interchangeable installation size

- Replacement can be smoothly performed because the installation size (frame number) is compatible with our standard efficiency motor SF-JR series.
- It is possible to use a power distribution control equipment (thermal relay and breaker), which is the same as a conventional model.



- \*1 For the frame number 180 LD or higher and some models of the 6-pole product, the total length or diametrical dimension is greatly different.
- \*2 The frame number is different from 1.5 kW6P (112M), 2.2 kW6P(132S) of the SF-JR models.
- \*3 When replacing the SF-JR to the SF-PR, it is required to consider upgrading the contactor to secure the same electric durability as using the SF-JR because the electric durability of the contactor may reduce by about 30%. Besides, when replacing the SF-JR to the SF-PR, the existing thermal relay may trip depending on the operating conditions (long starting time). As a countermeasure, consider "Adjusting the heater set value of the thermal" or "Adopting the thermal with a saturated reactor", etc.
- \*4 If the breaker NF400-SW manufactured by Mitsubishi Electric is used with the 55 kW motor, change the breaker. (Change the rated current of the breaker NF400-SW from 300 A to 350 A.)

We have released the superline premium series SF-PR models compatible with the Top Runner Standard in Japan, which is equivalent with IE3 premium efficiency for three-phase motors, and with the Energy Independence and Security Act (EISA) in the United States.

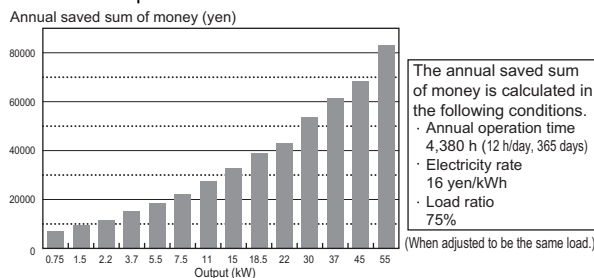
The SF-PR has achieved the efficiency class IE3 with the same dimensions as those of conventional models using our unique technology of the steel plate frame and new core materials. It maintains interchangeability with our standard efficiency motor SF-JR and easy replacement becomes possible.

By adopting a high-efficiency motor, energy savings in plant facilities and reduction of electricity consumption are expected, as well as the effects of recovering the investment cost.

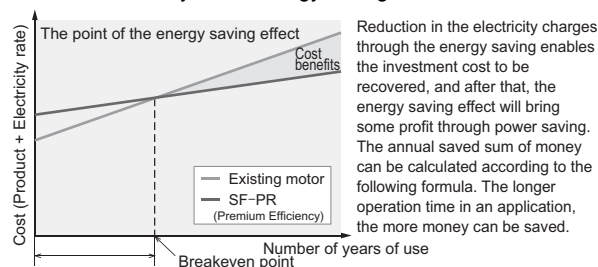
### ◆ Introduction effects of the superline premium series SF-PR

The SF-PR motor conforms to the Top Runner Standard (IE3 equivalent), which remarkably reduces its operation cost (electricity charges) and greatly contributes minimization of TCO (Total Cost Ownership).

- Trial calculation example of an annual saved sum of money (at upgrading the motor from energy-efficiency class IE1 to IE3) Motor with 4-poles 200 V50 Hz



- Economic efficiency on an energy saving effect



Recovery period for the amount of a price increase

<Calculation formula>

$$\text{Output (kW)} \times \left( \frac{100}{\text{Efficiency of current motor (\%)}} - \frac{100}{\text{Efficiency of SF-PR model (\%)}} \right) \times \text{Number of motors} \times \text{Number of hours of use (h/day)} \times \text{Number of days of operation (day/year)} \times \text{Electricity rate (yen/kWh)}$$

When replacing our standard motor SF-JR with the SF-PR on the ventilation fan in plant

<Condition>  
 Type : 11 kW 4P 200 V 50 Hz 75% load  
 Units : 10 units  
 Operation time : 12 h/day 365 day/year  
 Electricity rate : 16 yen/kWh

Reduced cost of about 350,000 yen per year

Trial calculation results in replacing the SF-JR with the SF-PR with improved efficiency by 5% under the same conditions of the load factor, operation time, and electricity charges, etc.

- Features
- Application Example
- PLC Function
- FR Configurator2
- Connection Examples
- Standard Specs
- Outline Dimensions
- Terminal Connection Diagrams
- Terminal Specs
- Operation Panel
- Parameter List
- Explanations of Parameters
- Protective Functions
- Options
- LVS/Cables
- Precautions
- Motors
- Compatibility
- Warranty Inquiry



◆ Lineup

●Model

S F - P R V O B - K R

Symbol	Structure	Symbol	Enclosure type	Symbol	Series	Symbol	Installation	Symbol	Classification	Symbol	Classification	Symbol	Country code
S	Superline series	F	Totally enclosed fan-cooled	PR	Premium series Steel plate frame	None	Foot mounting type	None	Indoor type (IP44)	None	Without brake	None	Japan and the U.S.A.
						V	Vertical type	O	Outdoor type (IP44)	B	With brake	KR	Korea
						F	Flange type	P	Dust-proof and waterproof type(IP55)			EU	Europe

●Available models

Type	Totally-enclosed fan-cooled type														
	Foot mounting type			Vertical type			Flange type			Outdoor type			Dustproof/waterproof type		
Model	SF-PR			SF-PRV			SF-PRF			SF-PRO			SF-PRP		
Number of poles	2P	4P	6P	2P	4P	6P	2P	4P	6P	2P	4P	6P	2P	4P	6P
Output (kW)	0.75	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	1.5	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	2.2	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	3.7	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	5.5	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	7.5	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	11	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	15	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	18.5	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	22	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	30	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	37	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	45	•	•	•	•	•	•	•	•	•	•	•	•	•	•
	55	•	•	—	•	•	—	—	—	—	•	•	—	•	•

• The vertical type and the flange type are also available for the outdoor type and the dustproof/waterproof type.

•: Available model

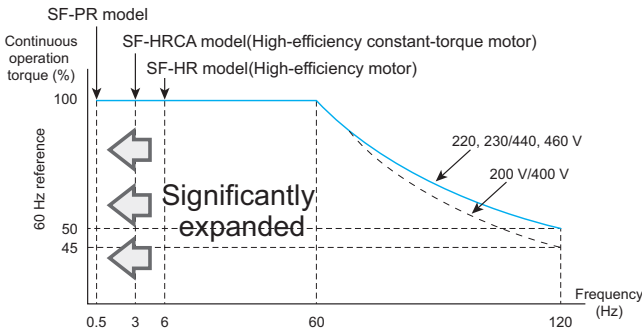
● The SF-PR best matches Mitsubishi inverters

◆ This enables a constant-torque operation in the low-speed range. (expanding the constant-torque range)

- Combining with the standard motor SF-PR enables a constant-torque operation in the low-speed range.
- The SF-PR has superior performance to the SF-HRCA.
- The 400 V class motors are insulation-enhanced motors as standard.

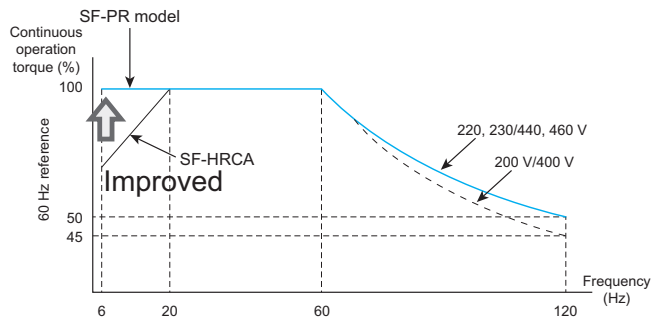
◆ Combination with Advanced magnetic flux vector control

- Enables a constant-torque operation down to 0.5 Hz in a super low-speed range.  
Expanding the constant-torque continuous operation range enables 0.5 to 60 Hz (1: 120) operation.



◆ Combination with V/F control

- Enables a constant-torque operation down to 6 Hz in a low-speed range.  
Expanding the constant-torque continuous operation range enables 6 to 60 Hz (1: 10) operation.

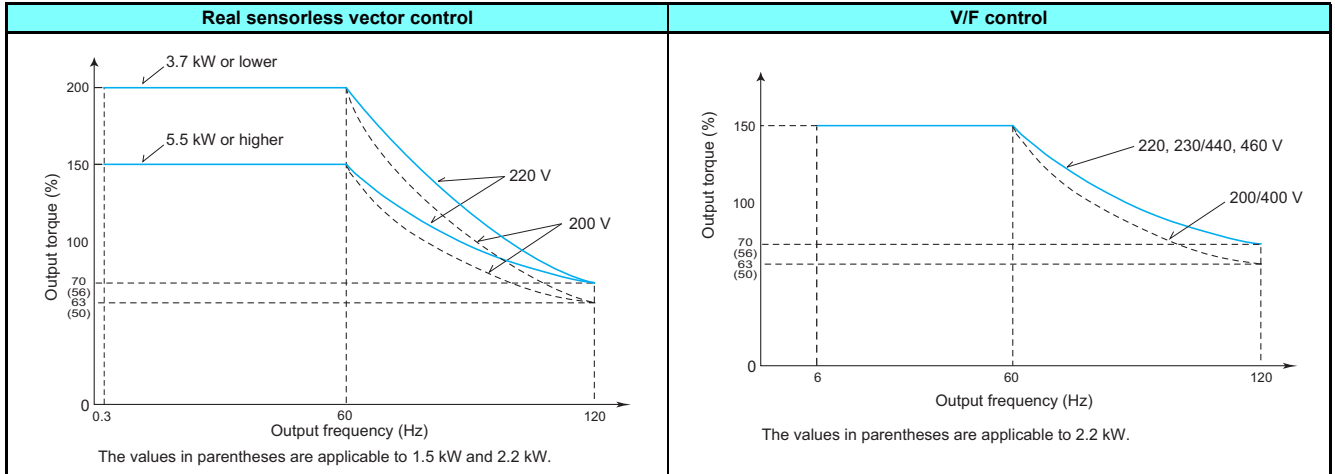


60 Hz torque reference indicates that the rated motor torque is 100% during 60 Hz operation.

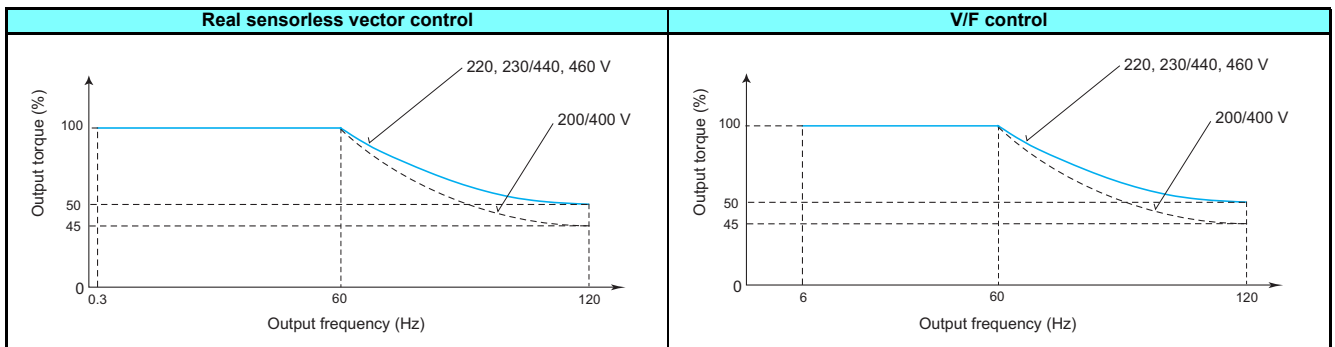
◆ Motor torque

The following shows torque characteristics of the high-performance, energy-saving motor (SF-PR, 4-pole) in combination with an inverter with the ND or HD rating. The overload capacity decreases for the LD or SLD rating. Observe the specified range of the inverter.

◆ Maximum short-time torque



◆ Continuous torque



Features  
Application Example  
PLC Function  
FR Configurator 2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry



## ● Application to standard motors

### ◆ Motor loss and temperature rise

The motor operated by the inverter has a limit on the continuous operating torque since it is slightly higher in temperature rise than the one operated by a commercial power supply. At a low speed, reduce the output torque of the motor since the cooling effect decreases. When 100% torque is needed continuously at low speed, consider using a constant-torque motor.

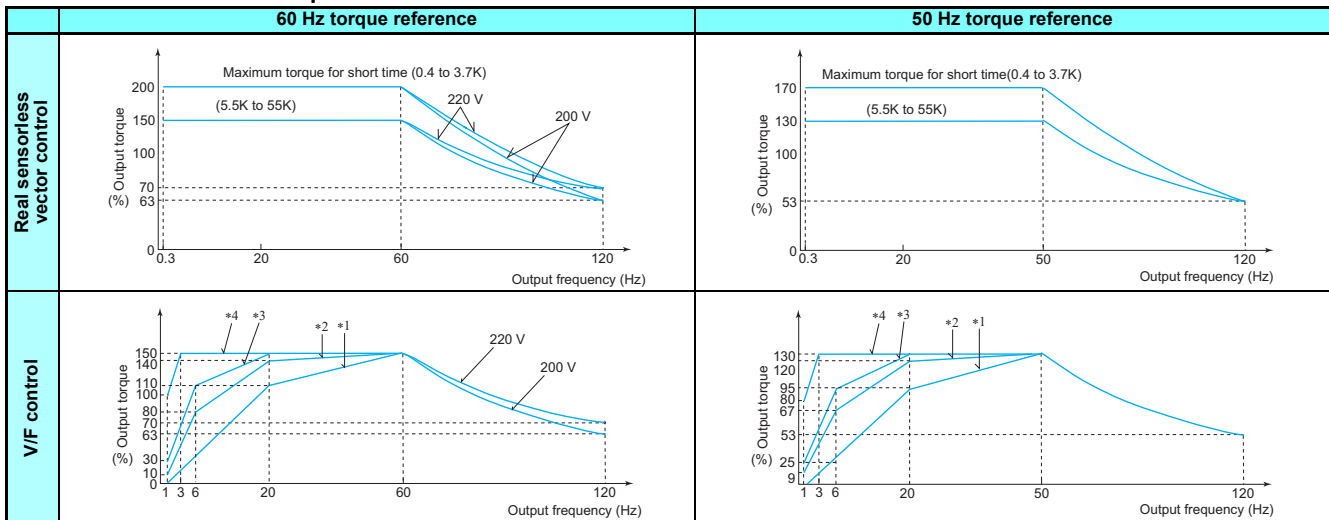
### ◆ Torque characteristic

The motor operated by the inverter may be less in motor torque (especially starting torque) than the one driven by the commercial power supply. It is necessary to fully check the load torque characteristic of the machine.

### ◆ Motor torque

When the Mitsubishi standard squirrel cage motor (SF-JR, 4-pole) and inverter of the same capacity are used, the torque characteristics are as shown below. It is assumed that the motor is used in combination with an inverter with the ND or HD rating. The overload capacity decreases when the LD or SLD rating is selected. Observe the specified range of the inverter.

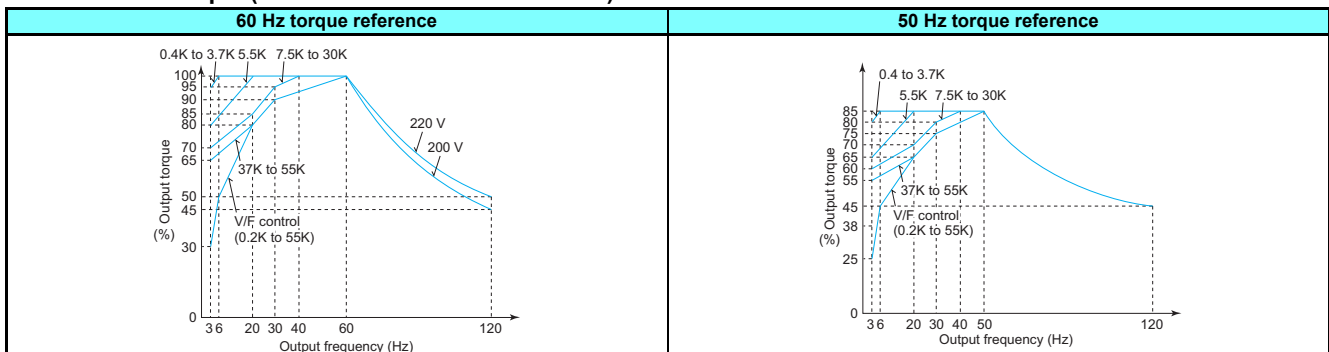
### ◆ Maximum short-time torque



- \*1 Torque boost minimum (0%)
- \*2 Torque boost standard (initial value)
- \*3 Torque boost large  
 10%: FR-A820-00046(0.4K), FR-A820-00077(0.75K), FR-A840-00023(0.4K), FR-A840-00038(0.75K)  
 7%: FR-A820-00105(1.5K) to FR-A820-00250(3.7K), FR-A840-00052(1.5K) to FR-A840-00126(3.7K)  
 6%: FR-A820-00340(5.5K), FR-A820-00490(7.5K), FR-A840-00170(5.5K), FR-A840-00250(7.5K)  
 4%: FR-A820-00630(11K) or higher, FR-A840-00310(11K) or higher
- \*4 Torque boost adjustment (3.7 kW or lower)

- The maximum short-time torque indicates the maximum torque characteristics within 60 s.
- Under Real sensorless vector control, 200% (150%) torque (60 Hz torque reference) is output at 0.3 Hz operation.
- A 60 Hz torque reference indicates that the rated torque of the motor running at 60 Hz is 100%, and a 50 Hz torque reference indicates that the rated torque of the motor running at 50 Hz is 100%
- Under V/F control, all of SF-JR 2-pole, 4-pole, and 6-pole motors have the same torque characteristics.

### ◆ Continuous torque (Real sensorless vector control)



- A general-purpose squirrel cage motor must be used at lower continuous operating torque in rated operation as shown in the chart since the cooling capability of the fan installed on the rotor reduces at a lower speed. (Instantaneous torque occurs.)
- The torque with 200 or 220 V at 60 Hz or 200 V at 50 Hz in the chart indicates a motor torque reference (base torque reference (base frequency set in Pr.3 of the inverter) and is not the frequency of the power supply. In a 50 Hz power supply area, the 60 Hz setting can be set.
- As shown in the chart, the 60 Hz torque reference setting can bring out the 100% torque of the motor continuously, enabling more efficient use of the motor.
- When continuously operating a motor with the 50 Hz torque reference setting, set the load torque to 85% or lower.

● Application to constant-torque motors

◆ SF-HRCA type

- Continuous operation even at low speed of 0.3 Hz is possible (when using Real sensorless vector control). For the 37 kW or lower (except for 22 kW), load torque is not needed to be reduced even at a low speed and constant torque (100% torque) continuous operation is possible within the range of speed ratio 1/20 (3 to 60 Hz). (The characteristic of motor running at 60 Hz or higher is that output torque is constant.)
- Installation size is the same as that of the standard motor.
- Note that operation characteristic in the chart below cannot be obtained if V/F control is used.

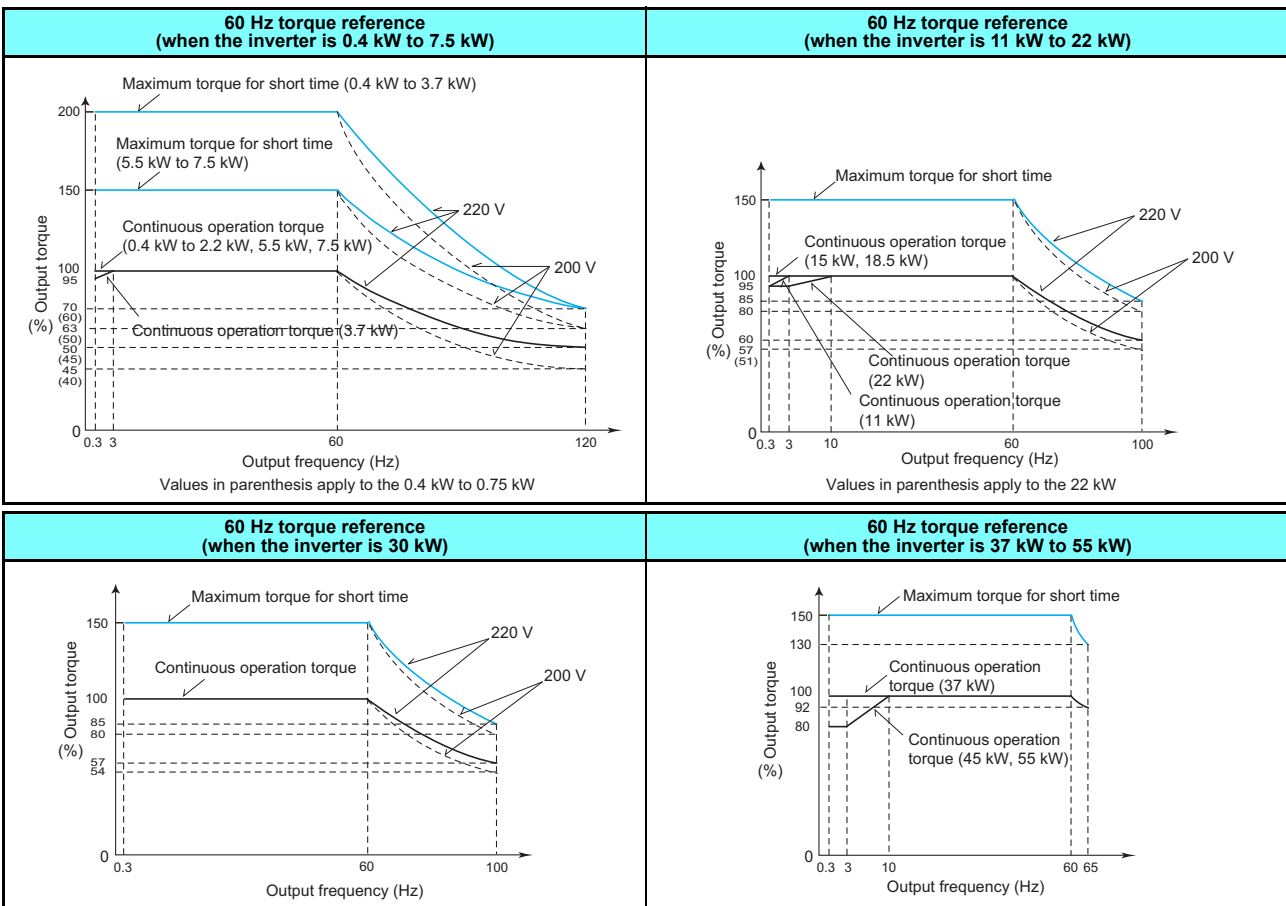
◆ Standard specifications (indoor type)

Output (kW)	Number of poles	Frequency range	Common specification
0.4	4	3 to 120 Hz	Base frequency 60 Hz • Rotation direction (CCW) Counterclockwise when viewed from the motor end • Lead wire 3.7 kW or lower: 3 wires 5.5 kW or higher: 6 or 12 wires • Surrounding air temperature: 40°C or lower The protective structure is IP44.
0.75			
1.5			
2.2			
3.7			
5.5		3 to 100 Hz	
7.5			
11			
15			
18.5			
22	3 to 65 Hz		
30			
37			
45			
55			

◆ Motor torque

It is assumed that the motor is used in combination with an inverter with the ND or HD rating. The overload capacity decreases when the LD or SLD rating is selected. Observe the specified range of the inverter.

◆ Continuous rated range of use (Real sensorless vector control)



The maximum short-time torque indicates the maximum torque characteristics within 60 s. For the motor constant under Real sensorless vector control, please contact your sales representative.

Features  
 Application Example  
 FR Configurator 2  
 Connection Examples  
 Standard Specs  
 Outline Dimensions  
 Terminal Connection Diagrams  
 Terminal Specs  
 Operation Panel  
 Parameter List  
 Explanations of Parameters  
 Protective Functions  
 Options  
 LVS/Cables  
 Precautions  
**Motors**  
 Compatibility  
 Warranty Inquiry

## ● Application to vector control dedicated motors (SF-V5RU) (55 kW or lower)

For performing vector control, the FR-A8AP/FR-A8TP (vector control compatible option) is required.

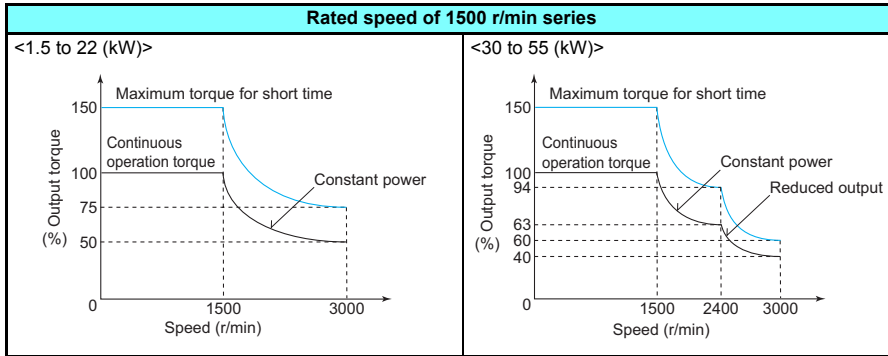
When the FR-A8TP is not used, a 12 V or 24 V power supply is required as the power supply for the encoder of the SF-V5RU. (When the FR-A8TP is used, the 24 V power supply of the FR-A8TP can be used for the encoder of the SF-V5RU.)

### ◆ Motor torque

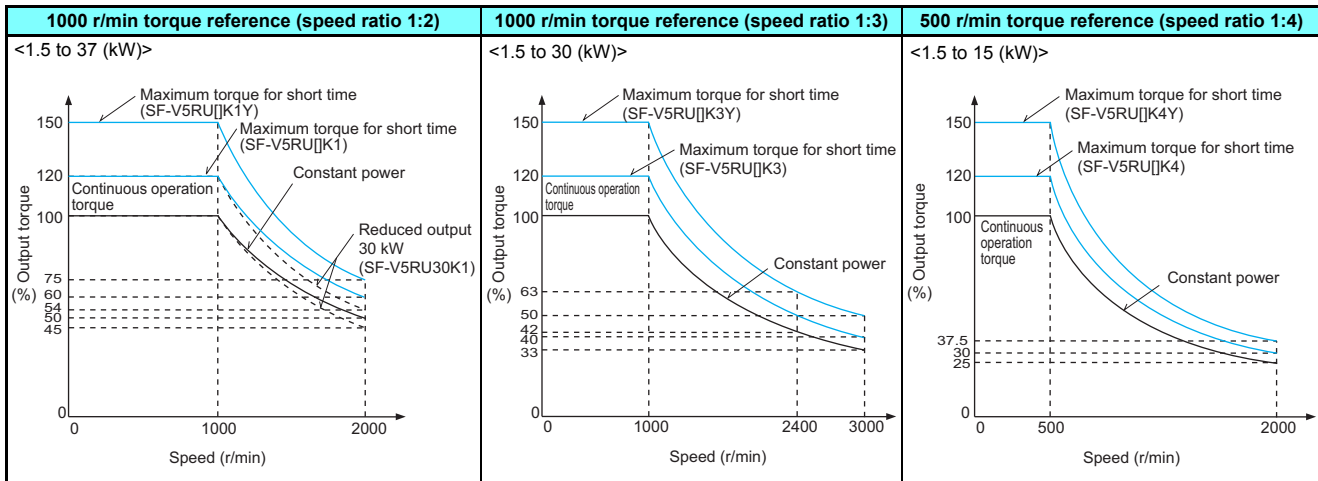
When the vector control dedicated motor (SF-V5RU) and inverter are used, the torque characteristics are as shown below.

It is assumed that the motor is used in combination with an inverter with the ND or HD rating. The overload capacity decreases when the LD or SLD rating is selected. Observe the specified range of the inverter.

- SF-V5RU

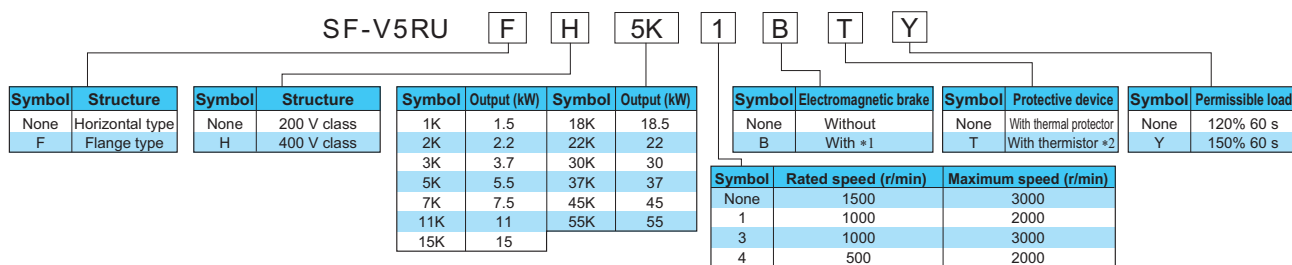


- SF-V5RU1, 3, and 4



- The maximum rotation speed of the SF-V5RU-55kW and SF-V5RU3-30kW is 2400 r/min.
- The SF-V5RU-3.7kW or lower can be operated with the maximum rotation speed of 3600 r/min. For the use of those motors, please contact your sales representative.
- The maximum rotation speed of motors with a brake is 1800 r/min.
- The maximum short-time torque of the SF-V5RU[K1], SF-V5RU[K3], and SF-V5RU[K4] is 120%. As the motor compatible with the maximum short-time torque of 150%, specify the SF-V5RU[K1Y], SF-V5RU[K3Y], or SF-V5RU[K4Y].

◆ Motor model



\*1 Since a brake power device is a stand-alone, install it inside the enclosure. (This device should be arranged at the customer side.)  
 \*2 To use the thermistor function of the thermistor-equipped motor SF-V5RU [T], the plug-in option (FR-A8AZ) is required additionally.

◆ Model lineup (●: Available model, -: Not available)

• Rated speed: 1500 r/min (4 poles)

Model	Standard type	Rated output (kW)	Frame number														
			90L	100L	112M	132S	132M	160M	160L	180M	180L	200L	200L	200L	225S		
Standard horizontal type	SF-V5RU(H)[ ]		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
Flange type	SF-V5RUF(H)[ ]		●	●	●	●	●	●	●	●	●	●	●	●	●	●	-
Standard horizontal type with brake	SF-V5RU(H)[ ]B		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●
Flange type with brake	SF-V5RUF(H)[ ]B		●	●	●	●	●	●	●	●	●	-	-	-	-	-	-

• Rated speed: 1000 r/min (4 poles), maximum speed: 2000 r/min, speed ratio 1:2

Model	Standard type	Rated output (kW)	Frame number											
			100L	112M	132S	132M	160M	160L	180M	180L	200L	200L	225S	
Standard horizontal type	SF-V5RU(H)[ ]1(Y)		●	●	●	●	●	●	●	●	●	●	●	●
Flange type	SF-V5RUF(H)[ ]1(Y)		●	●	●	●	●	●	●	●	●	●	●	-
Standard horizontal type with brake	SF-V5RU(H)[ ]1B(Y)		●	●	●	●	●	●	●	●	●	●	●	●
Flange type with brake	SF-V5RUF(H)[ ]1B(Y)		●	●	●	●	●	●	●	-	-	-	-	-

• Rated speed: 1000 r/min (4 poles), maximum speed: 3000 r/min, speed ratio 1:3

Model	Standard type	Rated output (kW)	Frame number										
			112M	132S	132M	160M	160L	180M	180L	200L	200L	225S	
Standard horizontal type	SF-V5RU(H)[ ]3(Y)		●	●	●	●	●	●	●	●	●	●	●
Flange type	SF-V5RUF(H)[ ]3(Y)		●	●	●	●	●	●	●	●	●	●	-
Standard horizontal type with brake	SF-V5RU(H)[ ]3B(Y)		●	●	●	●	●	●	●	●	●	●	●
Flange type with brake	SF-V5RUF(H)[ ]3B(Y)		●	●	●	●	●	●	-	-	-	-	-

• Rated speed: 500 r/min (4 poles), maximum speed: 2000 r/min, speed ratio 1:4

Model	Standard type	Rated output (kW)	Frame number						
			132M	160M	160L	180L	200L	225S	225S
Standard horizontal type	SF-V5RU(H)[ ]4(Y)		●	●	●	●	●	●	●
Flange type	SF-V5RUF(H)[ ]4(Y)		●	●	●	●	●	-	-
Standard horizontal type with brake	SF-V5RU(H)[ ]4B(Y)		●	●	●	●	●	●	●
Flange type with brake	SF-V5RUF(H)[ ]4B(Y)		●	●	●	-	-	-	-

Since motors with frame No. 250 or higher, 400 V class, speed ratio 1:4 specifications are available as special products, please contact your sales representative.

◆ Combination with the SF-V5RU1, 3, 4, SF-THY and inverter

When using the SF-V5RU1, 3, or 4(Y), always set Pr.83 Rated motor voltage and perform the offline auto tuning according to the instruction manual and additional materials, which are enclosed with the motor, and the instruction manual of the inverter.

		SF-V5RU[1] (1:2)			SF-V5RU[3] (1:3)			SF-V5RU[4] (1:4)		
Voltage		200 V class								
Rated speed		1000 r/min			1000 r/min			500 r/min		
Base frequency		33.33 Hz			33.33 Hz			16.6 Hz		
Maximum speed		2000 r/min			3000 r/min			2000 r/min		
Motor capacity	Motor frame number	Motor model	Inverter model FR-A820-[] (ND rating)	Motor frame number	Motor model	Inverter model FR-A820-[] (ND rating)	Motor frame number	Motor model	Inverter model FR-A820-[] (ND rating)	
1.5 kW	100L	SF-V5RU1K1(Y)	00167(2.2K)	112M	SF-V5RU1K3(Y)	00167(2.2K)	132M	SF-V5RU1K4(Y)	00167(2.2K)	
2.2 kW	112M	SF-V5RU2K1(Y)	00240(3.7K)	132S	SF-V5RU2K3(Y)	00240(3.7K)	160M	SF-V5RU2K4(Y)	00240(3.7K)	
3.7 kW	132S	SF-V5RU3K1(Y)	00340(5.5K)	132M	SF-V5RU3K3(Y)	00340(5.5K)	160L	SF-V5RU3K4-3	00490(7.5K)	
5.5 kW	132M	SF-V5RU5K1(Y)	00490(7.5K)	160M	SF-V5RU5K3(Y)	00490(7.5K)	180L	SF-V5RU5K4(Y)	00490(7.5K)	
7.5 kW	160M	SF-V5RU7K1(Y)	00630(11K)	160L	SF-V5RU7K3(Y)	00630(11K)	200L	SF-V5RU7K4(Y)	00630(11K)	
11 kW	160L	SF-V5RU11K1(Y)	00770(15K)	180M	SF-V5RU11K3(Y)	00770(15K)	225S	SF-V5RU11K4(Y)	00770(15K)	
15 kW	180M	SF-V5RU15K1(Y)	00930(18.5K)	180L	SF-V5RU15K3(Y)	00930(18.5K)	225S	SF-V5RU15K4-3	01250(22K)	
18.5 kW	180L	SF-V5RU18K1(Y)	01250(22K)	200L	SF-V5RU18K3(Y)	01250(22K)	250MD	SF-THY	01250(22K)	
22 kW	200L	SF-V5RU22K1(Y)	01540(30K)	200L	SF-V5RU22K3(Y)	01540(30K)	280MD	SF-THY	01540(30K)	
30 kW	200L-2	SF-V5RU30K1(Y)	01870(37K)	225S-1	SF-V5RU30K3(Y)	01870(37K)	280MD	SF-THY	01870(37K)	
37 kW	225S	SF-V5RU37K1(Y)	02330(45K)	250MD-1	SF-THY	02330(45K)	280MD	SF-THY	02330(45K)	
45 kW	250MD	SF-THY	03160(55K)	250MD-1	SF-THY	03160(55K)	280MD	SF-THY	03160(55K)	
55 kW	250MD	SF-THY	03800(75K)	280MD-1	SF-THY	03800(75K)	280L	SF-THY	03800(75K)	

Models surrounded by black borders and 400 V class are developed upon receipt of order. (For the SF-THY model, refer to page 192.)

\*1 The maximum speed is 2400 r/min.  
 \*2 90% output in the high-speed range. (The output is reduced when the speed is 1000 r/min or faster. For details, please contact your sales representative.)  
 \*3 For motors with overload capacity 150% 60 s ("Y" at the end of their model names), contact your sales representative.

Features  
 Application Example  
 FR Configurator2  
 Connection Examples  
 Standard Specs  
 Outline Dimensions  
 Terminal Connection Diagrams  
 Terminal Specs  
 Operation Panel  
 Parameter List  
 Explanations of Parameters  
 Protective Functions  
 Options  
 LV/S/Cables  
 Precautions  
 Motors  
 Compatibility  
 Warranty Inquiry

## ◆ Motor specifications

### ●200V class (Mitsubishi dedicated motor [SF-V5RU (1500 r/min series)])

Motor type SF-V5RU[ ]JK	1	2	3	5	7	11	15	18	22	30	37	45	55
Applicable inverter model FR-A820-[ ]JK (ND rating)	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
Rated output (kW)	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30 *1	37 *1	45 *1	55
Rated current (A)	8.5	11.5	17.6	28.5	37.5	54	72.8	88	102	126	168	198	264
Rated torque (N*m)	9.55	14.1	23.6	35.0	47.7	70.0	95.5	118	140	191	235	286	350
Maximum torque 150% 60 s (N*m)	14.3	21.1	35.4	52.4	71.6	105	143	176	211	287	353	429	525
Rated speed (r/min)	1500												
Maximum speed (r/min)	3000 *2												2400
Frame No.	90L	100L	112M	132S	132M	160M	160L	180M	180M	200L	200L	200L	225S
Inertia moment J ( $\times 10^{-4}$ kg*m <sup>2</sup> )	67.5	105	175	275	400	750	875	1725	1875	3250	3625	3625	6850
Noise *5	75 dB or less									80 dB or less			85 dB or less
Cooling fan (with thermal protector) *7*8	Voltage	Single-phase 200 V/50 Hz Single-phase 200 V to 230 V/60 Hz					Three-phase 200 V/50 Hz Three-phase 200 to 230 V/60 Hz						
	Input *3	36/55 W (0.26/0.32 A)		22/28 W (0.11/0.13 A)		55/71 W (0.39/0.39 A)			100/156 W (0.47/0.53 A)		85/130 W (0.46/0.52 A)		
	Recommended thermal setting	0.36 A		0.18 A		0.51 A			0.69 A		0.68 A		
Surrounding air temperature, humidity	-10 to +40°C (non-freezing), 90%RH or less (non-condensing)												
Structure (Protective structure)	Totally enclosed forced draft system (Motor: IP44, cooling fan: IP23S) *4												
Detector	Encoder 2048P/R, A phase, B phase, Z phase +12 V/24 VDC power supply *6												
Equipment	Encoder, thermal protector, fan												
Heat resistance class	F												
Vibration rank	V10												
Approx. mass (kg)	24	33	41	52	62	99	113	138	160	238	255	255	320

### ●400V class (Mitsubishi dedicated motor [SF-V5RUH (1500 r/min series)])

Motor type SF-V5RUH[ ]JK	1	2	3	5	7	11	15	18	22	30	37	45	55
Applicable inverter model FR-A840-[ ]JK (ND rating)	2.2	2.2	3.7	7.5	11	15	18.5	22	30	37	45	55	75
Rated output (kW)	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30 *1	37 *1	45 *1	55
Rated current (A)	4.2	5.8	8.8	14.5	18.5	27.5	35.5	44	51	67	84	99	132
Rated torque (N*m)	9.55	14.1	23.6	35.0	47.7	70.0	95.5	118	140	191	235	286	350
Maximum torque 150% 60 s (N*m)	14.3	21.1	35.4	52.4	71.6	105	143	176	211	287	353	429	525
Rated speed (r/min)	1500												
Maximum speed (r/min)	3000 *2												2400
Frame No.	90L	100L	112M	132S	132M	160M	160L	180M	180M	200L	200L	200L	225S
Inertia moment J ( $\times 10^{-4}$ kg*m <sup>2</sup> )	67.5	105	175	275	400	750	875	1725	1875	3250	3625	3625	6850
Noise *5	75 dB or less									80 dB or less			85 dB or less
Cooling fan (with thermal protector) *7*8	Voltage	Single-phase 200 V/50 Hz Single-phase 200 V to 230 V/60 Hz					Three-phase 380 to 400 V/50 Hz Three-phase 400 to 460 V/60 Hz						
	Input *3	36/55 W (0.26/0.32 A)		22/28 W (0.11/0.13 A)		55/71 W (0.19/0.19 A)			100/156 W (0.27/0.30 A)		85/130 W (0.23/0.26 A)		
	Recommended thermal setting	0.36 A		0.18 A		0.25 A			0.39 A		0.34 A		
Surrounding air temperature, humidity	-10 to +40°C (non-freezing), 90%RH or less (non-condensing)												
Structure (Protective structure)	Totally enclosed forced draft system (Motor: IP44, cooling fan: IP23S) *4												
Detector	Encoder 2048P/R, A phase, B phase, Z phase +12 V/24 VDC power supply *6												
Equipment	Encoder, thermal protector, fan												
Heat resistance class	F												
Vibration rank	V10												
Approx. mass (kg)	24	33	41	52	62	99	113	138	160	238	255	255	320

\*1 80% output in the high-speed range. (The output is reduced when the speed is 2400 r/min or more. Contact us separately for details.)

\*2 A dedicated motor of 3.7 kW or less can be run at the maximum speed of 3600 r/min. Consult our sales office when using the motor at the maximum speed.

\*3 Power (current) at 50 Hz/60 Hz.

\*4 Since a motor with brake has a window for gap check, the protective structure of both the cooling fan section and brake section is IP20. S of IP23S is an additional code indicating the condition that protection from water intrusion is established only when a cooling fan is not operating.

\*5 The value when high carrier frequency is set (Pr.72 = 6, Pr.240 = 0).

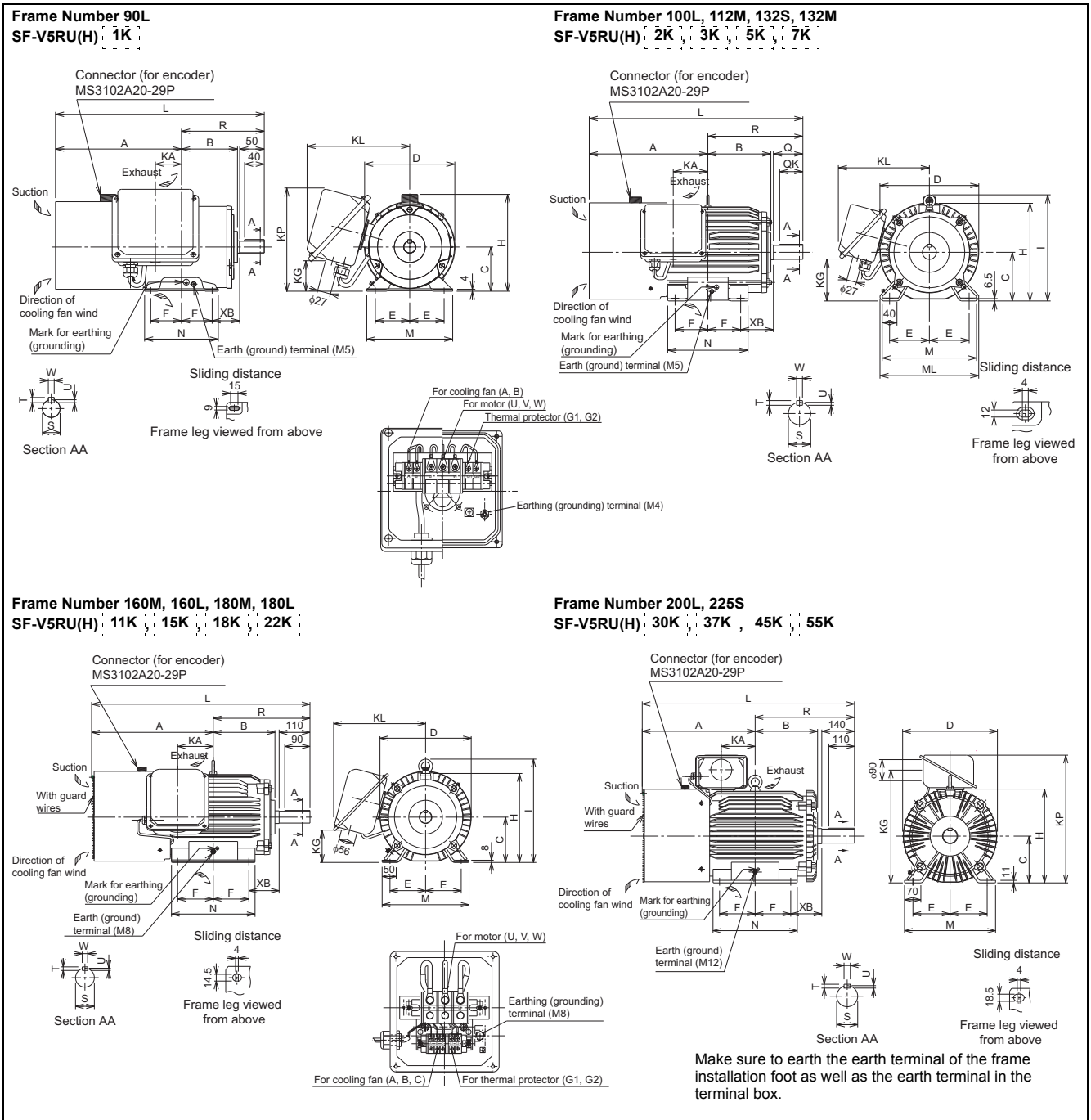
\*6 The 12 V/24 V power supply is required as the power supply for the encoder. (When the FR-A8TP is used, the 24 V power supply of the FR-A8TP can be used for the encoder of the SF-V5RU.)

\*7 The cooling fan is equipped with a thermal protector. The cooling fan stops when the coil temperature exceeds the specified value in order to protect the fan motor. A restrained cooling fan or degraded fan motor insulation could be causes for the rise in coil temperature. The cooling fan re-starts when the coil temperature drops to normal.

\*8 The cooling fan voltage and input values are the basic specifications of the cooling fan alone and free air values. The input value becomes slightly larger when it is rotated by this motor due to an increased workload, but the cooling fan can be used as it is. When preparing a thermal relay at the user side, use the recommended thermal setting.



◆ Dedicated motor outline dimension drawings (standard horizontal type)



Dimensions table

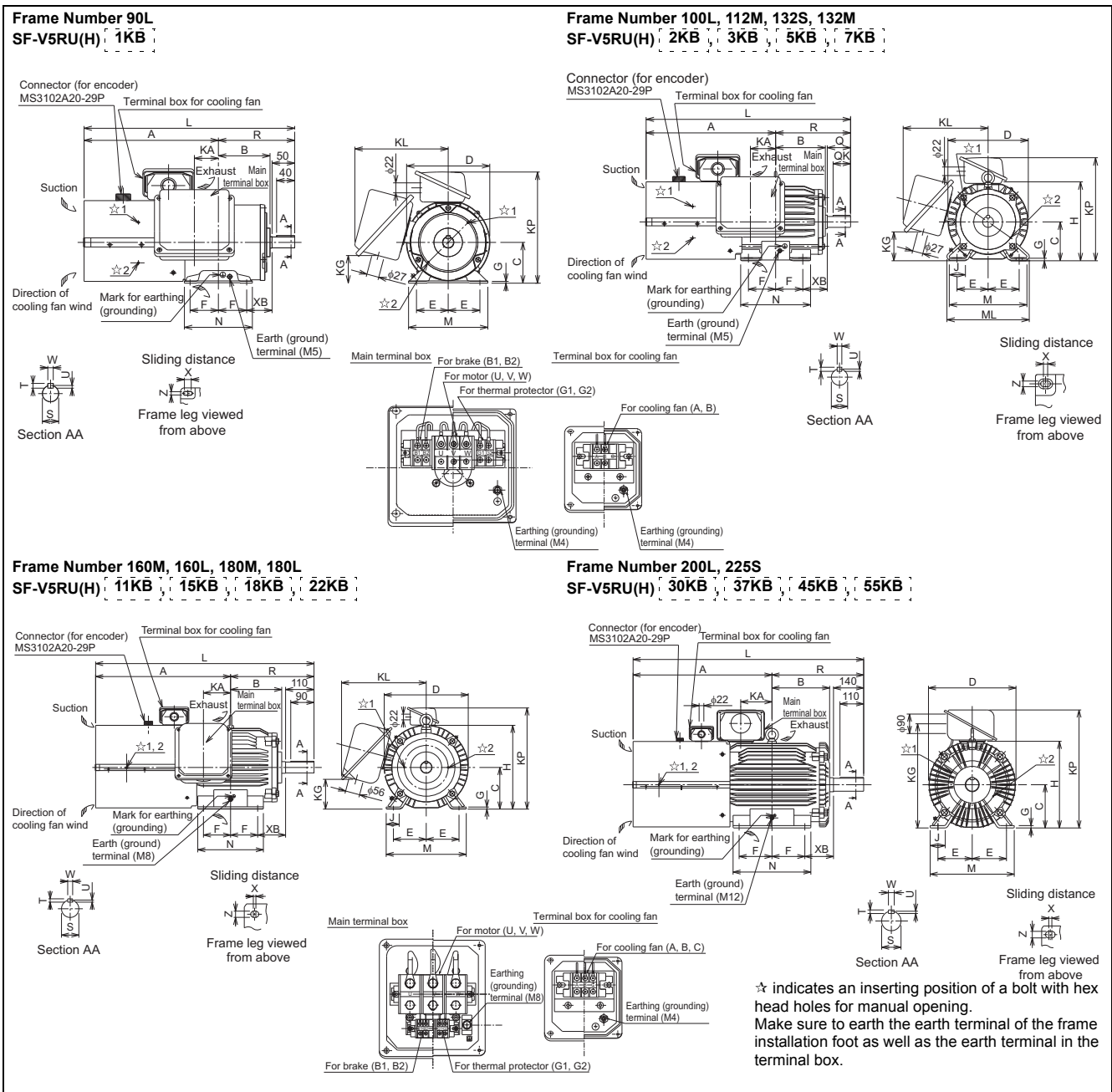
(Unit: mm)

SF-V5RU [JK]	SF-V5RU [JK1]	SF-V5RU [JK3]	SF-V5RU [JK4]	Frame No.	Mass (kg)	Motor																		Terminal screw size							
						A	B	C	D	E	F	H	I	KA	KG	KL(KP)	L	M	ML	N	XB	Q	QK	R	S	T	U	W	U,V,W	AB,C	G1,G2
1	—	—	—	90L	24	256.5	114	90	183.6	70	62.5	198	—	53	65	220(210)	425	175	—	150	56	—	168.5	246	7	4	8	M6	M4	M4	
2	1	—	—	100L	33	284	128	100	207	80	70	203.5	230	65	78	231	477	200	212	180	63	60	45	193	286	7	4	8	M6	M4	M4
3	2	1	—	112M	41	278	135	112	228	95	70	226	253	69	93	242	478	230	242	180	70	60	45	200	286	7	4	8	M6	M4	M4
5	3	2	—	132S	52	303	152	132	266	108	70	265	288	75	117	256	542	256	268	180	89	80	63	239	386	8	5	10	M6	M4	M4
7	5	3	1	132M	62	322	171	132	266	108	89	265	288	94	117	256	580	256	268	180	89	80	63	258	386	8	5	10	M6	M4	M4
11	7	5	2	160M	99	412	198	160	318	127	105	316	367	105	115	330	735	310	—	254	108	—	323	426	8	5	12	M8	M4	M4	
15	11	7	3	160L	113	434	220	160	318	127	127	316	367	127	115	330	779	310	—	298	108	—	345	426	8	5	12	M8	M4	M4	
18	—	—	—	180M	138	438.5	225.5	180	363	139.5	120.5	359	410	127	139	352	790	335	—	285	121	—	351.5	486	9	5.5	14	M8	M4	M4	
22	15	11	—	180L	160	457.5	242.5	180	363	139.5	139.5	359	410	146	139	352	828	335	—	323	121	—	370.5	556	10	6	16	M8	M4	M4	
—	18	15	5	200L	200	483.5	267.5	200	406	159	152.5	401	—	145	145	487	(546)	909	390	—	361	133	—	425.5	606	11	7	18	M10	M4	M4
30	—	—	7	225S	255	500	277	225	446	178	143	446	—	145	533	(592)	932	428	—	342	149	—	432	656	11	7	18	M10	M4	M4	

- Note) 1. Install the motor on the floor and use it with the shaft horizontal.  
 2. Leave an enough clearance between the fan suction port and wall to ensure adequate cooling. Also, check that the ventilation direction of a fan is from the opposite load side to the load side.  
 3. The size difference of top and bottom of the shaft center height is  $\pm 0.5$ .  
 4. The 400 V class motor has "-H" at the end of its type name.

Features  
 Application Example  
 PLC Function  
 FR Configurator 2  
 Connection Examples  
 Standard Specs  
 Outline Dimensions  
 Terminal Diagrams  
 Terminal Specs  
 Operation Panel  
 Parameter List  
 Explanations of Parameters  
 Protective Functions  
 Options  
 LVS/Cables  
 Precautions  
 Motors  
 Compatibility  
 Warranty Inquiry

◆ Dedicated motor outline dimension drawings (1500r/min series) (standard horizontal type with brake)



☆ indicates an inserting position of a bolt with hex head holes for manual opening.  
 Make sure to earth the earth terminal of the frame installation foot as well as the earth terminal in the terminal box.

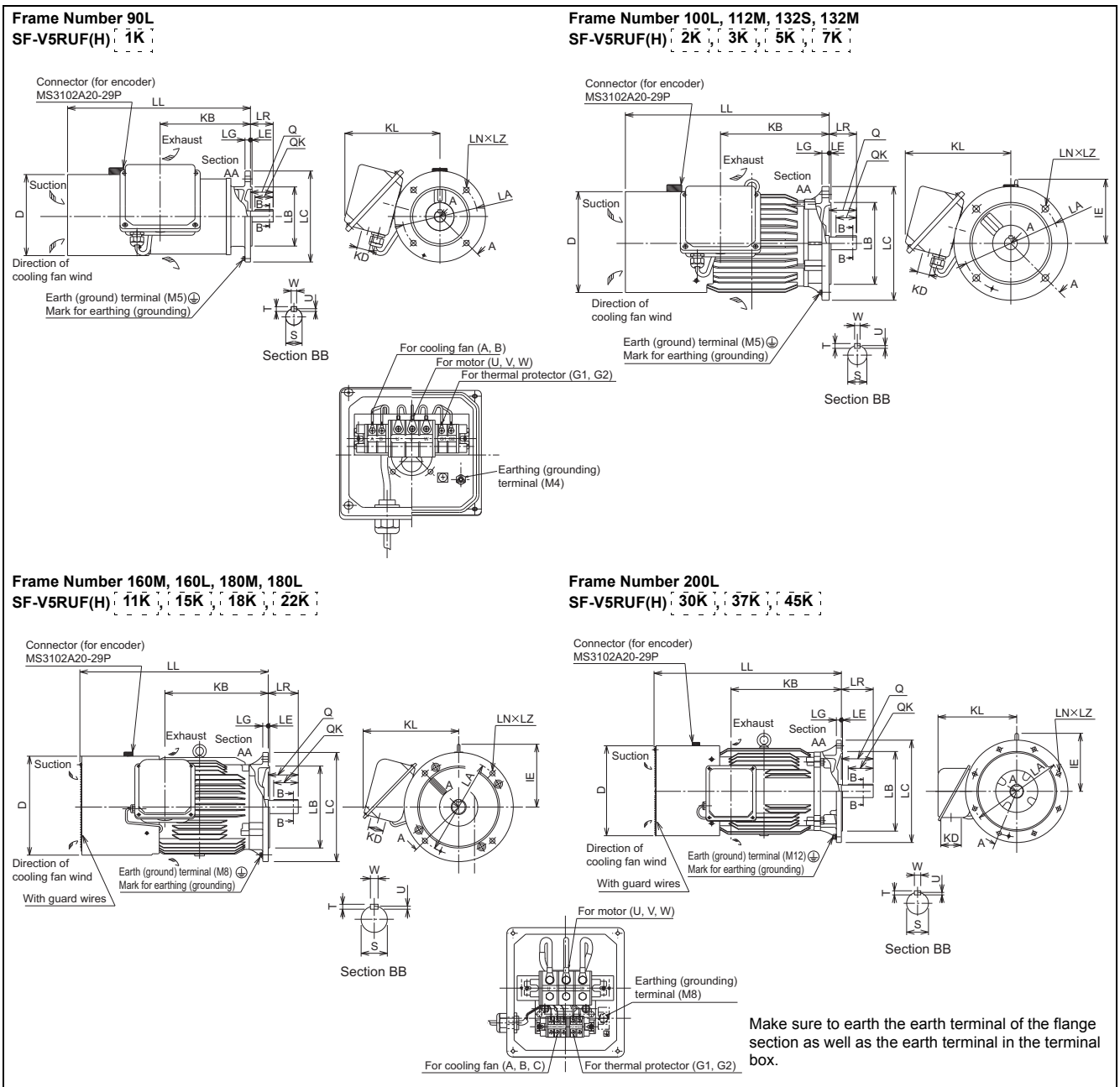
Dimensions table

(Unit: mm)

SF-V5RU [KB]	SF-V5RU [K1B]	SF-V5RU [K3B]	SF-V5RU [K4B]	Frame No.	Mass (kg)	Motor																				Shaft end					Terminal screw size							
						A	B	C	D	E	F	G	H	I	J	KA	KD	KG	KL	KP	L	M	ML	N	X	XB	Z	Q	QK	R	S	T	U	W	U,V, W	A,B (C)	G1, G2	B1, B2
1	—	—	—	90L	29	236.5	114	90	183.6	70	62.5	4	—	—	53	27	65	220	245	465	175	—	150	15	56	9	50	40	168.5	246	7	4	8	M6	M4	M4	M4	
2	1	—	—	100L	46	333.5	128	100	207	80	70	6.5	—	—	40	65	27	78	231	265	326.5	200	212	180	4	63	12	60	45	193	286	7	4	8	M6	M4	M4	M4
3	2	1	—	112M	53	355	135	112	228	95	70	6.5	—	—	40	69	27	93	242	290	555	230	242	180	4	70	12	60	45	200	286	7	4	8	M6	M4	M4	M4
5	3	2	—	132S	70	416	152	132	266	108	70	6.5	—	—	40	75	27	117	256	329	655	256	268	180	4	89	12	80	63	239	386	8	5	10	M6	M4	M4	M4
7	5	3	1	132M	80	435	171	132	266	108	89	6.5	—	—	40	94	27	117	256	329	693	256	268	218	4	89	12	80	63	258	386	8	5	10	M6	M4	M4	M4
11	7	5	2	160M	140	522.5	198	160	318	127	105	8	—	—	50	105	56	115	330	391	845.5	310	—	254	4	108	14.5	110	90	323	426	8	5	12	M8	M4	M4	M4
15	11	7	3	160L	155	544.5	220	160	318	127	127	8	—	—	50	127	56	115	330	391	889.5	310	—	298	4	108	14.5	110	90	345	426	8	5	12	M8	M4	M4	M4
18	—	—	—	180M	185	587.5	225.5	180	363	139.5	120.5	8	—	—	50	127	56	139	352	428	920	335	—	285	4	121	14.5	110	90	351.5	486	9	5.5	14	M8	M4	M4	M4
22	15	11	—	180L	255	587.5	242.5	180	363	139.5	139.5	8	—	—	50	146	56	139	352	428	958	335	—	323	4	121	14.5	110	90	370.5	556	10	6	16	M8	M4	M4	M4
—	18	15	5	200L	305	644.5	267.5	200	406	159	152.5	11	—	—	70	145	90	487	—	546	1070	390	—	361	4	133	18.5	140	110	425.5	606	11	7	18	M10	M4	M4	M4
37, 45	22, 30	18, 22	—	225S	395	659	277	225	446	178	143	11	—	—	70	145	90	533	—	592	1091	428	—	342	4	149	18.5	140	110	432	656	11	7	18	M10	M4	M4	M4

- Note) 1. Install the motor on the floor and use it with the shaft horizontal.  
 2. Leave an enough clearance between the fan suction port and wall to ensure adequate cooling.  
 Also, check that the ventilation direction of a fan is from the opposite load side to the load side.  
 3. The size difference of top and bottom of the shaft center height is  $\pm 0.5$   
 4. The 400 V class motor has "-H" at the end of its type name.  
 5. Since a brake power device is a stand-alone, install it inside the enclosure.  
 (This device should be arranged at the customer side.)

◆ Dedicated motor outline dimension drawings (1500r/min series) (flange type)



Dimensions table

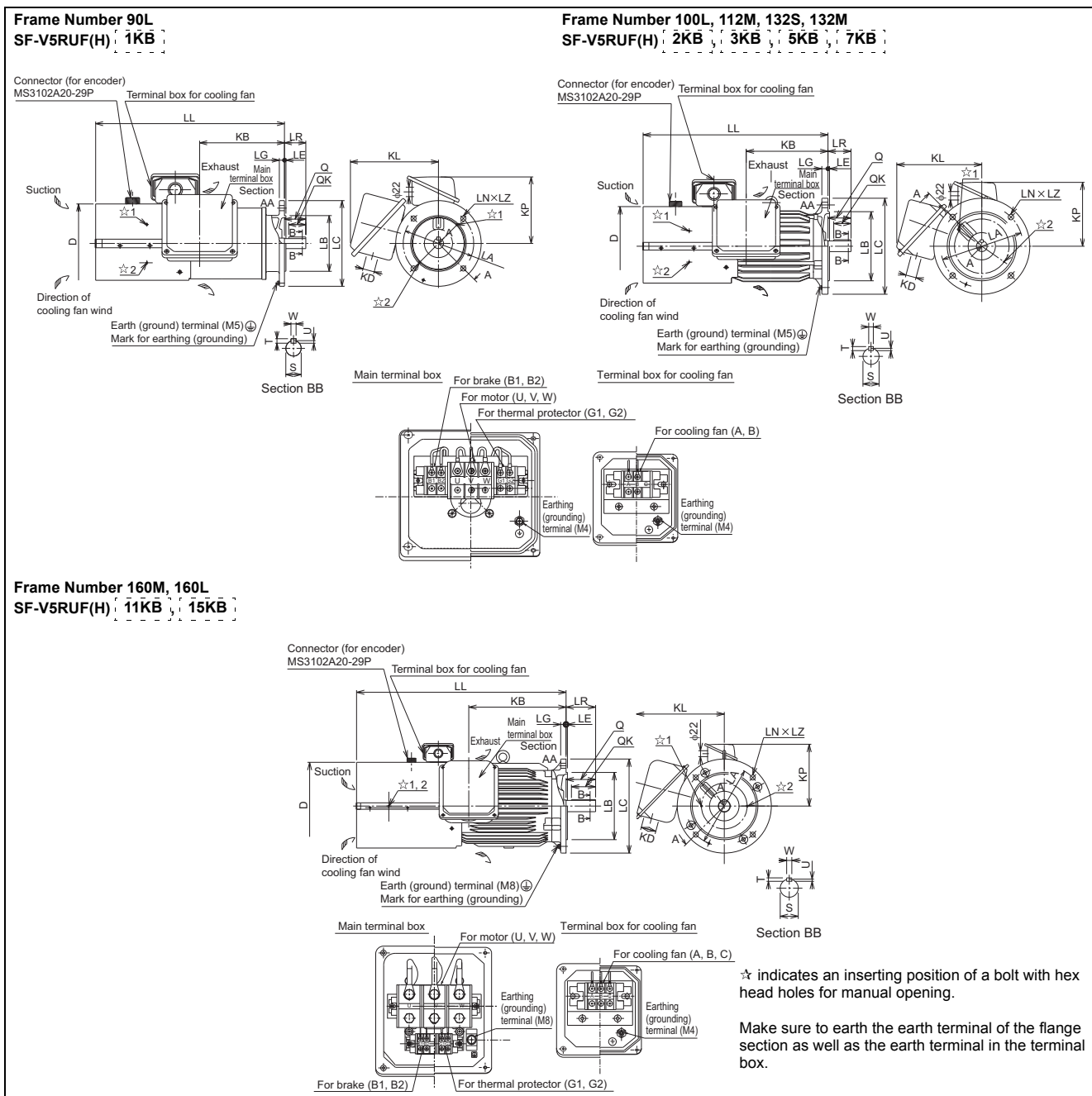
(Unit: mm)

SF-V5RU F[J]K	SF-V5RU F[J]K1	SF-V5RU F[J]K3	SF-V5RU F[J]K4	Flange Number	Frame No.	Mass (kg)	Motor												Shaft end						Terminal screw size				
							D	IE	KB	KD	KL	LA	LB	LC	LE	LG	LL	LN	LZ	LR	Q	QK	S	T	U	W	U,V,W	A,B,C	G1,G2
1	—	—	—	FF165	90L	26.5	183.6	—	198.5	27	220	165	130	6	12	402	4	12	50	50	40	24	6	7	4	8	M6	M4	M4
2	1	—	—	FF215	100L	37	207	130	213	27	231	215	180	6	16	432	4	14.5	60	60	45	28	6	7	4	8	M6	M4	M4
3	2	1	—	FF215	112M	46	228	141	239	27	242	215	180	6	16	448	4	14.5	60	60	45	28	6	7	4	8	M6	M4	M4
5	3	2	—	FF265	132S	65	266	156	256	27	256	265	230	6	20	484	4	14.5	80	80	63	38	6	8	5	10	M6	M4	M4
7	5	3	1	FF265	132M	70	266	156	294	27	256	265	230	6	20	522	4	14.5	80	80	63	38	6	8	5	10	M6	M4	M4
11	7	5	2	FF300	160M	110	318	207	318	56	330	300	250	6	20	625	4	18.5	110	110	90	42	6	8	5	12	M8	M4	M4
15	11	7	3	FF300	160L	125	318	207	362	56	330	300	250	6	20	669	4	18.5	110	110	90	42	6	8	5	12	M8	M4	M4
18	—	—	—	—	—	160	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
22	15	11	—	FF350	180M	185	363	230	378.5	56	352	350	300	6	20	690	4	18.5	110	110	90	48	6	9	5.5	14	M8	M4	M4
—	18	15	5	FF350	180L	225	363	230	416.5	56	352	350	300	6	20	728	4	18.5	110	110	90	55	6	10	6	16	M8	M4	M4
30	—	—	7	FF400	200L	270	406	255	485	90	346	400	350	6	22	823.5	8	18.5	140	140	110	60	6	11	7	18	M10	M4	M4
37, 45	22, 30	18, 22	—	—	—	290	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—

- Note) 1. Install the motor on the floor and use it with the shaft horizontal.  
 For use under the shaft, the protection structure of the cooling fan is IP20.  
 2. Leave an enough clearance between the fan suction port and wall to ensure adequate cooling.  
 Also, check that the ventilation direction of a fan is from the opposite load side to the load side.  
 3. The size difference of top and bottom of the shaft center height is  $\pm 0.5$ .  
 4. The 400 V class motor has "-H" at the end of its type name.

Features  
 Application Example  
 PLC Function  
 FR Configurator 2  
 Connection Examples  
 Standard Specs  
 Outline Dimensions  
 Terminal Connection Diagrams  
 Terminal Specs  
 Operation Panel  
 Parameter List  
 Explanations of Parameters  
 Protective Functions  
 Options  
 LV/SCables  
 Precautions  
 Motors  
 Compatibility  
 Warranty Inquiry

◆ Dedicated motor outline dimension drawings (1500r/min series) (flange type with brake)



☆ indicates an inserting position of a bolt with hex head holes for manual opening.

Make sure to earth the earth terminal of the flange section as well as the earth terminal in the terminal box.

Dimensions table

(Unit: mm)

SF-V5RU F1JKB	SF-V5RU F1K1B	SF-V5RU F1JK3B	SF-V5RU F1JK4B	Flange Number	Frame No.	Mass (kg)	Motor													Shaft end					Terminal screw size					
							D	KB	KD	KL	KP	LA	LB	LC	LE	LG	LL	LN	LZ	LR	Q	QK	S	T	U	W	U,V,W	A,B,C	B1,B2	G1,G2
1	—	—	—	FF165	90L	31.5	183.6	198.5	27	220	155	165	130j6	200	3.5	12	442	4	12	50	50	40	24j6	7	4	8	M6	M4	M4	M4
2	1	—	—	FF215	100L	50	207	213	27	231	165	215	180j6	250	4	16	481.5	4	14.5	60	60	45	28j6	7	4	8	M6	M4	M4	M4
3	2	1	—	FF215	112M	58	228	239	27	242	178	215	180j6	250	4	16	525	4	14.5	60	60	45	28j6	7	4	8	M6	M4	M4	M4
5	3	2	—	FF265	132S	83	266	256	27	256	197	265	230j6	300	4	20	597	4	14.5	80	80	63	38k6	8	5	10	M6	M4	M4	M4
7	5	3	1	FF265	132M	88	266	294	27	256	197	265	230j6	300	4	20	635	4	14.5	80	80	63	38k6	8	5	10	M6	M4	M4	M4
11	7	5	2	FF300	160M	151	318	318	56	330	231	300	250j6	350	5	20	735.5	4	18.5	110	110	90	42k6	8	5	12	M8	M4	M4	M4
15	11	7	3	FF300	160L	167	318	362	56	330	231	300	250j6	350	5	20	779.5	4	18.5	110	110	90	42k6	8	5	12	M8	M4	M4	M4

- Note) 1. Install the motor on the floor and use it with the shaft horizontal.  
 2. Leave an enough clearance between the fan suction port and wall to ensure adequate cooling. Also, check that the ventilation direction of a fan is from the opposite load side to the load side.  
 3. The size difference of top and bottom of the shaft center height is  $\pm 0.5$   
 4. The 400 V class motor has "-H" at the end of its type name.  
 5. Since a brake power device is a stand-alone, install it inside the enclosure. (This device should be arranged at the customer side.)

## ● Application to vector control dedicated motors (SF-THY) (75 kW or higher)

For performing vector control, the FR-A8AP/FR-A8TP (vector control compatible option) is required.

When the FR-A8TP is not used, a 12 V or 24 V power supply is required as the power supply for the encoder of the SF-THY. (When the FR-A8TP is used, the 24 V power supply of the FR-A8TP can be used for the encoder of the SF-THY.)

### ◆ Motor torque

When the vector control dedicated motor (SF-THY) and inverter of the same capacity are used and rated voltage is input, the torque characteristics are as shown below.



### ◆ Model lineup

- Rated speed: 1500 r/min (4 poles)

Model	Standard type	Rated output (kW)						
		75	90	110	132	160	200	250
Standard horizontal type	SF-THY[]	75	90	110	132	160	200	250

- Both 200 V and 400 V classes have the same model name.

Since motors speed ratio, 1:2, 1:3, or 1:4 specifications are available as special products, contact your sales representative.

### ◆ Motor specifications

Motor type		SF-THY									
Applicable inverter (ND rating)		FR-A820-[ ]K	FR-A840-[ ]K								
		90	90	110	132	160	185	220	280		
Rated output (kW)		75	75	90	110	132	160	200	250		
Rated torque (N·m)		477	477	572	700	840	1018	1273	1591		
Maximum torque 150%60 s (N·m)		715	715	858	1050	1260	1527	1909	2386		
Rated speed (r/min)		1500	1500								
Maximum speed (r/min)		2400	2400	1800							
Frame No.		250MD	250MD	250MD	280MD	280MD	280MD	280L	315H		
Inertia moment J (kg·m <sup>2</sup> )		1.1	1.1	1.7	2.3	2.3	4.0	3.8	5.0		
Noise		90 dB	90 dB			95 dB					
Cooling fan		Three-phase, 200 V/50 Hz, 200 V/60 Hz, 220 V/60 Hz (400 V class cooling fan is available upon order)									
Voltage											
Input (W)		50 Hz	400	400	400	400	400	750	750		
		60 Hz	750	750	750	750	750	1500	1500		
Approx. mass (kg)		610	610	660	870	890	920	1170	1630		
Common specifications		Surrounding air temperature, humidity: -10 to +40°C (non-freezing), 90%RH or less (non-condensing)									
		Structure: Totally enclosed forced draft system									
		Equipment: Encoder, thermal protector*2, fan									
		Insulation: Class F									
		Vibration rank: V10									
		Dedicated encoder		Resolution: 2048 pulse/rev							
				Power supply voltage: 12 V/24 VDC±10% *1							
Current consumption: 90 mA											
Output signal form: A, B phases (90° phase shift) Z phase: 1 pulse/rev											
Output circuit: Complementary (constant voltage output matched by emitter follow)											
		Output voltage: "H" level: Power supply voltage 9 V or more (IOH: -20 mA) "L" level: Power supply voltage 3 V or less (IOL: 20 mA)									

\*1 The 12 V/24 V power supply is required as the power supply for the encoder.

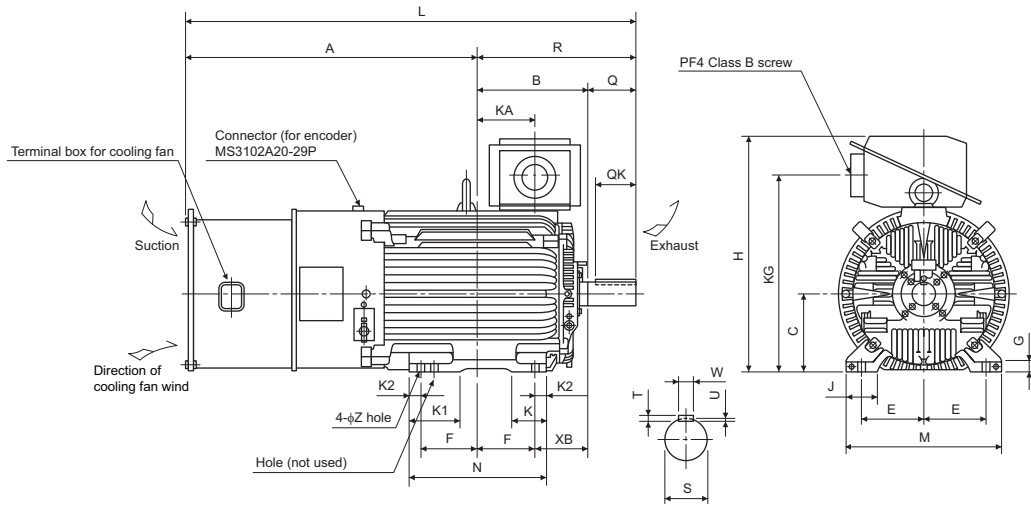
\*2 A motor with a thermal protector is also available. Contact your sales representative.

Features  
Application Example  
PLC Function  
FR Configurator2  
Connection Examples  
Standard Specs  
Outline Dimensions  
Terminal Connection Diagrams  
Terminal Specs  
Operation Panel  
Parameter List  
Explanations of Parameters  
Protective Functions  
Options  
LVS/Cables  
Precautions  
Motors  
Compatibility  
Warranty Inquiry

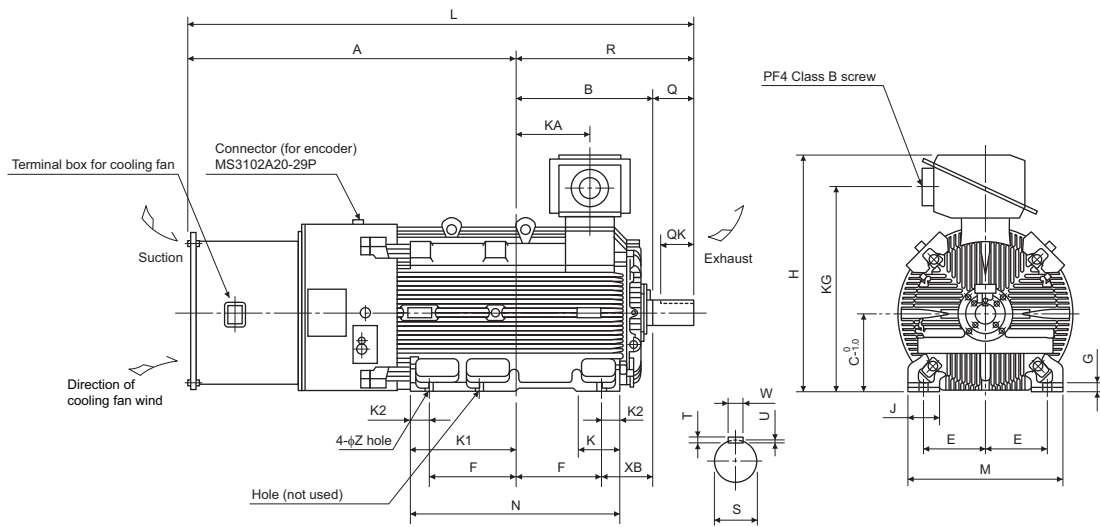


◆ Dedicated motor outline dimension drawings (1500 r/min series)

Frame Number 250MD, 280MD  
75 kW to 160 kW



Frame Number 280L, 315H  
200 kW, 250 kW



Dimensions table

(Unit: mm)

Output	Frame No.	Mass (kg)	Motor																	Shaft end size								
			A	B	C	D	E	F	G	H	J	K	K1	K2	L	M	N	R	Z	XB	KA	KG	Q	QK	S	W	T	U
75	250MD	610	988.5	340.5	250	557	203	174.5	30	775	100	130	168	50	1471	486	449	482.5	24	168	157.5	635	140	110	φ75m6	20	12	7.5
90	250MD	660	988.5	340.5	250	557	203	174.5	30	775	100	130	168	50	1471	486	449	482.5	24	168	157.5	635	140	110	φ75m6	20	12	7.5
110	280MD	870	1049.5	397.5	280	607	228.5	209.5	30	845	110	130	181	40	1619	560	449	569.5	24	190	210.5	705	170	140	φ85m6	22	14	9
132	280MD	890	1049.5	397.5	280	607	228.5	209.5	30	845	110	130	181	40	1619	560	449	569.5	24	190	210.5	705	170	140	φ85m6	22	14	9
160	280MD	920	1049.5	397.5	280	607	228.5	209.5	30	845	110	130	181	40	1619	560	499	569.5	24	190	210.5	705	170	140	φ85m6	22	14	9
200	280L	1170	1210.5	416.5	280	652	228.5	228.5	30	885	110	160	160	75	1799	560	607	588.5	24	190	214.5	745	170	140	φ85m6	22	14	9
250	315H	1630	1343	565	315	717	254	355	35	965	130	175	428	80	2084	636	870	741	28	216	306	825	170	140	φ95m6	25	14	9

Note) The tolerance of the top and bottom of the center shaft height \*C is  $\pm 0.05$  for the 250 frame and  $\pm 0.10$  for the 280 frame or more.

● Application to IPM motors (MM-CF series)

◆ Motor model

MM - CF 5 2 [ ] [ ] [ ] [ ]

Symbol	Output	Symbol	Output	Symbol	Rated speed	Symbol	Electromagnetic brake <sup>1</sup>	Symbol	Input power supply form	Symbol	Axis form
5	0.5 kW	35	3.5 kW	2	2000 r/min.	None	N/A	None	Terminal box lead (standard part)	None	Standard (straight axis)
10	1.0 kW	50	5.0 kW			B	Yes	C	Cannon connector	K	With key groove
15	1.5 kW	70	7.0 kW								
20	2.0 kW										

Rated speed	Motor model <small>(The rated output is indicated in square brackets.)</small>	Motor capacity							Remarks
		0.5 kW	1.0 kW	1.5 kW	2.0 kW	3.5 kW	5.0 kW	7.0 kW	
2000 r/min	MM-CF[]2	●	●	●	●	●	●	●	Standard
	MM-CF[]2B	●	●	●	●	●	-	-	Made on order
	MM-CF[]2C	●	●	●	●	●	●	●	
	MM-CF[]2K	●	●	●	●	●	●	●	

● : Released model - : Not available

◆ Motor specifications

◆ IPM motor MM-CF (2000 r/min series)

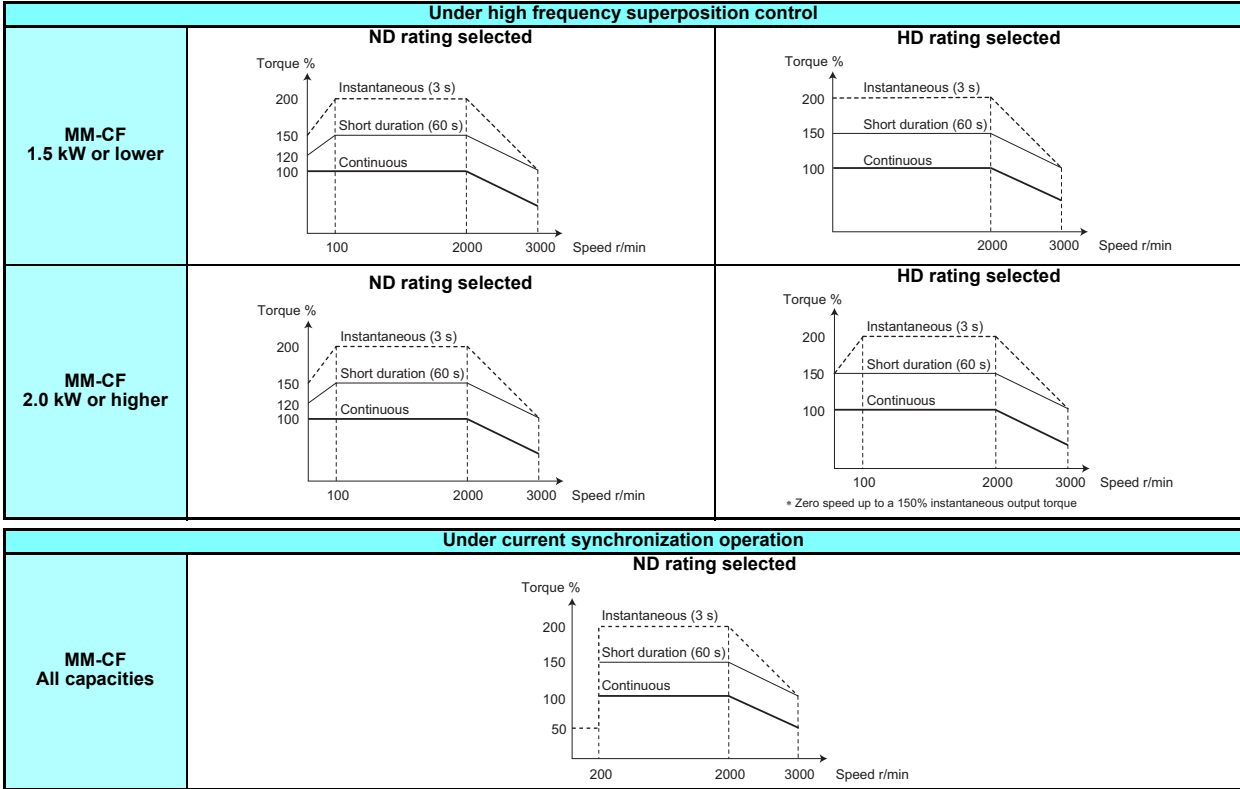
Motor type: MM-CF[]		52(C)(B)	102(C)(B)	152(C)(B)	202(C)(B)	352(C)(B)	502(C)	702(C)	
Applicable inverter	FR-A820-[]	SLD	0.4K	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K
		LD	0.4K	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K
		ND	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K
		HD	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K	11K
Continuous characteristics <sup>*1</sup>	Rated output (kW)	0.5	1.0	1.5	2.0	3.5	5.0	7.0	
	Rated torque (N·m)	2.39	4.78	7.16	9.55	16.70	23.86	33.41	
Rated speed <sup>*1</sup> (r/min)		2000							
Max. speed (r/min)		3000							
Instantaneous permissible speed (r/min)		3450 <sup>*6</sup>							
Maximum torque (N·m)		4.78	9.56	14.32	19.09	33.41	47.73	66.82	
Inertia moment J <sub>s</sub> (×10 <sup>-4</sup> kg·m <sup>2</sup> )		6.6 (7.0)	13.7 (14.9)	20.0 (21.2)	45.5 (48.9)	85.6 (89.0)	120.0	160.0	
Recommended ratio of load inertia moment to motor shaft inertia moment <sup>*2</sup>		100 times max.			50 times max.				
Rated current (A)		1.81	3.70	5.22	7.70	12.5	20.5	27.0	
Insulation rank		Class F							
Structure		Totally-enclosed, self-cooling (protective system: IP44 <sup>*3</sup> , IP65 <sup>*3*4</sup> )							
Surrounding air temperature, humidity		-10°C to +40°C (non-freezing), 90%RH or less (non-condensing)							
Storage temperature and humidity		-20°C to +70°C (non-freezing), 90%RH or less (non-condensing)							
Ambience		Indoors (no direct sunlight), free from corrosive gas, flammable gas, oil mist, dust and dirt							
Altitude		Max. 1000 m above sea level							
Vibration		X: 9.8 m/s <sup>2</sup> , Y: 24.5 m/s <sup>2</sup>							
Mass (kg) <sup>*5</sup>		5.1 (7.8)	7.2 (11)	9.3 (13)	13 (20)	19 (28)	27	36	

\*1 When the power supply voltage drops, we cannot guarantee the above output and rated speed.  
 \*2 When the load torque is 20% of the motor rating. The permissible load inertia moment ratio is smaller when the load torque is larger. Consult us if the load inertia moment ratio exceeds the above value.  
 \*3 This does not apply to the shaft through portion.  
 \*4 Value for the MM-CF[]2C.  
 \*5 The value for the MM-CF[]2B is indicated in parentheses.  
 \*6 Set 3150 r/min (210 Hz) or less in Pr.374 Overspeed detection level. The inverter may be damaged by the motor induction voltage if the motor speed exceeds 3150 r/min (210 Hz).

Features  
 Application Example  
 PLC Function  
 FR Configurator2  
 Connection Examples  
 Standard Specs  
 Outline Dimensions  
 Terminal Connection Diagrams  
 Terminal Specs  
 Operation Panel  
 Parameter List  
 Explanations of Parameters  
 Protective Functions  
 Options  
 LVS/Cables  
 Precautions  
 Motors  
 Compatibility  
 Warranty Inquiry



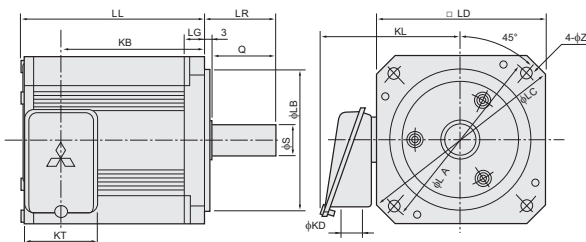
◆ Motor torque characteristic



◆ Motor outline dimension

**MM-CF[] (Standard)**

[Unit: mm]

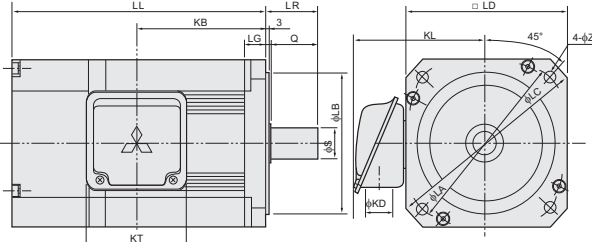


Model	Output (kW)	LL	φLA	φLB	φLC	φLD	LG	KB	φKD	KL	KT	φZ	LR	Q	φS
MM-CF52	0.5	97						62							
MM-CF102	1.0	122	145	110h7	165	130	12	87	22	110	56	9	55	50	24h6
MM-CF152	1.5	147						112							
MM-CF202	2.0	128						81.5							
MM-CF352	3.5	170	200	114.3 <sup>±0.025</sup>	230	176	18	123.5	27	141	93	13.5	79	75	35 <sup>±0.010</sup>
MM-CF502	5.0	224						172.5							
MM-CF702	7.0	299						247.5							

The outline dimensions may be changed. When precise outline dimensions are required, contact your sales representative.

**MM-CF[]B (With an electromagnetic brake)**

[Unit: mm]

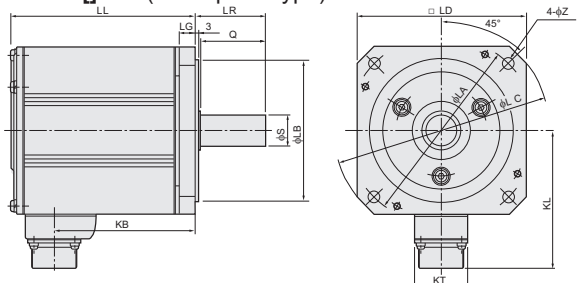


Model	Output (kW)	LL	φLA	φLB	φLC	φLD	LG	KB	φKD	KL	KT	φZ	LR	Q	φS
MM-CF52B	0.5	159						58							
MM-CF102B	1.0	184	145	110h7	165	130	12	83	22	108	80	9	55	50	24h6
MM-CF152B	1.5	209						108							
MM-CF202B	2.0	231						108							
MM-CF352B	3.5	279	200	114.3 <sup>±0.025</sup>	230	176	18	139.5	27	141	93	13.5	79	75	35 <sup>±0.010</sup>

The outline dimensions may be changed. When precise outline dimensions are required, contact your sales representative.

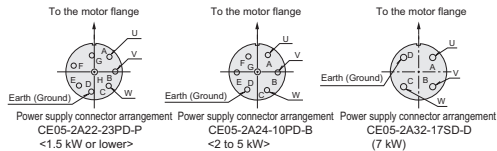
**MM-CF[]C (Waterproof type)**

[Unit: mm]



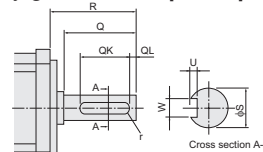
Model	Output (kW)	LL	φLA	φLB	φLC	φLD	LG	KB	KL	KT	φZ	LR	Q	φS
MM-CF52C	0.5	97						57.5						
MM-CF102C	1.0	122	145	110h7	165	130	12	82.5	111	41	9	55	50	24h6
MM-CF152C	1.5	147						107.5						
MM-CF202C	2.0	128						83.3						
MM-CF352C	3.5	170	200	114.3 <sup>±0.025</sup>	230	176	18	125.3	141	46	13.5	79	75	35 <sup>±0.010</sup>
MM-CF502C	5.0	224						179.3						
MM-CF702C	7.0	299						249.3	150	58				

The outline dimensions may be changed. When precise outline dimensions are required, contact your sales representative.



**With key groove**

[Unit: mm]



Motor	φS	R	Q	W	φK	φL	U	r
MM-CF52 to 152	24h6	55	50	8 <sup>±0.036</sup>	36	5	4 <sup>±0.2</sup>	4
MM-CF202 to 702	35 <sup>±0.010</sup>	79	75	10 <sup>±0.036</sup>	55	5	5 <sup>±0.2</sup>	5

## PM sensorless vector control, PM parameter initial setting

Pr.	GROUP	Name	Pr.	GROUP	Name
998	E430	PM parameter initialization	IPM		IPM initialization

Performing the IPM parameter initialization makes the IPM motor MM-CF ready for PM sensorless vector control.

PM sensorless vector control requires the following conditions.

- The motor capacity is equal to or one rank lower than the inverter capacity.
- Single-motor operation (one motor to one inverter) is preformed.
- The overall wiring length with the motor is 100 m or shorter. (Even with the IPM motor MM-CF, when the wiring length exceeds 30 m, perform offline auto tuning.)

### ◆ Setting procedure of PM sensorless vector control







#### ◆ Selecting the PM sensorless vector control by the IPM initialization mode

This inverter is set for an induction motor in the initial setting. Follow the following procedure to change the setting for the PM sensorless vector control.

#### POINT

- The parameters required to drive an MM-CF IPM motor are automatically changed as a batch.
- To change to the PM sensorless vector control, perform the following steps before setting other parameters. If the PM sensorless vector control is selected after setting other parameters, some of those parameters will be initialized too. (Refer to "IPM parameter initialization list" for the parameters that are initialized.)

### Operation

1.	Screen at power-ON The monitor display appears.
2.	Changing the operation mode Press  to choose the PU operation mode. [PU] indicator is lit.
3.	Parameter setting mode Press  to choose the parameter setting mode. [PRM] indicator is lit.
4.	IPM parameter initialization Turn  until <b>! PM</b> (IPM parameter initialization) appears.
5.	Setting value display Press  to read the present set value. "0" (initial value) appears.
6.	Changing the setting value Turn  to change the set value to "3003", then press  . "3003" and <b>! PM</b> flicker alternately. The setting is completed.

Setting value	Description
0	Parameter settings for an induction motor
3003	Parameter settings for an IPM motor MM-CF (rotations per minute)

#### NOTE

- Performing IPM parameter initialization in the parameter setting mode automatically changes the **Pr.998 PM parameter initialization** setting.
- In the initial parameter setting, the capacity same as the inverter capacity is set in **Pr.80 Motor capacity**. To use a motor capacity that is one rank lower than the inverter capacity, set Motor capacity by selecting the mode on the operation panel.
- To set a speed or to display monitored items in frequency, set **Pr.998**. (Refer to Instruction Manual (Detailed).)

#### ◆ Selecting the PM sensorless vector control by Pr.998

- Setting **Pr.998 PM parameter initialization** as shown in the following table activates PM sensorless vector control.

Pr.998 setting	Description	Operation on IPM parameter initialization
0 (initial value)	Parameter settings for an induction motor (frequency)	<b>! PM</b> (IPM) → write "0"
3003	Parameter settings for an IPM motor MM-CF (rotations per minute)	<b>! PM</b> (IPM) → write "3003"
3103	Parameter settings for an IPM motor MM-CF (frequency)	-
8009	Parameter (rotations per minute) settings for an IPM motor other than MM-CF (after tuning)	-
8109	Parameter (frequency) settings for an IPM motor other than MM-CF (frequency)	-
9009	Parameter (rotations per minute) settings for an SPM motor (after tuning)	-
9109	Parameter (frequency) settings for an SPM motor (after tuning)	-

#### NOTE

- The S-PM geared motor cannot be driven.

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## ◆ PM parameter initialization list

- The parameter settings in the following table are changed to the settings required to perform PM sensorless vector control by selecting PM sensorless vector control with the IPM parameter initialization mode on the operation panel or with **Pr.998 PM parameter initialization**.
- Performing parameter clear or all parameter clear sets back the parameter settings to the settings required to drive an induction motor.

Pr.	Name	Setting							Setting increments	
		Induction motor		PM motor (rotations per minute)		PM motor (frequency)				
		0 (initial value)		3003 (MM-CF)	8009 9009 (other than MM-CF)	3103 (MM-CF)	8109 9109 (other than MM-CF)	3003, 8009, 9009	0, 3103, 8109, 9109	
1	Maximum frequency	120 Hz <sup>*1</sup>		3000 r/min	Maximum motor frequency* <sup>8</sup>	200 Hz	Maximum motor frequency* <sup>8</sup>	1 r/min	0.01 Hz	
		60 Hz <sup>*2</sup>								
4	Multi-speed setting (high speed)	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
9	Electronic thermal O/L relay	Inverter rated current		Rated motor current (Refer to page 194.)	-	Rated motor current (Refer to page 194.)	-	0.01 A <sup>*1</sup>	0.1 A <sup>*2</sup>	
13	Starting frequency	0.5 Hz		8 r/min <sup>*3</sup>	Pr.84 × 10%	0.5 Hz <sup>*6</sup>	Pr.84 × 10%	1 r/min	0.01 Hz	
15	Jog frequency	5 Hz		200 r/min	Pr.84 × 10%	13.33 Hz	Pr.84 × 10%	1 r/min	0.01 Hz	
18	High speed maximum frequency	120 Hz <sup>*1</sup>		3000 r/min	-	200 Hz	-	1 r/min	0.01 Hz	
		60 Hz <sup>*2</sup>								
20	Acceleration/deceleration reference frequency	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
22	Stall prevention operation level	150% <sup>*7</sup>		150% <sup>*7</sup>				0.1%		
37	Speed display	0		0				1		
55	Frequency monitoring reference	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
56	Current monitoring reference	Inverter rated current		Rated motor current (Refer to page 194.)	Pr.859	Rated motor current (Refer to page 194.)	Pr.859	0.01 A <sup>*1</sup>	0.1 A <sup>*2</sup>	
71	Applied motor	0		330 <sup>*3</sup>	-	330 <sup>*3</sup>	-	1		
80	Motor capacity	9999		Motor capacity (MM-CF) <sup>*4</sup>	-	Motor capacity (MM-CF) <sup>*4</sup>	-	0.01 kW <sup>*1</sup>	0.1 kW <sup>*2</sup>	
81	Number of motor poles	9999		8 <sup>*4</sup>	-	8 <sup>*4</sup>	-	1		
84	Rated motor frequency	9999		2000 r/min	-	133.33 Hz	-	1 r/min	0.01 Hz	
116	Third output frequency detection	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
125 (903)	Terminal 2 frequency setting gain frequency	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
126 (905)	Terminal 4 frequency setting gain frequency	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
144	Speed setting switchover	4		108	Pr.81 + 100	8	Pr.81	1		
240	Soft-PWM operation selection	1		0				1		
263	Subtraction starting frequency	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
266	Power failure deceleration time switchover frequency	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
374	Overspeed detection level	9999		3150 r/min	Maximum motor frequency + 10 Hz <sup>*3</sup>	210 Hz	Maximum motor frequency + 10 Hz <sup>*3</sup>	1 r/min	0.01 Hz	
386	Frequency for maximum input pulse	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
505	Speed setting reference	60 Hz	50 Hz	133.33 Hz	Pr.84	133.33 Hz	Pr.84	0.01 Hz		
557	Current average value monitor signal output reference current	Inverter rated current		Rated motor current (Refer to page 194.)	Pr.859	Rated motor current (Refer to page 194.)	Pr.859	0.01 A <sup>*1</sup>	0.1 A <sup>*2</sup>	
820	Speed control P gain 1	60%		30%				1%		
821	Speed control integral time 1	0.333 s		0.333 s				0.001 s		
824	Torque control P gain 1 (current loop proportional gain)	100%		100%				1%		
825	Torque control integral time 1 (current loop integral time)	5 ms		20 ms				0.1 ms		
870	Speed detection hysteresis	0 Hz		8 r/min		0.5 Hz		1 r/min	0.01 Hz	
885	Regeneration avoidance compensation frequency limit value	6 Hz		200 r/min	Pr.84 × 10%	13.33 Hz	Pr.84 × 10%	1 r/min	0.01 Hz	
893	Energy saving monitor reference (motor capacity)	Inverter rated current		Motor capacity (Pr.80)				0.01 kW <sup>*1</sup>	0.1 kW <sup>*2</sup>	
C14 (918)	Terminal 1 gain frequency (speed)	60 Hz	50 Hz	2000 r/min	Pr.84	133.33 Hz	Pr.84	1 r/min	0.01 Hz	
1121	Per-unit speed control reference frequency	120 Hz <sup>*1</sup>		3000 r/min	Maximum motor frequency* <sup>8</sup>	200 Hz	Maximum motor frequency* <sup>8</sup>	1 r/min	0.01 Hz	
		60 Hz <sup>*2</sup>								

-: Not changed

\*1 Initial value for the FR-A820-03160(55K) or lower and FR-A840-01800(55K) or lower

\*2 Initial value for the FR-A820-03800(75K) or higher and FR-A840-02160(75K) or higher

\*3 Setting Pr.71 Applied motor = "333, 334, 8093, 8094, 9093, or 9094" does not change the Pr.71 Applied motor setting.

\*4 When a value other than "9999" is set, the set value is not changed.

\*5 200 r/min when Pr.788 Low speed range torque characteristic selection = "0"

\*6 13.33 Hz when Pr.788 Low speed range torque characteristic selection = "0"

\*7 110% for SLD, 120% for LD, 150% for ND, and 200% for HD (Refer to Pr.570 Multiple rating setting on page 131.)

\*8 Pr.702 Maximum motor frequency is used as the maximum motor frequency. When Pr.702 = "9999 (initial value)", Pr.84 Rated motor frequency is used as the maximum motor frequency.

### NOTE

- If IPM parameter initialization is performed in rotations per minute (Pr.998 = "3003, 8009, or 9009"), the parameters not listed in the table and the monitored items are also set and displayed in rotations per minute.



## ◆ Specification comparison between PM sensorless vector control and induction motor control

Item	PM sensorless vector control (MM-CF)		Induction motor control
<b>Applicable motor</b>	IPM motor MM-CF series (0.5 to 7.0 kW) (Refer to page 194.) IPM motors other than MM-CF (tuning required) *1		Induction motor *1
<b>Starting torque</b>	High frequency superposition control	200% (200% for the 1.5 kW or lower with MM-CF, 150% for the 2.0 kW or higher)	200% (FR-A820-00046(0.4K) to FR-A820-00250(3.7K), FR-A840-00023(0.4K) to FR-A840-00126(3.7K))
	Current synchronization operation	50%	150% (FR-A820-00340(5.5K), FR-A840-00170(5.5K) or higher) under Real sensorless vector control and vector control
<b>Zero speed</b>	High frequency superposition control	Available (Select the HD rating for zero speed 200%)	Available under Real sensorless vector control and vector control
	Current synchronization operation	Not available	
<b>Carrier frequency</b>	High frequency superposition control	6 kHz (Pr.72 = "0 to 9"), 10 kHz (Pr.72 = "10 to 13"), 14 kHz (Pr.72 = "14 or 15") (6 kHz in a low-speed range of 10 kHz or higher. The frequency of 2 kHz is not selectable.)	FR-A820-03160(55K) or lower, FR-A840-01800(55K) or lower : Any value in the range of 0.75 kHz to 14.5 kHz FR-A820-03800(75K) or higher, FR-A840-02160(75K) or higher : 0.75 kHz to 6 kHz
	Current synchronization operation	2 kHz (Pr.72 = "0 to 5"), 6 kHz (Pr.72 = "6 to 9"), 10 kHz (Pr.72 = "10 to 13"), 14 kHz (Pr.72 = "14 or 15") (6 kHz in a low-speed range of 10 kHz or higher.)	
<b>Automatic restart after instantaneous power failure</b>	No startup waiting time. Using the regeneration avoidance function or retry function together is recommended.		Startup waiting time exists.
<b>Startup delay</b>	Startup delay of about 0.1 s for magnetic pole position detection.		No startup delay (when online auto tuning is not performed at startup).
<b>Driving by the commercial power supply</b>	Cannot be driven by the commercial power supply.		Can be driven by the commercial power supply. (Other than vector control dedicated motor.)
<b>Operation during coasting</b>	While the motor is coasting, potential is generated across motor terminals.		While the motor is coasting, potential is not generated across motor terminals.
<b>Torque control</b>	Not available		Available under Real sensorless vector control and vector control
<b>Position control</b>	High frequency superposition control	Available (sensorless)	Available under vector control.
	Current synchronization operation	Not available	

\*1 The motor capacity is equal to or one rank lower than the inverter capacity. (It must be 0.4 kW or higher.) Using a motor with the rated current substantially lower than the inverter rated current will cause torque ripples, etc. and degrade the speed and torque accuracies. As a reference, select the motor with the rated motor current that is about 40% or higher of the inverter rated current.

### NOTE

- Before wiring, make sure that the motor is stopped. Otherwise an electric shock may occur.
- Never connect an IPM motor to the commercial power supply.
- No slippage occurs with an IPM motor because of its characteristic. If an IPM motor, which took over an induction motor, is driven at the same speed as for the induction motor, the running speed of the IPM motor becomes faster by the amount of the induction motor's slippage. Adjust the speed command to run the IPM motor at the same speed as the induction motor, as required.

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LV/SCables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## Countermeasures against deterioration of the 400 V class motor insulation

When driving a 400 V class motor by the inverter, surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor. When the 400 V class motor is driven by the inverter, consider the following countermeasures:

### ◆ With induction motor

It is recommended to take one of the following countermeasures:

#### ◆ Rectifying the motor insulation and limiting the PWM carrier frequency according to the wiring length

For the 400 V class motor, use an insulation-enhanced motor.

The Mitsubishi high-efficiency motor SF-HR, the Mitsubishi constant-torque motor SF-HRCA, and the Mitsubishi high-performance energy-saving motor SF-PR are insulation-enhanced motors as standard.

Specifically,

- Order a "400 V class inverter-driven insulation-enhanced motor".
- For the dedicated motor such as the constant-torque motor and low-vibration motor, use an "inverter-driven dedicated motor".
- Set **Pr.72 PWM frequency selection** as indicated below according to the wiring length.

Inverter	Wiring length 50 m or shorter	Wiring length 50 m to 100 m	Wiring length Longer than 100 m
Standard model	15 (14.5 kHz) or lower	9 (9 kHz) or lower	4 (4 kHz) lower
IP55 compatible model			
Separated converter type	6 (6 kHz) or lower	6 (6 kHz) or lower	4 (4 kHz) lower

#### ◆ Suppressing the surge voltage on the inverter side

- For FR-A840-01800(55K) or lower, connect a surge voltage suppression filter (FR-ASF-H/FR-BMF-H) at the output side of the inverter.
- For FR-A840-02160(75K) or higher, connect a sine wave filter (MT-BSL/BSC) at the output side of the inverter.

### ◆ With PM motor

Set **Pr.72 PWM frequency selection** as indicated below according to the wiring length.

Applicable Inverter	Wiring length	
	50 m or shorter	50 m to 100 m
FR-A840-00023(0.4K), 00038(0.75K)	0 (2 kHz) to 15 (14 kHz)	5 (2 kHz) or lower
Others	0 (2 kHz) to 15 (14 kHz)	9 (6 kHz) or lower

### NOTE

- A surge voltage suppression filter (FR-ASF-H/FR-BMF-H) can be used under V/F control and Advanced magnetic flux vector control. A sine wave filter (MT-BSL/BSC) can be used under V/F control. Do not use the filters under unspecified controls.

## Application to special motors

### ◆ Motors with brake

Use the motor with brake having independent power supply for the brake, connect the brake power supply to the inverter primary side power and make the inverter output off using the output stop terminal (MRS) when the brake is applied (motor stop). Rattle may be heard according to the type of the brake in the low speed region but it is not a fault.

### ◆ Pole changing motor

As this motor differs in rated current from the standard motor, confirm the maximum current of the motor and select the inverter. Be sure to change the number of poles after the motor has stopped. If the number of poles is changed during rotation, the regenerative overvoltage protection circuit may be activated to cause an inverter alarm, coasting the motor to a stop.

### ◆ Submersible motor

Since the motor rated current is larger than that of the standard motor, make selection of the inverter capacity carefully. In addition, the wiring distance between the motor and inverter may become longer, refer to **page 171** to perform wiring with a cable thick enough. Leakage current may flow more than the land motor, take care when selecting the earth leakage current breaker.

### ◆ Explosion-proof motor

To drive an explosion-proof type motor, an explosion-proof test of the motor and inverter together is necessary. The test is also necessary when driving an existing explosion-proof motor.

The inverter is a non-explosion proof structure, install it in a safety location.

### ◆ Geared motor

The continuous operating rotation range of this motor changes depending on the lubrication system and maker. Especially in the case of oil lubrication, continuous operation in the low-speed range only can cause gear seizure. For fast operation at higher than 60 Hz, please consult the motor maker.

### ◆ Synchronous motor other than PM motor

This motor is not suitable for applications of large load variation or impact, where out-of-sync is likely to occur. Please contact your sales representative when using this motor because its starting current and rated current are greater than those of the standard motor and will not rotate stably at low speed.

### ◆ Single phase motor

The single phase motor is not suitable for variable operation by the inverter.

For the capacitor starting system, the capacitor may be damaged due to harmonic current flowing to the capacitor. For the split-phase starting system and repulsion starting system, not only output torque is not generated at low speed but it will result in starting coil burnout due to failure of centrifugal force switch inside. Replace with a three-phase motor for use.

## ● Major differences from the FR-A700 series

Item	FR-A700	FR-A800
<b>Control method</b>	V/F control Advanced magnetic flux vector control Real sensorless vector control Vector control (with plug-in option) PM sensorless vector control (IPM motor)	V/F control Advanced magnetic flux vector control Real sensorless vector control Vector control (with plug-in option/control terminal option) PM sensorless vector control (IPM motor/SPM motor)
<b>Added functions</b>	—	USB host function Safety stop function PLC function etc.
<b>Brake transistor (brake resistor usable)</b>	Built in for the FR-A720-0.4K to 22K Built in for the FR-A740-0.4K to 22K	Built in for the FR-A820-00046(0.4K) to 01250(22K) Built in for the FR-A840-00023(0.4K) to 01800(55K)
<b>Maximum output frequency</b>	<b>V/F control</b>	400 Hz
	<b>Advanced magnetic flux vector control</b>	120 Hz
	<b>Real sensorless vector control</b>	120 Hz
	<b>vector control</b>	120 Hz
	<b>PM sensorless vector control</b>	300 Hz
<b>PID control</b>	Turn the X14 signal ON to enable PID control.	The X14 signal does not need to be assigned. (PID control is available by the <b>Pr.128</b> setting.) The PID pre-charge function and dancer control are added.
<b>Automatic restart after instantaneous power failure</b>	Turn the CS signal ON to enable restart.	CS signal assignment not required. (Restart is enabled with the <b>Pr.57</b> setting only.)
<b>Number of motor poles V/F control switching</b>	The V/F switching signal (X18) is valid when <b>Pr.81</b> = "12 to 20 (2 to 10 poles)".	<b>Pr.81</b> = "12 (12 poles)" X18 is valid regardless of the Pr.81 setting. (The <b>Pr.81</b> settings "14 to 20" are not available.)
<b>PTC thermistor input</b>	Input from the terminal AU (The function of the terminal AU is switched by a switch.)	Input from the terminal 2. (The function of the terminal 2 is switched by the <b>Pr.561</b> setting.)
<b>USB connector</b>	B connector	Mini B connector
<b>Control circuit terminal block</b>	Removable terminal block (screw type)	Removable terminal block (spring clamp type)
<b>Terminal response level</b>	The FR-A800's I/O terminals have better response level than the FR-A700's terminals. By setting <b>Pr.289 Inverter output terminal filter</b> and <b>Pr.699 Input terminal filter</b> , the terminal response level can be compatible with that of FR-A700. Set to approximately 5 to 8 ms and adjust the setting according to the system.	
<b>PU</b>	FR-DU07 (4-digit LED) FR-PU07	FR-DU08 (5-digit LED) FR-LU08 (LCD operation panel) FR-PU07 (Some functions, such as parameter copy, are unavailable.) FR-DU07 is not supported.
<b>Plug-in option</b>	Dedicated plug-in options (not interchangeable)	
<b>Communication option</b>	Connected to the connector 3	Connected to the connector 1
<b>Installation size</b>	For standard models, installation size is compatible for all capacities. (Replacement between the same capacities does not require new mounting holes.) For separated converter types, installation size is not compatible. (New mounting holes are required.)	
<b>Converter</b>	Built-in for all capacities	An optional converter unit (FR-CC2) is required for separated converter types.
<b>DC reactor</b>	The 75K or higher comes with a DC reactor (FR-HEL).	For the FR-A820-03800(75K) or higher, the FR-A840-02160(75K) or higher, and when a 75 kW or higher motor is used, select a DC reactor suitable for the applicable motor capacity. (A DC reactor is not included.) Separated converter types (converter unit FR-CC2) and IP55 compatible models have a built-in DC reactor.

### ◆ Installation precautions

- Removal procedure of the front cover is different. (Refer to the Instruction Manual.)
- Plug-in options of the FR-A700 series are not compatible.
- Operation panel (FR-DU07) cannot be used.

### ◆ Wiring precautions

- The spring clamp type terminal block has changed to the screw type. Use of blade terminals is recommended.

### ◆ Instructions for continuous use of the FR-PU07 (parameter unit)

- For the FR-A800 series, many functions (parameters) have been added. When setting these parameters, the parameter names and setting ranges are not displayed.
- Only the parameter with the numbers up to "999" can be read and set. The parameters with the numbers after "999" cannot be read or set.
- Many protective functions have been added for the FR-A800 series. These functions are available, but all faults are displayed as "Fault". When the faults history is checked, "ERR" appears. Added faults will not appear on the parameter unit. (However, MT1 to MT3 are displayed as MT.)
- Parameter copy/verification function are not available.

### ◆ Copying parameter settings

- The FR-A700 series' parameter settings can be easily copied to the FR-A800 series by using the setup software (FR Configurator2). (Not supported by the setup software FR-SW3-SETUP or older.)

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry

## ● Comparison with the FR-A700 series in functions

Parameter/function	Addition	Modification	Related parameter	Remarks
Maximum frequency		○	Pr.1 etc.	Max. 590 Hz (Max. 400 Hz under other than V/F control)
Free thermal (electronic thermal O/L relay)	○		Pr.600 to Pr.604, Pr.692 to Pr.696	Thermal characteristics can be freely set.
PTC thermistor		○	Pr.561	The protection level can be set by parameters.
Strengthened excitation deceleration	○		Pr.660 to Pr.662	Loss of the motor is increased to reduce regenerative power.
4 mA input check	○		Pr.573, Pr.777, Pr.778	Loss of 4 mA input is detected.
Input terminal filter	○		Pr.699	The terminal response can be adjusted.
Output terminal filter	○		Pr.289	The terminal response can be adjusted.
Remote output terminal (analog)	○		Pr.655 to Pr.659	Optional analog output
Parameter display by group	○		Pr.Md	The parameters are displayed in the conventional numerical order in the initial state.
Speed smoothing	○		Pr.653, Pr.654	Machine resonance is reduced.
Traverse function	○		Pr.592 to Pr.597	Only speed control is available under vector control.
USB host (USB memory connection)	○		Pr.1049	Parameter read/copy, data logging, execution of the ladder in the USB (PLC function), etc.
Second PID control	○		Pr.753 to Pr.758, Pr.1134, Pr.1135, Pr.1140, Pr.1141, Pr.1143 to Pr.1149	
PID pre-charge function	○		Pr.760 to Pr.769	
PID output suspension function	○		Pr.575 to Pr.577	
PLC function	○		Pr.414 to Pr.417, Pr.498, Pr.1150, Pr.1199	
Maintenance timer		○	Pr.503, Pr.504, Pr.686 to Pr.689	Up to three timers can be set.
Fault initiation	○		Pr.997	Faults can be initiated.
Multiple rating selection	○		Pr.570	The rating can be selected from SLD, LD, ND, or HD.
Fast-response operation selection	○		Pr.800	High response of the vector control, real sensorless vector control, and PM sensorless vector control
24 V external power supply input	○		—	Operation is unavailable. (Communication and parameter setting are available.)
Cooling fan operation selection		○	Pr.244	Waiting time at stop can be changed.
GOT automatic recognition	○		—	The GOT2000 series is supported.
Optimum excitation control mode	○		Pr.60	

## ● Major differences between the standard model (FR-A840) and the separated converter type (FR-A842)

Item	FR-A842	Remarks (FR-A840)
Pr.30 Regenerative function selection	Setting ranges "2, 10, 11, 102, 110, 111" Initial value "10"	Setting ranges "0 to 2, 10, 11, 20, 21, 100, 101, 110, 111, 120, 121" Initial value "0"
Pr.70 Special regenerative brake duty	Without the parameter	
Monitor function (Pr.52, Pr.54, Pr.158, Pr.774 to Pr.776, Pr.992, Pr.1027 to Pr.1034)	Regenerative brake duty Without (Unacceptable)	
Input terminal function selection (Pr.178 to Pr.189)	DC feeding operation permission (X70), DC feeding cancel (X71) Without (Unacceptable)	
Pr.187 MRS terminal function selection	Initial value "10" (X10)	Initial value "24" (MRS)
Output terminal function assignment selection (Pr.190 to Pr.196, Pr.313 to Pr.322)	Instantaneous power failure/undervoltage (IPF), During deceleration at occurrence of power failure (retained until release) (Y46), Regenerative brake pre-alarm (RBP), DC current feeding (Y85), Main circuit capacitor life (Y87), Inrush current limit circuit life (Y89) Without (Unacceptable)	
Pr.192 IPF terminal function selection	Initial value "9999" (No function)	Initial value "2" (IPF)
Inrush current limit circuit life display, Main circuit capacitor life display (Pr.256, Pr.258, Pr.259)	Without the parameter	
Pr.599 X10 terminal input selection	Initial value "1"(NC contact specification)	Initial value "0" (NO contact specification)
Pr.872 Input phase loss protection selection	Without the parameter	
Warning, protective functions	Regenerative brake pre-alarm (RB), Instantaneous power failure (E.IPF), Undervoltage (E.UVT), Input phase loss (E.ILF), Brake transistor alarm detection (E.BE), Inrush current limit circuit fault (E.IOH) Not available	

## ● Major differences between the standard model (FR-A840) and the IP55 compatible model (FR-A846)

Item	FR-A840	FR-A846
Protective structure	Enclose type (IP20): FR-A840-00620(22K) or lower Open type (IP00): FR-A840-00770(30K) or higher	Dust-proof and waterproof type (IP55): All capacities
DC reactor	Optional	Built-in
Internal air circulation fan	Without	With
Protective function	—	Internal fan alarm (FN2), Abnormal internal temperature (E.IAH)
Circuit board coating (conforming to IEC60721-3-3 3C2/3S2)	With / Without (Selectable)	With
Environment	Surrounding air temperature LD, ND, HD rating: -10°C to +50°C (non-freezing) SLD rating: -10°C to +40°C (non-freezing)	LD, ND rating: -10°C to +40°C (non-freezing)
	Surrounding air humidity With circuit board coating: 95% RH or less (non-condensing) Without circuit board coating: 90% RH or less (non-condensing)	95% RH or less (non-condensing)
Brake transistor (usable brake resistor)	Built-in for the FR-A820-00046(0.4K) to 01250(22K) Built-in for the FR-A840-00023(0.4K) to 01800(55K)	Without (Brake resistor is not applicable.)
Multiple rating (Pr.570 Multiple rating setting)	SLD, LD, ND (initial setting), HD rating (Setting range: "0 to 3")	LD, ND (initial setting) rating (Setting range: "1 or 2")
Pr.30 Regenerative function selection	Setting range: "0 to 2, 10, 11, 20, 21, 100, 101, 110, 111, 120, or 121"	Setting range: "0, 2, 10, 20, 100, 110, or 120"
Pr.70 Special regenerative brake duty	Available	Not available
Regenerative brake duty (Pr.52, Pr.54, Pr.158, Pr.774 to Pr.776, Pr.992, Pr.1027 to Pr.1034 setting "9")	Available (can be set)	Not available (cannot be set)
Operation panel	FR-DU08: IP40 (except for the PU connector section)	FR-DU08-01: IP55 (except for the PU connector section)

Features

Application Example  
PLC Function  
FR Configurator2Connection  
ExamplesStandard  
SpecsOutline  
DimensionsTerminal Connection  
Diagrams  
Terminal Specs

Operation Panel

Parameter List

Explanations  
of  
ParametersProtective  
Functions

Options

LVS/Cables

Precautions

Motors

Compatibility

Warranty  
Inquiry





When using this product, make sure to understand the warranty described below.

### 1. Warranty period and coverage

We will repair any failure or defect (hereinafter referred to as "failure") in our FA equipment (hereinafter referred to as the "Product") arisen during warranty period at no charge due to causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit are repaired or replaced.

#### [Term]

The term of warranty for Product is twelve months after your purchase or delivery of the Product to a place designated by you or eighteen months from the date of manufacture whichever comes first ("Warranty Period"). Warranty period for repaired Product cannot exceed beyond the original warranty period before any repair work.

#### [Limitations]

- (1) You are requested to conduct an initial failure diagnosis by yourself, as a general rule. It can also be carried out by us or our service company upon your request and the actual cost will be charged. However, it will not be charged if we are responsible for the cause of the failure.
- (2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.
- (3) Even during the term of warranty, the repair cost will be charged on you in the following cases;
  - 1) a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem
  - 2) a failure caused by any alteration, etc. to the Product made on your side without our approval
  - 3) a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry
  - 4) a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced
  - 5) any replacement of consumable parts (condenser, cooling fan, etc.)
  - 6) a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters
  - 7) a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company
  - 8) any other failures which we are not responsible for or which you acknowledge we are not responsible for

### 2. Term of warranty after the stop of production

- (1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.
- (2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

### 3. Service in overseas

Our regional FA Center in overseas countries will accept the repair work of the Product; however, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA center for details.

### 4. Exclusion of responsibility for compensation against loss of opportunity, secondary loss, etc.

Whether under or after the term of warranty, we assume no responsibility for any damages arisen from causes for which we are not responsible, any losses of opportunity and/or profit incurred by you due to a failure of the Product, any damages, secondary damages or compensation for accidents arisen under a specific circumstance that are foreseen or unforeseen by our company, any damages to products other than the Product, and also compensation for any replacement work, readjustment, start-up test run of local machines and the Product and any other operations conducted by you.

### 5. Change of Product specifications

Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

### 6. Application and use of the Product

- (1) For the use of our product, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in product, and a backup or fail-safe function should operate on an external system to product when any failure or malfunction occurs.
- (2) Our product is designed and manufactured as a general purpose product for use at general industries. Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used. In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, man-operated material handling equipment, entertainment machines, safety machines, etc. are not recommended, and we assume no responsibility for any failure caused by these applications when used. We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.

# We visualize our customers' factories to solve problems and troubles.

"Visualization" of production and energy achieves future factories that advance one step forward.

The integrated solution, e-F@ctory, is based on our consolidated know-how, which has been developed through our own experiences as a user of FA products. Our e-F@ctory provides total cost reduction ranging from development to production and maintenance to achieve optimized production. This solution makes it possible to save energy and to optimize production by "visualization" that links upstream information systems and production site information, thus solving various problems on production sites.

## Sharing information across production systems

### MES Interface

Information sharing is easy and inexpensive because communication gateways, such as personal computers, are not necessary to connect factory equipment to the Manufacturing Execution System (MES).

## Optimizing production from a TCO\* stand point

### iQ Platform

Factory automation components such as controllers, human-machine interfaces, engineering environments, and networks are all seamlessly integrated to reduce TCO across different stages, from development to production and maintenance.

\* TCO : Total Cost of Ownership



## Visualization of energy consumption

### e&eco-F@ctory

It is indispensable for today's factory to be energy conscious and efficient. The e-F@ctory solution enables management of specific energy consumption, which provides the visibility needed to improve productivity. Additionally, this solution takes the total life cycle into account, including factors such as "measurement and diagnosis", "countermeasures", and "operation and management". Backed by several successes and achievements, our know-how will support your energy saving efforts.



### Network

CC-Link Family, the open field network of the world standard, and SSCNET III/H, the servo network for achieving high-speed processing and enhancement of instruction synchronization, flexibly expanding the connectivity among equipment and devices in the e-F@ctory environment.

### iQ Platform-compatible equipment

The inter-multi-CPU high-speed base unit provides slots for arbitrarily connecting programmable controllers, motion controllers, on-line CNCs, and robot controllers. Data communication speed among devices is enhanced, and their compatibility is extremely improved.

### iQ Platform-compatible engineering environments

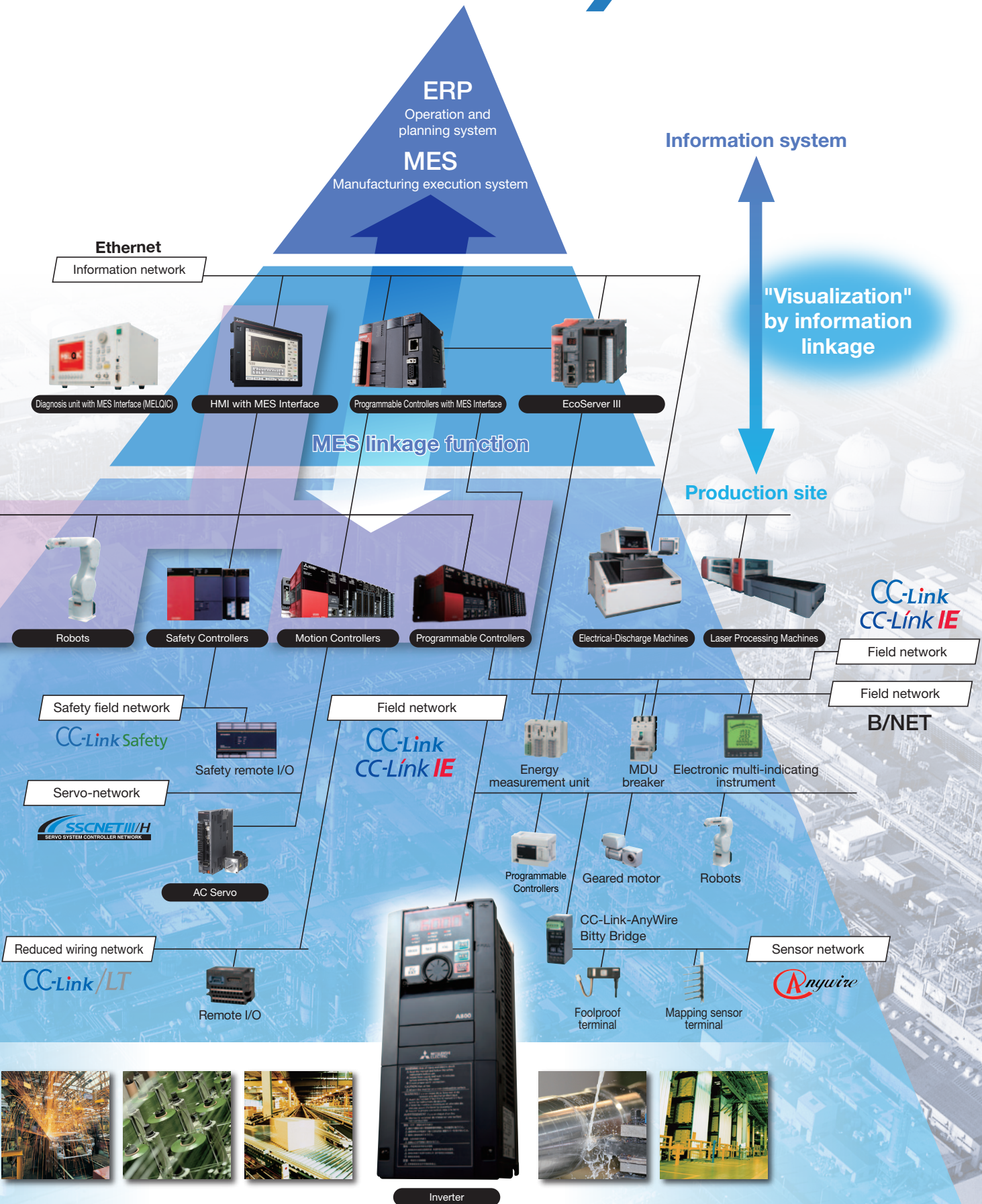
Design information is integrated and shared at stages from system design to programming, tests and startup, and operation and maintenance. In addition, programming software programs for programmable controllers, motion controllers, on-line CNCs, robots, inverters, and GOTs, which are separately provided in a conventional environment, can be integrated.





# e-Factory

Products for achieving e-F@ctory



## [ Related Factory Automation Products ]

PLC

MELSEC iQ-R Series



Revolutionary, next generation controllers building a new era in automation

- ◎High-speed, high-accuracy multiple CPU control system based on the iQ Platform
- ◎New high-speed system bus and inter-module sync realizes improved productivity and reduced TCO\*
- ◎Reducing development costs through intuitive engineering (GX Works3)
- ◎Robust security features (such as security key authentication, IP filter)

Product Specifications

Program capacity	40K steps to 1200K steps
LD instruction speed	0.98 ns
Available modules	I/O, analog, high-speed counter, positioning, simple motion, network module
Control system architecture	Rack-mounted modular based system
Supported networks	Ethernet, CC-Link IE Control Network, CC-Link IE Field Network, CC-Link, RS-232, RS-422/485

\*Total Cost of Ownership

Programmable Controller | MELSEC-L Series

“Light & Flexible” condensing various functions easily and flexibly.

- ◎CPU equipped as a standard with various functions including counter, positioning and CC-Link.
- ◎The base-less structure with high degree of freedom saves space in the control panel.
- ◎Easily confirm the system status and change the settings with the display unit.
- ◎Ten models are available in program capacities from 20 k steps to 260 k steps.



Product specifications

Program capacity	20 k steps/60 k steps/260 k steps
Number of input/output points [X/Y]	1024 points/4096 points
Number of input/output device points [X/Y]	8192 points
Basic instruction processing speed (LD instruction)	60 ns/ 40 ns/ 9.5 ns
External connection interface	USB, Ethernet, RS-232, SD memory card, CC-Link (L26CPU-BT/PBT)
Function modules	I/O, analog, high-speed counter, positioning, simple motion, temperature control, network module
Unit expansion style	Base-less structure
Network	Ethernet, CC-Link IE Field network, CC-Link, CC-Link/LT, SSCNETIII(/H), RS-232, RS-422

Programmable Controller | MELSEC-F Series

All-in-One Micro Programmable Controller equipped with all necessary functions in a compact body

- ◎Supporting small-scale control from 10 points to 384 points (using CC-Link) with an outstanding cost performance.
- ◎Wide range of options available for additional functions required by your system.
- ◎Easy to use and highly reliable. More than 12 million units have shipped worldwide. (April 2013)
- ◎Small-scale control is available in various networks such as CC-Link, Ethernet, and MODBUS.



Product specifications

Program capacity	16k steps (FX <sub>3S</sub> ) to 64 k steps (FX <sub>3U</sub> /FX <sub>3UC</sub> )
Number of input/output points	10 points (FX <sub>3S</sub> ) to 384 points (FX <sub>3U</sub> /FX <sub>3UC</sub> with CC-Link)
Basic instruction processing speed	0.21 μs (FX <sub>3S</sub> ) to 65 ns (FX <sub>3U</sub> /FX <sub>3UC</sub> )
External connection interface	RS-422, USB (FX <sub>3S</sub> /FX <sub>3U</sub> /FX <sub>3UC</sub> /FX <sub>3GE</sub> only), Ethernet (FX <sub>3GE</sub> only), CC-Link/LT (FX <sub>3UC</sub> -32MT-LT(-2) only)
Built-in functions	I/O, high-speed counter input, positioning pulse output, analog (FX <sub>3GE</sub> only)
Extended functions	I/O, analog, temperature control, high-speed counter, positioning, network
Unit expansion style	Backplane-less design
Network	Ethernet, CC-Link, CC-Link/LT, SSCNETIII, CANopen, J1939, RS-232C, RS-422, RS-485, MODBUS





## HMI

## Graphic Operation Terminal GOT2000 Series GT27 Model



To the top of HMIs with further user-friendly, satisfactory standard features.

- ◎ Comfortable screen operation even if high-load processing (e.g. logging, device data transfer) is running. (Monitoring performance is twice faster than GT16)
- ◎ Actual usable space without using a SD card is expanded to 128MB for more flexible screen design.
- ◎ Multi-touch features, two-point press, and scroll operations for more user-friendliness.
- ◎ Outline font and PNG images for clear, beautiful screen display.

## Product Specifications

Screen size	15", 12.1", 10.4", 8.4"
Resolution	XGA, SVGA, VGA
Intensity adjustment	32-step adjustment
Touch panel type	Analog resistive film
Built-in interface	RS-232, RS-422/485, Ethernet, USB, SD card
Applicable software	GT Works3
Input power supply voltage	100 to 240VAC (+10%, -15%), 24VDC (+25%, -20%)

## AC Servo

## Mitsubishi General-Purpose AC Servo MELSERVO-J4 Series



Industry-leading level of high performance servo

- ◎ Industry-leading level of basic performance: Speed frequency response (2.5kHz), 4,000,000 (4,194,304p/rev) encoder
- ◎ Advanced one-touch tuning function achieves the one-touch adjustment of advanced vibration suppression control II, etc.
- ◎ Equipped with large capacity drive recorder and machine diagnosis function for easy maintenance.
- ◎ 2-axis and 3-axis servo amplifiers are available for energy-conservative, space-saving, and low-cost machines.

## Product Specifications

Power supply specifications	1-phase/3-phase 200V AC, 1-phase 100V AC, 3-phase 400V AC
Command interface	SSCNET III/H, SSCNET III (compatible in J3 compatibility mode), CC-Link IE Field Network interface with Motion, pulse train, analog
Control mode	Position/Speed/Torque/Positioning function/Fully closed loop
Speed frequency response	2.5kHz
Tuning function	Advanced one-touch tuning, advanced vibration suppression control II, robust filter, etc.
Functional safety	Conforms to functions of IEC/EN 61800-5-2, STO: Category 3 PL d, SIL 2 Conforms to Category 4 PL e, SIL 3 by a combination with MR-D30 functional safety unit
Compatible servo motor	Rotary servo motor (rated output: 0.05 to 55kW), linear servo motor (continuous thrust 50 to 3000N), direct drive motor (rated torque: 2 to 240N·m)

## AC Servo

## Mitsubishi General-Purpose AC Servo MELSERVO-JE Series



High performance and easy to use servo system for all machines

- ◎ Easy To Use: The advanced one-touch tuning function enables servo adjustment with one-touch ease without a personal computer.
- ◎ High Performance: Class top-level basic performance including speed frequency response of 2.0kHz.
- ◎ Global Standard: Digital input/output is compatible with both sink and source type connections as a standard.

## Product specifications

Power supply specifications	1-phase/3-phase 200V AC
Command interface	Pulse train, analog
Control mode	Position/speed/torque
Speed frequency response	2.0kHz
Tuning function	Advanced one-touch tuning, advanced vibration control II, robust filter, etc.
Compatible servo motor	Rotary servo motor (rated output: 0.1 to 3kW)

## [ Related Factory Automation Products ]

Three-Phase Motor

High Performance Energy-Saving Motor

Super Line Premium Series

SF-PR



Premium Efficiency & Compatible. New Launch of Super Line Premium Series SF-PR Model

- ◎Compared to general efficiency motor SF-JR model, generated loss is reduced by 37% on average, and it is compatible with highly efficient premium IE3.
- ◎Easy replacement is achieved as mounting dimension (frame number) is compatible with general efficiency motor SF-JR model.
- ◎One motor can accommodate different power sources of Japan and the U.S. Three ratings in Japan meet the Top Runner standards, while it corresponds to EISA in the U.S.
- ◎Can be driven by inverters as standard. Advanced magnetic-flux vector control by our FR-A800 achieves steady torque drive up to 0.5Hz.

### Product Specifications

Number of poles	2-poles, 4-poles, 6-poles
Voltage · Frequency	200/200/220/230V 50/60/60/60Hz EISA 230V 60Hz or 400/400/440/460V 50/60/60/60Hz EISA 460V 60Hz
Exterior	Totally enclosed fan cooled type (inside, outside installation)
Protection system	IP44
Power transmission system	Motor with 2-poles over 11kW is dedicated for a direct connection. Motors with 4-poles and 6-poles are for both direct and crossed belt connections.
Rotation direction	Counter-clock-wise (CCW) direction viewed from the edge of axis.
Compatible standard	JEC-2137-2000 (Efficiency is compatible with IEC 60034-30.)

Robot

MELFA F Series



High speed, high precision and high reliability industrial robot

- ◎Compact body and slim arm design, allowing operating area to be expanded and load capacity increased.
- ◎The fastest in its class using high performance motors and unique driver control technology.
- ◎Improved flexibility for robot layout design considerations.
- ◎Optimal motor control tuning set automatically based on operating position, posture, and load conditions.

### Product Specifications

Degrees of freedom	Vertical:6 Horizontal:4
Installation	Vertical:Floor-mount, ceiling mount, wall mount (Range of motion for J1 is limited) Horizontal:Floor-mount
Maximum load capacity	Vertical:2-20kg Horizontal:3-20kg
Maximum reach radius	Vertical:504-1503mm Horizontal:350-1,000mm

EDM

Wire EDM MV1200R



Next-generation Innovations of our best selling Performance Machine.

- ◎Total running cost reduced up to 42%, which is accounted for 90% by filter, ion exchange resin and power consumption.
- ◎Improved productivity by an innovative automatic wire threading.
- ◎Faster machining is realized with improved power-supply performance.  
(Rz3. 5 $\mu$ m/Ra0. 45 $\mu$ m with 3cuts) (Rz2. 0 $\mu$ m/Ra0. 28 $\mu$ m with 4cuts)

### Product Specifications

Model	MV1200R
Machining travel (X×Y×Z)[mm]	(in) 400(15.7)×300(11.8)×220(8.7)(XY axis OPT-drive specifications)
Machining travel (U×V)[mm]	(in) ±60(2.4)×±60(2.4)(OPT-drive specifications)
Max. taper angle [°]	15° (maximum 200mm)(7.9°)
Max. workpiece dimensions [mm]	(in) 810(31.9)×700(27.6)×215(8.5)
Wire diameter [mm]	(in) 0.1(.004) to 0.3(.012)*1
Dielectric fluid	Water
Footprint (W×D)[mm]	(in) 2025(79.7)×2760(108.7)

\*1:  $\Phi$ 0.2(0.08) DD guides and  $\Phi$ 1.5(0.06) jet nozzle are standard equipment.



## Laser Processing Machine | CO<sub>2</sub> 2-Dimensional Laser Processing Machine eX-Series

A global standard CO<sub>2</sub> 2-dimensional laser processing systems.

- ◎Productivity has been dramatically enhanced owing to improved acceleration and the latest control technologies exclusive to Mitsubishi Electric.
- ◎2 Action Cutting allows for the entire process, from job setup to parts cutting, to be completed in two simple actions.
- ◎When not processing, the system switches to ECO mode and the resonator stops idling. Minimizes energy consumption, reducing running costs by up to 99%<sup>\*1</sup> during standby.

\*1: Compared to the previous LV-Series with Mitsubishi's designated benchmark shape.



### Product specifications

Model Name	ML3015eX
Drive system	Flying optic (3-axis beam movement)
Stroke (X×Y×Z) [mm]	3100×1565×150
Rapid feedrate [m/min]	X,Y axes: Max. 100; Z-axis: Max. 65
Processing feedrate [m/min]	Max. 50
Positioning accuracy [mm]	0.05 / 500 (X,Y axes)
Repeat accuracy [mm]	± 0.01 (X,Y axes)
Rated output [W]	4500

## Laser Processing Machine for Substrate Drilling | GTW4 Series

Ever-evolving global standard machine

- ◎Newly-developed super-fast galvano and 360W high-power resonator achieve industry-leading productivity.
- ◎Laser beam generated by unparalleled resonator enables stable high-quality copper-direct processing on various surface treatments.
- ◎Single machine can support variety of processing application with Mitsubishi unique powerful laser and optimum beam control.
- ◎Original resonator structure, which can be refreshed by replacing some parts only, realizes low operating cost.



### Product specifications

Model name	ML605GTW4(-H)-5350U / ML605GTW4 (-P) -5350U / ML706GTW4-5350U
Processing workpiece dimensions (mm)	620×560 / 815×662
XY table maximum feedrate (m/min)	50
Laser type	CO <sub>2</sub> laser
Oscillator power (W)	360W
Oscillator set pulse frequency	10 to 10000Hz

## CNC

## Mitsubishi CNC M700V Series

High-grade model equipped with advanced complete nano control

- ◎Achieve complete nano control with the latest RISC-CPU and high-speed optical servo network.
- ◎Realize super-high grade processing by combining the complete nano control, state-of-the-art SSS control and OMR control, etc.
- ◎Display of essential information of grouped on three screens to greatly reduce processing setup time with easy operability.
- ◎The M700VW Series with WindowsXPe and M700VS Series with integrated control unit and display type are available.

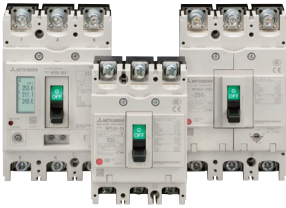


### Product Specifications

Maximum number of control axes (NC axes + spindles + PLC axes)	16 axes (M720VW/M720VS have 12 axes)
Maximum number of part systems	Machining center system: 2 systems Lathe system: 4 systems
Least command increment	1nm (M720VW/M720VS 0.1μm)
Least control increment	1nm
Maximum program capacity	2,000kB (5,120m)
Maximum PLC program capacity	128,000 steps
Main functions (for machining center)	Simultaneous 5-axis machining, SSS control, high-speed high-accuracy control, tool nose point control, tilt plane machining, etc.
Main functions (for lathe)	Milling interpolation, 2-system simultaneous thread cutting, inter-system control axis synchronization, control axis superimposition, combination control, etc.

## [ Related Factory Automation Products ]

### Low Voltage Circuit Breakers | Mitsubishi WS-V Series Molded Case Circuit Breakers, Earth Leakage Circuit Breakers



Technologies based on long year experience realize more improved performance.

- ◎The new electronic circuit breakers can display various measurement items.
- ◎Improvement of breaking performance with new breaking technology “Expanded ISTAC”.
- ◎Compliance with global standard for panel and machine export.
- ◎Commoditization of internal accessories for shorter delivery time and stock reduction.

Product Specifications.

Frame	32-250A Frame
Applicable standard	Applicable to IEC, GB, UL, CSA, JIS and etc.
Expansion of UL listed product line-up	New line-up of 480VAC type with high breaking performance for SCCR requirement
Commoditization of internal accessories	Reduction of internal accessory types from 3 to 1
Commoditization for AC and DC circuit use	Common use of 32/63A frame in both AC and DC circuit
Compact size for easy to use	Thermal adjustable and electronic circuit breakers are same size as 250AF fixed type
Measuring Display Unit (MDU) breakers	MDU breakers measure, display and transmit energy date to realize energy management.

### Magnetic Starter | MS-T Series



Exceed your expectations.

- ◎10A frame model is over 16% smaller with a width of just 36mm!!
- ◎New integrated terminal covers.
- ◎Reduce your coil inventory by up to 50%.
- ◎Be certified to the highest international levels while work is ongoing to gain other country.

Product specifications

Frame	10 A to 32 A
Applicable standards	Certification to various standards including IEC, JIS, CE, UL, TÜV, CCC.
Terminal cover	Standard terminal cover improves safety, simplifies ordering, and reduces inventory, etc.
Improved wiring	Wiring and operability are improved with streamlining wiring terminal BC specifications.
Operation coil rating	Wide range of operation coil ratings reduces number of coil types from 14 (N Series) to 7 types and simplifies selection.
Option units	Diverse lineup includes Auxiliary Contact Block, Operation Coil Surge Absorber Unit, Mechanical Interlock Unit.

### Low-voltage switch | Mitsubishi Motor Circuit Breaker MMP-T Series



Introducing a Motor Circuit Breaker from Mitsubishi Electric!

- ◎Design smaller panels by using the Motor Circuit Breaker, various options and MS-T Series Magnetic Contactor.
- ◎Prevent secondary damage with Motor Circuit Breaker and Magnetic Contactor combination.
- ◎Streamlined wiring terminal BC specifications (option) contribute to improving your productivity.
- ◎Supports your overseas business with compliance to various International Standards as well as the UL Type E/F combination.

Product specifications

Rated current	0.16 A to 32 A (15 types)
Applicable (compliant) standards	Standard product compliant with various International Standards including IEC, JIS, CCC, TÜV and UL (certified)
Wiring types	Bare wire, rod terminal, Y crimp and round crimp supported
Improvement of wiring	Wiring and operability are improved with connection conductor unit and streamlined wiring terminal BC specifications (option)
Optional units	Auxiliary/Alarm Contact Unit, Short-Circuit Indicator Unit, Line Side Terminal Adapter, Connection Conductor Unit, etc., available
DIN rail mounting	Standard product mountable on rail
Finger protection support	Standard product compliant with IP20 from front side of terminals
Application in North America	Type E/F combination certification acquired. Compatible up to maximum SCCR value 50 kA



A series of horizontal lines for writing or drawing.

**•Trademarks**

LONWORKS® is a registered trademark of Echelon Corporation, DeviceNet™ is a trademark of the ODVA, PROFIBUS™ is a trademark of the PROFIBUS User Organization, and MODBUS® is a registered trademark of Schneider Automation Incorporated, and ETHERNET® is a registered trademark of Xerox Corporation of the United States.

Other company and product names herein are the trademarks and registered trademarks of their respective owners.

 **Safety Warning**

To ensure proper use of the products listed in this catalog, please be sure to read the instruction manual prior to use.



# Global network for comprehensive support of

- Global FA Center
- FA Center Satellite (China)
- Mechatronics Service Base (China)
- Mitsubishi Sales Offices
- Production Facility
- ◆ Development Center



**Ratingsen, Germany**

Mitsubishi Electric Europe B.V.  
German Branch (Germany FA Center)



**Kraków, Poland**

Mitsubishi Electric Europe B.V.  
Polish Branch (Europe FA Center)



**Hatfield, UK**

Mitsubishi Electric Europe B.V.  
UK Branch (UK FA Center)



**Praha, Czech Republic**

Mitsubishi Electric Europe B.V.  
Czech Branch (Czech Republic FA Center)



**Pune, Gurgaon, Bangalore, Chennai, Ahmedabad, India**

Mitsubishi Electric India Pvt. Ltd.



**Bangkok, Thailand**

Mitsubishi Electric Factory Automation (Thailand) Co., Ltd. (Thai FA Center)




**Singapore**

Mitsubishi Electric Asia Pte. Ltd. (ASEAN FA Center)




**Nagoya, Japan**

### China (including Hong Kong District)




**Beijing**

Mitsubishi Automation (China) Ltd.  
Beijing Office (Beijing FA Center)



**Tianjin**

Mitsubishi Automation (China) Ltd.  
Tianjin Office (Tianjin FA Center)



**Guangzhou**

Mitsubishi Electric Automation (China) Ltd. Guangzhou Office (Guangzhou FA Center)

**Shanghai**

Mitsubishi Automation (China) Ltd. (Shanghai FA Center)

**Shanghai**

Mitsubishi Electric Automation Solution Center

# customers' manufacturing.



Service bases are established around the world to globally provide the same services as in Japan.

**Overseas bases are opened one after another to support business expansion of our customers.**

Overseas bases | As of July 2014 \* Some includes distributors

Area	Our overseas offices		Bases providing our products	Countries (Regions)
		FA Center (Satellite)		
EMEA	11	6 (2)	146	54
China	13	4 (10)	171	1
Asia	21	13	79	10
America	14	4 (0)	130	16
Others	1	0	3	2
<b>Total</b>	<b>60</b>	<b>27 (12)</b>	<b>529</b>	<b>83</b>



Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO14001 (standards for environmental management systems) and ISO9001 (standards for quality assurance management systems)



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